

### 3.13

Time Series Analysis by Shumway and Stoffer 4th ed.

Michael Jagdharry

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Let

$$\epsilon_t = x_t - \sum_{i=1}^{h-1} a_i x_{t-i}$$

$$\delta_{t-h} = x_{t-h} - \sum_{j=1}^{h-1} b_j x_{t-j}$$

be two residuals where  $\{a_1, \dots, a_n\}$  and  $\{b_1, \dots, b_n\}$  minimize  $E(\epsilon_t^2)$  and  $E(\delta_{t-h}^2)$  respectively.

If  $x_t^h$  is the best linear predictor of  $x_t$  given  $\{x_{t-1}, x_{t-2}, \dots, x_{t-h}\}$ , that is,

$$x_t^h = \alpha_{h1}x_{t-1} + \alpha_{h2}x_{t-2} + \dots + \alpha_{hh}x_{t-h}$$

Show that

$$\phi_{hh} = \frac{E(\epsilon_t \delta_{t-h})}{\sqrt{E(\epsilon_t^2)E(\delta_{t-h}^2)}} = \frac{\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}}{1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}} = \alpha_{hh}$$

Before proceeding, let's establish the following vector definitions:

$$\begin{aligned} \gamma_{h-1} &= [\gamma(1) \ \gamma(2) \ \dots \ \gamma(h-1)]^T \\ \rho_{h-1} &= [\rho(1) \ \rho(2) \ \dots \ \rho(h-1)]^T \\ \tilde{\rho}_{h-1} &= [\rho(h-1) \ \rho(h-2) \ \dots \ \rho(1)]^T \\ \phi &= [\phi_{h1} \ \phi_{h2} \ \dots \ \phi_{hh}]^T \\ \alpha &= [\alpha_{h1} \ \alpha_{h2} \ \dots \ \alpha_{hh}]^T \\ \alpha_1 &= [\alpha_{h1} \ \alpha_{h2} \ \dots \ \alpha_{h(h-1)}]^T \\ a &= [a_1 \ a_2 \ \dots \ a_{h-1}]^T \\ b &= [b_1 \ b_2 \ \dots \ b_{h-1}]^T \\ x &= [x_{t-1} \ x_{t-2} \ \dots \ x_{t-h+1}]^T \end{aligned}$$

From the results of (3.53) and (3.54), we see the coefficient of  $x_{t+i}$  in (3.54) is the coefficient of  $x_{t+h-i}$  in (3.53). Applying these results here, the coefficient of  $x_{t-i}$  in  $\epsilon_t$  is the coefficient of  $x_{t-h+i} = x_{t-(h-i)}$  in  $\delta_{t-h}$ . This means that  $a_i = b_{h-i}$ , i.e.

$$b = [b_1 \ b_2 \ \dots \ b_n]^T = [a_{h-1} \ a_{h-2} \ \dots \ a_1]^T = \tilde{a}$$

With the knowledge that for any two column vectors  $c$  and  $k$ ,  $c^T k = \sum c_i k_i$ , we can express  $E(\epsilon_t \delta_{t-h})$  as

$$\begin{aligned}
E(\epsilon_t \delta_{t-h}) &= \\
E[(x_t - \sum_{i=1}^{h-1} a_i x_{t-i})(x_{t-h} - \sum_{j=1}^{h-1} b_j x_{t-j})] &= \\
E[(x_t - a^T x)(x_{t-h} - \sum_{j=1}^{h-1} a_{h-j} x_{t-j})] &= \\
E[(x_t - a^T x)(x_{t-h} - \tilde{a}^T x)] &= \\
E[(x_t x_{t-h} - x_{t-h} a^T x - x_t \tilde{a}^T x + a^T x x^T \tilde{a}] &= \\
E(x_t x_{t-h}) - a^T E(x_{t-h} x) - \tilde{a}^T E(x_t x) + a^T E(x x^T) \tilde{a} &= \\
\gamma(h) - a^T \tilde{\gamma}_{h-1} - \tilde{a}^T \gamma_{h-1} + a^T \Gamma_{h-1} \tilde{a} &
\end{aligned}$$

In this problem, the vectors  $a = \alpha$ , and since the coefficients  $\alpha_{hi}$  are such that they produce the BLP for  $x_t^h$ , we can apply the prediction equations (3.63) and (3.64) to them, for  $n = h - 1$ . In other words,  $a = \alpha = \phi = \Gamma_{h-1}^{-1} \gamma_{h-1}$  in (3.64), and  $\Gamma_{h-1} \tilde{a} = \tilde{\gamma}_{h-1}$ . Furthermore, we can show the following relationship between the variance-covariance matrix  $\Gamma$  and the correlation matrix  $R$ :

$$\begin{aligned}
\phi_n &= \Gamma_n^{-1} \gamma_n \\
\Gamma_n \phi_n &= \gamma_n \\
\gamma(0) R_n \phi_n &= \gamma(0) \rho_n \\
R_n \phi_n &= \rho_n \\
\phi_n &= R^{-1} \rho_n
\end{aligned}$$

Comparing the initial and final equations here,

$$\Gamma_n^{-1} \gamma_n = R^{-1} \rho_n$$

Continuing from where we left off,

$$\begin{aligned}
\gamma(h) - a^T \tilde{\gamma}_{h-1} - \tilde{a}^T \gamma_{h-1} + a^T \Gamma_{h-1} \tilde{a} &= \\
\gamma(h) - \tilde{a}^T \gamma_{h-1} - a^T \tilde{\gamma}_{h-1} + a^T \tilde{\gamma}_{h-1} &= \\
\gamma(h) - \tilde{a}^T \gamma_{h-1} &= \\
\gamma(h) - (\Gamma_{h-1}^{-1} \tilde{\gamma}_{h-1})^T \gamma_{h-1} &= \\
\gamma(h) - \tilde{\gamma}_{h-1}^T \Gamma_{h-1}^{-1} \gamma_{h-1} &= \\
\gamma(0) \rho(h) - \gamma(0) \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1} &= \\
\gamma(0) [\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}] &= \\
E(\epsilon_t \delta_{t-h}) &
\end{aligned}$$

We can compute  $E(\epsilon_t^2)$  and  $E(\delta_{t-h}^2)$  as follows:

$$\begin{aligned}
E(\epsilon_t^2) &= \\
E[(x_t - a^T x)^2] &= \\
E(x_t^2 - 2a^T x_t x + a^T x x^T a) &= \\
E(x_t^2) - 2a^T E(x_t x) + a^T E(x x^T) a &= \\
E(x_t^2) - 2a^T E(x_t x) + a^T E(x x^T) a &= \\
\gamma(0) - 2a^T \gamma_{h-1} + a^T \Gamma_{h-1} a &= \\
\gamma(0) - 2a^T \gamma_{h-1} + a^T \gamma_{h-1} &= \\
\gamma(0) - a^T \gamma_{h-1}
\end{aligned}$$

$$\begin{aligned}
E(\delta_{t-h}^2) &= \\
E[(x_t - \tilde{a}^T x)^2]
\end{aligned}$$

Replacing  $a$  with  $\tilde{a}$  and proceeding with the same steps as above, we obtain

$$\gamma(0) - \tilde{a}^T \tilde{\gamma}_{h-1}$$

To show that  $E(\epsilon_t^2) = E(\delta_{t-h}^2)$ , we need only show that  $\tilde{a}^T \tilde{\gamma}_{h-1} = a^T \gamma_{h-1}$ . This is true for the following:

$$\begin{aligned}
&\tilde{a}^T \tilde{\gamma}_{h-1} = \\
&a_{h-1} \gamma(h-1) + a_{h-2} \gamma(h-2) + \cdots + a_2 \gamma(2) + a_1 \gamma(1)
\end{aligned}$$

$$\begin{aligned}
&a^T \gamma_{h-1} = \\
&a_1 \gamma(1) + a_2 \gamma(2) + \cdots + a_{h-2} \gamma(h-2) + a_{h-1} \gamma(h-1)
\end{aligned}$$

But these are exactly the same sums, with one's summands in the reverse order of the other. Hence,

$$\tilde{a}^T \tilde{\gamma}_{h-1} = a^T \gamma_{h-1}$$

It follows

$$\begin{aligned}
E(\epsilon_t^2) &= E(\delta_{t-h}^2) \\
\frac{E(\epsilon_t \delta_{t-h})}{\sqrt{E(\epsilon_t^2) E(\delta_{t-h}^2)}} &= \frac{E(\epsilon_t \delta_{t-h})}{\sqrt{E(\epsilon_t^2)^2}} = \frac{E(\epsilon_t \delta_{t-h})}{E(\epsilon_t^2)} =
\end{aligned}$$

$$\frac{\gamma(0)[\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}]}{\gamma(0) - \tilde{a}^T \tilde{\gamma}_{h-1}} =$$

$$\frac{\gamma(0)[\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}]}{\gamma(0) - \tilde{\gamma}_{h-1}^T \Gamma_{h-1}^{-1} \tilde{\gamma}_{h-1}} =$$

$$\frac{\gamma(0)[\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}]}{\gamma(0) - \gamma(0) \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}} =$$

$$\frac{\gamma(0)[\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}]}{\gamma(0)[1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}]} =$$

$$\frac{\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}}{1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}}$$

as desired.

To show the rightmost equality

$$\frac{\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}}{1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}} = \alpha_{hh}$$

Write the matrix equation  $R_n \alpha_n = \rho_n$  in partitioned form as:

$$\begin{bmatrix} R_{h-1} & \tilde{\rho}_{h-1} \\ \tilde{\rho}_{h-1}^T & \rho(0) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_{hh} \end{bmatrix} = \begin{bmatrix} \rho_{h-1} \\ \rho(h) \end{bmatrix}$$

The first implied equation is

$$\begin{aligned} R_{h-1} \alpha_1 + \tilde{\rho}_{h-1} \alpha_{hh} &= \rho_{h-1} \\ R_{h-1} \alpha_1 &= \rho_{h-1} - \tilde{\rho}_{h-1} \alpha_{hh} \\ \alpha_1 &= R_{h-1}^{-1} (\rho_{h-1} - \tilde{\rho}_{h-1} \alpha_{hh}) \end{aligned}$$

Substituting into the second implied equation yields

$$\begin{aligned} \tilde{\rho}_{h-1}^T \alpha_1 + \rho(0) \alpha_{hh} &= \rho(h) \\ \tilde{\rho}_{h-1}^T R_{h-1}^{-1} (\rho_{h-1} - \tilde{\rho}_{h-1} \alpha_{hh}) + \alpha_{hh} &= \rho(h) \\ \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1} - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1} \alpha_{hh} + \alpha_{hh} &= \rho(h) \\ \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1} + \alpha_{hh} (1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}) &= \rho(h) \\ \alpha_{hh} (1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}) &= \rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1} \\ \alpha_{hh} &= \frac{\rho(h) - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \rho_{h-1}}{1 - \tilde{\rho}_{h-1}^T R_{h-1}^{-1} \tilde{\rho}_{h-1}} \end{aligned}$$

as desired.