## Backgropagate (y, A, n, error function)

Mote: Here we use the identity  $\sigma'(x) = \sigma(x)(1 - \sigma(x))$ 

Given: weight matrices  $W^2, ..., W^L$ bias vectors  $\tilde{b}^2, ..., \tilde{b}^L$ at each layer

· Declare vars:

· da C, deriv. of error wrt current layer's activations

· dz C, same but wrt current layer's z values

. DB, change in B at current layer

. DW, same for W

· á, current layer's activations

· a', prev. layer's activations

· g , vector corresponding to classification y

 $\vec{y} = \hat{e}_y$  $\vec{a} = lost$  element of A

. If error function is Euclidean Distance:

 $\vec{J}_{\vec{a}}C = \vec{a} - \vec{g}$   $\vec{J}_{\vec{z}}C = \vec{J}_{\vec{a}}C \circ \left[\vec{a} \circ (\vec{1} - \vec{a})\right]$ 

· Else if error function is Cross Entropy:

. d= C = a-g

. For each layer I from L down to 2:

 $\begin{bmatrix} \cdot \vec{a} = l^{+1} & \text{elem. of } A \\ \cdot \vec{a}' = (l-1)^{+1} & \text{elem. of } A \end{bmatrix}$ 

 $\begin{cases}
. \Delta \vec{b} = - \eta \vec{d}_{\hat{z}} C \\
. \Delta W = - \eta \vec{d}_{\hat{z}} C \otimes \vec{a}'
\end{cases}$ 

 $\begin{bmatrix} \cdot \vec{A}_{\vec{a}} C = (W^{I})^{t} \vec{A}_{\vec{z}} C \\ \cdot \vec{A}_{\vec{z}} C = \vec{A}_{\vec{a}} C O [\vec{a}' O (\vec{1} - \vec{a}')] \end{bmatrix}$ 

 $\begin{bmatrix} \cdot \vec{b} & + = \Delta \vec{b} \\ \cdot W^{\ell} & + = \Delta W \end{bmatrix}$ 

Train  $(\vec{x}_1, ..., \vec{x}_n, y_1, ..., y_n, \eta, T, error function)$ :

· Declare vars:

· A, the list of activations returned by Feedforward

· Repeat T times:

· For each \$,y:

. A = Feed forward (x)

· Backpropagate (y, A, n, error function)