

Jan 30, 2024 14:45

array\_sol.f

Page 1/6

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c sol_0(*,i) : contains the imaginary and real parts of the solution for point
s such that ineq(i) != 0
c sol(i) : contains solution for all points
c The dimension of the geometric domain is : dim_32 = 2
c The dimension of the vector field is : dim2 = 3
c

subroutine array_sol (i_cond, num_modes, n_msh_el, n_msh_pts,
* n_ddl, neq, nnodes, n_core, bloch_vec, iindex, table_nod,
* table_N_E_F, type_el, ineq,
* ip_period_N, ip_period_N_E_F, x, x_N_E_F,
* v_cmplx, mode_pol, sol_0, sol)

implicit none
integer*8 i_cond, num_modes, n_msh_el, n_msh_pts, n_ddl
integer*8 neq, nnodes
integer*8 n_core(2), type_el(n_msh_el)
integer*8 ineq(3,n_ddl), iindex(*)
integer*8 ip_period_N(n_msh_pts), ip_period_N_E_F(n_ddl)
integer*8 table_nod(nnodes,n_msh_el), table_N_E_F(14,n_msh_el)
double precision bloch_vec(2), x(2,n_msh_pts), x_N_E_F(2,n_ddl)
complex*16 sol_0(neq,num_modes)
c sol(3, 1..nnodes,num_modes, n_msh_el) contains the values of the
3 components at P2 interpolation nodes
c sol(3, nnodes+1..nnodes+7,num_modes, n_msh_el) contains the values of Ez c
omponent at P3 interpolation nodes (per element: 6 edge-nodes and 1 interior nod
e)
complex*16 sol(3,nnodes+7,num_modes,n_msh_el)
complex*16 v_cmplx(num_modes), v_tmp(num_modes)
complex*16 mode_pol(4,num_modes)

c Local variables
integer*8 nnodes_0, nddl_0, nddl_t
c 32-bit integers for BLAS and LAPACK
integer*4 dim_32
parameter (nnodes_0 = 6)
parameter (nddl_0 = 14)
parameter (nddl_t=4)
parameter (dim_32=2)

c
double precision mode_comp(4)
integer*8 nod_el_p(nnodes_0), basis_list(4,3,nddl_t)
double precision xn(dim_32,nnodes_0), xel(dim_32,nnodes_0)
complex*16 sol_el(3,nnodes_0+7)

double precision phi1_list(3), grad1_mat0(dim_32,3)
double precision grad1_mat(dim_32,3)

double precision phi2_list(6), grad2_mat0(dim_32,6)
double precision grad2_mat(dim_32,6)

double precision phi3_list(10), grad3_mat0(dim_32,10)
double precision grad3_mat(dim_32,10)

double precision vec_phi_j(dim_32), curl_phi_j, phi_z_j
double complex val_exp(nddl_0)

integer*8 info_curved
double precision xx(dim_32), xx_g(dim_32), det, r_tmp1

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Monday June 03, 2024

../array\_sol.f

Jan 30, 2024 14:45

array\_sol.f

Page 2/6

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double precision delta_xx(dim_32)
double precision mat_B(dim_32,dim_32)
double precision mat_T(dim_32,dim_32)

double precision ZERO, ONE
parameter (ZERO = 0.0D0)
parameter (ONE = 1.0D0)

c
integer*8 j, k, il, jl, m, inod, typ_e
integer*8 debug, i_sol_max
integer*8 iel, ival, ival2, jtest, jp, ind_jp, j_eq
double precision ddot
complex*16 ii, z_tmp1, z_tmp2, z_sol_max

c ii = sqrt(-1)
ii = cmplx(0.0d0, 1.0d0, 8)

c debug = 0

c
if ( nnodes .ne. 6 ) then
write(*,*) "array_sol: problem nnodes = ", nnodes
write(*,*) "array_sol: nnodes should be equal to 6 !"
write(*,*) "array_sol: Aborting..."
stop
endif

c
do j=1,num_modes
jl=iindex(j)
v_tmp(j) = v_cmplx(jl)
enddo
do j=1,num_modes
v_cmplx(j) = v_tmp(j)
enddo

c
c Coordinates of the interpolation nodes
call interp_nod_2d (nnodes, xn)
do ival=1,num_modes
ival2 = iindex(ival)
do j=1,4
mode_pol(j,ival) = 0.0d0
enddo
z_sol_max = 0.0d0
i_sol_max = 0
do iel=1,n_msh_el
typ_e = type_el(iel)
do j=1,4
mode_comp(j) = 0.0d0
enddo
do inod=1,nnodes
j = table_nod(inod,iel)
nod_el_p(inod) = j
xel(1,inod) = x(1,j)
xel(2,inod) = x(2,j)
enddo
if (i_cond .eq. 2) then
c Periodic boundary condition
do inod=1,nnodes
j = table_nod(inod,iel)
k = ip_period_N(j)
if (k .ne. 0) j=k
nod_el_p(inod) = j
enddo

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1/3

Jan 30, 2024 14:45

array\_sol.f

Page 3/6

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endif
do j=1,nddl_0
  val_exp(j) = 1.0d0
enddo
if (i_cond .eq. 2) then
  val_exp: Bloch mod ephase factor between the origin point and destination point
  For a pair of periodic points, one is chosen as origin and the other is the destination
  do j=1,nddl_0
    jp = table_N_E_F(j,iel)
    jl = ip_period_N_E_F(jp)
    if (jl .ne. 0) then
      do k=1,dim_32
        delta_xx(k) = x_N_E_F(k,jp) - x_N_E_F(k,jl)
      enddo
      r_tmp1 = ddot(dim_32, bloch_vec, 1, delta_xx, 1)
      val_exp(j) = exp(ii*r_tmp1)
    endif
  enddo
endif
call basis_ls (nod_el_p, basis_list)
call curved_elem_tri (nnodes, xel, info_curved, r_tmp1)
P2 Lagrange Interpolation nodes for the unit triangle
xn = coordinate on the reference triangle
do inod=1,nnodes+7
  do j=1,3
    sol_el(j,inod) = 0.00
  enddo
enddo
do inod=1,nnodes
  do j=1,dim_32
    xx(j) = xn(j,inod)
  enddo
  do j=1,3
    sol_el(j,inod) = 0.00
  enddo
enddo
We will also need the gradients of the P1 element
call phi1_2d_mat (xx, phi1_list, grad1_mat0)
grad2_mat0 = gradient on the reference triangle (P2 element)
call phi2_2d_mat (xx, phi2_list, grad2_mat0)
grad3_mat0 = gradient on the reference tetrahedron (P3 element)
call phi3_2d_mat (xx, phi3_list, grad3_mat0)

if (info_curved .eq. 0) then
  Rectilinear element
  call jacobian_p1_2d (xx, xel, nnodes,
    * xx_g, det, mat_B, mat_T)
  if (det .le. 0 .and. debug .eq. 1) then
    write(*,*) " !!!"
    write(*,*) "array_sol: det <= 0: iel, det ", iel, det
  endif
else
  Isoparametric element
  call jacobian_p2_2d (xx, xel, nnodes, phi2_list,
    * grad2_mat0, xx_g, det, mat_B, mat_T)
endif
C if(abs(det) .lt. 1.0d-10) then
if(abs(det) .lt. 1.0d-20) then
  write(*,*)
  write(*,*) " ??? "
  write(*,*) "array_sol: det = 0: iel, det = ", iel, det

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Jan 30, 2024 14:45

array\_sol.f

Page 4/6

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write(*,*) "array_sol: Aborting..."
stop
endif
grad_i = gradient on the actual triangle
grad_i0 = Transpose(mat_T)*grad_i0
Calculation of the matrix-matrix product:
call DGEMM('Transpose','N', dim_32, 3, dim_32, ONE, mat_T,
  * dim_32, grad1_mat0, dim_32, ZERO, grad1_mat, dim_32)
call DGEMM('Transpose','N', dim_32, 6, dim_32, ONE, mat_T,
  * dim_32, grad2_mat0, dim_32, ZERO, grad2_mat, dim_32)
call DGEMM('Transpose','N', dim_32, 10, dim_32, ONE, mat_T,
  * dim_32, grad3_mat0, dim_32, ZERO, grad3_mat, dim_32)

C
C Contribution to the transverse component
do jtest=1,nddl_t
  do j_eq=1,3
    jp = table_N_E_F(jtest,iel)
    ind_jp = ineq(j_eq,jp)
    if (ind_jp .gt. 0) then
      m = basis_list(2, j_eq, jtest)
      if (m .eq. inod) then
        ! inod correspond to a P2 interpolation node
        The contribution is nonzero only whe
        Determine the basis vector
        call basis_vec (j_eq, jtest, basis_list, phi2_list,
          * grad1_mat, grad2_mat, vec_phi_j, curl_phi_j)
        z_tmp1 = sol_0(ind_jp, ival2)
        z_tmp1 = z_tmp1 * val_exp(jtest)
        do j=1,dim_32
          z_tmp2 = z_tmp1 * vec_phi_j(j)
          sol_el(j,inod) = sol_el(j,inod) + z_tmp2
          if (m .ne. inod .and. abs(z_tmp2) .gt. 1.0d-7) then
            write(*,*)
            write(*,*) iel, inod, m, abs(z_tmp2)
            write(*,*) "vec_phi_j=", vec_phi_j
            write(*,*) "xx=", xx
            write(*,*) "xn=", (xn(k,inod),k=1,dim_32)
            write(*,*) "phi2_list=", phi2_list
          endif
        enddo
      endif
    endif
  enddo
enddo
Contribution to the longitudinal component
! The initial P3 value of Ez is interpolated over P2 nodes
do jtest=nddl_t+1,nddl_0
  ! 3
  do j_eq=1,1
    jp = table_N_E_F(jtest,iel)
    ind_jp = ineq(j_eq,jp)
    if (ind_jp .gt. 0) then
      z_tmp1 = sol_0(ind_jp, ival2)
      m = jtest-nddl_t
      phi_z_j = phi3_list(m)
      z_tmp1 = z_tmp1 * val_exp(jtest)
      z_tmp2 = z_tmp1 * phi_z_j
      sol_el(3,inod) = sol_el(3,inod) + z_tmp2
    endif
  enddo
enddo
enddo

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Jan 30, 2024 14:45

array\_sol.f

Page 5/6

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do j=1,3
  z_tmp2 = sol_el(j,inod)
  sol(j,inod,ival,iel) = z_tmp2
  if (abs(z_sol_max) .lt. abs(z_tmp2)) then
    z_sol_max = z_tmp2
    i_sol_max = table_nod(inod,iel)
  endif
enddo
c Contribution of the element iel to the mode component
do j=1,3
  mode_comp(j) = mode_comp(j) + abs(sol_el(j,inod))*2
enddo
cccccccccc
c Saving the P3 values of Ez at: the 6 edge nodes and the interior node
do inod=nnodes+1,nnodes+7
  do j=1,3
    sol_el(j,inod) = 0.00
  enddo
  jtest = nddl_t+inod-nnodes+3
  j_eq = 1
  jp = table_N_E_F(jtest,iel)
  ind_jp = ineq(j_eq,jp)
  if (ind_jp .gt. 0) then
    z_tmp1 = sol_0(ind_jp, ival2)
    z_tmp1 = z_tmp1 * val_exp(jtest)
    sol_el(3,inod) = z_tmp1
  endif
  do j=1,3
    z_tmp2 = sol_el(j,inod)
    sol(j,inod,ival,iel) = z_tmp2
  enddo
enddo
cccccccccc
c Avarage values
do j=1,3
  mode_comp(j) = abs(det)*mode_comp(j)/dble(nnodes)
enddo
c Add the contribution of the element iel to the mode component
do j=1,3
  mode_pol(j,ival) = mode_pol(j,ival) + mode_comp(j)
enddo
if (typ_e .eq. n_core(1) .or. typ_e .eq. n_core(2)) then
  z_tmp2 = mode_comp(1) + mode_comp(2)
  + mode_comp(3)
  mode_pol(4,ival) = mode_pol(4,ival) + z_tmp2
endif
enddo
c Total energy and normalization
z_tmp2 = mode_pol(1,ival) + mode_pol(2,ival)
+ mode_pol(3,ival)
if (abs(z_tmp2) .lt. 1.0d-10) then
  write(*,*) "array_sol: the total energy ",
  "is too small: ", z_tmp2
  write(*,*) "array_sol: ival ival2 = ", ival, ival2
  write(*,*) "array_sol: zero eigenvector; aborting..."
  stop
endif
do j=1,3
  mode_pol(j,ival) = mode_pol(j,ival) / z_tmp2
enddo
j=4

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Jan 30, 2024 14:45

array\_sol.f

Page 6/6

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mode_pol(j,ival) = mode_pol(j,ival) / z_tmp2
c Check if the eigenvector is nonzero
if (abs(z_sol_max) .lt. 1.0d-10) then
  z_sol_max = z_tmp2
  write(*,*) "array_sol: z_sol_max is too small"
  write(*,*) "array_sol: z_sol_max = ", z_sol_max
  write(*,*) "ival, ival2, num_modes = ", ival, ival2, num_modes
  write(*,*) "array_sol: zero eigenvector; aborting..."
  stop
endif
c Normalization so that the maximum field component is 1
do iel=1,n_msh_el
  do inod=1,nnodes
    il = table_nod(inod,iel)
    do j=1,3
      z_tmp1 = sol(j,inod,ival,iel)/z_sol_max
      sol(j,inod,ival,iel) = z_tmp1
    enddo
    il = table_nod(inod,iel)
    if (il .eq. i_sol_max .and. debug .eq. 1) then
      write(*,*) "array_sol:"
      write(*,*) "ival, il, iel = ", ival, il, iel
      write(*,*) "array_sol: Field normalisaion point:"
      write(*,*) "x = ", dble(x(1,il))
      write(*,*) "y = ", dble(x(2,il))
      write(*,*) "i_sol_max = ", i_sol_max
      write(*,*) ival, il, iel,
      * (dble(sol(j,inod,ival,iel)),j=1,3)
      * write(*,*) ival, il, iel,
      * (imag(sol(j,inod,ival,iel)),j=1,3)
    endif
  enddo
cccccccccc
do inod=nnodes+1,nnodes+7
  do j=1,3
    z_tmp1 = sol(j,inod,ival,iel)/z_sol_max
    sol(j,inod,ival,iel) = z_tmp1
  enddo
enddo
cccccccccc
do j=1,neq
  z_tmp1 = sol_0(j,ival2)/z_sol_max
  sol_0(j,ival2) = z_tmp1
enddo

if (debug .eq. 1) then
  write(*,*)
endif
enddo
c
return
end

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