5. a.
$$\tilde{X} = \begin{bmatrix} \tilde{X} & \tilde{X} \\ \tilde{X} & \tilde{I}_{f} \end{bmatrix}$$
 $\tilde{Y} = \begin{bmatrix} \tilde{Y} \\ \tilde{Q}_{f} & \tilde{I}_{f} \end{bmatrix}$ $\tilde{P}_{out} = \begin{bmatrix} \tilde{X}^{T} & \tilde{X} & \tilde{I}_{f} \end{bmatrix} \begin{bmatrix} \tilde{X} \\ \tilde{A} & \tilde{I}_{f} \end{bmatrix} \begin{bmatrix} \tilde{X} \\ \tilde{A} & \tilde{I}_{f} \end{bmatrix} \begin{bmatrix} \tilde{Y} \\ \tilde{Q}_{f+1} \end{bmatrix} = X^{T} X + \lambda I_{f}$

$$\tilde{P}_{out} = \begin{bmatrix} \tilde{X}^{T} & \tilde{X} & \tilde{I}_{f} \end{bmatrix} \begin{bmatrix} \tilde{Y} \\ \tilde{Q}_{f+1} \end{bmatrix} = X^{T} Y + 0 = X^{T} Y$$

