```
% IDS/ACM/CS 158: Fundamentals of Statistical Learning
% PS5, Problem 1: Maximal Margin Hyperplane
% Author: Michael Li, mlli@caltech.edu
clear;
D = readmatrix('dataset7.csv');
X = D(:, 1:end-1);
ys = D(:,end);
g_plus = D(ys == 1, 1:end-1);
q minus = D(ys == -1, 1:end-1);
N = size(D,1);
p = size(D(1,1:end-1), 2);
X_{with\_bias} = [ones(N,1),X];
% Primal values for beta
primal_margin = quadprog(eye(p+1), zeros(p+1, 1), ys.*X_with_bias*-1,
 -1+zeros(N, 1));
fprintf("\nPrimal Maximal Margin Hyperplane Beta: \n")
disp(primal_margin)
x = linspace(-3, 8, 10000);
f=@(x) (-primal_margin(2) / primal_margin(3))*x - (primal_margin(1) /
primal_margin(3));
Y=f(x);
% Dual approach for beta
H = (ys*transpose(ys)) .* (X*transpose(X));
dual_margin = quadprog(H, -1*ones(1,N), zeros(1,N), 0, transpose(ys),
 0, zeros(N,1), 10^10*ones(N,1));
% Find beta from lambdas
support_vecs = X(abs(dual_margin) > 10^-5, :);
beta = sum(dual margin .* ys .* X, 1);
beta0 = -1/2 * (min(beta*transpose(g_plus)) +
 max(beta*transpose(q minus)));
dual_beta = [beta0 beta];
fprintf("\nDual Maximal Margin Hyperplane Beta: \n")
disp(dual_beta)
% plot
figure
hold on
plot(x, Y, 'k')
plot(g_plus(:,1), g_plus(:, 2), 'or')
plot(g_minus(:,1), g_minus(:, 2), 'ob')
plot(support_vecs(:,1), support_vecs(:,2), 'og')
title('Dataset 7 with Maximal Margin Hyperplane and Support Vectors')
xlabel('X1')
ylabel('X2')
```

```
% primal margin hyperplane beta = [-13.6254, 2.7269, 3.2707]
% dual margin hyperplane beta = [-13.6254, 2.7269, 3.2707]
```

Minimum found that satisfies the constraints.

Optimization completed because the objective function is nondecreasing in

feasible directions, to within the value of the optimality tolerance, and constraints are satisfied to within the value of the constraint tolerance.

Primal Maximal Margin Hyperplane Beta:

-13.6254

2.7269

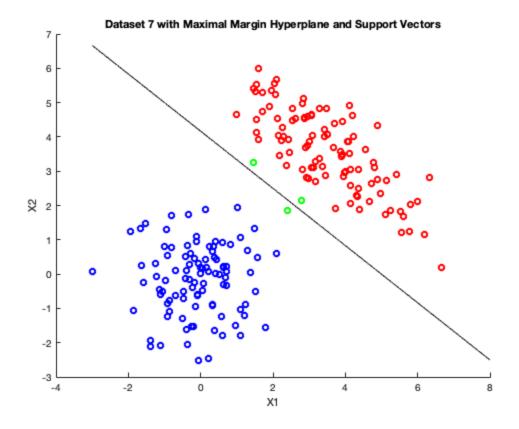
3.2707

Minimum found that satisfies the constraints.

Optimization completed because the objective function is nondecreasing in

feasible directions, to within the value of the optimality tolerance, and constraints are satisfied to within the value of the constraint tolerance.

Dual Maximal Margin Hyperplane Beta: -13.6254 2.7269 3.2707



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Z. a. Hp. p = 3X: Bo+BTX=03 < Rt From Lecture 14 Page 81 2= 11811 We want to shift all X a distance \hat{d} in the direction orthogonal to $\beta \rightarrow X^{\pm} = X \pm \frac{d\hat{\beta}}{|\hat{\beta}|}$ $X = X^{\pm} - \frac{d\hat{\beta}}{|\hat{\beta}|}$ X=X+161 H = \(\times \) = \(\begin{align*} H = {x+ | Bo+ B (x+ - 18112) = 0} H = {x- | Bo+ B (x+ + 18112) = 0} H = {X : \$\hat{\beta}_0 + \beta^T \times = 13 H = {\times \times : \$\hat{\beta}_0 + \beta^T \times = -13

```
% IDS/ACM/CS 158: Fundamentals of Statistical Learning
% PS5, Problem 2: Soft Margin Hyperplane
% Author: Michael Li, mlli@caltech.edu
clear;
D = readmatrix('dataset8.csv');
X = D(:, 1:end-1);
ys = D(:,end);
g_plus = D(ys == 1, 1:end-1);
q minus = D(ys == -1, 1:end-1);
% C = .1
C = .1;
N = size(D,1);
p = size(D(1,1:end-1), 2);
% solve dual problem using C constraint
H = (ys*transpose(ys)) .* (X*transpose(X));
dual_margin = quadprog(H, -1*ones(1,N), zeros(1,N), 0, transpose(ys),
 0, zeros(N,1), (1/C)*ones(N,1));
% finding beta using lambdas
support vecs = D(abs(dual margin) > 10^-5, :);
support_plus = support_vecs(support_vecs(:,3)==1, 1:end-1);
support_minus = support_vecs(support_vecs(:,3)==-1, 1:end-1);
beta = sum(dual_margin .* ys .* X, 1);
beta0 = -1/2 * (max(beta*transpose(support_plus)) +
 min(beta*transpose(support_minus)));
dual_beta = [beta0 beta];
fprintf("\nNumber of Support Vectors C=.1 are %i\n",
 size(support_vecs, 1))
% C=.1 has 8 support vectors
% get points for decision boundary and margins
x = linspace(-3, 5, 10000);
f=@(x) (-dual_beta(2) / dual_beta(3))*x - (dual_beta(1) /
dual_beta(3));
Y=f(x);
g=@(x) (-dual_beta(2) / dual_beta(3))*x - ((dual_beta(1) - 1) /
dual_beta(3));
Z=g(x);
h=@(x) (-dual_beta(2) / dual_beta(3))*x - ((dual_beta(1) + 1) /
dual beta(3));
P=h(x);
% plot
figure
hold on
plot(x, Y, 'k')
```

```
plot(x, Z, '--k')
plot(x, P, '--k')
plot(g_plus(:,1), g_plus(:, 2), 'or')
plot(g_minus(:,1), g_minus(:, 2), 'ob')
plot(support_vecs(:,1), support_vecs(:,2), 'xk')
title('Dataset 8 with Soft Margin Hyperplane C=.1')
xlabel('X1')
ylabel('X2')
% C = 10
C = 10;
% solve dual problem using C constraint
H = (ys*transpose(ys)) .* (X*transpose(X));
dual_margin = quadprog(H, -1*ones(1,N), zeros(1,N), 0, transpose(ys),
 0, zeros(N,1), (1/C)*ones(N,1);
% finding beta using lambdas
support_vecs = D(abs(dual_margin) > 10^-5, :);
support_plus = support_vecs(support_vecs(:,3)==1, 1:end-1);
support_minus = support_vecs(support_vecs(:,3)==-1, 1:end-1);
beta = sum(dual_margin .* ys .* X, 1);
beta0 = -1/2 * (max(beta*transpose(support_plus)) +
 min(beta*transpose(support minus)));
dual_beta = [beta0 beta];
% disp(dual beta)
fprintf("\nNumber of Support Vectors C=10 are %i\n",
 size(support_vecs, 1))
% C=10 has 27 support vectors
% get points for decision boundary and margins
x = linspace(-3, 5, 10000);
f=@(x) (-dual_beta(2) / dual_beta(3))*x - (dual_beta(1) /
dual_beta(3));
Y=f(x);
g=@(x) (-dual_beta(2) / dual_beta(3))*x - ((dual_beta(1) - 1) /
dual beta(3));
Z=q(x);
h=@(x) (-dual_beta(2) / dual_beta(3))*x - ((dual_beta(1) + 1) /
 dual_beta(3));
P=h(x);
% plot
figure
hold on
plot(x, Y, 'k')
plot(x, Z, '--k')
plot(x, P, '--k')
plot(g_plus(:,1), g_plus(:, 2), 'or')
plot(g_minus(:,1), g_minus(:, 2), 'ob')
plot(support_vecs(:,1), support_vecs(:,2), 'xk')
title('Dataset 8 with Soft Margin Hyperplane C=10')
xlabel('X1')
ylabel('X2')
```

Minimum found that satisfies the constraints.

Optimization completed because the objective function is nondecreasing in

feasible directions, to within the value of the optimality tolerance, and constraints are satisfied to within the value of the constraint tolerance.

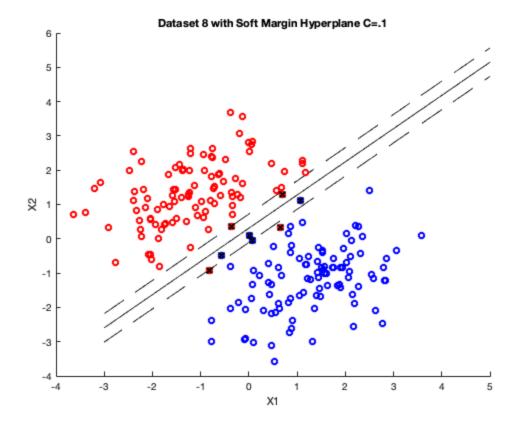
Number of Support Vectors C=.1 are 8

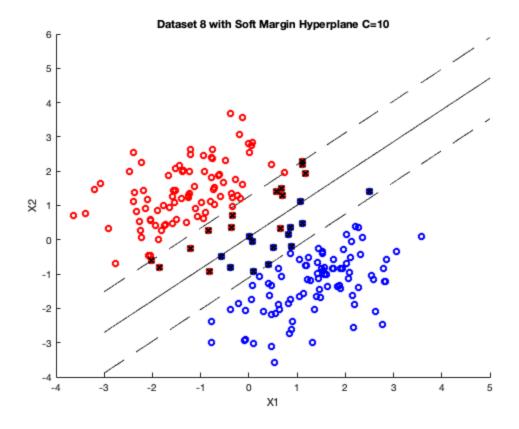
Minimum found that satisfies the constraints.

Optimization completed because the objective function is non-decreasing in

feasible directions, to within the value of the optimality tolerance, and constraints are satisfied to within the value of the constraint tolerance.

Number of Support Vectors C=10 are 27





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```
% IDS/ACM/CS 158: Fundamentals of Statistical Learning
% PS5, Problem 3: Support Vector Machine
% Author: Michael Li, mlli@caltech.edu
clear;
D = readmatrix('dataset9.csv');
X = D(:, 1:end-1);
ys = D(:,end);
g_plus = D(ys == 1, 1:end-1);
q minus = D(ys == -1, 1:end-1);
% C = 0
C = 0;
N = size(D,1);
p = size(D(1,1:end-1), 2);
K = ones(size(ys*transpose(ys)));
% generate kernel matrix and find lambdas
for i=1:length(X)
    for j=1:length(X)
        K(i, j) = gaussKernel(X(i, i), X(j, i));
    end
end
H = (ys*transpose(ys)) .* K;
svm = quadprog(H, -1*ones(1,N), zeros(1,N), 0, transpose(ys), 0,
zeros(N,1), (1/C)*ones(N,1));
% find support vectors
support_vecs = D(abs(svm) > 10^-5, :);
support_plus = support_vecs(support_vecs(:,3)==1, 1:end-1);
support minus = support vecs(support vecs(:,3)==-1, 1:end-1);
nonzero_lambs = svm(abs(svm) > 10^-5, :);
lambs plus = nonzero lambs(support vecs(:,3)==1);
lambs_minus = nonzero_lambs(support_vecs(:,3)==-1);
% find beta0
b0 \max = 0;
for i=1:length(support_plus)
    tot = 0;
    for j=1:length(support_plus)
        tot = tot + lambs_plus(j) * gaussKernel(support_plus(j,:),
 support plus(i,:));
    end
    if tot > b0_max
        b0 \max = tot;
    end
end
b0_{min} = 10^100;
```

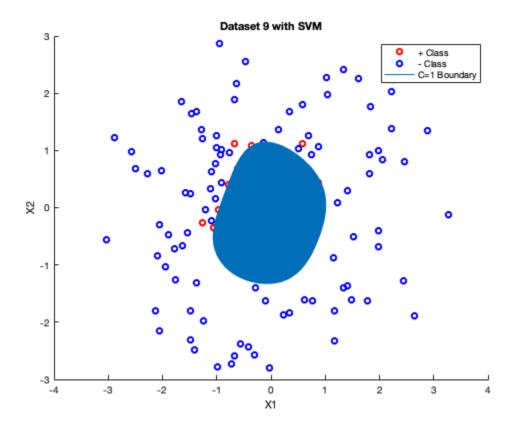
```
for i=1:length(support_minus)
    tot = 0;
    for j=1:length(support_minus)
        tot = tot + -lambs_minus(j) * gaussKernel(support_minus(j,:),
 support_minus(i,:));
    end
    if tot < b0 max</pre>
        b0_min = tot;
    end
end
b0 = -1/2*(b0 \max + b0 \min);
fprintf("\nNumber of Support Vectors C=0 are %i\n", size(support_vecs,
1))
% For C=0, there are 30 Support Vectors
% get points for boundary
x1 = -2:.004:2;
x2 = -2:.004:2;
boundary_x_0 = [];
boundary_y_0 = [];
% test each point
for i=x1
    for j=x2
        tot = b0;
        for k=1:length(support_vecs)
            tot = tot + support_vecs(k,3) * nonzero_lambs(k) *
 gaussKernel(support_vecs(k, 1:end-1), [i j]);
        end
        if abs(tot) < .04
            boundary x \ 0 = [boundary \ x \ 0 \ i];
            boundary_y_0 = [boundary_y_0 j];
        end
    end
end
% C=1
C = 1;
N = size(D,1);
p = size(D(1,1:end-1), 2);
K = ones(size(ys*transpose(ys)));
% generate kernel matrix and find lambdas
for i=1:length(X)
    for j=1:length(X)
        K(i, j) = gaussKernel(X(i,:), X(j,:));
    end
end
H = (ys*transpose(ys)) .* K;
```

```
svm = quadprog(H, -1*ones(1,N), zeros(1,N), 0, transpose(ys), 0,
 zeros(N,1), (1/C)*ones(N,1));
% find support vectors
support_vecs = D(abs(svm) > 10^-5, :);
support_plus = support_vecs(support_vecs(:,3)==1, 1:end-1);
support_minus = support_vecs(support_vecs(:,3)==-1, 1:end-1);
nonzero lambs = svm(abs(svm) > 10^-5, :);
lambs_plus = nonzero_lambs(support_vecs(:,3)==1);
lambs_minus = nonzero_lambs(support_vecs(:,3)==-1);
% find beta0
b0 \max = 0;
for i=1:length(support_plus)
    tot = 0;
    for j=1:length(support_plus)
        tot = tot + lambs_plus(j) * gaussKernel(support_plus(j,:),
 support_plus(i,:));
    end
    if tot > b0_max
        b0_{max} = tot;
    end
end
b0 min = 10^100;
for i=1:length(support_minus)
    tot = 0;
    for j=1:length(support_minus)
        tot = tot + -lambs_minus(j) * gaussKernel(support_minus(j,:),
 support_minus(i,:));
    end
    if tot < b0_max</pre>
        b0 min = tot;
    end
end
b0 = -1/2*(b0_max + b0_min);
fprintf("\nNumber of Support Vectors C=1 are %i\n", size(support_vecs,
 1))
% For C=1, there are 61 Support Vectors
% get points for boundary
x1 = -2:.004:2;
x2 = -2:.004:2;
boundary x = [];
boundary_y = [];
% test each point
for i=x1
    for j=x2
        tot = b0;
```

```
for k=1:length(support_vecs)
            tot = tot + support vecs(k,3) * nonzero lambs(k) *
 gaussKernel(support_vecs(k, 1:end-1), [i j]);
        if abs(tot) < .04
            boundary_x = [boundary_x i];
            boundary y = [boundary y j];
        end
    end
end
% plot
figure
hold on
plot(g_plus(:,1), g_plus(:, 2), 'or')
plot(g_minus(:,1), g_minus(:, 2), 'ob')
plot(boundary_x_0, boundary_y_0)
plot(boundary_x, boundary_y)
legend('+ Class', '- Class', 'C=1 Boundary', 'C=0 Boundary')
title('Dataset 9 with SVM')
xlabel('X1')
ylabel('X2')
function res = gaussKernel(x, y)
    res = \exp(-(norm(x-y))^2);
end
% Clearly there's something wrong with my code. I'm not sure if the
lambdas
% are just incorrect or if i'm calculating the decision boundaries
% incorrectly, but I think if I were to guess, that using the decision
% boundary for C=1 makes more sense because the training data is
% definitely not all encompassing. C=0 overfits the data for sure and
 would
% not generalize well to other cases not seen in this data.
Minimum found that satisfies the constraints.
Optimization completed because the objective function is non-
decreasing in
feasible directions, to within the value of the optimality tolerance,
and constraints are satisfied to within the value of the constraint
 tolerance.
Number of Support Vectors C=0 are 30
Minimum found that satisfies the constraints.
Optimization completed because the objective function is non-
decreasing in
feasible directions, to within the value of the optimality tolerance,
```

and constraints are satisfied to within the value of the constraint tolerance.

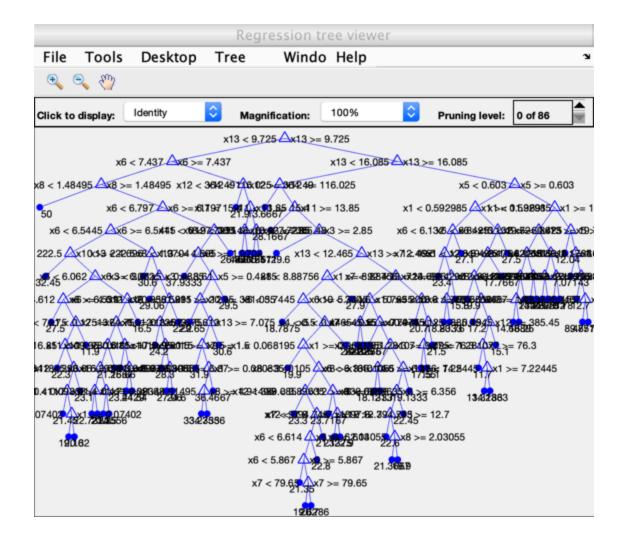
Number of Support Vectors C=1 are 61 Warning: Ignoring extra legend entries.

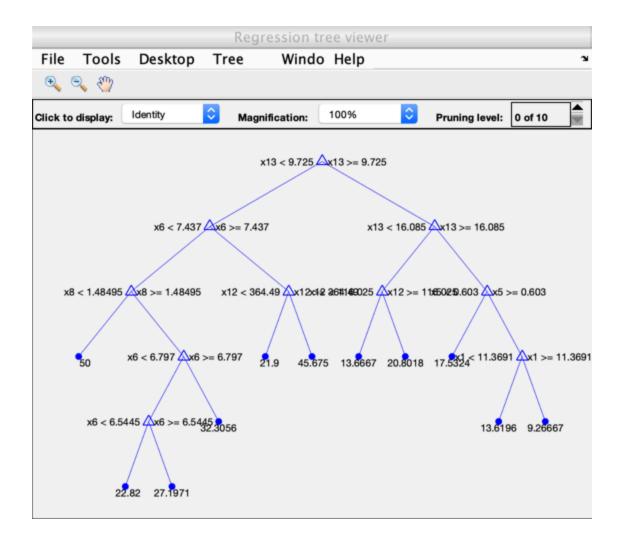


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```
% IDS/ACM/CS 158: Fundamentals of Statistical Learning
% PS5, Problem 4: Regression Trees for Boston Housing Data
% Author: Michael Li, mlli@caltech.edu
clear;
% Boston housing Data
train = readmatrix('Boston_train.csv');
test = readmatrix('Boston_test.csv');
TO = fitrtree(train(:,1:end-1), train(:,end));
view(TO, 'Mode', 'graph')
train_preds = predict(TO, train(:,1:end-1));
test_preds = predict(TO, test(:, 1:end-1));
train_err = norm(train(:,end) - train_preds)^2 / length(train);
test_err = norm(test(:,end) - test_preds)^2 / length(test);
fprintf("Training Error for T_0: %s\n", train_err);
fprintf("Test Error for T_0: %s\n", test_err);
% The training error for TO is 2.1707
% the test error is for TO 12.9867
alphas = linspace(0, 2, 21);
best = [];
lowest err = 10^10;
% loop over each alpha and run loocv
for a = alphas
    err = 0;
    tree = [];
    % for each datapoint leave it out and test error
    for i = 1:length(train)
        x = repmat(train, 1);
        x(i,:) = [];
        test_x = train(i,:);
        tree = fitrtree(x(:,1:end-1), x(:,end));
        tree = prune(tree, 'Alpha', a);
        pred = predict(tree, test_x(1, 1:end-1));
        err = err + (test_x(1, end) - pred)^2;
    end
    err = err / length(train);
    % if error is lower than previous, replace
    if err < lowest_err</pre>
        best = a;
        lowest_err = err;
    end
end
```

```
% refit best alpha on all data
T_best = fitrtree(train(:,1:end-1), train(:,end));
T_best = prune(T_best, 'Alpha', best);
view(T_best, 'Mode', 'graph');
train_preds = predict(T_best, train(:,1:end-1));
test_preds = predict(T_best, test(:, 1:end-1));
train_err = norm(train(:,end) - train_preds)^2 / length(train);
test_err = norm(test(:,end) - test_preds)^2 / length(test);
fprintf("\nBest Alpha: %s\n", best);
fprintf("Training Error for T_best: %s\n", train_err);
fprintf("Test Error for T_best: %s\n", test_err);
% Optimal value of pruning parameter is .7
% The training error for T is 10.21203
% the test error for T is 9.607979
Training Error for T_0: 2.170719e+00
Test Error for T_0: 1.298670e+01
Best Alpha: 7.000000e-01
Training Error for T_best: 1.021203e+01
Test Error for T_best: 9.607979e+00
```

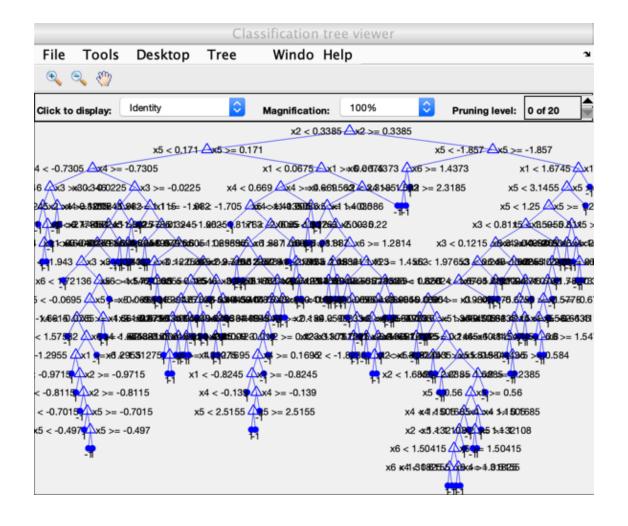


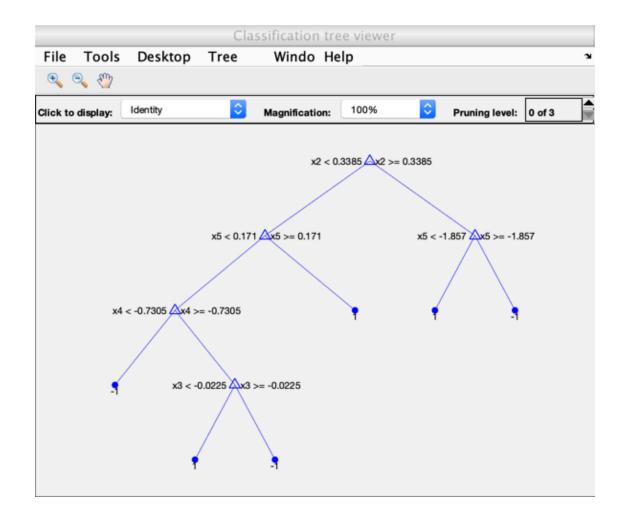


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```
% IDS/ACM/CS 158: Fundamentals of Statistical Learning
% PS5, Problem 5: Classification Trees for Stock Market Data
% Author: Michael Li, mlli@caltech.edu
clear;
% Stock market Data
train = readmatrix('stock_market_train.csv');
test = readmatrix('stock_market_test.csv');
TO = fitctree(train(:,1:end-1), train(:,end));
view(TO, 'Mode', 'graph')
train_preds = predict(TO, train(:,1:end-1));
test_preds = predict(TO, test(:, 1:end-1));
train_err = mean(train(:,end) ~= train_preds);
test_err = mean(test(:,end) ~= test_preds);
fprintf("Training Error for T_0: %s\n", train_err);
fprintf("Test Error for T_0: %s\n", test_err);
% The training error is .118
% the test error is .476
% loop over each alpha and run loocv
alphas = linspace(0, .04, 41);
best = [];
lowest err = 1;
for a = alphas
    err = 0;
    tree = [];
    % for each datapoint leave it out and test error
    for i = 1:length(train)
        x = repmat(train, 1);
        x(i,:) = [];
        test_x = train(i,:);
        tree = fitctree(x(:,1:end-1), x(:,end));
        tree = prune(tree, 'Alpha', a);
        pred = predict(tree, test_x(1, 1:end-1));
        err = err + (pred \sim = test_x(1, end));
    end
    err = err / length(train);
    % if error is lower than previous, replace
    if err < lowest_err</pre>
        best = a;
        lowest err = err;
    end
end
```

```
% refit best alpha on all data
T_best = fitctree(train(:,1:end-1), train(:,end));
T_best = prune(T_best, 'Alpha', best);
view(T_best, 'Mode', 'graph');
train_preds = predict(T_best, train(:,1:end-1));
test_preds = predict(T_best, test(:, 1:end-1));
train_err = mean(train(:,end) ~= train_preds);
test_err = mean(test(:,end) ~= test_preds);
fprintf("\nBest Alpha: %s\n", best);
fprintf("Training Error for T_best: %s\n", train_err);
fprintf("Test Error for T_best: %s\n", test_err);
% Optimal value of pruning parameter is .01
% The training error for T is .401
% the test error for T is .584
Training Error for T 0: 1.180000e-01
Test Error for T_0: 4.760000e-01
Best Alpha: 1.000000e-02
Training Error for T_best: 4.010000e-01
Test Error for T best: 5.840000e-01
```





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