

NATIONAL UNIVERSITY OF SINGAPORE

EXAMINATION FOR
(Semester I : 2015/2016)

EE3731C – SIGNAL PROCESSING METHODS

Nov 2015 – Time Allowed: 2 Hours

INSTRUCTIONS TO CANDIDATES

1. This paper contains **FOUR (4)** questions and comprises **FIVE (5)** printed pages.
2. All questions are compulsory. Answer **ALL** questions.
3. This is a **CLOSED BOOK** examination. One A4-size formula sheet is allowed.
4. Programmable calculators are not allowed.

Q1 The sub-questions (a), (b) and (c) can be answered independently.

- (a) The impulse response $h[n]$ of a linear time-invariant system is 0, except in the interval $N_0 \leq n \leq N_1$. The input $x[n]$ is 0, except in the interval $N_2 \leq n \leq N_3$. Therefore the output is 0, except in the interval $N_4 \leq n \leq N_5$. Determine N_4 and N_5 in terms of N_0, N_1, N_2, N_3 .
(6 marks)

- (b) Let $x_1[n] = n + 1$ for $0 \leq n \leq 5$ and $x_2[n] = \begin{cases} 2 & \text{for } n = 3 \\ 0 & \text{for } n = 0, 1, 2, 4, 5 \end{cases}$

Let $y[n]$ be the circular convolution $x_1[n] \otimes x_2[n]$. What is $y[n]$ for $0 \leq n \leq 5$?

(9 marks)

- (c) Consider an ideal high-pass filter with 0 delay and frequency response

$$H_{hp}(e^{j\omega}) = \begin{cases} 0 & \text{for } |\omega| < \omega_{hp} \\ 0.5 & \text{for } |\omega_{hp}| < |\omega| < \pi \end{cases}$$

Consider an ideal low-pass filter with 0 delay and frequency response

$$H_{lp}(e^{j\omega}) = \begin{cases} 1 & \text{for } |\omega| < \omega_{lp} \\ 0 & \text{for } |\omega_{lp}| < |\omega| < \pi \end{cases}$$

whose impulse response is $h_{lp}[n] = \frac{\sin \omega_{lp} n}{\pi n}$

- (i) To obtain the above high-pass filter, we can scale the above low-pass filter (with appropriate ω_{lp}) by 1/2 and translate by π in the frequency domain. What is the resulting impulse response of the ideal high-pass filter in terms of ω_{hp} ?
(4 marks)
- (ii) Modify the impulse response from (i) so that the resulting high-pass filter has a linear phase of $M/2$.
(1 mark)
- (iii) We wish to use the Kaiser window method to design a FIR filter with generalized linear phase that meets the following specifications:

$$\begin{aligned} |H(e^{j\omega})| &< 0.03 & |\omega| < 0.575\pi \\ 0.45 &< |H(e^{j\omega})| < 0.55 & 0.625\pi \leq |\omega| \leq \pi \end{aligned}$$

The Kaiser window will be applied to the ideal impulse response from (ii) with $\omega_{hp} = 0.6\pi$. Find the Kaiser window parameters β and M so that the resulting windowed filter satisfies the above criteria.

(5 marks)

Q2 The sub-questions (a), (b), (c) and (d) can be answered independently.

- (a) Alice and Bob play the same game everyday. On day n , Alice independently sampled (x_n, y_n) from the joint probability distribution $p(x, y)$. Given observation y_n , Bob guesses x_n to be \hat{x}_n and pays Alice $e(x_n, \hat{x}_n)$ dollars.

(i) Suppose $e(x_n, \hat{x}_n) = (x_n - \hat{x}_n)^2$. What estimation strategy should Bob use to minimize the payout to Alice on a daily basis (on average)?

(1 mark)

(ii) Suppose $e(x_n, \hat{x}_n) = 0$ if $x_n = \hat{x}_n$ and $e(x_n, \hat{x}_n) = 10$ if $x_n \neq \hat{x}_n$. What estimation strategy should Bob use to minimize the payout to Alice on a daily basis (on average)?

(1 mark)

- (b) Given the observation y , suppose we use Metropolis algorithm to generate ten independent samples of x from the posterior distribution $p(x | y)$. Let $x_1 = 2, x_2 = 5, x_3 = 3, x_4 = 4, x_5 = 1, x_6 = 2, x_7 = 2, x_8 = 5, x_9 = 3$ and $x_{10} = 1$ be the ten samples. Use the ten samples to compute an approximate MAP estimate of x given y .

(2 marks)

- (c) Let x_n be a random walk defined as

$$x_0 = 0$$

$$x_N = x_0 + \sum_{n=1}^N z_n$$

where $z_n, n \geq 1$ is a discrete time white Gaussian noise process, i.e. z_1, z_2, \dots are i.i.d $\mathcal{N}(0, 1)$. Find the MMSE estimate of x_{20} given x_1, \dots, x_{10}

(7 marks)

- (d) Suppose $\phi(t)$ is the scaling function of a multi-resolution wavelet analysis. Let $\phi_{s,u}(t) = 2^{-s/2} \phi(2^{-s}t - u)$. In class, we mentioned that there exists $g_0[u]$, such that the two-scale relationship $\phi(t) = \sum_{u=-\infty}^{\infty} g_0[u] \phi_{-1,u}(t)$ holds.

(i) Show that $\|g_0\|^2 = \sum_u (g_0[u])^2 = 1$.

(5 marks)

(ii) Show that $g_0[u] = \int_{-\infty}^{\infty} \phi(t) \phi_{-1,u}(t) dt$.

(4 marks)

(iii) Suppose $\phi(t)$ is the Haar scaling function. Show that

$$g_0[u] = \begin{cases} \frac{1}{\sqrt{2}} & u = 0 \text{ or } 1 \\ 0 & \text{otherwise} \end{cases}$$

(5 marks)

Q3 The sub-questions (a), (b), (c) can be answered independently.

- (a) Perform PCA on the following set of data: $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$, $\begin{pmatrix} 3 \\ 5 \end{pmatrix}$, $\begin{pmatrix} -1 \\ -3 \end{pmatrix}$ and $\begin{pmatrix} 3 \\ 0 \end{pmatrix}$.

What is the first principal axis? What is the first principal component of the data point $x = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$?

(14 marks)

- (b) Suppose we project D -dimensional data points $x_1 = [x_1^1, \dots, x_1^D]^T$ and $x_2 = [x_2^1, \dots, x_2^D]^T$ onto K principal axes, resulting in principal components $a_1 = [a_1^1, \dots, a_1^K]^T$ and $a_2 = [a_2^1, \dots, a_2^K]^T$ respectively. Let's denote the reconstructed x 's

as \hat{x}_1 and \hat{x}_2 . Show that $\|\hat{x}_1 - \hat{x}_2\| \triangleq \sqrt{\sum_{i=1}^D (\hat{x}_1^i - \hat{x}_2^i)^2}$ is equal to

$\sqrt{\sum_{i=1}^K (a_1^i - a_2^i)^2}$. In other words, Euclidean distance between reconstructed data points is the same as Euclidean distance of principal components.

(6 marks)

- (c) Consider training data $x_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $x_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $x_3 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$, $x_4 = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$ with corresponding class labels $y_1 = 0, y_2 = 0, y_3 = 1, y_4 = 1$. What is the 3-NN estimate of the class label posterior probabilities of data points $x_5 = \begin{pmatrix} 0.5 \\ 0.5 \end{pmatrix}$ and $x_6 = \begin{pmatrix} -0.5 \\ 0 \end{pmatrix}$, where the distance metric used is the Euclidean distance? What are the MAP classifications of data points x_5 and x_6 ?

(5 marks)

Q4 Sub-questions (a) and (b) can be answered independently. Sub-question (c) depends on sub-questions (a) and (b), but you might be able to answer it without fully answering sub-questions (a) and (b).

- (a) Consider a biased coin where θ is the probability of getting a head when the coin is tossed. The coin is tossed N times independently (θ is fixed for all the coin tosses), resulting in N_1 heads. Consider a uniform prior where $p_1(\theta) \sim U[0,1]$. What is the MAP estimate of θ in terms of N_1 and N . Show your steps.

(10 marks)

- (b) Consider the same coin from part (2a). Now consider the following prior, that believes the coin is fair, or is slightly biased towards tails:

$$p_2(\theta) = \begin{cases} 0.5 & \text{for } \theta = 0.5 \\ 0.5 & \text{for } \theta = 0.4 \\ 0 & \text{otherwise} \end{cases}$$

Derive the MAP estimate under the prior as a function of N_1 and N .

(10 marks)

- (c) Suppose the true parameter is $\theta = 0.41$. Does the uniform prior (sub-question 4a) or the biased coin prior (sub-question 4b) lead to a better estimate when N is small? Which leads to a better estimate when N is large?

(5 marks)

END OF PAPER