

## EE3731C Tutorial - Classical Signal 2

### Department of Electrical and Computer Engineering

1. From lecture, the DTFT of  $a^n u[n]$  is  $\frac{1}{1-ae^{-j\omega}}$ . Since  $h[n] = 5(-1/2)^n u[n]$ , then  $H(e^{j\omega}) = \frac{5}{1+\frac{1}{2}e^{-j\omega}}$ . Since  $x[n] = (1/3)^n u[n]$ , then  $X(e^{j\omega}) = \frac{1}{1-\frac{1}{3}e^{-j\omega}}$ . The output

$$\begin{aligned} Y(e^{j\omega}) &= H(e^{j\omega})X(e^{j\omega}) \\ &= \left( \frac{5}{1+\frac{1}{2}e^{-j\omega}} \right) \left( \frac{1}{1-\frac{1}{3}e^{-j\omega}} \right) \\ &= \frac{3}{1+\frac{1}{2}e^{-j\omega}} + \frac{2}{1-\frac{1}{3}e^{-j\omega}}, \end{aligned}$$

where we have used the result that  $\frac{1}{(1-ae^{-j\omega})(1-be^{-j\omega})} = \frac{a/(a-b)}{1-ae^{-j\omega}} - \frac{b/(a-b)}{1-be^{-j\omega}}$ , with  $a = -1/2$  and  $b = 1/3$ .

Taking the inverse DTFT of  $Y(e^{j\omega})$ , we get by linearity of DTFT

$$y[n] = 3(-1/2)^n u[n] + 2(1/3)^n u[n]$$

2.

$$\begin{aligned} H(e^{j\omega}) &= \sum_n \left( \frac{1}{M_1 + M_2 + 1} \sum_{k=-M_1}^{M_2} \delta[n-k] \right) e^{-j\omega n} \\ &= \frac{1}{M_1 + M_2 + 1} \sum_{k=-M_1}^{M_2} \left( \sum_n \delta[n-k] e^{-j\omega n} \right) = \frac{1}{M_1 + M_2 + 1} \sum_{k=-M_1}^{M_2} e^{-j\omega k} \end{aligned}$$

Using the following geometric series formula  $\sum_{k=N_1}^{N_2} a^k = \frac{a^{N_1} - a^{N_2+1}}{1-a}$  for  $N_2 \geq N_1$ , we get

$$\begin{aligned} H(e^{j\omega}) &= \frac{1}{M_1 + M_2 + 1} \frac{e^{j\omega M_1} - e^{-j\omega(M_2+1)}}{1 - e^{-j\omega}} \\ &= \frac{1}{M_1 + M_2 + 1} \frac{e^{j\omega(M_1+M_2+1)/2} - e^{-j\omega(M_1+M_2+1)/2}}{1 - e^{-j\omega}} e^{-j\omega(M_2-M_1+1)/2} \\ &= \frac{1}{M_1 + M_2 + 1} \frac{e^{j\omega(M_1+M_2+1)/2} - e^{-j\omega(M_1+M_2+1)/2}}{e^{j\omega/2} - e^{-j\omega/2}} e^{-j\omega(M_2-M_1)/2} \\ &= \frac{1}{M_1 + M_2 + 1} \frac{\sin[\omega(M_1 + M_2 + 1)/2]}{\sin(\omega/2)} e^{-j\omega(M_2-M_1)/2}, \end{aligned}$$

where we have exploited the fact that  $\sin x = \frac{e^{jx} - e^{-jx}}{2j}$ . Therefore  $|H(e^{j\omega})| = \left| \frac{1}{M_1 + M_2 + 1} \frac{\sin(\omega(M_1 + M_2 + 1)/2)}{\sin(\omega/2)} \right|$  and  $\angle H(e^{j\omega}) = -\omega(M_2 - M_1)/2 + \{0, \pi\}$ , where  $+ \{0, \pi\}$  comes from  $\frac{\sin(\omega(M_1 + M_2 + 1)/2)}{\sin(\omega/2)}$  switching signs, i.e., we have  $+0$  if  $\frac{\sin(\omega(M_1 + M_2 + 1)/2)}{\sin(\omega/2)}$  is positive and  $+\pi$  if  $\frac{\sin(\omega(M_1 + M_2 + 1)/2)}{\sin(\omega/2)}$  is negative (because  $-1 = e^{j\pi}$ ). This “ $+\pi$ ” explains the sudden jumps in the phase plots shown in class.

3. A LTI system is causal if and only if  $h[n] = 0$  for  $n < 0$ . Therefore
  - (a)  $h[n] = 0$  for  $n < 1$ , hence system is causal
  - (b)  $h[n] \neq 0$  for  $n < 0$ , hence system is not causal.
  - (c)  $h[-1] = 1$ , hence system is not causal
4. In general, a LTI is stable if and only if  $\sum_k |h[k]| < \infty$  (see previous tutorial answers)
  - (a)  $\sum_n |h[n]| = \sum_{n=-\infty}^{-1} 3^n = \sum_{n=1}^{\infty} (1/3)^n$ , which is bounded. Hence system is stable.
  - (b)  $\sum_n |h[n]| = \sum_{n=0}^{\infty} |\sin(\pi n/3)|$ , which is unbounded. Hence system is not stable.
  - (c)  $\sum_n |h[n]| = \sum_{n=-\infty}^{\infty} |(3/4)^{|n|} \cos(\pi n/4 + \pi/4)| \leq \sum_{n=-\infty}^{\infty} (3/4)^{|n|}$ , which is bounded. Hence system is stable.
- 5.

$$\begin{aligned}
 H(e^{j\omega}) &= \sum_n h[n] e^{-j\omega n} \\
 &= -\frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} e^{-j\omega} \\
 &= \frac{\sqrt{2}}{2} (-1 + \cos \omega) - \frac{\sqrt{2}}{2} j \sin \omega
 \end{aligned}$$

$$\begin{aligned}
 |H(e^{j\omega})| &= \sqrt{\frac{1}{2} [(-1 + \cos \omega)^2 + \sin^2 \omega]} \\
 &= \sqrt{\frac{1}{2} [1 + \cos^2 \omega - 2 \cos \omega + \sin^2 \omega]} \\
 &= \sqrt{1 - \cos \omega}
 \end{aligned}$$

Therefore  $|H(e^{j\omega})|$  is equal to 0 at  $\omega = 0$ , and monotonically increases to  $\sqrt{2}$  at  $\omega = \pi$ . Therefore  $h[n]$  is a high-pass filter.