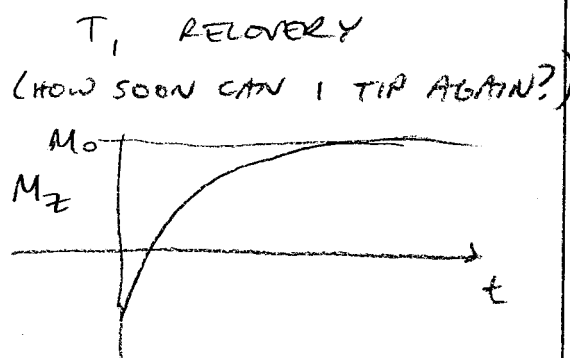
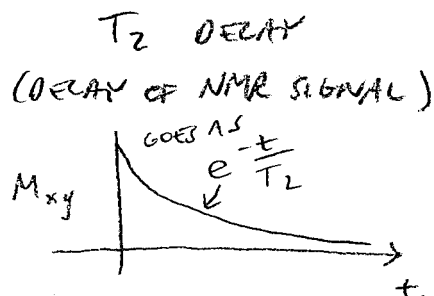


THE MR SIGNAL EQUATION AND K-SPACE:

WE HAVE NOW TALKED SEVERAL TIMES ABOUT THE BLOCH EQU:

$$\frac{d\vec{M}}{dt} = \underbrace{\vec{M} \times \gamma \vec{B}}_{\text{PRECESSION}} - \underbrace{\frac{M_x \hat{i} + M_y \hat{j}}{T_2}}_{T_2 \text{ DELAY}} - \underbrace{\frac{(M_z - M_0) \hat{k}}{T_1}}_{T_1 \text{ RECOVERY}}$$

AND WE HAVE REVIEWED HOW THE FIRST TERM DESCRIBES PRECESSION, THE SECOND T_2 DELAY, AND THE THIRD T_1 RECOVERY.



THE TRANSVERSE MAGNETIZATION M_{xy} DETERMINES THE TIME SIGNAL WE RECORD.

IT IS CONVENIENT TO THINK OF THE XY PLANE AS THE COMPLEX PLANE, AND DESCRIBE THE PROJECTION OF \vec{M} ONTO THAT PLANE AS A COMPLEX NUMBER (A KIND OF PHASOR NOTATION).

LET'S DEFINE:

$$M \equiv M_x + iM_y = M^0 \cos \theta + M^0 i \sin \theta = M^0 e^{i\theta}$$

$\Rightarrow M^0$ IS INITIAL LENGTH OF M_{xy} AFTER EXCITATION

\Rightarrow (NOT THE SAME AS M_0 UNLESS TIPPED BY 90°)

AFTER A TIP, WE HAVE:

$$M = M^0 e^{-t/T_2} e^{-i\omega_0 t}$$

↑ DENSITY, TIP ANGLE T_2 DELAY PRECESSION

ASSUMING A UNIFORM FIELD B_0 , $\omega_0 = \gamma B_0$

NOW LET'S LOOK AT M AS A FUNCTION OF POSITION \vec{r}
(DIVIDE OBJECT UP INTO VOXELS):

$$M(\vec{r}) = M^0(\vec{r}) e^{-\frac{t}{T_2(\vec{r})}} e^{-i\omega_0 t}$$

WHAT IF ω_0 VARIES WITH \vec{r} ?? (LIKE WHEN WE
APPLY GRADIENTS OR HAVE CHEMICAL SHIFT ??)

THEN:

$$M(\vec{r}) = M^0(\vec{r}) e^{-\frac{t}{T_2(\vec{r})}} e^{-i \underbrace{\omega(\vec{r}) t}_{\text{PHASE } \phi(\vec{r}, t)}}$$

LET'S IGNORE CHEMICAL SHIFT FOR A MOMENT AND THINK
ABOUT OUR GRADIENT FIELDS G_x , G_y , AND G_z .

IN A PREVIOUS LECTURE, WE WROTE:

$$B_z = B_0 + G_x x + G_y y + G_z z$$

$$\omega = \gamma B_z = \gamma (B_0 + G_x x + G_y y + G_z z)$$

IF WE LET OUR GRADIENTS VARY W/ TIME, WHAT IS
 $\phi(\vec{r}, t)$??

$$\omega(t) = \gamma B_0 + \gamma (G_x(t)x + G_y(t)y + G_z(t)z)$$

$$\phi(t) = \gamma B_0 t + \gamma \int_0^t G_x(\tau) d\tau + \gamma y \int_0^t G_y(\tau) d\tau + \gamma z \int_0^t G_z(\tau) d\tau$$

$$M(\vec{r}) = M^0(\vec{r}) e^{-\frac{t}{T_2(\vec{r})}} e^{-i \underbrace{\gamma B_0 t}_{\omega_0}} e^{-i \gamma \int_0^t \vec{G}(\tau) \cdot \vec{r} d\tau}$$

OUR SIGNAL WILL BE:

$$S_r(t) = \left(\iiint M(\vec{r}) d\vec{r} \right) = \iiint M^0(\vec{r}) e^{-\frac{t}{T_2(\vec{r})}} e^{-i\omega_0 t} e^{-i \gamma \int_0^t \vec{G}(\tau) \cdot \vec{r} d\tau} dx dy dz$$

NEW:

⇒ IGNORE RELAXATION

⇒ DEMODULATE AT $\omega_0 = \gamma B_0$

⇒ 2D

$$S(t) = \int_x \int_y \underbrace{m(x,y)}_{\substack{\uparrow \\ \text{DENSITY} \\ \text{OF OBJECT} \\ M^0}} e^{-i\gamma \int_0^t \vec{G}(\tau) \cdot \vec{r} d\tau} dx dy$$

$$\text{DEFINE } k_x(t) = \frac{\gamma}{2\pi} \int_0^t G_x(\tau) d\tau$$

$$k_y(t) = \frac{\gamma}{2\pi} \int_0^t G_y(\tau) d\tau$$

$$S(t) = \int_x \int_y m(x,y) e^{-i\gamma (k_x(t)x + k_y(t)y)} dy dx$$

MR SIGNAL EQUATION

GRADIENTS LET US "WALK" THROUGH K-SPACE!!
 THEN WE CAN SAMPLE SIGNAL $S(t)$ AT VARIOUS
 POINTS IN K-SPACE, GIVING US THE FOURIER-DOMAIN
 DATA FOR OUR IMAGE!

⇒ THE WAY WE NAVIGATE THROUGH K-SPACE IS CALLED A
K-SPACE TRAJECTORY.

⇒ TIE THIS BACK TO PULSE SEQUENCE DIAGRAMS FOR
 2DFT AND 2DPR.