

# Macro PS2

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## 1 Question 1

The planner solves the following maximization problem subject to the capital law of motion and the resource constraint:

$$\begin{aligned} \max_{\{C_t, I_t, K_t\}_{t=1}^{\infty}} \quad & \sum_{t=0}^{\infty} \beta^t \log C_t \\ \text{s.t.} \quad & K_{t+1} = K_t^{1-\delta} I_t^{\delta} \\ & \text{and } AK_t^{\alpha} = C_t + I_t \end{aligned}$$

We can solve the resource constraint for  $I_t$  and plug it into the capital law of motion. Using this simplification, we can write down our Lagrangian:

$$\mathcal{L} = \sum_{t=0}^{\infty} \beta^t \log C_t + \lambda_t \left( -K_{t+1} + K_t^{1-\delta} (AK_t^{\alpha} - C_t)^{\delta} \right)$$

Taking first order conditions with respect to  $C_t, K_{t+1}$  we find the following:

$$\begin{aligned} \frac{\beta^t}{C_t} &= \lambda_t K_t^{1-\delta} (AK_t^{\alpha} - C_t)^{\delta-1} \\ \lambda_t &= \lambda_{t+1} (K_{t+1}^{1-\delta} \delta (AK_{t+1}^{\alpha} - C_{t+1})^{\delta-1} A \alpha K_{t+1}^{\alpha-1} + (1-\delta) K_{t+1}^{-\delta} (AK_{t+1}^{\alpha} - C_{t+1})^{\delta}) \\ \Rightarrow \lambda_t &= \frac{\beta^t}{C_t K_t^{1-\delta} I_t^{\delta-1}} \\ \Rightarrow \frac{1}{C_t K_t^{1-\delta} I_t^{\delta-1}} &= \frac{\beta}{C_{t+1} K_{t+1}^{1-\delta} I_{t+1}^{\delta-1}} (A \alpha \delta K_{t+1}^{\alpha-\delta} I_{t+1}^{\delta-1} + (1-\delta) K_{t+1}^{-\delta} I_{t+1}^{\delta}) \end{aligned}$$

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$$\frac{1}{C_t K_t^{1-\delta} I_t^{\delta-1}} = \frac{\beta}{C_{t+1}} (A\alpha\delta K_{t+1}^{\alpha-1} + (1-\delta)K_{t+1}^{-1}I_{t+1}) \quad (1)$$

The above equation forms our Euler equation.

Assume we are on the optimal trajectory at time  $t$ , and consider a one-period deviation in consumption by an amount  $\Delta$ . Our resource constraint implies that this results in a decrease in  $I_t$  by an equal amount,  $\Delta$ . Then, our  $K_{t+1}$  is reduced (to first order approximation) to  $K_t^{1-\delta}I_t^\delta - \delta\Delta K_t^{1-\delta}I_t^{\delta-1}$ . Then, our consumption in the second equation is reduced by two effects: reduced  $K_{t+1}$  leads to less production at time  $t+1$ , and a larger gap to make up via  $I_{t+1}$  to get back onto the optimal trajectory at time  $t+2$ . The net effect of the first of these terms, to first order expansion, is  $-(\delta\Delta K_t^{1-\delta}I_t^{\delta-1})(A\alpha K_{t+1}^{\alpha-1})$ , in other words, the reduction in  $C_{t+1}$  from the (first order approximation of the) decrease in production in period  $(t+1)$ . Now we must address the second of these turns.  $K_{t+2} = K_{t+1}^{1-\delta}I_{t+1}^\delta$  is fixed and we know the value of  $K_{t+1}$  so we can determine the value of  $I_{t+1}$ .

Our marginal utility by making this move is thus

$$dU = \beta^t C_t^{-1} \Delta - \beta^{t+1} C_{t+1}^{-1} () \Delta$$

$$dU/\Delta = 0 \Rightarrow C_t^{-1} = \beta C_{t+1}^{-1} (\delta\Delta K_t^{1-\delta} I_t^{\delta-1})$$