Macro PS1

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1 Question 1

The social planner maximizes the agent's utility subject to the resource constraint.

$$\max_{\{C_t, K_{t+1}\}} \sum_{t=0}^{\infty} \beta^t U(C_t)$$
$$\text{s.t. } F(K_t) = C_t + I_t$$

We can solve our law of motion for capital for I_t and write our lagrangian as follows:

$$\mathcal{L} = \sum_{t=0}^{\infty} \beta^t U(C_t) + \lambda_t (F(K_t) - C_t + (1-\delta)K_t - K_{t+1} - D_t).$$

We solve for our Euler equation by taking first order conditions with respect to consumption and capital:

$$\begin{aligned} \beta^t U'(C_t) &= \lambda_t \\ \lambda_{t+1}(F'(K_{t+1}) + 1 - \delta) &= \lambda_t \\ \Rightarrow U'(C_t) &= \beta U'(C_{t+1})(F'(K_{t+1}) + 1 - \delta). \end{aligned}$$

We combine our euler equation with the law of motion of capital along with our transversality condition to define the solution to the planner's problem:

$$U'(C_t) = \beta U'(C_{t+1})(F'(K_{t+1}) + 1 - \delta), \tag{1}$$
$$K_{t+1} = (1-\delta)K_t + F(K_t) - C_t - D_t \tag{2}$$
$$\lim_{t\to\infty} \beta^t U'(C_t) K_{t+1} = 0. \tag{3}$$

*I worked on this assignment with my study group: Alex von Hafften, Andrew Smith, and Ryan Mather. I have also discussed problem(s) with Emily Case, Sarah Bass, Katherine Kwok, and Danny Edgel.

2 Question 2

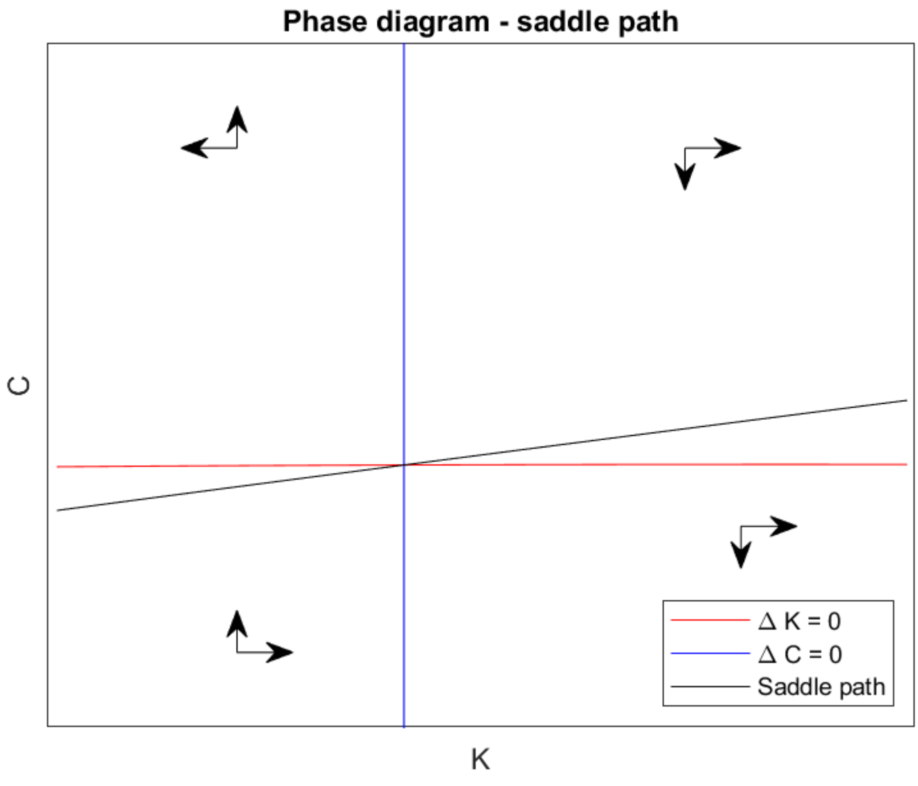
Given D, we can use (1), (2) to solve for $\bar{K}(D), \bar{C}(D)$ as follows:

$$1 = \beta(F'(\bar{K}(D)) + 1 - \delta)$$
$$\Rightarrow \bar{K}(D) = (F')^{-1}\left(\frac{1}{\beta} - 1 + \delta\right),$$
$$\bar{C}(D) = F(\bar{K}(D)) - \delta\bar{K}(D) - D.$$

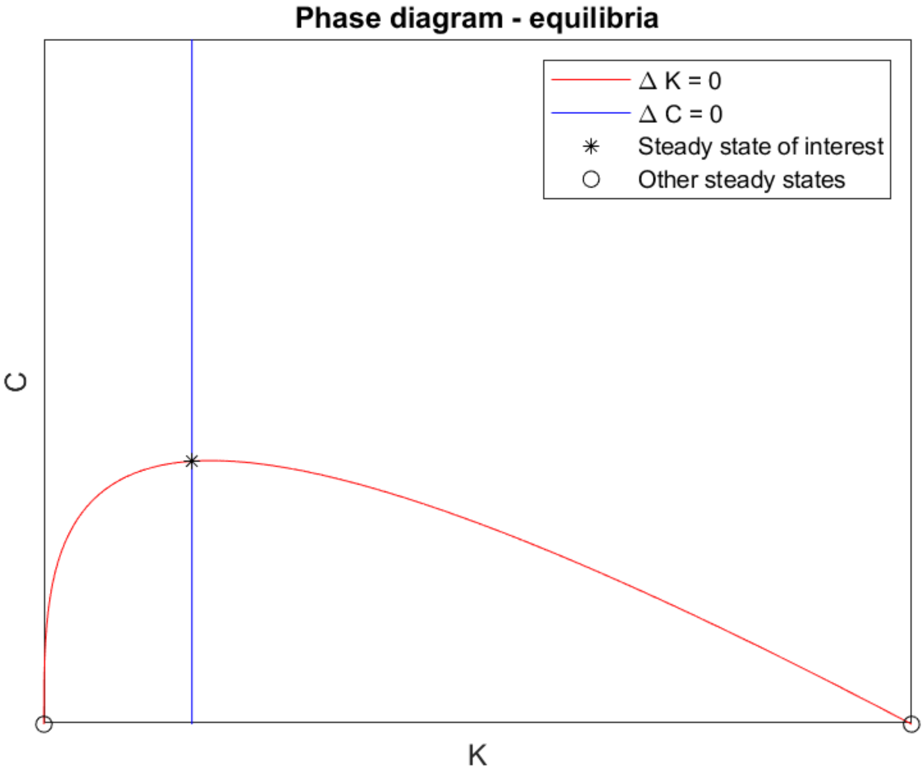
We can find the curves for the phase diagram by setting $\Delta K = 0, \Delta C = 0:$

$$\Delta C = 0 \Rightarrow 1 = \beta(F'(K) + 1 - \delta)$$
$$\Delta K = 0 \Rightarrow C = F(K) - \delta K - D.$$

The phase diagram is plotted below, drawn in Matlab using the specifications detailed in question (4) of this problem set. Saddle path is calculated using the shooting method.



The above figure shows the curves defining $\Delta K = 0$ and $\Delta C = 0$, the saddle path, and arrows representing the direction of change. Below I plot the zoomed-out phase diagram that shows all three steady states.

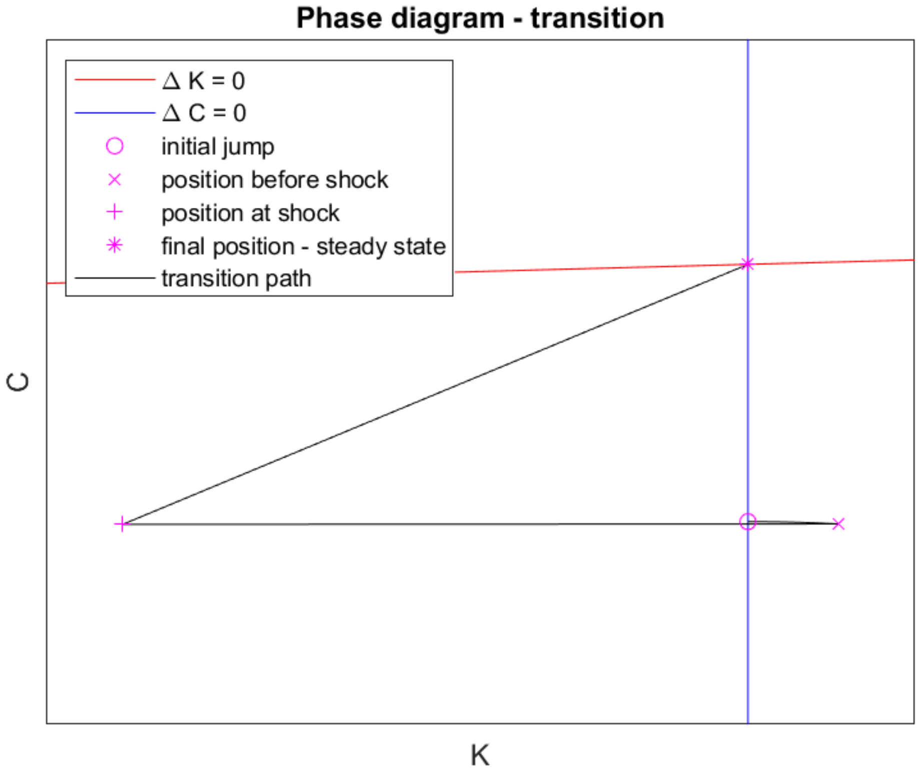


The above figure shows all three steady states. The main steady state is at the intersection of the curves defining $\Delta K = 0$ and $\Delta C = 0$. The other two equilibria are at the intersection of the curve defining $\Delta K = 0$ and the x-axis.

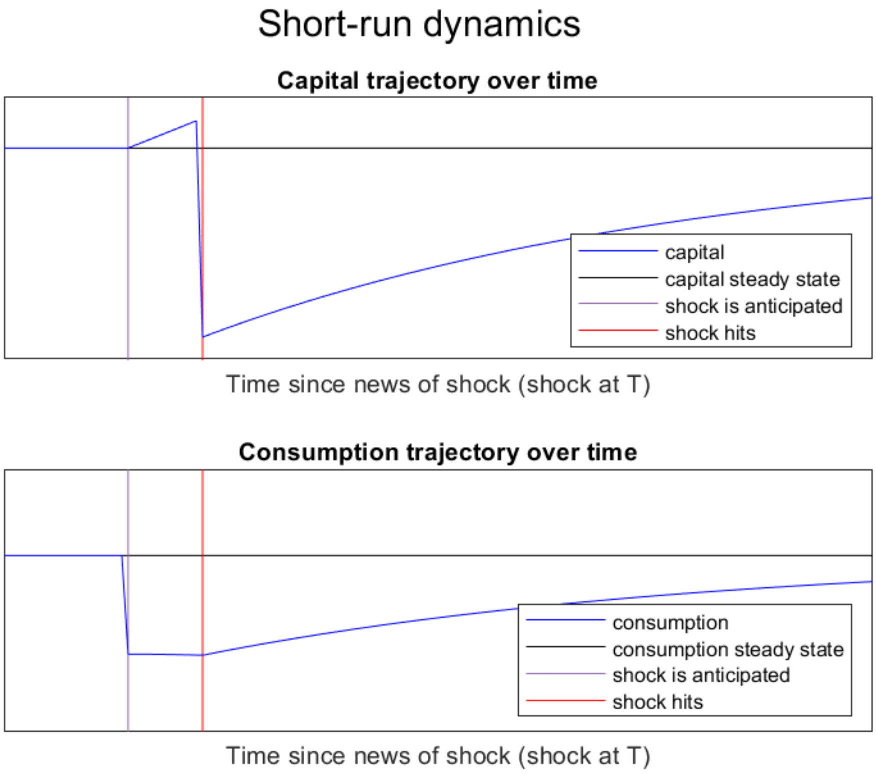
3 Question 3

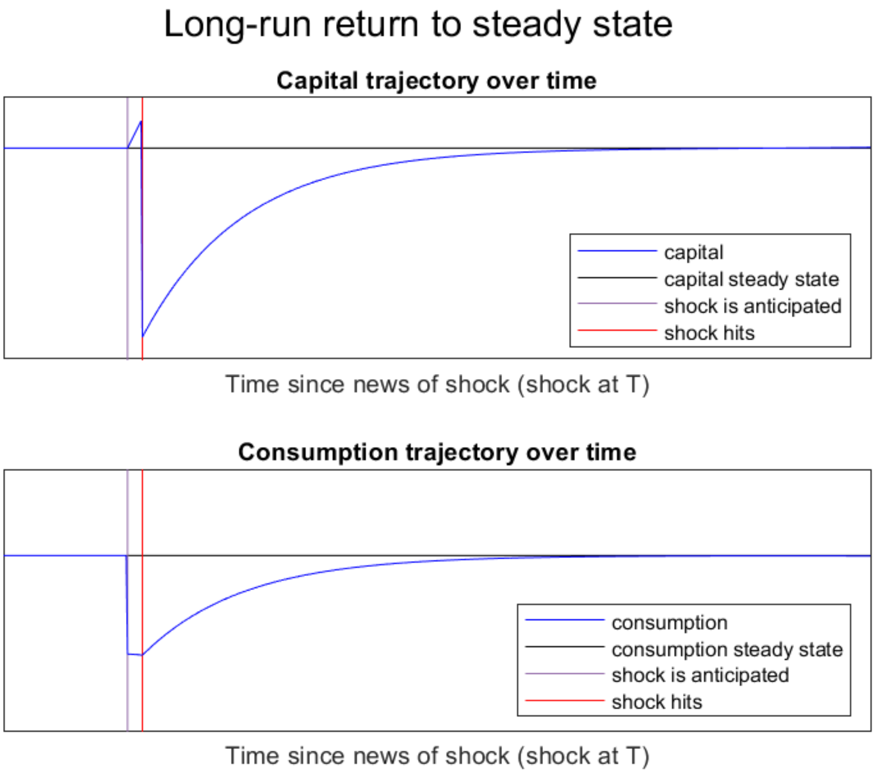
The control variable will adjust such that at time T the economy is on the saddle path. As the earthquake is temporary, the earthquake has no long-term impact. In other words, the steady state of the economy before and after the shock are the same. However, there is a temporary transition. At the time of the news, the agents anticipate the shock, which will negatively affect capital at time T, and to offset this the agents will consume less and save more in the short run to build up capital in anticipation of the earthquake. Then, after the earthquake, the economy will be on the saddle path and will eventually return to the steady state.

Below, I plot the transition of the economy in a phase diagram. At the time of the news, the agents reduce their consumption to invest in capital to offset the earthquake. So, consumption immediately falls, and over the next T-1 periods capital rises. At time T, capital falls due to the earthquake, and the economy ends up on the saddle path. It follows the saddle path until it eventually converges back to the steady state in the limit as $t \to \infty$.



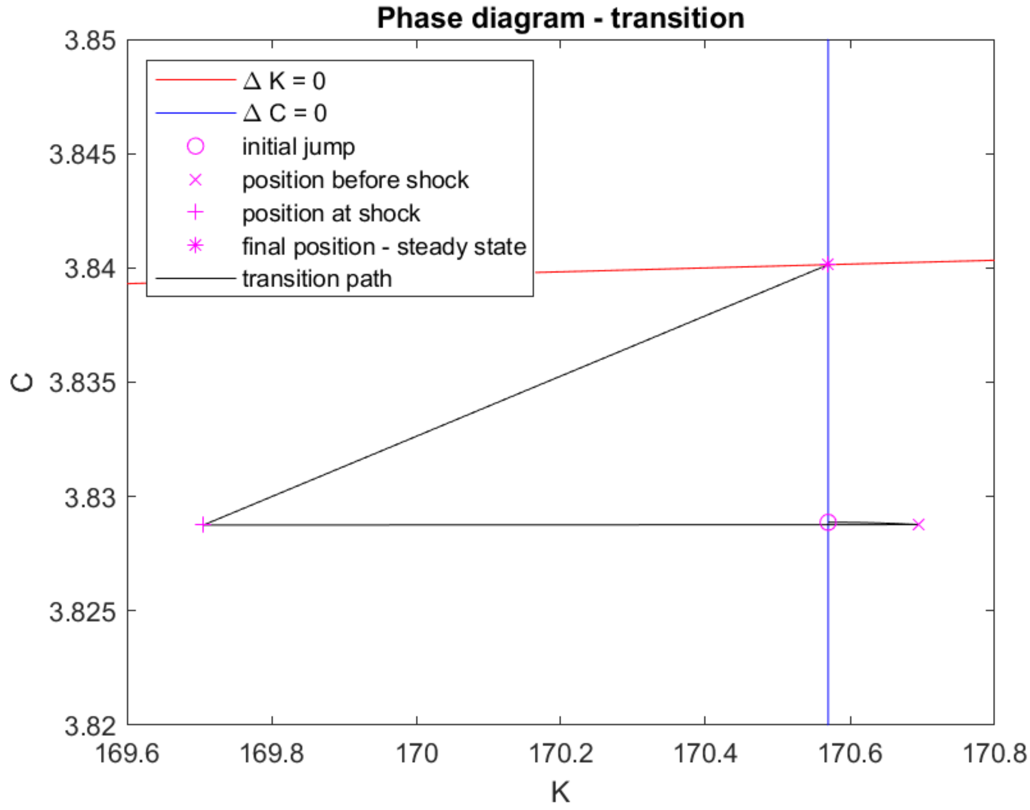
The above figure shows the transition of the economy via a phase diagram, as described above. Below we show the transition of the economy in the short-run and the long-run transition to the steady state.

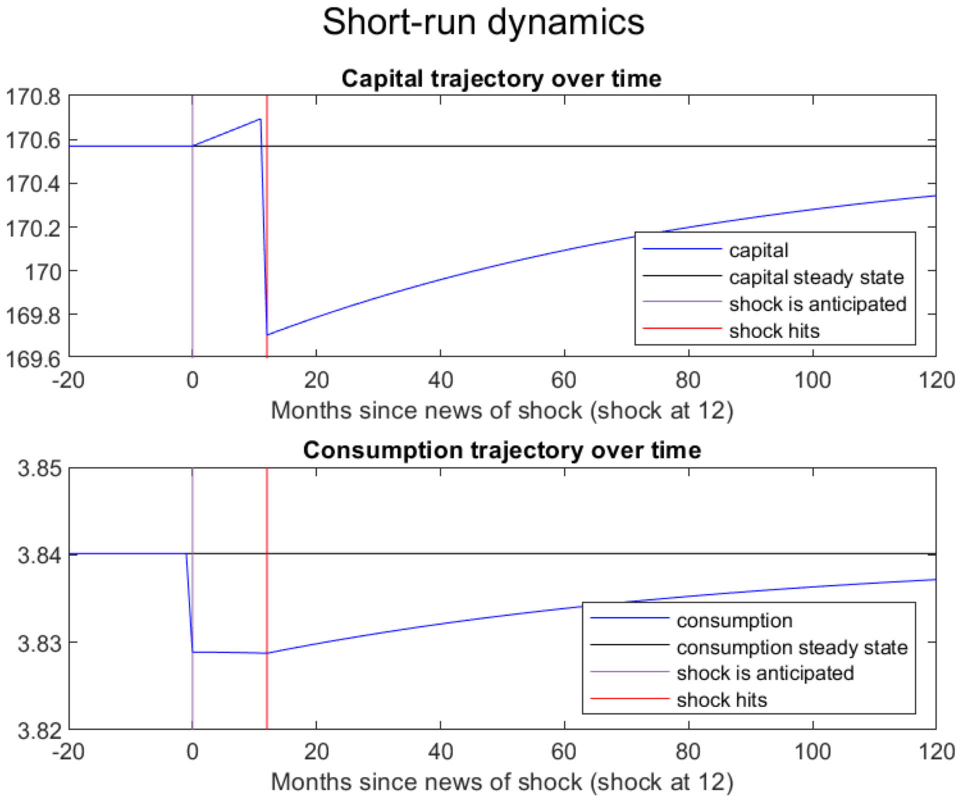

Short-run dynamics
Capital trajectory over time
capital
capital steady state
shock is anticipated
shock hits
Time since news of shock (shock at T)
Consumption trajectory over time
consumption
consumption steady state
shock is anticipated
shock hits
Time since news of shock (shock at T)

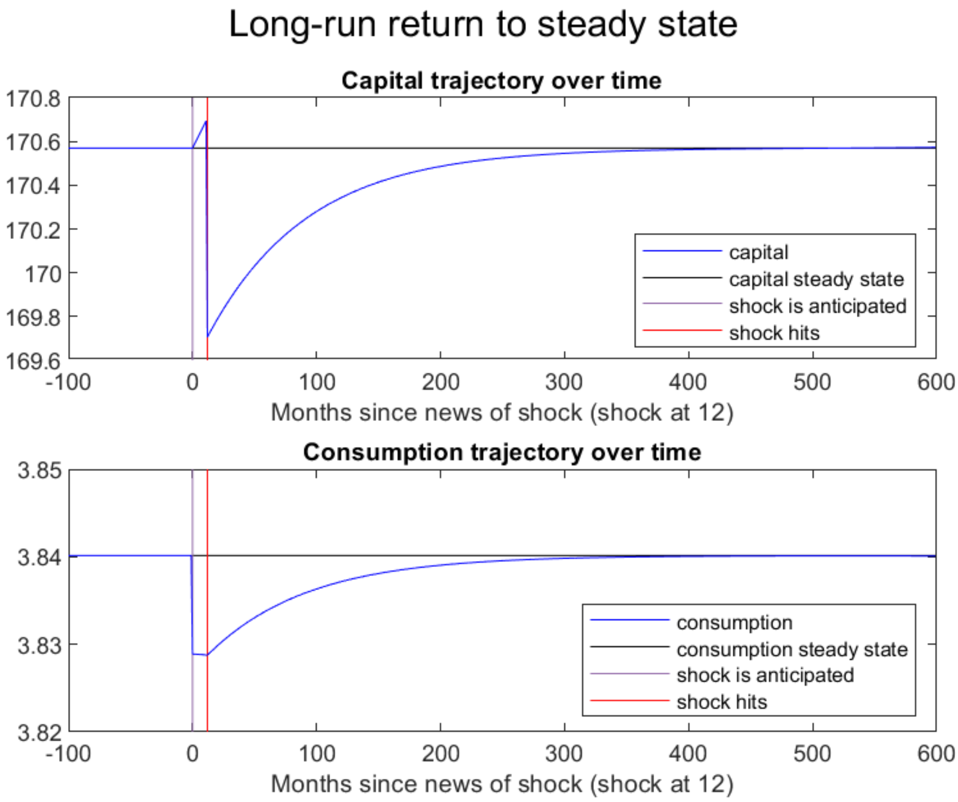


4 Question 4

Below we plot the numerical solutions.


Phase diagram - transition
Δ K = 0
Δ C = 0
initial jump
position before shock
position at shock
final position - steady state
transition path
C
3.85
3.845
3.84
3.835
3.83
3.825
3.82
K
169.6
169.8
170
170.2
170.4
170.6
170.8


Short-run dynamics
Capital trajectory over time
170.8
170.6
170.4
170.2
170
169.8
169.6
-20
0
20
40
60
80
100
120
Months since news of shock (shock at 12)
capital
capital steady state
shock is anticipated
shock hits
Consumption trajectory over time
3.85
3.84
3.83
3.82
-20
0
20
40
60
80
100
120
Months since news of shock (shock at 12)
consumption
consumption steady state
shock is anticipated
shock hits



Long-run return to steady state
Capital trajectory over time
170.8
170.6
170.4
170.2
170
169.8
169.6
-100
0
100
200
300
400
500
600
Months since news of shock (shock at 12)
capital
capital steady state
shock is anticipated
shock hits
Consumption trajectory over time
3.85
3.84
3.83
3.82
-100
0
100
200
300
400
500
600
Months since news of shock (shock at 12)
consumption
consumption steady state
shock is anticipated
shock hits