Ex0909A3: The generalized canonical transformation

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The problem: A system is described by the Hamiltonian H(q,p,t). The coordinate q is transformed $q \to Q = \psi(q,t)$

- 1. Find the most general transformation $p \to P(q,p,t)$ so that $(q,p) \to (Q,P)$ will be canonical.
- 2. Calculate the appropriate generating function (explain why $F_1(q,Q,t)$ isn't relevant).
- 3. Given the new Hamiltonian H'=0. Find the original Hamiltonian.
- 4. Prove that for $\psi(q+\omega t)$, the original Hamiltonian is a function of p alone. What does it mean?

The solution:

1. We will derive here the transformation for P:

$$[Q, P] = \frac{\partial Q}{\partial q} \cdot \frac{\partial P}{\partial p} - \frac{\partial Q}{\partial p} \frac{\partial P}{\partial q} = \frac{\partial Q}{\partial q} \cdot \frac{\partial P}{\partial p} = \frac{\partial \psi(q, t)}{\partial q} \cdot \frac{\partial P}{\partial p} = 1$$
 (1)

$$\frac{\partial P}{\partial p} = \frac{\partial q}{\partial \psi} = \frac{\partial q}{\partial Q} \Rightarrow \boxed{P = p \cdot \frac{\partial q}{\partial Q} + f(q, t)}$$
(2)

2. Finding the generative function:

We will choose the third class of generative function, And we will define q with (Q,t), leading to q=g(Q,t), because we have $Q=\psi(q,t)$. So f can be expressed with (Q,t).

$$F_3(p,Q,t),$$
 $(1) - P = \frac{\partial F_3}{\partial Q}, (2) - q = \frac{\partial F_3}{\partial p}$ (3)

$$(1) \frac{\partial F_3}{\partial Q} = -p \cdot \frac{\partial q}{\partial Q} - f(q, t) \tag{4}$$

$$F_3 = -pq - \int f(Q, t)dQ + h(p, t) \tag{5}$$

$$(2)\frac{\partial F_3}{\partial p} = -q + \frac{\partial h}{\partial p} = -q \implies h = l(t)$$
(6)

$$F_3 = -pq - \int f(Q, t)dQ + l(t) \Rightarrow \boxed{F_3 = -p \cdot g(Q, t) - \int f(Q, t)dQ}$$

$$\tag{7}$$

Where we dropped the function that depends only on time because it can affect the equation of motion.

3. Here we will find the original Hamiltonian. we know that :

$$0 = \dot{\mathcal{H}} = \mathcal{H} + \frac{\partial F_3}{\partial t} \tag{8}$$

$$\mathcal{H} = -\frac{\partial F_3}{\partial t} \Rightarrow \boxed{\mathcal{H} = \frac{\partial (p \cdot g(Q, t))}{\partial t} + \frac{\partial (\int f(g(q, t), t) dQ)}{\partial t}}$$
(9)

- 4. answer 4
- 5. This is how you write an equation

$$\mathcal{I} = \int_{0}^{z} d^{4}x \sqrt{-g} \left[\varphi^{2} \left(\mathcal{R} - 6sg^{\mu\nu} \kappa_{\mu} \kappa_{\nu} \right) + 4\omega g^{\mu\nu} D_{\mu} \varphi D_{\nu} \varphi + \lambda \varphi^{4} + \frac{1}{4} g^{\mu\nu} g^{\lambda\sigma} X_{\mu\lambda} X_{\nu\sigma} \right]. \tag{10}$$

6. If you wish to add a set of equations (add the ampersands to align the two equations):

$$s = \frac{3+2\omega}{2\omega} \neq 1,\tag{11}$$

$$D_{\mu}\varphi = \varphi_{:\mu} + s\kappa_{\mu}\varphi, \tag{12}$$

If you wish to have equations with no numbers add an asterisk

$$g^{\mu\nu} \left(\varphi_{;\mu}^2 + 2\kappa_{\mu}\varphi^2\right)_{;\nu} = \frac{\partial W_{eff}(\varphi^2)}{\partial \varphi^2},$$
$$\frac{\partial W_{eff}(\varphi^2)}{\partial \varphi^2} = \frac{1}{3+2}\omega \left(\frac{1}{2}\varphi V'(\varphi) - 2V(\varphi)\right).$$

To write a vector

$$\vec{r} = x\hat{x} + y\hat{y} + z\hat{z} \quad ; \quad \vec{r}_i = |\vec{r}|\,\hat{r} \tag{13}$$

To write a matrix

$$\lambda_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \text{"\qquad" makes space in equations and this is how you add text.}$$
(14)

You can also use "align" to tightly align the equal sign, i.e "=" is aligned: see Eq. (15) and Eq. (16), also note that **every end** of an equation needs to be punctuated, i.e : "," or ".", according to the sentence.

$$\lambda_7 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix},\tag{15}$$

$$\lambda_8 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 0 \end{pmatrix},\tag{16}$$

and centered

$$\left[\frac{\lambda_i}{2}, \frac{\lambda_j}{2}\right] = i \sum_{k=1}^n f^{ijk} \frac{\lambda_k}{2},$$

$$f^{147} = f^{165} = f^{246} = f^{257} = f^{345} = f^{376} = \frac{1}{2}.$$

7. Known arguments are **not** written in italic mode, some have special syntax in LaTeX otherwise just use "\mathrm":

$$\cos(\omega t); \quad \sin(\omega t); \quad \operatorname{Tr}\left[\hat{\mathbf{A}}\right]; \quad \det\left[\hat{\mathcal{A}}\right]; \quad \tan(\omega t); \quad \mathbf{e}^{\frac{t}{\tau}}; \quad \exp\left(\frac{t}{\tau}\right); \quad \log\left(\frac{t}{\tau}\right).$$
 (17)

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