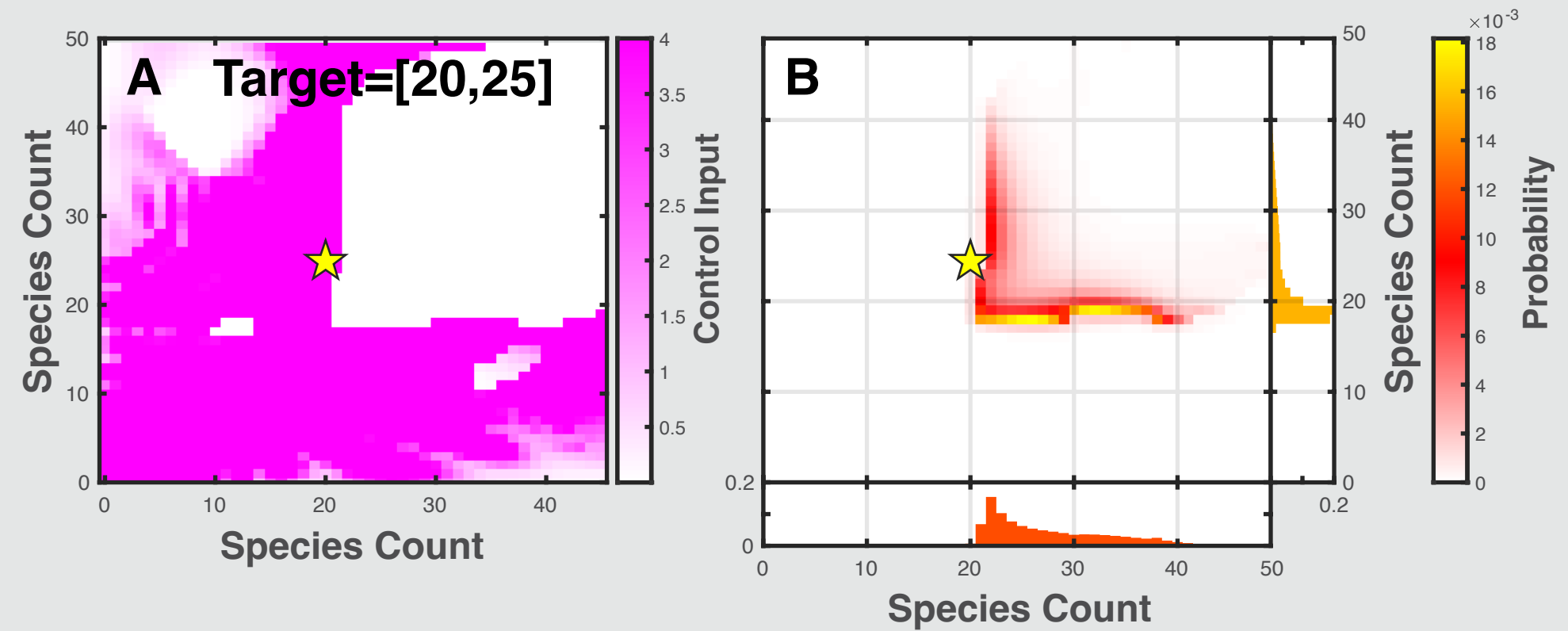
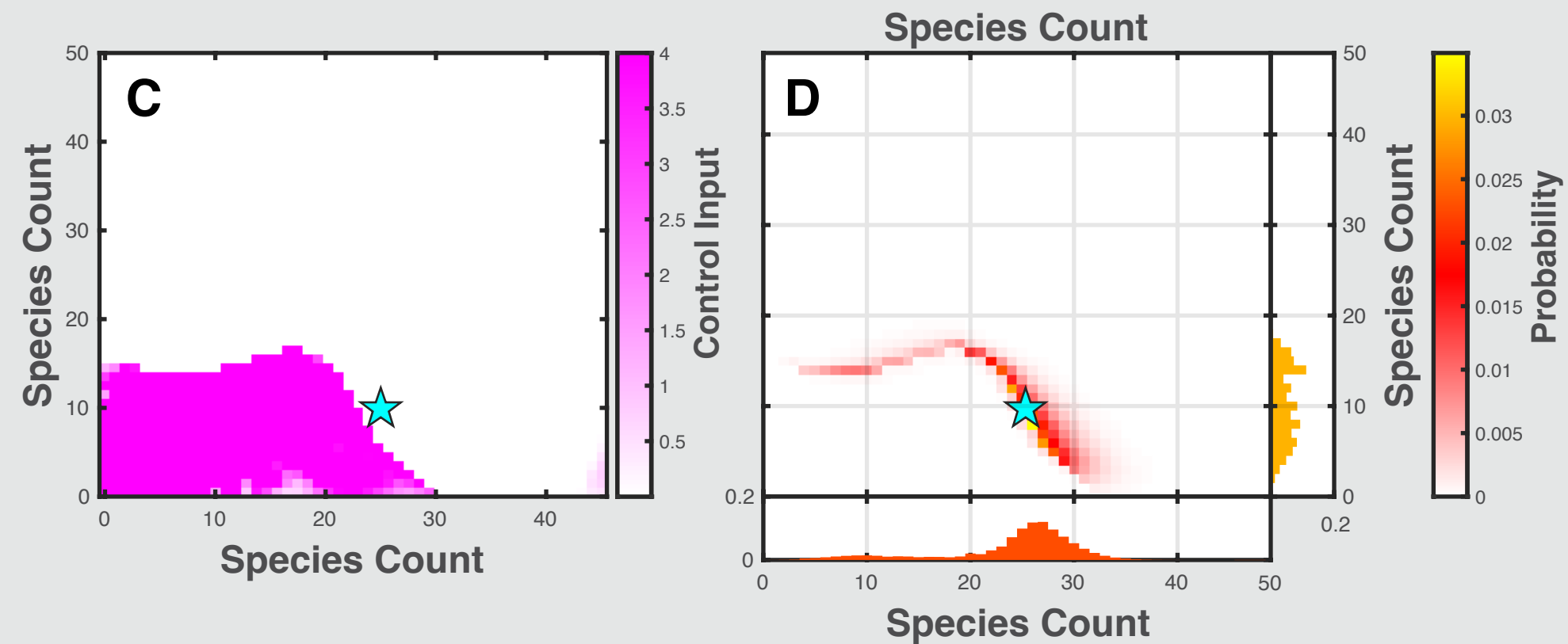


## Control Performance & Probability Distribution Target = [20,25]



## Control Performance & Probability Distribution Target = [10,25]



## Static Control Performance

