# Compiler Design and Optimization

## Mathematical Notes

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## 1 Introduction to Compilers

## 1.1 What is a Compiler?

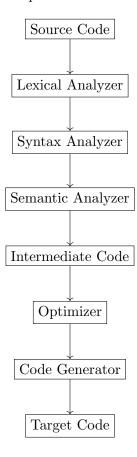
**Definition 1.1** (Compiler). A compiler is a computer program that translates source code written in a high-level programming language into target code (usually machine code or bytecode) that can be executed by a computer.

The compilation process typically involves several phases:

- 1. Lexical Analysis Breaking source code into tokens
- 2. Syntax Analysis Parsing tokens into abstract syntax trees
- 3. Semantic Analysis Type checking and semantic validation
- 4. Intermediate Code Generation Creating intermediate representation
- 5. Code Optimization Improving the intermediate code
- 6. Code Generation Producing target machine code

### 1.2 Compiler Architecture

Modern compilers typically follow a multi-pass architecture:



## 2 Lexical Analysis

## 2.1 Regular Expressions and Finite Automata

**Definition 2.1** (Regular Expression). A regular expression over alphabet  $\Sigma$  is defined recursively:

- ∅ (empty set)
- $\varepsilon$  (empty string)
- $a \text{ for } a \in \Sigma$
- $r_1 + r_2$  (union)
- $r_1 \cdot r_2$  (concatenation)
- $r^*$  (Kleene star)

**Theorem 2.1** (Kleene's Theorem). A language is regular if and only if it can be described by a regular expression.

#### 2.2 Finite State Automata

**Definition 2.2** (Deterministic Finite Automaton (DFA)). A DFA is a 5-tuple  $M = (Q, \Sigma, \delta, q_0, F)$  where:

- Q is a finite set of states
- $\bullet$   $\Sigma$  is the input alphabet
- $\delta: Q \times \Sigma \to Q$  is the transition function
- $q_0 \in Q$  is the start state
- $F \subseteq Q$  is the set of accepting states

**Definition 2.3** (Non-deterministic Finite Automaton (NFA)). An NFA is a 5-tuple  $M = (Q, \Sigma, \delta, q_0, F)$  where:

- Q is a finite set of states
- $\Sigma$  is the input alphabet
- $\delta: Q \times (\Sigma \cup \{\varepsilon\}) \to 2^Q$  is the transition function
- $q_0 \in Q$  is the start state
- $F \subseteq Q$  is the set of accepting states

## 2.3 Lexical Analysis Implementation

The lexical analyzer (lexer) converts a stream of characters into a stream of tokens. Common token types include:

- Keywords (if, while, class, etc.)
- Identifiers (variable names)
- Literals (numbers, strings)
- Operators (+, -, \*, /, etc.)
- Delimiters (parentheses, semicolons, etc.)

## 3 Syntax Analysis

#### 3.1 Context-Free Grammars

**Definition 3.1** (Context-Free Grammar). A context-free grammar is a 4-tuple G = (V, T, P, S) where:

- V is a finite set of non-terminals
- T is a finite set of terminals
- P is a finite set of productions of the form  $A \to \alpha$
- $S \in V$  is the start symbol

Example 3.1 (Simple Arithmetic Grammar).

$$E \to E + T \mid T \tag{1}$$

$$T \to T * F \mid F \tag{2}$$

$$F \to (E) \mid id \tag{3}$$

### 3.2 Parsing Algorithms

## 3.2.1 Top-Down Parsing

**Definition 3.2** (LL(k) Grammar). A grammar is LL(k) if it can be parsed deterministically from left to right, producing a leftmost derivation, using k tokens of lookahead.

#### **Recursive Descent Parsing:**

- Each non-terminal corresponds to a procedure
- Procedure bodies implement the grammar rules
- Requires LL(1) grammar for deterministic parsing

#### **Predictive Parsing:**

- Uses parsing table to make decisions
- Constructs FIRST and FOLLOW sets
- Eliminates left recursion and left factoring

#### 3.2.2 Bottom-Up Parsing

**Definition 3.3** (LR(k) Grammar). A grammar is LR(k) if it can be parsed deterministically from left to right, producing a rightmost derivation in reverse, using k tokens of lookahead.

#### LR(1) Parsing:

- Uses canonical LR(1) items
- Constructs parsing table with ACTION and GOTO
- Handles reduce-reduce and shift-reduce conflicts

## LALR(1) Parsing:

- Merges LR(1) states with same core
- Smaller parsing tables than LR(1)
- May introduce reduce-reduce conflicts

### 3.3 Abstract Syntax Trees

**Definition 3.4** (Abstract Syntax Tree (AST)). An AST is a tree representation of the syntactic structure of source code, where each node represents a construct occurring in the source code.

The AST abstracts away from the concrete syntax and focuses on the essential structure of the program.

## 4 Semantic Analysis

#### 4.1 Type Systems

**Definition 4.1** (Type System). A type system is a tractable syntactic method for proving the absence of certain program behaviors by classifying phrases according to the kinds of values they compute.

#### 4.1.1 Type Checking

### Static Type Checking:

- Performed at compile time
- Catches type errors before execution
- Requires type annotations or type inference

#### Dynamic Type Checking:

- Performed at runtime
- More flexible but less efficient
- Runtime type errors possible

#### 4.1.2 Type Inference

**Definition 4.2** (Type Inference). Type inference is the process of automatically determining the types of expressions in a program without explicit type annotations.

## Hindley-Milner Type System:

- Polymorphic type system
- Algorithm W for type inference
- Unification-based approach

### 4.2 Symbol Tables

**Definition 4.3** (Symbol Table). A symbol table is a data structure used by a compiler to keep track of semantic information about various source language constructs.

Symbol tables typically store:

- Variable names and types
- Function signatures
- Class definitions
- Scope information

### 5 Intermediate Code Generation

#### 5.1 Intermediate Representations

#### 5.1.1 Three-Address Code

**Definition 5.1** (Three-Address Code). Three-address code is an intermediate representation where each instruction has at most one operator and three operands.

Example 5.1 (Three-Address Code).

$$t_1 = a + b \tag{4}$$

$$t_2 = t_1 * c \tag{5}$$

$$d = t_2 \tag{6}$$

#### 5.1.2 Static Single Assignment (SSA)

**Definition 5.2** (Static Single Assignment). In SSA form, each variable is assigned exactly once, and every use of a variable is dominated by its definition.

SSA form enables:

- Efficient data-flow analysis
- Dead code elimination
- Constant propagation
- Register allocation

## 5.2 Control Flow Graphs

**Definition 5.3** (Control Flow Graph). A control flow graph (CFG) is a directed graph where nodes represent basic blocks and edges represent control flow between blocks.

**Definition 5.4** (Basic Block). A basic block is a sequence of consecutive statements with a single entry point and a single exit point.

## 6 Code Optimization

## 6.1 Optimization Levels

- 1. Local Optimization Within basic blocks
- 2. Global Optimization Across basic blocks
- 3. Interprocedural Optimization Across procedure boundaries

#### 6.2 Data-Flow Analysis

**Definition 6.1** (Data-Flow Analysis). Data-flow analysis is a technique for gathering information about the possible set of values calculated at various points in a computer program.

#### 6.2.1 Reaching Definitions

**Definition 6.2** (Reaching Definition). A definition d reaches a point p if there exists a path from d to p such that d is not killed along that path.

The reaching definitions problem can be formulated as:

$$REACH[n] = GEN[n] \cup (REACH[m] - KILL[n])$$
(7)

where m is a predecessor of n.

#### 6.2.2 Live Variables

**Definition 6.3** (Live Variable). A variable v is live at a point p if there exists a path from p to a use of v that does not redefine v.

## 6.3 Optimization Techniques

#### 6.3.1 Constant Folding and Propagation

**Definition 6.4** (Constant Folding). Constant folding is the process of evaluating constant expressions at compile time.

**Definition 6.5** (Constant Propagation). Constant propagation is the process of replacing variables with their constant values when possible.

#### 6.3.2 Dead Code Elimination

**Definition 6.6** (Dead Code). Dead code is code that can never be executed or whose results are never used.

Dead code elimination removes:

- Unreachable code
- Unused variables
- Unused functions

#### 6.3.3 Common Subexpression Elimination

**Definition 6.7** (Common Subexpression Elimination). CSE identifies and eliminates redundant computations of the same expression.

#### 6.3.4 Loop Optimizations

#### **Loop Invariant Code Motion:**

- Moves computations outside loops
- Reduces redundant calculations

#### Loop Unrolling:

- Replicates loop body multiple times
- Reduces loop overhead
- Enables further optimizations

## **Induction Variable Elimination:**

- Eliminates unnecessary induction variables
- Simplifies loop conditions

#### 6.3.5 Function Inlining

**Definition 6.8** (Function Inlining). Function inlining replaces a function call with the body of the called function.

#### Benefits:

- Eliminates call overhead
- Enables further optimizations
- May increase code size

## 7 Register Allocation

## 7.1 Graph Coloring

**Definition 7.1** (Register Allocation). Register allocation is the process of assigning program variables to processor registers.

**Theorem 7.1** (Graph Coloring Theorem). A graph is k-colorable if and only if it does not contain a complete subgraph of size k + 1.

### 7.2 Interference Graphs

**Definition 7.2** (Interference Graph). An interference graph is a graph where nodes represent variables and edges represent variables that cannot be assigned to the same register.

#### Chaitin's Algorithm:

- 1. Build interference graph
- 2. Simplify graph by removing low-degree nodes
- 3. Spill nodes if graph is not colorable
- 4. Color the graph

## 7.3 Spilling

**Definition 7.3** (Spilling). Spilling is the process of storing variables in memory when there are not enough registers.

Spill heuristics:

- Spill variables with high spill cost
- Spill variables with low usage frequency
- Consider loop nesting levels

### 8 Code Generation

#### 8.1 Instruction Selection

**Definition 8.1** (Instruction Selection). Instruction selection is the process of choosing appropriate machine instructions to implement each intermediate code operation.

#### Tree Pattern Matching:

- Represent instructions as tree patterns
- Use dynamic programming for optimal selection
- Handle complex addressing modes

## 8.2 Instruction Scheduling

**Definition 8.2** (Instruction Scheduling). Instruction scheduling is the process of reordering instructions to improve performance while maintaining correctness.

#### Pipeline Scheduling:

- Minimize pipeline stalls
- Consider instruction latencies
- Handle data dependencies

## 8.3 Peephole Optimization

**Definition 8.3** (Peephole Optimization). Peephole optimization is a local optimization technique that examines a small window of instructions and replaces them with more efficient sequences.

Common peephole optimizations:

- Redundant load elimination
- Strength reduction
- Branch optimization

## 9 Advanced Topics

## 9.1 Just-In-Time Compilation

**Definition 9.1** (Just-In-Time Compilation). *JIT compilation is a method of executing computer code that involves compilation during program execution rather than before.* 

JIT compilation benefits:

- Profile-guided optimization
- Adaptive optimization
- Runtime specialization

### 9.2 Parallel Compilation

**Definition 9.2** (Parallel Compilation). Parallel compilation distributes compilation tasks across multiple processors to reduce compilation time.

Parallelization strategies:

- File-level parallelism
- Function-level parallelism
- Phase-level parallelism

## 9.3 Compiler Correctness

**Definition 9.3** (Compiler Correctness). A compiler is correct if it preserves the semantics of the source program in the target program.

Verification techniques:

- Translation validation
- Formal verification
- Testing and validation

## 10 Modern Compiler Design

#### 10.1 Multi-Pass Architecture

Modern compilers often use multiple passes for:

- Modularity and maintainability
- Different optimization levels
- Language-specific processing

## 10.2 Plugin Architecture

**Definition 10.1** (Plugin Architecture). A plugin architecture allows extending compiler functionality through dynamically loaded modules.

Benefits:

- Language-specific optimizations
- Target-specific code generation
- Custom analysis passes

## 10.3 Compiler Infrastructure

Popular compiler infrastructures:

- LLVM Low Level Virtual Machine
- GCC GNU Compiler Collection
- MLIR Multi-Level Intermediate Representation

## 11 Performance Analysis

## 11.1 Compilation Metrics

Key performance metrics:

- Compilation time
- Memory usage
- Generated code size
- Runtime performance

### 11.2 Optimization Effectiveness

Measuring optimization effectiveness:

- Benchmark suites
- Profiling tools
- Performance counters

## 12 Conclusion

Compiler design and optimization is a complex field that combines theoretical computer science with practical engineering. The key principles include:

- Modular design with clear separation of concerns
- Systematic application of optimization techniques
- Careful balance between compilation time and code quality
- Adaptation to modern hardware architectures

The field continues to evolve with new languages, architectures, and optimization techniques, making it an exciting area of computer science research and development.