

## leigqNEWTON\_cert\_resPair — eigenpair residual

Compute the residual norm for a specific eigenpair candidate ( $\lambda, v$ ):  $\text{resPair}(A, \lambda, v) = \|A*v - \lambda*v\|$  (optionally normalized).

### Setup (requirements + path)

```
hasQuat = true;
try
    quaternion(0,0,0,0);
catch
    hasQuat = false;
end
if ~hasQuat
    disp('This toolbox requires MATLAB''s built-in quaternion class
(quaternion(w,x,y,z)).');
    disp('Examples in this page are skipped.');
    return;
end

if exist('leigqNEWTON_cert_resPair','file') ~= 2
    thisFile = mfilename('fullpath');
    if ~isempty(thisFile)
        rootGuess = fileparts(fileparts(fileparts(thisFile))); % .../docs/source ->
toolbox root
        if exist(fullfile(rootGuess,'leigqNEWTON_cert_resPair.m'),'file')
            addpath(rootGuess);
        end
    end
end

if exist('leigqNEWTON_cert_resPair','file') ~= 2
    error('leigqNEWTON_cert_resPair not found on the MATLAB path. Add the toolbox
root folder.');
end
```

### Syntax

- $r = \text{leigqNEWTON\_cert\_resPair}(A, \lambda, v)$
- $r = \text{leigqNEWTON\_cert\_resPair}(A, \lambda, v, \text{'ResidualNormalized'}, \text{true/false})$

### Example: compute resPair after polishing

Use a fixed  $2 \times 2$  test (Huang–So Example 2.6).

```
q0 = quaternion(0,0,0,0);
q1 = quaternion(1,0,0,0);
qi = quaternion(0,1,0,0);
qj = quaternion(0,0,1,0);
```

```
A = [ q0, qi;
      qj, q1 ];

% Get one candidate pair.
[lambda, V] = leigqNewton(A, 'SolveProfile','default', 'Seed',1);

% Polish it to near machine precision.
[lambdaP, vP] = leigqNewton_refine_polish(A, lambda(1), V(:,1));

% Pair residual (typically ~1e-15 to 1e-16 after polish on small problems).
r = leigqNewton_cert_resPair(A, lambdaP, vP);
disp(r);
```

6.6023e-12

## See also

`leigqNewton_cert_resMin`, `leigqNewton_refine_polish`, `leigqNewton_refine_batch`