

ExNEWTON_2_MVPS

Reproduce the explicit 3×3 examples (topological cases) from:

E. Macías-Virgós and M. J. Pereira-Sáez. Cayley–Hamilton theorem for left eigenvalues of 3×3 quaternionic matrices. Special Matrices, 2(1):11–18, 2014. DOI: 10.2478/SPMA-2014-0002.

Reproduce explicit 3×3 examples from paper by Macías-Virgos & Pereira-Sáez (MVPS) using the shipped script examples/ExNEWTON_2_MVPS.m.

Requirements

```
hasQuat = true;
try
    quaternion(0,0,0,0);
catch
    hasQuat = false;
end
if ~hasQuat
    disp('This toolbox requires MATLAB''s built-in quaternion class
(quaternion(w,x,y,z)).');
    disp('Examples in this page are skipped.');
    return;
end

if exist('leigqNewton','file') ~= 2
    thisFile = mfilename('fullpath');
    if ~isempty(thisFile)
        rootGuess = fileparts(fileparts(fileparts(thisFile))); % .../docs/source ->
toolbox root
        if exist(fullfile(rootGuess,'leigqNewton.m'),'file')
            addpath(rootGuess);
        end
    end
end

if exist('leigqNewton','file') ~= 2
    error('leigqNewton not found on the MATLAB path. Add the toolbox root folder.');
end
```

Run the shipped script

```
root = fileparts(which('leigqNewton'));
ex   = fullfile(root,'examples','ExNEWTON_2_MVPS.m');
if exist(ex,'file')
    run(ex);
else
    error('Example not found: %s', ex);
end
```

MVPS topological examples (leigqNEWTON)

```
=====
A19 =
 0 + 1i + 0j + 0k      0 + 0i + 0j + 0k      0 + 0i + 0j + 0k
 0 + 0i + 0j + 1k      0 + 0i + 1j + 0k      0 + 0i + 0j + 0k
 0 - 3i + 0j + 0k      0 + 0i + 0j + 2k      0 + 0i + 0j + 1k

A38 =
 0 + 0i + 0j + 0k      0 + 1i + 0j + 0k      1 + 0i + 0j + 0k
 0 + 3i + 0j - 1k      0 + 0i + 0j + 0k      1 + 0i + 0j + 0k
 0 + 0i + 0j + 1k      -1 + 0i + 1j + 1k      0 + 0i + 0j + 0k

B51 =
 0 + 1i + 0j + 0k      0 + 1i + 0j + 0k      1 + 0i + 0j + 0k
 0 + 3i + 0j - 1k      0 + 1i + 0j + 0k      1 + 0i + 0j + 0k
 0 + 0i + 0j + 1k      -1 + 0i + 1j + 1k      0 + 1i + 0j + 0k

Binv51 =
 0 + 0.4i + 0j - 0.2k    0 - 0.4i + 0j + 0.2k    0 + 0i + 0j + 0k
 -0.1 - 0.3i + 0.8j - 0.6k  0.1 + 0.3i - 0.3j + 0.1k  0 + 0i - 0.5j - 0.5k
 1.1 + 0.1i - 0.8j - 0.8k  -0.1 - 0.1i + 0.3j + 0.3k  0 + 0i - 0.5j + 0.5k

A52 =
 0 + 0i + 1j + 0k      1 + 0i + 0j + 0k      0 + 0i + 0j + 0k
 0 + 2i + 0j + 0k      0 + 0i + 0j - 1k      1 + 0i + 0j + 0k
 2 - 1i - 2j + 0k      -1 + 0i - 1j + 1k      0 - 1i + 0j - 1k

A54 =
 0 + 0i + 0j + 0k      0 + 0i - 1j + 0k      0 + 1i + 0j + 0k
 -1 + 0i + 1j + 0k      0 + 0i + 1j + 0k      0 + 0i + 0j + 1k
 NaN + NaNi + NaNj + NaNk  NaN + NaNi + NaNj + NaNk  NaN + NaNi + NaNj + NaNk

A55 =
 0 + 0i + 0j + 1k      0 + 0i + 0j + 0k      0 + 0i + 0j + 0k
 0 + 3i - 1j + 0k      0 - 1i + 0j + 0k      0 + 1i + 0j + 0k
 1 + 0i + 0j - 2k      0 + 0i + 1j + 0k      0 + 0i - 1j + 0k

A56 =
 0 - 1i - 1j + 0k      0 + 0i + 0j + 0k      0 + 0i + 0j + 0k
 0 + 0i + 0j + 1k      0 - 1i + 0j + 0k      0 + 1i + 0j + 0k
 1 - 1i + 0j + 0k      0 + 0i + 1j + 0k      0 + 0i - 1j + 0k
```

Inverse check for Example 51: max|B51*Binv51 - I| = 8.327e-17

Example 19

== checkNEWTON ==

Matrix: 3x3 quaternion

Lambdas: 3 (computed). Vectors: 3 columns (computed).

Certificate/residual summary (median | max):

```
resMin abs: 1.37e-18 | 9.18e-18    resMin rel: 2.68e-19 | 1.79e-18
resPair abs: 2.29e-16 | 3.48e-16   resPair rel: 4.48e-17 | 6.80e-17
```

Per-eigenvalue residuals:

# lambda (cleaned/rounded)	resMin(abs/rel)	resPair(abs/rel)
1 0 +1i +0j +0k	9.18e-18/ 1.79e-18	3.48e-16/ 6.80e-17
2 0 +0i +1j +0k	1.37e-18/ 2.68e-19	2.29e-16/ 4.48e-17
3 0 +0i +0j +1k	0.00e+00/ 0.00e+00	0.00e+00/ 0.00e+00

Interestingness:

Standard: Kdistinct = n = 3.

Sphere check: not run. Use checkNEWTON(...,'SphereCheck','on') to force.

Outputs:

```
out          : main struct (out.lambda, out.v, out.resMinAbs, out.resPairAbs, ...).
cases{1}     : simple case struct with fields A, lamAll, lamSamples, sph, info (sphere tooling style).
S           : summary struct (n, Ktot, Kdistinct, spheresFound, ...).
```

Example 38

== checkNEWTON ==

```

Matrix: 3x3 quaternion
Lambdas: 3 (computed). Vectors: 3 columns (computed).
Certificate/residual summary (median | max):
  resMin abs: 1.03e-15 | 1.38e-13    resMin rel: 1.76e-16 | 2.53e-14
  resPair abs:1.33e-15 | 1.39e-13    resPair rel:2.28e-16 | 2.53e-14

Per-eigenvalue residuals:
# lambda (cleaned/rounded)          resMin(abs/rel)          resPair(abs/rel)
 1  0.02387 -1.716i +0.2257j -0.04859k  3.63e-17/ 6.20e-18  6.04e-16/ 1.03e-16
 2  0.0983 -0.07397i +1.137j -0.7198k  1.38e-13/ 2.53e-14  1.39e-13/ 2.53e-14
 3  0.02387 -1.716i +0.2257j -0.04859k  1.03e-15/ 1.76e-16  1.33e-15/ 2.28e-16

Interestingness:
Nonstandard: Kdistinct = 2 < n = 3. Consider running longer: leigqNewton(A,'SolveProfile','reliable').
Sphere check: not run. Use checkNewton(...,'SphereCheck','on') to force.

Outputs:
out      : main struct (out.lambda, out.v, out.resMinAbs, out.resPairAbs, ...).
cases{1}  : simple case struct with fields A, lamAll, lamSamples, sph, info (sphere tooling style).
S        : summary struct (n, Ktot, Kdistinct, spheresFound, ...).

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Example 51 (B)
== checkNewton ==
Matrix: 3x3 quaternion
Lambdas: 3 (computed). Vectors: 3 columns (computed).
Certificate/residual summary (median | max):
  resMin abs: 8.79e-16 | 1.39e-13    resMin rel: 1.68e-16 | 2.27e-14
  resPair abs:1.55e-15 | 1.39e-13    resPair rel:2.96e-16 | 2.27e-14

Per-eigenvalue residuals:
# lambda (cleaned/rounded)          resMin(abs/rel)          resPair(abs/rel)
 1  0.02387 -0.7155i +0.2257j -0.04859k  5.35e-17/ 1.02e-17  5.29e-16/ 1.01e-16
 2  0.0983 +0.926i +1.137j -0.7198k   1.39e-13/ 2.27e-14  1.39e-13/ 2.27e-14
 3  0.02387 -0.7155i +0.2257j -0.04859k  8.79e-16/ 1.68e-16  1.55e-15/ 2.96e-16

Interestingness:
Nonstandard: Kdistinct = 2 < n = 3. Consider running longer: leigqNewton(A,'SolveProfile','reliable').
Sphere check: not run. Use checkNewton(...,'SphereCheck','on') to force.

Outputs:
out      : main struct (out.lambda, out.v, out.resMinAbs, out.resPairAbs, ...).
cases{1}  : simple case struct with fields A, lamAll, lamSamples, sph, info (sphere tooling style).
S        : summary struct (n, Ktot, Kdistinct, spheresFound, ...).

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Example 52
== checkNewton ==
Matrix: 3x3 quaternion
Lambdas: 3 (computed). Vectors: 3 columns (computed).
Certificate/residual summary (median | max):
  resMin abs: 2.20e-13 | 2.99e-11    resMin rel: 4.06e-14 | 6.37e-12
  resPair abs:2.21e-13 | 2.99e-11    resPair rel:4.07e-14 | 6.37e-12

Per-eigenvalue residuals:
# lambda (cleaned/rounded)          resMin(abs/rel)          resPair(abs/rel)
 1  -0.1941 +0.1022i -0.01561j -0.5378k  3.98e-17/ 7.54e-18  1.12e-15/ 2.13e-16
 2  0 +0i +0j +6.501e-06k            2.99e-11/ 6.37e-12  2.99e-11/ 6.37e-12
 3  0.2796 +0.3996i +0.3945j +0.3843k  2.20e-13/ 4.06e-14  2.21e-13/ 4.07e-14

Interestingness:
Standard: Kdistinct = n = 3.
Sphere check: not run. Use checkNewton(...,'SphereCheck','on') to force.

```

Outputs:

```

out      : main struct (out.lambda, out.v, out.resMinAbs, out.resPairAbs, ...).
cases{1} : simple case struct with fields A, lamAll, lamSamples, sph, info (sphere tooling style).
S        : summary struct (n, Ktot, Kdistinct, spheresFound, ...).

```

Example 54
Skipped: matrix contains NaN placeholders (fill p,q,r first).

Example 55
== checkNEWTON ==
Matrix: 3x3 quaternion
Lambdas: 3 (computed). Vectors: 3 columns (computed).
Certificate/residual summary (median | max):

resMin abs: 8.90e-12 2.23e-11	resMin rel: 1.51e-12 4.08e-12
resPair abs: 8.90e-12 2.23e-11	resPair rel: 1.51e-12 4.08e-12

Per-eigenvalue residuals:

# lambda (cleaned/rounded)	resMin(abs/rel)	resPair(abs/rel)
1 0 +0i +0j +0k	6.12e-18 / 1.37e-18	3.65e-16 / 8.16e-17
2 -1.091e-11 -1i -1j -8.211e-12k	8.90e-12 / 1.51e-12	8.90e-12 / 1.51e-12
3 -1.401e-11 +3.79e-11i +4.676e-11j +1k	2.23e-11 / 4.08e-12	2.23e-11 / 4.08e-12

Interestingness:
Standard: Kdistinct = n = 3.
Sphere check: not run. Use checkNEWTON(...,'SphereCheck','on') to force.

Outputs:

```

out      : main struct (out.lambda, out.v, out.resMinAbs, out.resPairAbs, ...).
cases{1} : simple case struct with fields A, lamAll, lamSamples, sph, info (sphere tooling style).
S        : summary struct (n, Ktot, Kdistinct, spheresFound, ...).

```

Example 56
== checkNEWTON ==
Matrix: 3x3 quaternion
Lambdas: 3 (computed). Vectors: 3 columns (computed).
Certificate/residual summary (median | max):

resMin abs: 2.99e-11 3.75e-11	resMin rel: 6.78e-12 8.49e-12
resPair abs: 2.99e-11 3.75e-11	resPair rel: 6.78e-12 8.49e-12

Per-eigenvalue residuals:

# lambda (cleaned/rounded)	resMin(abs/rel)	resPair(abs/rel)
1 0 +0i +0j +0k	4.40e-18 / 1.47e-18	5.00e-16 / 1.67e-16
2 4.24e-06 -1i -1j -3.338e-06k	2.99e-11 / 6.78e-12	2.99e-11 / 6.78e-12
3 -7.412e-06 -1i -1j -6.125e-07k	3.75e-11 / 8.49e-12	3.75e-11 / 8.49e-12

Interestingness:
Standard: Kdistinct = n = 3.
Sphere check: not run. Use checkNEWTON(...,'SphereCheck','on') to force.

Outputs:

```

out      : main struct (out.lambda, out.v, out.resMinAbs, out.resPairAbs, ...).
cases{1} : simple case struct with fields A, lamAll, lamSamples, sph, info (sphere tooling style).
S        : summary struct (n, Ktot, Kdistinct, spheresFound, ...).

```

Done.

What to look for

- The script prints the matrices (cleaned) and runs `checkNEWTON` on each case.
- Some cases are non-generic (e.g., more than n distinct left eigenvalues).
- If you want to increase solver budgets, edit the script and change `SolveProfile` (e.g., '`default`' → '`reliable`') or pass larger trial counts.

See also

`checkNEWTON`, `doc_RefinementAndCertificates`, `leigqNewton_refine_batch`