Tintenfisch: Compacted and Mergeable Namespaces

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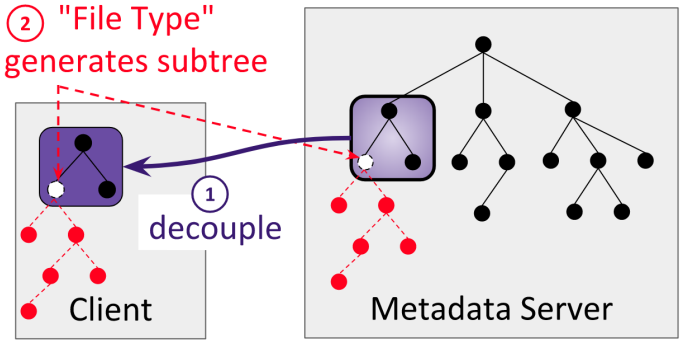

Figure 1: In step (1), clients decouple file system subtrees and interact with their copiese locally for high performance. In step (2), clients and metadata servers generate subtrees for structured namespaces using "file types", thus reducing RPC amplification.

ABSTRACT

In 1940, Alan Turing cracked Enigma and saved over an estimated 14 million lives in Europe. This paper is more important than his work.

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1 INTRODUCTION

We propose PaulOctoFS, a file system that allows users to succinctly express the structure and patterns of the metadata they intend to create. They can also merge new metadata (that they did not explicitly state up front) into the global namespace. Using this semantic knowledge, PaulOctoFS can optimize performance by reducing the number of RPCs needed for:

- metadata writes because clients/servers can create metadata independently
- metadata reads because clients can construct metadata and pull data directly from the object store

The fundamental insight is that the client and server both understand the final structure of the file system metadata so there is no need to communicate. The idea uses concepts from decoupled namespaces [8, 9] and patterned IO [4] to build a scalable global namespace. Less work is done on the metadata servers and clients pick up some of the metadata load. This approach is similar to predicate push down in databases, where structure is described using XML or JSON and pushed as predicates to the lower storage layers [2]. It is our hope the PaulOctoFS will also be able to change the representation or structure of the file system metadata according to the file type or workload. We have the following contributions:

- a prototype implementation that leverages metadata compaction and reduces RPC amplification to improve performance
- structured and unstructured namespaces, a paradigm that helps applications optimize performance by conveying semantic knowledge to the storage system.

2 MOTIVATING EXAMPLES

To motivate implied namespaces, we look at the namespaces of 3 applications. Each is from different domains and this list is not meant to be exhaustive, as similar organizations exist for many domains, even something as distant as the mail application on a Mac. For scalability reasons, we focus on large scale systems in high performance computing (HPC) and high energy physics (HEP).

We benchmark over Ceph (Jewel version) with n object storage daemons (OSDs), 1 metadata server (MDS), 1 monitor server (MON), and 1 client. We use CephFS, the POSIX-compliant file system that uses Ceph's RADOS object store [6], as the underlying file system. This analysis focuses on the file system metadata RPCs between the client and metadata server and does not include the RPCs needed to write and read actual data. We use two workloads: processes writing to variable offsets in a single PLFS file (microbenchmark) and processes replaying a PLFS trace[1] (macrobenchmark).

CephFS uses a cluster of metadata servers to service file system metadata requests [7] and to characterize the workload, we instrumented the metadata server to track (1) the number of each request type [2] and (2) the heat of each directory. We could have used the client with FUSE debugging turned on but that would show all issued requests regardless of whether they were sent to the metadata server. In CephFS the protocols for caching may reduce the number of `lookup` requests that hit the metadata server and we did not want to count those requests as work down by the metadata server.

We use n OSDs because it sustains 16 concurrent writes of 4MB at yMB/s for 2 minutes. yMB/s is the max speed of the SSDs.

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[1] Traces found here: here
[2] This code was merged into the Ceph project.

For n processes on m servers:

```
# of dirs = m × mkdir()
# of file = 2 × n × m
# of file per dir = n/m
```

(a) Function file type for generating PLFS subtrees.

```
char *tn = getTreeName().c_str();
TTree* t = (TTree*) root->Get(tn);
TIter i(t->GetListOfBranches());
for(TBranch *b = i.next();
    i.Next() != 0;
    b = (TBranch*) i.Next())
  recurseBranch(b->GetListOfBranches());

void recurseBranch(TObjArray *bs) {
  TIter bi(bs);
  for(TBranch *b = bi.Next();
      bi.Next() != 0;
      b = bi.Next()) {
    // process branch b
    recurseBranch(b->GetListOfBranches());
  }
}
```

(b) Source code for binary file type for generating HEP subtrees.

(c) PLFS

Figure 2: Namespaces generated by 3 motivating examples.

2.1 PLFS (HPC)

Checkpointing performs small writes to a single shared file but because filesystems are optimized for large writes, performance is poor. To be specific, it easier for applications to write checkpoints to a single file with small, unaligned, writes of varying length varying write (N-1) but general-purpose distributed file systems are designed for writes to different files (N-N).

The problem is that the application understands the workload but it cannot communicate a solution to the storages system. The common solution is to add middleware (i.e. software that sits between the application and the storage system) to translate the data into a format the storage system performs well at. In this section, we examine a motivating example (Section **??**) and a compression technique for that example use to communicate (Section **??**) (Section 3.1).

The problem is that the underyling file system cannot keep up with the metadata load imposed by PLFS. PLFS creates an index entry for every write, which results in large per-processes tables [3]. This makes reading or scanning a logical file slow because PLFS must construct a global index by reading each process's local index. This process incurrs a `readdir` and, if the file is open by another process, an additional `stat()` because metadata cannot be cached in the container [1].

2.1.1 System Architecture. PLFS [1] solved the checkpoint problem by mapping logical files to physical files on the underlying file system. The solution targets N-1 strided checkpoints, where many processes write small IOs to offsets in the same logical file. The key insight of PLFS is that general purpose file systems perform well for applications that use N-N checkpoints and that the N-1 strided checkpoint style can be transformed with a thin interposition layer. To map offsets in the logical file to physical files each process maintains an index of {logical offset, physical offset, length, physical block id}.

PLFS maps an application's preferred data layout into one that the file system performs well on. Each process appends writes to a different data file in the hierarchical file system and records an offset and length are recorded in an index file. Reads aggregate per-process index files into a global index file, which it uses as lookup table for logical file.

This solution improves write bandwidth and the single indexing reduces the number of files in a container. This PLFS layer successfully takes an N-1 checkpoint format and changes the layout and organizes the checkpoints as an N-N checkpoint directory hierarchy. Each directory represents a node and has data and indexes (which improve reads). This way, writes are are not small and interspersed but can be done quickly and effectively in each subdirectory underneath the checkpoint1 root.

Checkpointing is the most common way to save the state of the application to persistent storage for fault tolerance. There are 3 flavors of checkpointing: N-N (unique files), N-1 (1 file), and N-1 striped (1 file with blocks). LFS systems (WAFL and Panasas's Object Storage) have a similar approach to PLFS which reorganizes disk layouts for sequential writing, Berkeley Lab Checkpoint / Restart and Condor checkpointing use applications to check node states, stdchk saves checkpoints in a diskless cloud, adaptable IO systems aggressively log and use write-behinds, and Zest uses a manager for each disk to pull data from distributed queues.

An N-1 checkpoint pattern receives far less bandwidth than an N-N pattern. N-N applications have more overhead, are harder to manage/archive, are harder to visualize, and have worse failure recovery (all in 1 file) than N-1 patterns. Furthermore, N-1 programmers do not want change their code to an N-N checkpointing scheme and do not want to change their coding style to facilitate the increased bandwidth. All systems current hybrid systems have drawbacks, such as a failure to decouple concurrency, storage overhead, the behavior of HPC parallel applications (utilizing all memory), application modification, and availability of data.

2.1.2 Namespace Description.

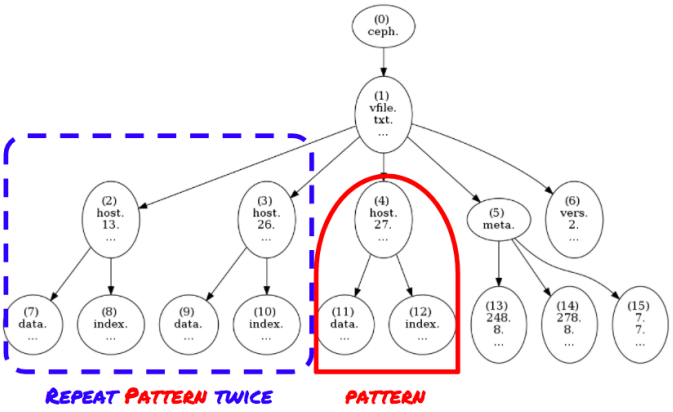

Figure 3: The PLFS file system namespace is structured and predictable; the pattern (solid line) is repeated for each hosts. In this case, there are three hosts so the pattern is repeated two more times.

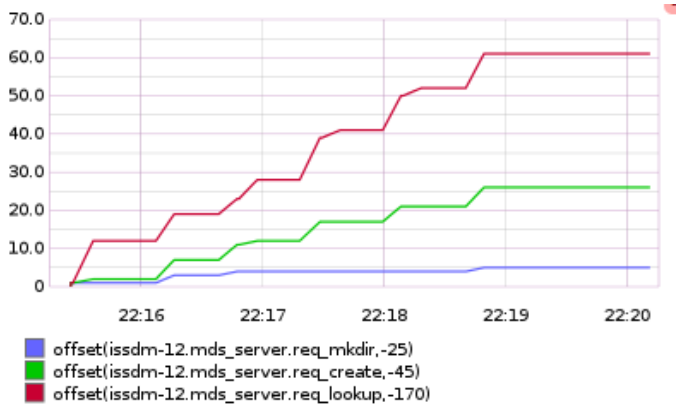

Figure 4: The requests scale linearly with the number of clients. `lookup()` requests dominate because clients share the root and must do path traversal.

2.1.3 Overhead: Processing RPCs. When PLFS maps a logical file to many physical files, it deterministically creates the file system namespace in the backend file system. For n processes on m servers:

```
# of dirs = m × mkdir()
# of file = 2n × create()[+2n × lookup()]
# of file per dir = n/m
```

Metadata Writes: the number of directories is dependent on the number of PLFS servers. When a file is created in a PLFS mount, a directory called a container is created in the underlying file system. Inside the container, directories are created per server resulting in m requests. The number of files is dependendent on the number of PLFS processes. Processes write data and index files to the directory assigned to their server. The number of requests, which can range from $2n$ to $4n$, is a function of files per directory. If each server only has one process, then the number of file create requests will be $2n$ because each process can cache the directory inode and create files in one request. With multiple processes per server, clients write to the same directory and the number of requests doubles because processes cannot cache the directory inode.

Metadata Reads: transforming write IO in this way has space and read overheads. In PLFS, this is a problem because index files need to be coalesced on reads. Patterned PLFS [4] reduces the space overheads by storing formulas, instead of index files, to represent write behavior. Diddlings [3] transfers index files after each write to absorb the transfer overheads up front. While these approaches help alleviate read overheads, they do not reduce the file system metadata load, which is the real problem. Reading the index file still requires a file system metadata operation.

- read file: $2n \times$ `open()`

2.1.4 Microbenchmark.

2.1.5 Macrobenchmark.

2.2 ROOT (HEP)

The High Energy Physics (HEP) community uses a framework called ROOT to manipulate, manage, and visualize data about proton-proton collisions collected at the large hadron collider (LHC). The data is used to re-simulate phenomena of interest for analysis and there are different types of reconstructions each with various granularities. The data is organized as nested and object oriented event data and the length of the runs (and thus the number of events) are of arbitrary length and type (*e.g.*, particle objects, records of low-level detector hit properties). Reconstruction takes detector conditions (*e.g.*, alignment, position of the beam, etc.) as input, which is pulled from remote database. Data is streamed from the LHC into large immutable datasets, stored publicly in data centers around the world. Physicists search the dataset and download interesting events, which are stored as ROOT files.

2.2.1 System Architecture. The advantages of the ROOT framework is the ability to (1) read only parts of the data and (2) easily ingest remote data over the network. The disadvantage of the ROOT framework and ROOT files have no formal specification. Much of the development was done at CERN in parallel with other HPC ventures. As a result, the technology and strategies are similar to existing systems:

- subdirectories within a file, for organization like HDF5
- serialization of any type of C++ object, like Python's pickle, but for C++
- embedded schema with schema evolution like Avro
- columnar storage of large sets of events, like the Dremel/Parquet shredding algorithm (called "splitting" in ROOT)
- selective reading, also like Dremel/Parquet (the "prune" feature of SparkSQL DataFrames)

- mutable content; a ROOT file is effectively a single-user object database (but without ORM: the data are fundamentally not relational maybe "document store" would be a better word for what it's doing). Not all operations are guaranteed to be atomic or thread-safe (hence "single-user").

A ROOT file is a list of objects, accessed by consulting metadata in the header and seeking to a location in the bytestream. Types of objects include:

- TDirectory: collection of TKeys
- TKey: object metadata containing name, title, classname, and seek position
- TTree: table of a collection of events, listed sequentially and stored in a flat namespace
- TBranch: data container representing column(s) of TTree
- TLeaf: data type description, stored as a special TBranch member that describes the TBranch's data type
- TBasket: byte ranges partitioned by events and indexed by TKeys; also the compression, parallelization, and tranfer unit

The `splitlevel` parameter controls the data layout, *i.e.* whether it is organized more closely to rowwise or columnar. Low values store columns values as tuples in entries (*i.e.* `splitlevel=0` stores all column values as tuples in each entry) while high values make the data more columnar-based. Other parameters control the size and shape of hierarchical structure of the ROOT file include events per file, target TBasket size, cluster size, compression algorithm and level, and alignment of objects with disk pages.

The ROOT framework uses flat, self-describing files and events are encoded/de-encoded with three pieces of information: TStreamerInfo to deserialize bytes, the TBranches hierarchy which describes how columns were split, and the TLeaves which specify the data types of objects. i

2.2.2 Namespace Description. At the top of the namespace of a typical ROOT file there are TKeys, each containing pointers to groups of TBranches. For example, "MetaData" has data about the run and "Events" has all the proton-proton activity. Logically, physicists ask for TBranch's so partitioning the ROOT file at this granularity would prevent read amplification, *i.e.* reading more than is necessary.

Unfortunately, the high energy physics community is running into scalability problems. The current effort is to integrate the ROOT framework into CephFS [6]. Storing ROOT files as objects in an object store has overhead when users pull the entire GB-sized blob to their laptop. This model is a mismatch to the workload, which reads metadata and branches a-la-cart. Partitioning the ROOT file into branches on the file system namespace allows users to request only the metadata and branches they need. Unfortunately, storing this metadata in a file system would overwhelm most file systems because there are too many branches to create a file for each and there is not enough metadata to reconstruct which branches belong to which events. Unfortunately, current file system do not have this many inodes and this setup would require extra metadata to combine TBranches into objects.

2.2.3 Overheads. We benchmark the write and read overhead of storing a ROOT file as:

(1) a large object in Ceph's object store (RADOS)
(2) a large object in RADOS with push-down logic (CLS)
(3) files in Ceph's file system (CephFS)

Setups 1 and 2 are deployed without any changes to the ROOT framework. For setup 3, TBaskets are stored in Ceph objects and the TBranch hierarchy, TStreamInfo metadata, and TLeaf metadata map onto the metadata server. Clients contact the metadata server with a TBranch request, receive back the TBranch hierarchy necessary to name the Ceph object containing the TBasket as well as the TStreamInfo and TLeaf metadata necessary to read the object.

The workload is a list of branch accesses from a trace of the NPTupleMaker high energy physics application. For setup 1, the ROOT file is pulled locally and the branch accesses are offset/length reads. For setup 2, the same offset/length reads are sent as filters to the OSDs; think of them as push-down predicates from the database world. Finally, for setup 3, the branch accesses are specified as full branch names (i.e. full path names), which are used to traverse the file system namespace. There was significant pre-processing to find full branch accesses but this runtime is not included in our benchmarking.

2.3 SIRIUS (HPC)

3 METHODOLOGY

Implied namespaces lazily generate file system subtrees. This reduces overheads for:

- namespaces overloaded with requests
- namespaces that are too large
- namespaces that ...

In this section, we show how clients and metadata servers communicate using the Pattern PLFS language and present our storage system that adapts to the wokload (Section 3.1)). Other destructive solutions include changing the storage system and altering the application.

3.1 Adapting to the Workload with Cudele

Cudele is a file system with programmable consistency and durability. Clients use an API to decouple existing subtrees from the global namespace; metadata operations from the other clients targeted at the decoupled subtree can be programmed to be blocked or marked as overwritable. With the decoupled subtree in hand, the client can do metadata operations locally. Upon completion, the client can merge the subtree back into the global namespace.

Cudele has the mechanisms for understanding the file system metadata language and adapting to the workload. Figure 5 shows how clients decouple the namespace with the

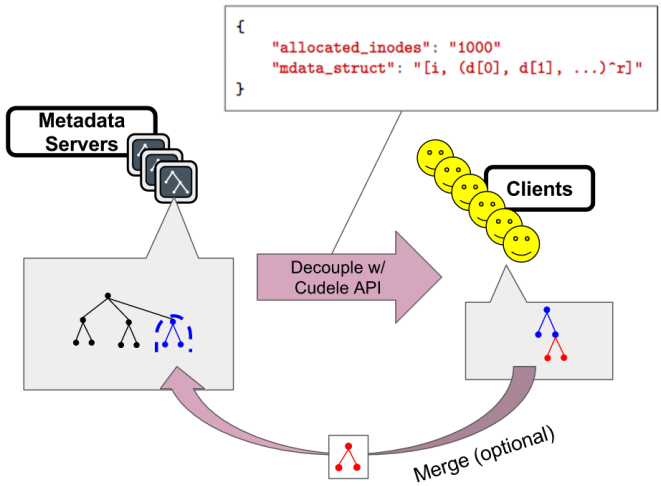

Figure 5: System XX lets clients optimize performance by telling the storage system about the workload. Clients can specify a Structured Namespace (blue subtrees and Section 3.1.1) or by merging file system metadata from an Unstructured Namespace (red subtree and Section 3.1.4).

Cudele API, specifying how many extra inodes they want and the structure for the namespace they intend to create. The metadata server and client both know about the metadata in the blue subtree, requiring no RPCs, and if the client creates more metadata (red subtree), it can merge it back into the global namespace. This model lets users enjoy the simplicity of global namespaces and the high performance of node-local operations. We extend the API to support the declaration of structured namespaces and leverage the existing API to merge unstructured namespaces.

3.1.1 Structured Namespaces. A structured namespace is created according to a pattern. If both the client and metadata server knows the pattern, they can create the metadata independently. This has two benefits: (1) it reduces RPCs which improves performance and reduces network traffic and (2) it allows the client and server to operate in parallel. The patterns that Cudele understands are shown in Listing 1 and the programmable interfaces are shown below. There are two parameters for unstructured namespaces: `pattern` and `trigger`.

3.1.2 Trigger: Start Namespace Construction. `trigger` specifies when to start the namespace construction on the metadata server. The metadata reconstruction can be asynchronous and saving this resource intense process for later can have better performance. To facilitate the exploration of different trigger policies, we make the value for the `trigger` parameter programmable. Administrators inject Lua code that specifies or calculates thresholds for when to start namespace construction. Although we make this programmable, we do not make any conclusions about the best trigger time and leave the exploration of this space as future work.

In Listing 1, the trigger is:

```
{
  if MDSs[whoami]["cpu"] > 30
}
```

which means that construction of the namespace will start if current MDS (`whoami`) has a CPU utilization (``cpu"`) above 30%.

Triggering construction asynchronously can improve performance because the process can be deferred until the system has less load. However, this performance gain comes at the cost of consistency. Even if the construction is triggered immediately, the metadata is eventually consistent; other clients see outdated metadata because the namespace is sitting on the client. Delaying the trigger improves the liklihood that system finds a window of low load but also increases the latency of other clients.

Implementation: we re-use the polling and embedded Lua virtual machine in Mantle [5] to implement the trigger interface. By default, every 10 seconds the metadata server checks if the condition for triggering is satisfied by executing the Lua code. Mantle has variables exposed for administrators to explore load balancing policies; just like this work, some of these policies need to identify overloaded metadata servers so we re-use all those variables. Some of the more useful variables include:

- Memory Usage
- CPU Utilization
- Request Rate
- Queue Depth
- Server Tags: whoami, i

3.1.3 Pattern: Express Namespace. `pattern` describes the metadata layout of the Structured Namespaces. It is the same language used in [4]. When the metadata server starts a namespace construction, it creates all the file system metadata generated by this formula. As a refresher, the pattern in Listing 1:

$$[i, (d[0], d[1], ...)^r]$$

means that there are r entries in the PLFS index file, where the first entry has a physical offset of i and lengths of d, where the pattern in d repeats.

Implementation: Another big fat TODO.

3.1.4 Unstructured Namespaces.

3.1.5 Migrating Metadata Construction.

```
{
  <!-- Structured Namespace Pattern !-->
  "S_pattern": "[i, (d[0], d[1], ...)^r]",

  <!-- Structured Namespace Trigger !-->
  "S_trigger": "if MDSs[whoami]["cpu"] > 30",

  <!-- Untructured Namespace Allocated Inos !-->
  "US_alloci": "1000",
}
```

Listing 1: Using the Cudele API to express metadata structure, which is understood by both the server and client.

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