

Chem 195: Problem Set 9

Michael Stephen Chen

April 6, 2016

Problem 1

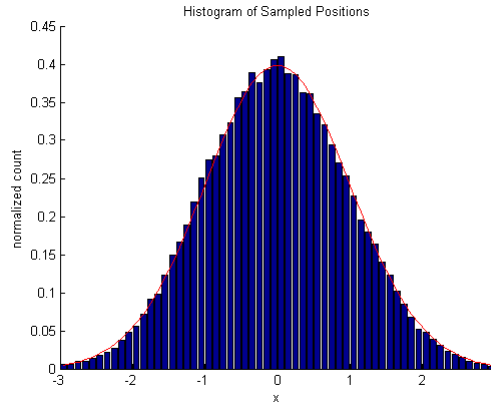
See *ho_metro.m* for my comments

Problem 2

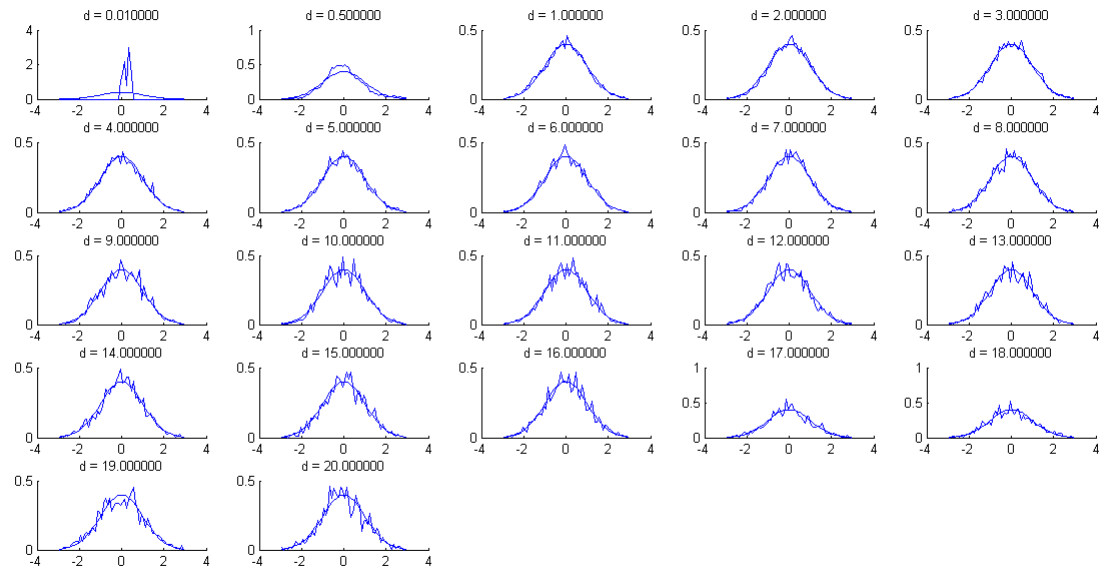
- i. A low f_{acc} means that the simulation is only accepting a small fraction of attempted moves, and is wasting runtime generating unaccepted samples; it takes a lot more samples for the simulation to move away from the initial state.

On the otherhand a f_{acc} approaching 1 is accepting just about all attempted moves. However this is also problematic because this is usually the result of our step size being too small, and consequently the state doesn't change much per step.

- ii. A histogram of my oscillator simulation for step $d = 1$ is presented below. The simulation was run for 10,000 steps. The fraction $f_{acc} = 0.9038$.



- iii. Below are the plots of our histograms for all of our trials. I decided to use a line plot as opposed to the traditional bar plots for histograms as I thought it would be easier to view. All of the simulations were run for 100,000 steps.

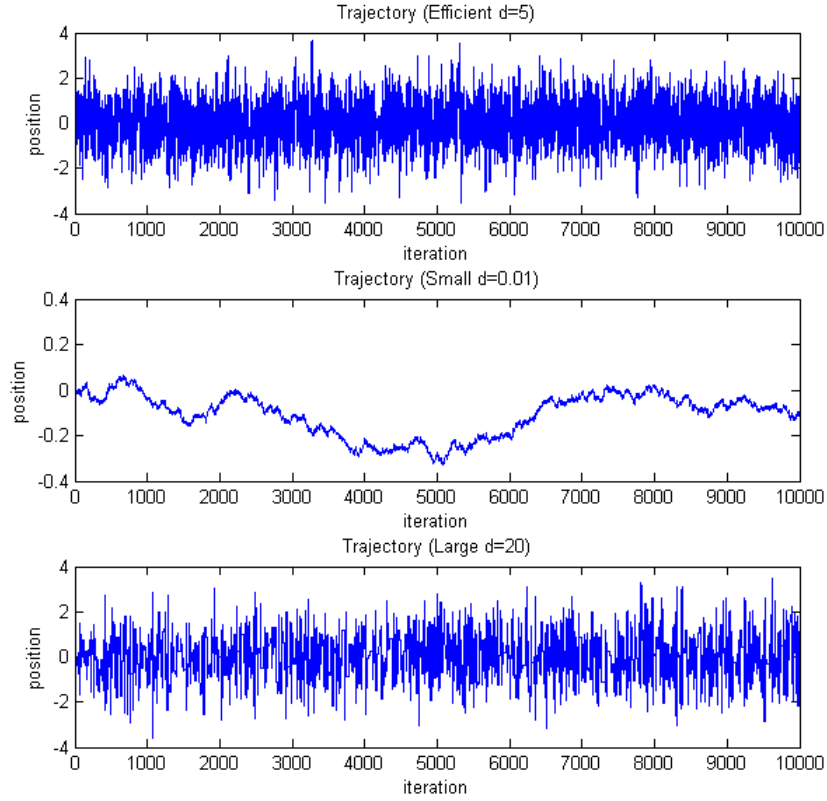


The table below displays the f_{acc} values for each step d

d	f_{acc}
0.01	0.9998
0.50	0.9582
1.00	0.9047
2.00	0.8151
3.00	0.7127
4.00	0.6349
5.00	0.5580
6.00	0.4975
7.00	0.4409
8.00	0.3880
9.00	0.3455
10.00	0.3226
11.00	0.2911
12.00	0.2607
13.00	0.2472
14.00	0.2307
15.00	0.2065
16.00	0.2046
17.00	0.1923
18.00	0.1748
19.00	0.1714
20.00	0.1579

iv. In part (i) we noted that f_{acc} close to 0 or 1 would result in low efficiency. Extrapolating, we assume that f_{acc} around 0.5 would result in the most efficient sampling for our simulation. From the results in part (iii), we see that ranges of $4 \leq d \leq 8$ appear to offer high sampling efficiency with $f_{acc} \approx 0.5$ and a histogram that qualitatively looks like what we would ideally expect.

v. The plots below depict the trajectories for a few MC simulations with different step size d :



Problem 3

- i. Generally, the autocorrelation function for time series results is given by:

$$C(X(m), X(m+n)) \propto \text{Cov}(X(m), X(m+n)) \quad (1)$$

$$= E[(X(m) - E[X(m)])(X(m+n) - E[X(m+n)])] \quad (2)$$

$$= E[X(m)X(m+n)] - E[X(m)]E[X(m+n)] \quad (3)$$

Since we are sampling from an equilibrium distribution, we can assume translational invariance (on average) with respect to time

$$E[X(m)] = E[X(m+n)] = E[X]$$

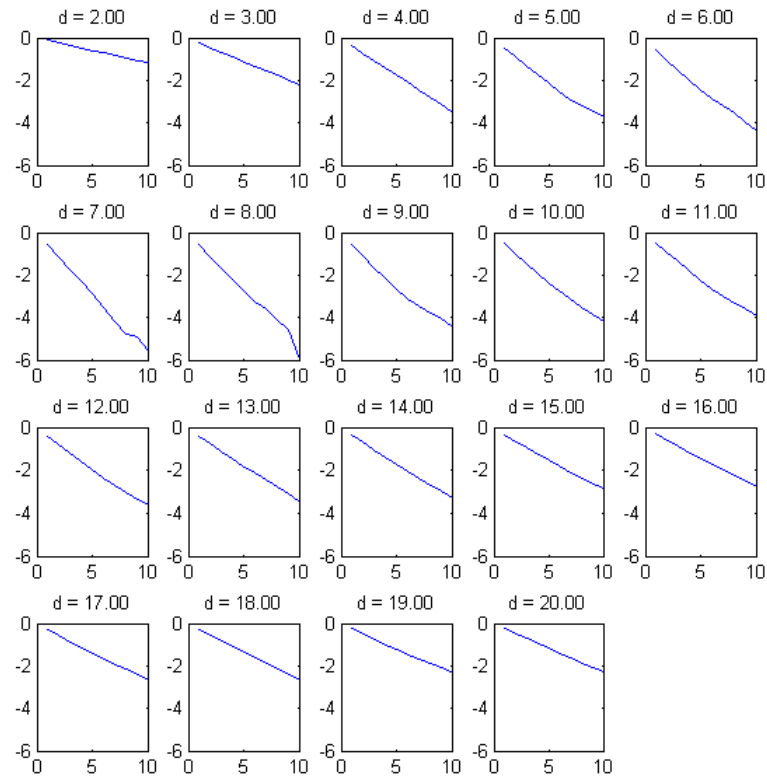
$$E[X(m)X(m+n)] = E[X((m+i))X((m+i)+n)] = E[X(0)X(n)]$$

So we can simplify the correlation function to be solely a function of the separation n .

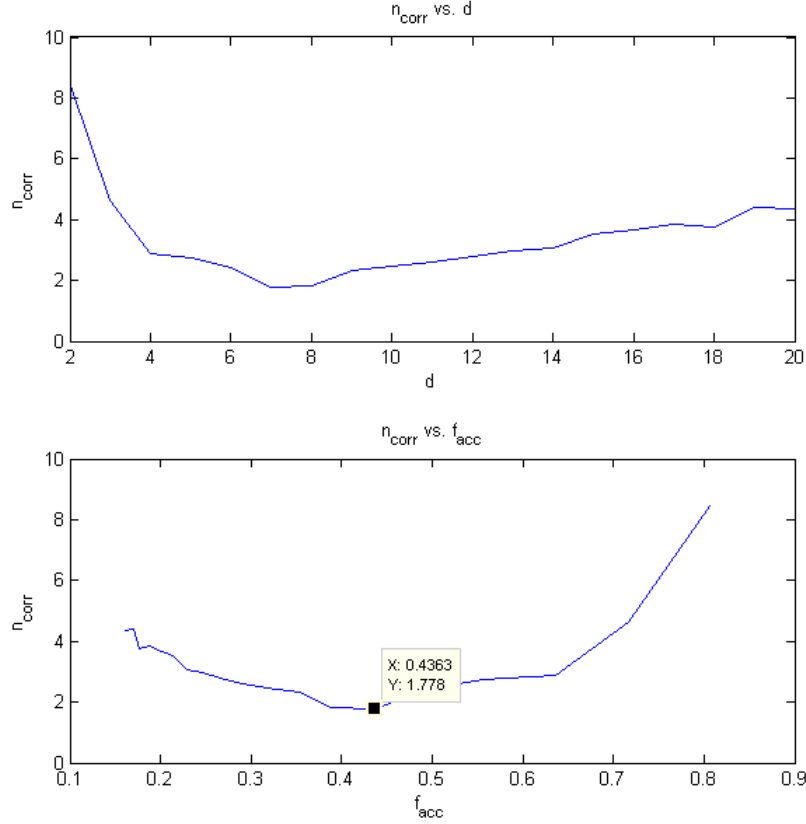
$$\text{Cov}(n) = E[X(0)X(n)] - E[X]^2$$

In our case $E[X] = 0$ given that our potential energy function bottoms out at $x = 0$.

- ii. Below are our results of $\ln|C(n)|$ as a function of $0 \leq n \leq 10$ for various step sizes d . Each simulation was run with 100,000 steps



- iii. Using MATLAB's `polyfit` function with a degree of 1, we fit a line to our results from the previous part. With the slope k , we can calculate an estimate for $n_{corr} = 1/k$. The plots below display our results for n_{corr} as a function of d and f_{acc} , respectively



- iv. From part(iii) we see that $0.35 \leq f_{\text{acc}} \leq 0.5$, corresponding to $6 \leq d \leq 9$, appears to produce the lowest n_{corr} . A lower n_{corr} means a higher efficiency because there are fewer steps on average needed to obtain a statistically independent sample. In problem 2, we assumed that $f_{\text{acc}} \approx 0.5$, $d = 6$, would make for the most efficient sampling. Now quantitatively, we see that our estimate is slightly off; from part (iii) $f_{\text{acc}} = 0.4363$, $d = 7$, would be most efficient for our simulation with an average $n_{\text{corr}} = 1.778$.

Problem 4

- i. At equilibrium, we want to satisfy the “detailed balance” condition for the Boltzmann distribution.

$$\frac{\text{acc}(v \rightarrow v')}{\text{acc}(v' \rightarrow v)} = \frac{P(v')}{P(v)} = \exp[-\beta(U(v') - U(v))]$$

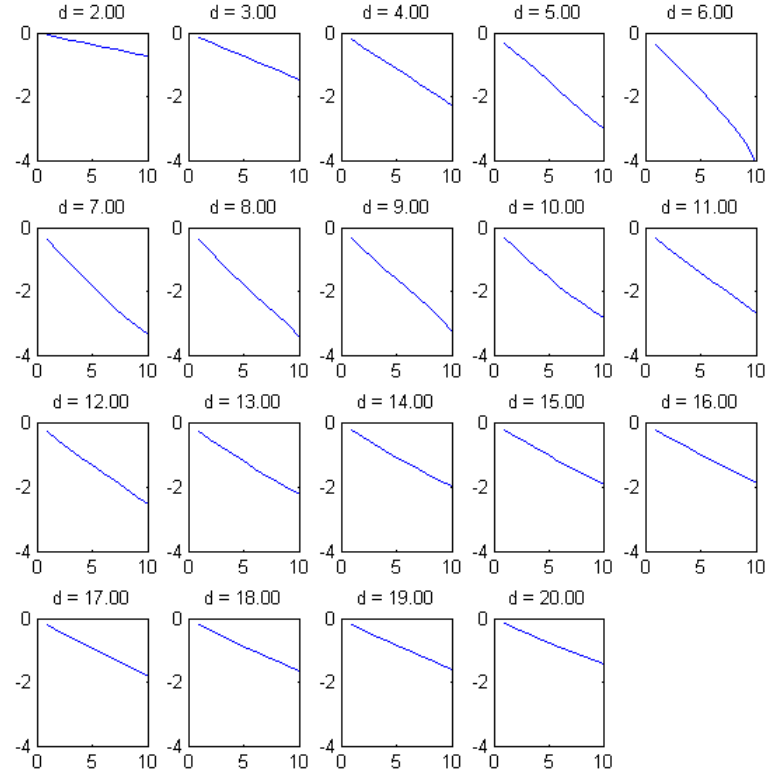
From the following we, see that the Glauber criterion does indeed satisfy this condition:

$$\frac{\text{acc}(v \rightarrow v')}{\text{acc}(v' \rightarrow v)} = \frac{\exp[-\beta U(v')] / \exp[-\beta U(v')] + \exp[-\beta U(v)]}{\exp[-\beta U(v)] / \exp[-\beta U(v')] + \exp[-\beta U(v)]} \quad (4)$$

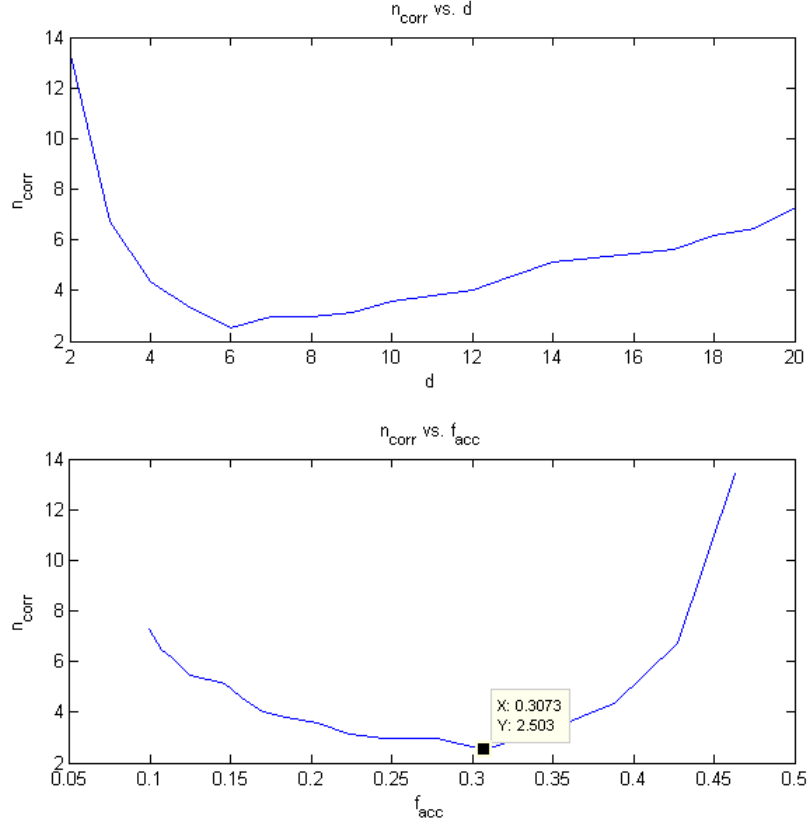
$$= \frac{\exp[-\beta U(v')]}{\exp[-\beta U(v)]} \quad (5)$$

$$= \exp[-\beta(U(v') - U(v))] \quad (6)$$

- ii. Like in problem 3, plots of $\ln|C(n)|$ as functions of n were generated. Each simulation was run for 100,000 steps.



From the slopes of the lines above, we found $n_{corr} = 1/k$ for different values of d , with their respective f_{acc} . Our results are depicted below:



From our results we see that the $f_{acc} = 0.3073$, $d = 6$, provides the best efficiency with an average $n_{corr} = 2.503$.

- iii. If we measure efficiency based on n_{corr} , which is our estimate of the average number of simulation steps to obtain one independent sample, we find that using the Metropolis criterion (min of $n_{corr} = 1.778$ for $d = 7$) is more efficient than the Glauber acceptance rule (min of $n_{corr} = 2.503$ for $d = 6$).