

Chapter 8

Heaps

Data Structures and Algorithms

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Heaps

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Heap Definition

Heap Structure

Basic Heap Algorithms

ReheapUp

ReheapDown

Heap Data Structure

Heap Algorithms

ReheapUp

ReheapDown

Build a Heap

Insert a Node

Delete a Node

Heap Applications

Selection Algorithms

Priority Queues

- **L.O.4.1** - List some applications of Heap.
- **L.O.4.2** - Depict heap structure and relate it to array.
- **L.O.4.3** - List necessary methods supplied for heap structure, and describe them using pseudocode.
- **L.O.4.4** - Depict the working steps of methods that maintain the characteristics of heap structure for the cases of adding/removing elements to/from heap.



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- **L.O.4.5** - Implement heap using C/C++.
- **L.O.4.6** - Analyze the complexity and develop experiment (program) to evaluate methods supplied for heap structures.
- **L.O.8.4** - Develop recursive implementations for methods supplied for the following structures: list, tree, heap, searching, and graphs.
- **L.O.1.2** - Analyze algorithms and use Big-O notation to characterize the computational complexity of algorithms composed by using the following control structures: sequence, branching, and iteration (not recursion).



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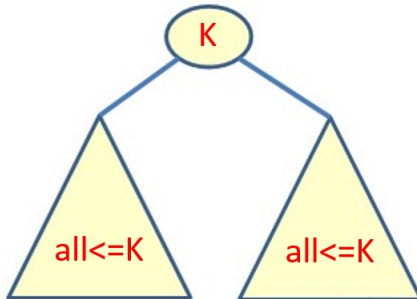
Priority Queues

Heap Definition

Definition

A **heap** (max-heap) is a binary tree structure with the following properties:

- 1 The tree is complete or nearly complete.
- 2 The key value of each node is **greater than or equal to** the key value in each of its descendents.



(Source: Data Structures - A Pseudocode Approach with C++)



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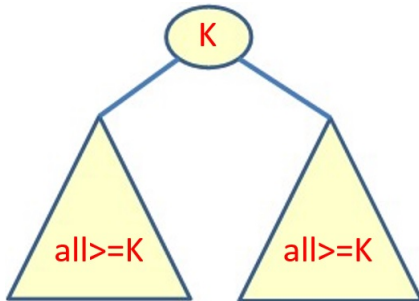
Priority Queues



Definition

A **min-heap** is a binary tree structure with the following properties:

- 1 The tree is complete or nearly complete.
- 2 The key value of each node is less than or equal to the key value in each of its descendents.



(Source: Data Structures - A Pseudocode Approach with C++)

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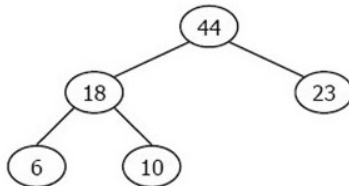
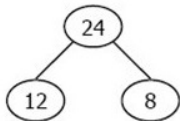
Selection Algorithms

Priority Queues

Heap Structure



Heap trees



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Heap Data Structure

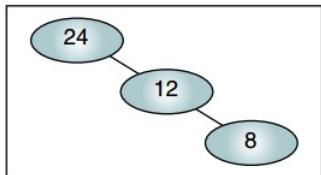
Heap Algorithms

- ReheapUp
- ReheapDown
- Build a Heap
- Insert a Node
- Delete a Node

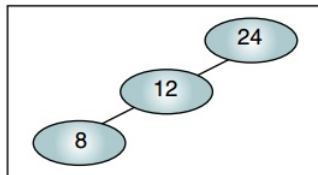
Heap Applications

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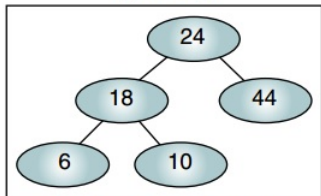
Invalid Heaps



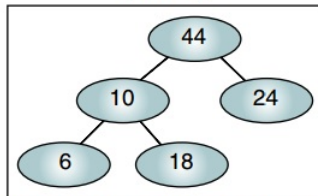
**(a) Not nearly complete
(rule 1)**



**(b) Not nearly complete
(rule 1)**



**(c) Root not largest
(rule 2)**



**(d) Subtree 10 not a heap
(rule 2)**

(Source: Data Structures - A Pseudocode Approach with C++)





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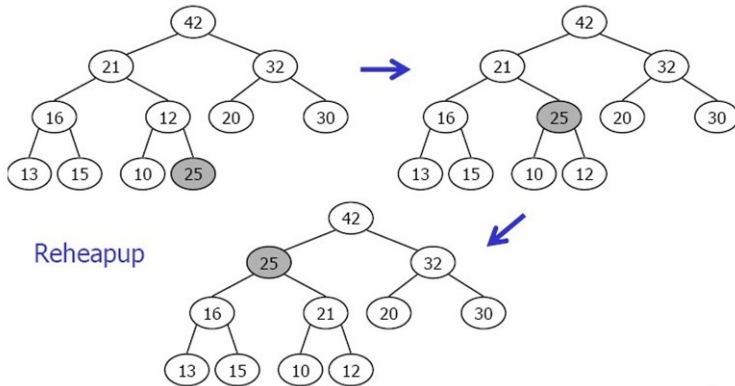
Selection Algorithms

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Basic Heap Algorithms

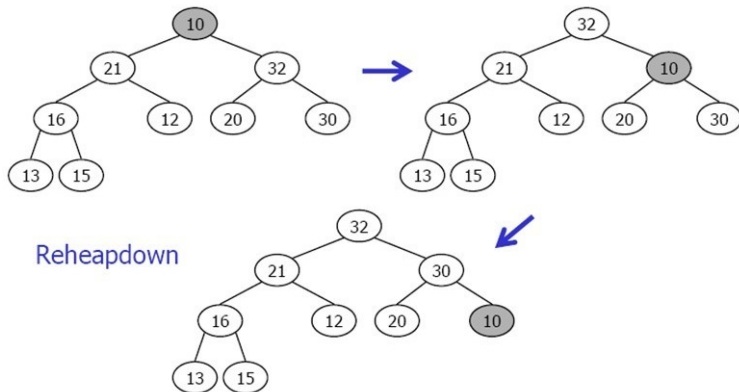
ReheapUp

The **reheapUp** operation repairs a "broken" heap by **floating the last element up** the tree until it is in its correct location in the heap.



ReheapDown

The **reheapDown** operation repairs a "broken" heap by **pushing the root down** the tree until it is in its correct location in the heap.





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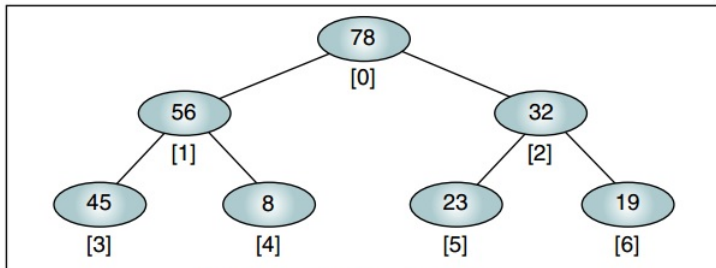
Properties of Heaps

- A complete or nearly complete binary tree.
- If the height is h , the number of nodes N is between 2^{h-1} and $2^h - 1$.
- **Complete tree**: $N = 2^h - 1$ when last level is full.
- **Nearly complete**: All nodes in the last level are on the left.

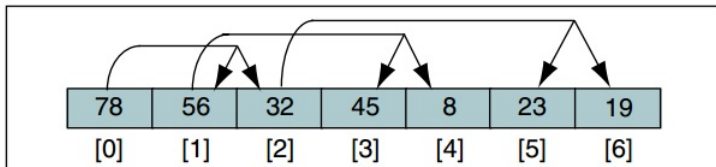
→ **Heap can be represented in an array.**



Heap in arrays



(a) Heap in its logical form



(b) Heap in an array

(Source: Data Structures - A Pseudocode Approach with C++)



Heap Data Structure

The relationship between a node and its children is fixed and can be calculated:

- ① For a node located at index i , its children are found at
 - Left child: $2i + 1$
 - Right child: $2i + 2$
- ② The parent of a node located at index i is located at $\lfloor (i - 1) / 2 \rfloor$.
- ③ Given the index for a left child, j , its right sibling, if any, is found at $j + 1$. Conversely, given the index for a right child, k , its left sibling, which must exist, is found at $k - 1$.
- ④ Given the size, N , of a complete heap, the location of the first leaf is $\lfloor N/2 \rfloor$.
- ⑤ Given the location of the first leaf element, the location of the last nonleaf element is 1 less.



Heap Algorithms

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Algorithm reheapUp(ref heap <array>, val position <integer>)

Reestablishes heap by moving data in position up to its correct location.

Pre: All data in the heap above this position satisfy key value order of a heap, except the data in position

Post: Data in position has been moved up to its correct location.



ReheapUp Algorithm

```
if position > 0 then  
    |  
    parent = (position-1)/2  
    if heap[position].key > heap[parent].key  
    then  
        |  
        swap(position, parent)  
        reheapUp(heap, parent)  
    end  
end  
return  
End reheapUp
```



ReheapDown Algorithm

Algorithm reheapDown(ref heap <array>, val position <integer>, val lastPosition <integer>)

Reestablishes heap by moving data in position down to its correct location.

Pre: All data in the subtree of position satisfy key value order of a heap, except the data in position
lastPosition is an index to the last element in heap

Post: Data in position has been moved down to its correct location.



ReheapDown Algorithm

```
leftChild = position * 2 + 1
rightChild = position * 2 + 2
if leftChild <= lastPosition then
    if (rightChild <= lastPosition) AND
        (heap[rightChild].key > heap[leftChild].key) then
        | largeChild = rightChild
    else
        | largeChild = leftChild
    end
    if heap[largeChild].key > heap[position].key then
        | swap(largeChild, position)
        | reheapDown(heap, largeChild, lastPosition)
    end
end
return
End reheapDown
```



Build a Heap

- Given a filled array of elements in random order, to build the heap we need to rearrange the data so that each node in the heap is greater than its children.
- We begin by dividing the array into two parts, the left being a heap and the right being data to be inserted into the heap. Note the "wall" between the first and second parts.
- At the beginning the root (the first node) is the only node in the heap and the rest of the array are data to be inserted.
- Each iteration of the insertion algorithm uses reheap up to insert the next element into the heap and moves the wall separating the elements one position to the right.



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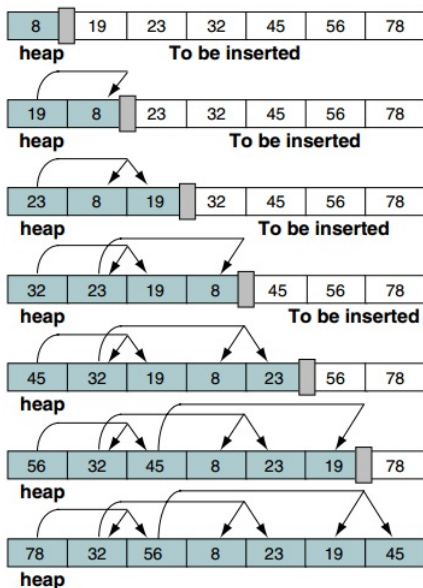
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Build a Heap



(Source: Data Structures - A Pseudocode Approach with C++)



Build a Heap

Algorithm buildHeap(ref heap <array>, val size <integer>)

Given an array, rearrange data so that they form a heap.

Pre: heap is array containing data in nonheap order
size is number of elements in array

Post: array is now a heap.

walker = 1

```
while walker < size do  
    | reheapUp(heap, walker)  
    | walker = walker + 1  
end  
End buildHeap
```

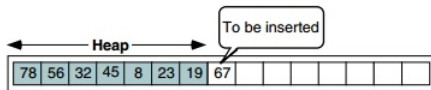
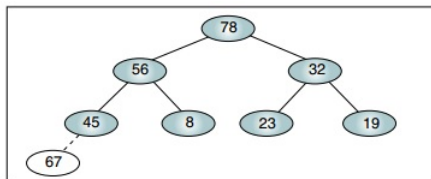


Insert a Node into a Heap

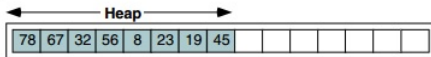
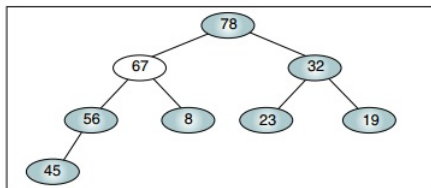
- To insert a node, we need to locate the first empty leaf in the array.
- We find it immediately after the last node in the tree, which is given as a parameter.
- To insert a node, we move the new data to the first empty leaf and reheap up.



Insert a Node into a Heap



(a) Before reheap up



(b) After reheap up

(Source: Data Structures - A Pseudocode Approach with C++)



Insert a Node into a Heap

Algorithm insertHeap(ref heap <array>, ref last <integer>, val data <dataType>)
Inserts data into heap.

Pre: heap is a valid heap structure
last is reference parameter to last node in heap
data contains data to be inserted

Post: data have been inserted into heap.

Return true if successful; false if array full



Insert a Node into a Heap

```
if heap full then
    | return false
end
last = last + 1
heap[last] = data
reheapUp(heap, last)
return true
End insertHeap
```

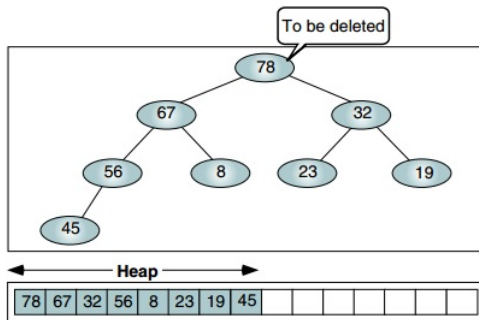


Delete a Node from a Heap

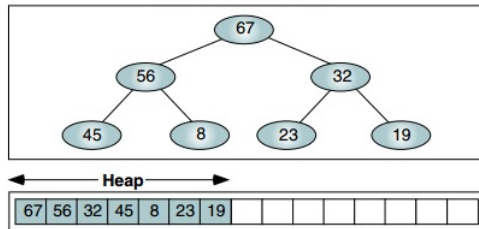
- When deleting a node from a heap, the most common and meaningful logic is to delete the root.
- After it has been deleted, the heap is thus left without a root.
- To reestablish the heap, we move the data in the last heap node to the root and reheap down.



Delete a Node from a Heap



(a) Before delete



(b) After delete

(Source: Data Structures - A Pseudocode Approach with C++)



Delete a Node from a Heap

Algorithm deleteHeap(ref heap <array>, ref last <integer>, ref dataOut <dataType>)

Deletes root of heap and passes data back to caller.

Pre: heap is a valid heap structure

last is reference parameter to last node

dataOut is reference parameter for output data

Post: root deleted and heap rebuilt

root data placed in dataOut

Return true if successful; false if array empty



Delete a Node from a Heap

```
if heap empty then
    | return false
end
dataOut = heap[0]
heap[0] = heap[last]
last = last - 1
reheapDown(heap, 0, last)
return true
End deleteHeap
```



Complexity of Binary Heap Operations

- ReheapUp: $O(\log_2 n)$
- ReheapDown: $O(\log_2 n)$
- Build a Heap: $O(n \log_2 n)$
- Insert a Node into a Heap: $O(\log_2 n)$
- Delete a Node from a Heap: $O(\log_2 n)$



Heap Applications



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Three common applications of heaps are:

- ① selection algorithms,
- ② priority queues,
- ③ and sorting.

We discuss heap sorting in Chapter 10 and selection algorithms and priority queues here.



Selection Algorithms

Problem

Determining the k^{th} element in an unsorted list.

Two solutions:

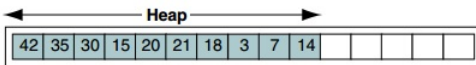
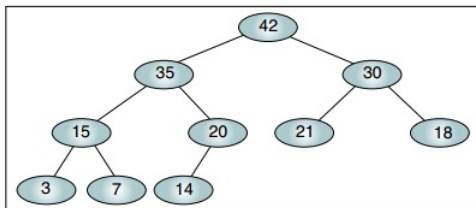
- ① Sort the list and select the element at location k . The complexity of a simple sorting algorithm is $O(n^2)$.
- ② Create a heap and delete $k - 1$ elements from the heap, leaving the desired element at the top. The complexity is $O(n \log_2 n)$.

Rather than simply discarding the elements at the top of the heap, a better solution would be to place the deleted element at the end of the heap and reduce the heap size by 1.

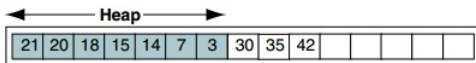
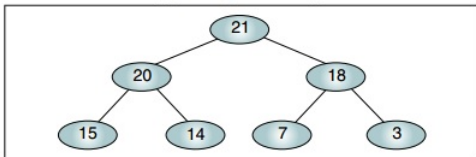
After the k^{th} element has been processed, the temporarily removed elements can then be inserted into the heap.



Selection Algorithms



(a) Original heap



(b) After three deletions

(Source: Data Structures - A Pseudocode Approach with C++)



Algorithm selectK(ref heap <array>, ref k
<integer>, ref last <integer>)

Select the k-th largest element from a list.

Pre: heap is an array implementation of a heap
k is the ordinal of the element desired
last is reference parameter to last element

Post: k-th largest value returned



Selection Algorithms

if $k > \text{last} + 1$ **then**

 | return 0

end

$i = 1$

$\text{originalSize} = \text{last} + 1$

while $i < k$ **do**

 | $\text{temp} = \text{heap}[0]$

 | $\text{deleteHeap}(\text{heap}, \text{last}, \text{dataOut})$

 | $\text{heap}[\text{last} + 1] = \text{temp}$

 | $i = i + 1$

end



Selection Algorithms

// Desired element is now at top of heap

holdOut = heap[0]

// Reconstruct heap

while *last* < *originalSize* **do**

last = *last* + 1
 reheapUp(heap, *last*)

end

return holdOut

End selectK



Priority Queues

The heap is an excellent structure to use for a **priority queue**.

Example

Assume that we have a priority queue with three priorities: **high (3), medium (2), and low (1)**.

Of the first five customers who arrive, the second and the fifth are high-priority customers, the third is medium priority, and the first and the fourth are low priority.

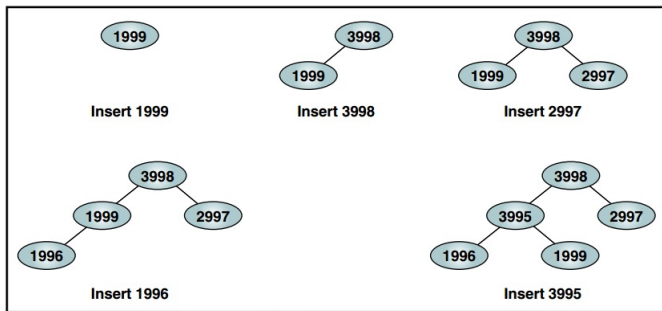
Arrival	Priority	Priority
1	low	1999 (1 & (1000 - 1))
2	high	3998 (3 & (1000 - 2))
3	medium	2997 (2 & (1000 - 3))
4	low	1996 (1 & (1000 - 4))
5	high	3995 (3 & (1000 - 5))

(Source: Data Structures - A Pseudocode Approach with C++)



Priority Queues

The customers are served according to their priority and within equal priorities, according to their arrival. Thus we see that **customer 2 (3998)** is served first, followed by **customer 5 (3995)**, **customer 3 (2997)**, **customer 1 (1999)**, and **customer 4 (1996)**.

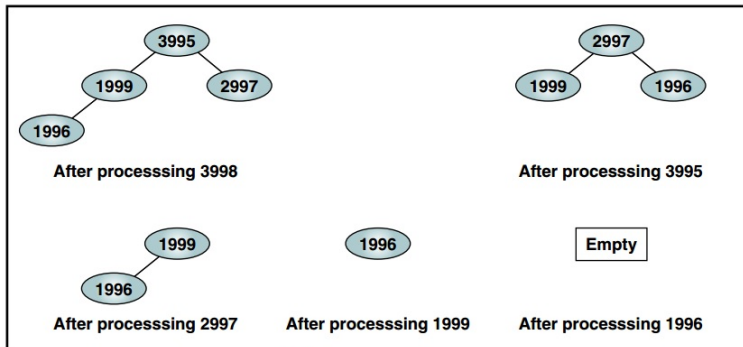


(a) Insert customers

(Source: Data Structures - A Pseudocode Approach with C++)



Priority Queues



(b) Process customers

(Source: Data Structures - A Pseudocode Approach with C++)

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