

```
function [F] = F_ip1lip1(m_ip1, vcdot_ip1lip1)
% This function summarizes the forces at the current link.
% Eqn. 6.49 in the textbook.
    arguments
        m_ip1
        vcdot_ip1lip1 (3,1)
    end

    F = m_ip1 .* vcdot_ip1lip1;

end
```