Computer Science M146, Homework 3

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Problem 1

The VC dimension of H is 3. An example of 3 points x such that $x \in R$ that can be shattered are $x_1 = -1$, $x_2 = 0$, and $x_3 = 1$. Then the following table shows how we can shatter these points, with $h \in H$ being the classifier used.

x_1 label	x_2 label	x_3 label	h
0	0	0	$\operatorname{sgn}(-1)$
0	0	1	sgn(x - 0.5)
0	1	0	$\operatorname{sgn}(-x^2 + 0.5)$
0	1	1	sgn(x+0.5)
1	0	0	sgn(-x - 0.5)
1	0	1	$sgn(x^2 - 0.5)$
1	1	0	sgn(-x+0.5)
1	1	1	sgn(1)

For any set $S = \{x_1, x_2, x_3, x_4\}$ of four points where $x_1 < x_2 < x_3 < x_4$, we cannot shatter S if we label $x_1 = 1$, $x_2 = 0$, $x_3 = 1$, $x_4 = 0$. This is because any classifier in H at most splits R into three distinct regions where the quadratic $ax^2 + bx + c$ is above or below zero, and we have 4 distinct regions of classification in our set. So our hypothesis space cannot shatter S because no h can correctly classify this training set.

Problem 2

$$K_{\beta}(\mathbf{x}, \mathbf{z}) = (1 + \beta \mathbf{x} \cdot \mathbf{z})^{3}$$

$$= (1 + \beta(x_{1}z_{1} + \dots + x_{D}z_{D}))^{3}$$

$$= 1 + 3\beta \sum_{i=1}^{D} x_{i}z_{i} + 3\beta^{2} \left(\sum_{i=1}^{D} x_{i}z_{i}\right)^{2} + \beta^{3} \left(\sum_{i=1}^{D} x_{i}z_{i}\right)^{3}$$

$$= 1 + 3\beta \sum_{i=1}^{D} x_{i}z_{i} + 3\beta^{2} \sum_{i,j=1}^{D} x_{i}z_{i}x_{j}z_{j} + \beta^{3} \sum_{i,j,k=1}^{D} x_{i}z_{i}x_{j}z_{j}x_{k}z_{k}$$

$$= \left\langle 1, \sqrt{3\beta}x_{i} \Big|_{i=1}^{D}, \sqrt{3\beta}x_{i}x_{j} \Big|_{i,j=1}^{D}, \beta^{\frac{3}{2}}x_{i}x_{j}x_{k} \Big|_{i,j,k=1}^{D} \right\rangle$$

$$\cdot \left\langle 1, \sqrt{3\beta}z_{i} \Big|_{i=1}^{D}, \sqrt{3\beta}z_{i}z_{j} \Big|_{i,j=1}^{D}, \beta^{\frac{3}{2}}z_{i}z_{j}z_{k} \Big|_{i,j,k=1}^{D} \right\rangle$$

Thus we have

$$\phi_{\beta}(\mathbf{x}) = \left\langle 1, \sqrt{3\beta} x_i \Big|_{i=1}^D, \sqrt{3\beta} x_i x_j \Big|_{i,j=1}^D, \beta^{\frac{3}{2}} x_i x_j x_k \Big|_{i,j,k=1}^D \right\rangle$$

The kernel $K(\mathbf{x}, \mathbf{z}) = (1 + \mathbf{x} \cdot \mathbf{z})^3$ is equivalent to setting $\beta = 1$, and corresponds to the feature map

$$\phi_1(\mathbf{x}) = \left\langle 1, \sqrt{3}x_i \Big|_{i=1}^D, \sqrt{3}x_i x_j \Big|_{i,j=1}^D, x_i x_j x_k \Big|_{i,j,k=1}^D \right\rangle$$

For D=2 this is

$$\phi_{\beta}(\mathbf{x}) = \left\langle 1, \sqrt{3\beta}x_1, \sqrt{3\beta}x_2, \sqrt{3}\beta x_1^2, \sqrt{3}\beta x_1 x_2, \sqrt{3}\beta x_2 x_1, \sqrt{3}\beta x_2^2, \right.$$

$$\beta^{\frac{3}{2}}x_1^3, \beta^{\frac{3}{2}}x_1^2 x_2, \beta^{\frac{3}{2}}x_1^2 x_2, \beta^{\frac{3}{2}}x_1 x_2^2, \beta^{\frac{3}{2}}x_1^2 x_2, \beta^{\frac{3}{2}}x_1 x_2^2, \beta^{\frac{3}{2}}x_1 x_2^2, \beta^{\frac{3}{2}}x_1 x_2^2, \beta^{\frac{3}{2}}x_1^2 \right\rangle$$

$$\phi_{1}(\mathbf{x}) = \left\langle 1, \sqrt{3}x_1, \sqrt{3}x_2, \sqrt{3}x_1^2, \sqrt{3}x_1 x_2, \sqrt{3}x_2 x_1, \sqrt{3}x_2^2, x_1^2 x_2, x_1^2 x_2, x_1^2 x_2, x_1^2 x_2, x_1^2 x_2^2, x_1^2 x$$

Note that we allow duplicate terms in order to have a nicer formula for the general case of any D. If we were to simplify K_{β} for D=2, we would get the feature maps

$$\phi_{\beta}(\mathbf{x}) = \left\langle 1, \sqrt{3\beta}x_1, \sqrt{3\beta}x_2, \sqrt{3}\beta x_1^2, \sqrt{6}\beta x_1 x_2, \sqrt{3}\beta x_2^2, \right.$$
$$\beta^{\frac{3}{2}} x_1^3, \sqrt{3}\beta^{\frac{3}{2}} x_1^2 x_2, \sqrt{3}\beta^{\frac{3}{2}} x_1 x_2^2, \beta^{\frac{3}{2}} x_2^3 \right\rangle$$
$$\phi_1(\mathbf{x}) = \left\langle 1, \sqrt{3}x_1, \sqrt{3}x_2, \sqrt{3}x_1^2, \sqrt{6}x_1 x_2, \sqrt{3}x_2^2, x_1^3, \sqrt{3}x_1^2 x_2, \sqrt{3}x_1 x_2^2, x_2^3 \right\rangle$$

The parameter β scales the features up and down by a constant. It effectively replaces the vector \mathbf{x} by $\sqrt{\beta}\mathbf{x}$ such that $\phi_{\beta}(\mathbf{x}) = \phi_1(\sqrt{\beta}\mathbf{x})$.

Problem 3

a) We wish to find $\mathbf{w}^* = \langle w_1, w_2 \rangle$ such that we minimize $\frac{1}{2}\sqrt{w_1^2 + w_2^2}$ subject to $w_1 + w_2 \ge 1$ and $-w_1 \ge 1$. Equivalently we would like to find the point closest to the origin such that $w_2 \ge 1 - w_1$ and $w_1 \le -1$. Thus we get

$$\mathbf{w}^* = \langle -1, 2 \rangle$$

and the margin is $\gamma = \frac{1}{\sqrt{5}}$.

b) We wish to find $\mathbf{w}^* = \langle w_1, w_2 \rangle$ such that we minimize $\frac{1}{2}\sqrt{w_1^2 + w_2^2}$ subject to $w_1 + w_2 + b \ge 1$ and $-w_1 - b \ge 1$. The classifier changes by making the decision boundary a horizontal line that crosses $(0, \frac{1}{2})$, and the margin will increase compared to our previous results. We get

$$\mathbf{w}^* = \langle 0, 2 \rangle$$

and

$$b^* = -1$$

Our margin is $\gamma = \frac{1}{2}$. This makes sense because our two points $\mathbf{x}_1 = (1, 1)$ and $\mathbf{x}_2 = (1, 0)$ have a distance of 1 between them, so our margin is exactly half of this distance. Our solution with offset has a higher margin γ and smaller magnitude of \mathbf{w}^* than our solution without offset.

Problem 4

4.1

a) I created the dictionary using the following code

b) I extracted the feature vectors using the following code

```
with open(infile, 'rU') as fid :
lineNum=0
for line in fid:
   wordListLine = extract_words(line)
   for word in wordListLine:
       feature_matrix[lineNum,word_list[word]]=1
   lineNum+=1
return feature_matrix
```

c) I split the features and labels into train and test sets using the following code

```
trainX = X[0:560]
trainy = y[0:560]
testX = X[560:630]
testy = y[560:630]
```

d) The feature matrix has the dimensions (630, 1811). The trainX set has dimensions (560, 1811), the trainy set has dimensions (560, 1), the testX set has dimensions (70, 1811), and the testy set has the dimensions (70, 1).

4.2

a) I implemented performance using the following code

```
score = 0
if metric=="accuracy":
    score=metrics.accuracy_score(y_true,y_label)
if metric=="f1-score":
    score=metrics.f1_score(y_true,y_label)
if metric=="auroc":
    score=metrics.roc_auc_score(y_true,y_pred)
return score
```

b) I implemented cv_performance using the following code

```
return cross_val_score(clf, X, y, scoring=metric, cv=kf).mean()
and in main I added
```

```
kf=StratifiedKFold(trainy, 5)
```

It is beneficial to use a stratified K-fold so that the percentage of positive and negative reviews are the same across folds because this ensures that our cross validation gets a good representation of our training data in each fold. Otherwise we may accidentally divide the folds such that one gets a small number of negative or positive reviews, making our classifier performance inaccurate.

c) I implemented select_param_linear with the following code

```
best=0
cBest=0
for c in C_range:
    score=cv_performance(SVC(kernel="linear",C=c),X,y,kf,metric)
    print "C="+str(c)+" score="+str(score)
    if score>best:
        best=score
        cBest=c
return cBest
```

d) My results were as follows

C	Accuracy	F1-score	AUROC
10^{-3}	0.7089	0.8297	0.8105
10^{-2}	0.7107	0.8306	0.8111
10^{-1}	0.8060	0.8755	0.8576
10^{0}	0.8146	0.8749	0.8712
10^{1}	0.8182	0.8766	0.8696
10^{2}	0.8182	0.8766	0.8696
- best C	10^{1}	10^{1}	10^{0}

4.3

a) I chose the hyperparameter c=10 and trained my classifier using the following code

```
clf=SVC(kernel="linear", C=10)
clf.fit(trainX, trainy)
```

b) I implemented performance_test using the following code

```
y_pred=clf.decision_function(X)
print "Performance test with metric "+str(metric)+":"
return performance(y, y_pred, metric)
```

c) My results were as follows

Metric	Score
Accuracy	0.7429
F1-score	0.4375
AUROC	0.7454