ECE102, Fall 2018

Homework #4

Signals & Systems

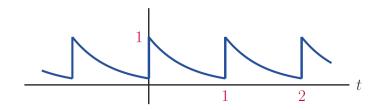
University of California, Los Angeles; Department of ECE

Prof. J.C. Kao TAs: H. Salami & S. Shahsavari

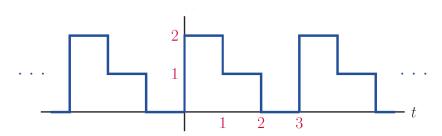
Due Thursday, 1 Nov 2018, by 11:59pm to Gradescope. Covers material up to Lecture 8. 100 points total.

1. (28 points) Fourier Series

- (a) (18 points) Find the Fourier series coefficients for each of the following periodic signals:
 - i. $f(t) = \cos(3\pi t) + \frac{1}{2}\sin(4\pi t)$
 - ii. f(t) is a periodic signal with period T = 1 s, where one period of the signal is defined as e^{-2t} for 0 < t < 1 s, as shown below.



iii. f(t) is the periodic signal shown below:



- (b) (10 points) Suppose you have two periodic signals x(t) and y(t), of periods T_1 and T_2 respectively. Let X_k and Y_k be the Fourier series coefficients of x(t) and y(t), respectively.
 - i. If $T_1 = T_2$, express the Fourier series coefficients of z(t) = x(t) + y(t) in terms of X_k and Y_k .
 - ii. If $T_1 = 2T_2$, express the Fourier series coefficients of w(t) = x(t) + y(t) in terms of X_k and Y_k .
- 2. (20 points) Fourier series of transformation of signals

Suppose that f(t) is a periodic signal with period T_0 , with the following Fourier series:

$$f(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$$

Determine the period of each of the following signals, then express its Fourier series coefficients in terms of c_k :

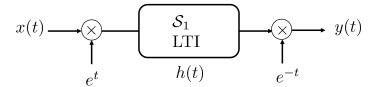
- (a) g(t) = f(t) + 1
- (b) g(t) = f(-t)
- (c) $g(t) = f(t t_0)$
- (d) g(t) = f(at), where a is positive real number

3. (10 points) Eigenfunctions and LTI systems

- (a) (5 points) Show that $f(t) = \cos(\omega_0 t)$ is not an eigenfunction of an LTI system.
- (b) (5 points) Show that f(t) = t is not an eigenfunction of an LTI system.

4. (29 points) LTI systems

Consider the following system:



The system takes as input x(t), it first multiplies the input with e^t , then sends it through an LTI system. The output of the LTI system gets multiplied by e^{-t} to form the output y(t).

(a) (3 points) Show that we can write y(t) as follows:

$$y(t) = \left[\left(e^t x(t) \right) * h(t) \right] e^{-t} \tag{1}$$

(b) (4 points) Use the definition of convolution to show that (1) can be equivalently written as:

$$y(t) = \int_{-\infty}^{\infty} h'(\tau)x(t-\tau)d\tau$$
 (2)

where h'(t) is a function to define in terms of h(t).

- (c) (12 points) Equation (2) represents a description of the equivalent system that maps x(t) to y(t). Show using (2) that the equivalent system is LTI and determine its impulse response $h_{eq}(t)$ in terms of h(t).
- (d) (10 points) Suppose that system S_1 is given by its step response s(t) = r(t-1). Find the impulse response h(t) of S_1 . What can you say about the causality and stability of system S_1 ? What can you say about the causality and stability of the overall equivalent system?

5. (13 points) MATLAB

You must submit all plots and code for each task to receive full credit

(a) (6 points) **Task 1**

Write an m-file that takes a set of Fourier series coefficients, a fundamental frequency, and a vector of output times, and computes the truncated Fourier series evaluated at these times. The declaration and help for the m-file might be:

```
function fn = myfs(Dn,omega0,t)

%
 fn = myfs(Dn,omega0,t)

% % Evaluates the truncated Fourier Series at times t

%
 Dn -- vector of Fourier series coefficients

%
 omega0 -- fundamental frequency

% t -- vector of times for evaluation

%

% fn -- truncated Fourier series evaluated at t
The output of the m-file should be
```

$$f_N(t) = \sum_{n=-N}^{N} D_n e^{j\omega_0 nt}$$

The length of the vector Dn should be 2N + 1. You will need to calculate N from the length of Dn.

(b) (7 points) **Task 2**

Verify the output of your routine by checking the Fourier series coefficients for the signal from Problem 1-a-ii. Try for N = 10, N = 50 and N = 100. Use the MATLAB subplot command to put multiple plots on a page.