# Micro Controller Unit and Motor Driver Board

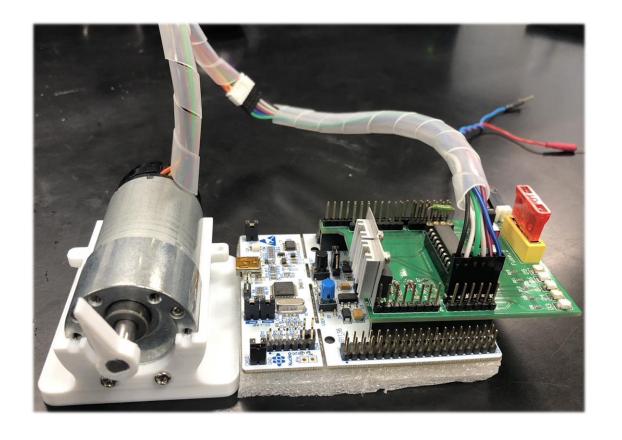
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日期:2023/09/20

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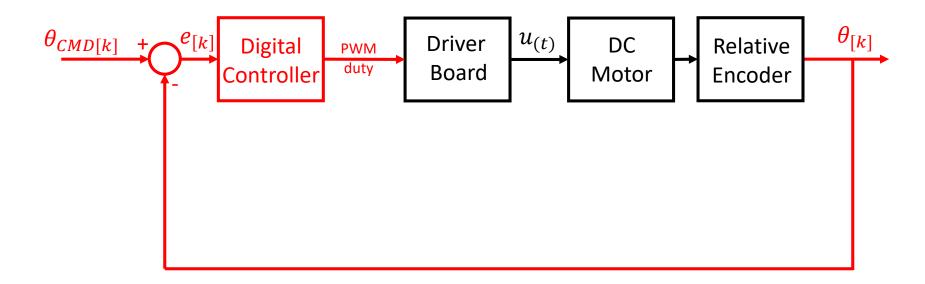
- 1. <u>MCU</u>
- 2. Motor Driver Board
- 3. Lab1 Check



## 1. MCU

- > Introduction
- > STM32 F446RE
- > Arm Keil Studio
- > Instruction

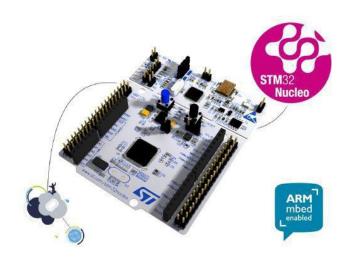
## 1-1. Introduction



The red part is the job that MCU does.

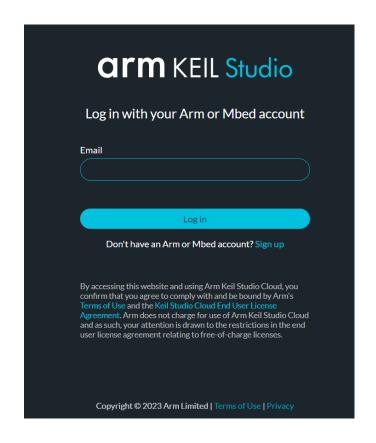
#### 1-2. STM32 F446RE

- ➤ MCU Tutorial: <u>Link</u> (主要使用Serial, Timer, Interrupt, PWM, Digital I/O)
- ➤ Spec: *Link*
- ➤ USB driver update: <u>Link</u>(若第一次燒錄程式失敗,可嘗試更新)



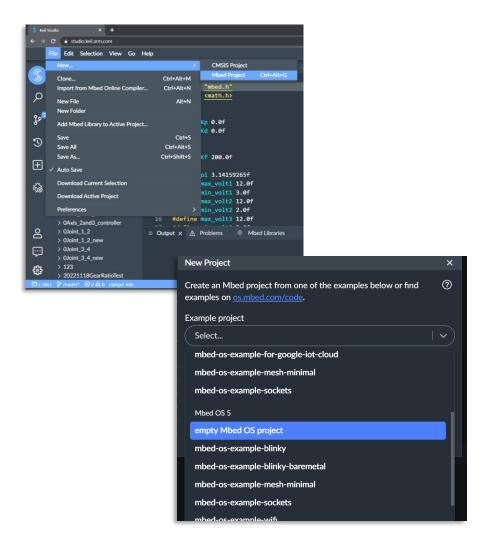
## 1-3. Arm Keil Studio

- ➤由ARM公司官方開發的線上開發環境
- ▶可用C/C++編寫程式
- ▶支援git版本管理
- ▶註冊帳號 (需等待5天審核,盡快申請)



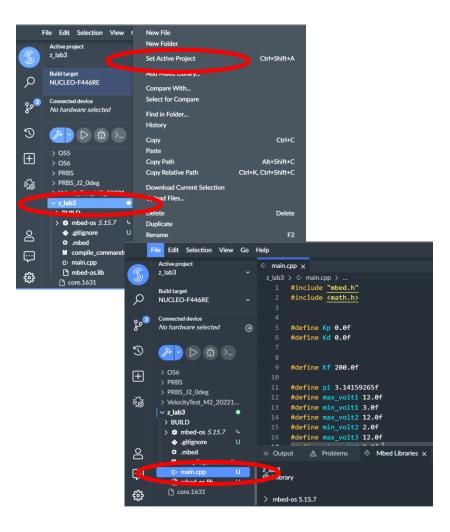
#### 1-4. Instruction

- 1. Sign in
- 2. Click
  - >>File
  - >>New
  - >>Mbed Project
- 3. Select...
  - >> (Mbed OS5) empty Mbed OS Project
- 4. Change the "Project name" as you want



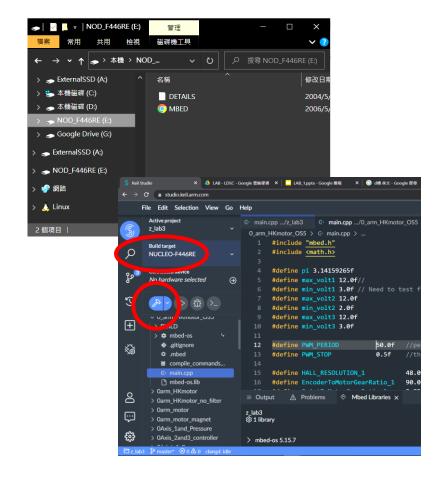
#### 1-4. Instruction

- 5. Right click on the project>Set Active Project
- 6. Click "main.cpp" in the project
- 7. Copy paste the given codes on ppt/elearn
- 8. Modify the code as required.



#### 1-4. Instruction

- 9. Connect ST with your PC>>NOD\_F446RE(E:) will show up
- 10. Turn back to Mbed
  - >>set Build target as NUCLEO-F446RE
    - >>click on the **hammer mark**
    - >>wait until it build completely
- 11. Put the .bin file into NOD\_F446RE(E:)
  - >>The .bin file will disappear.
  - >>The file is programmed into ST.



# 2. Motor Driver Board

- Material List
- Circuit Layout
- Description
- Reminders

## 2-1. Material List

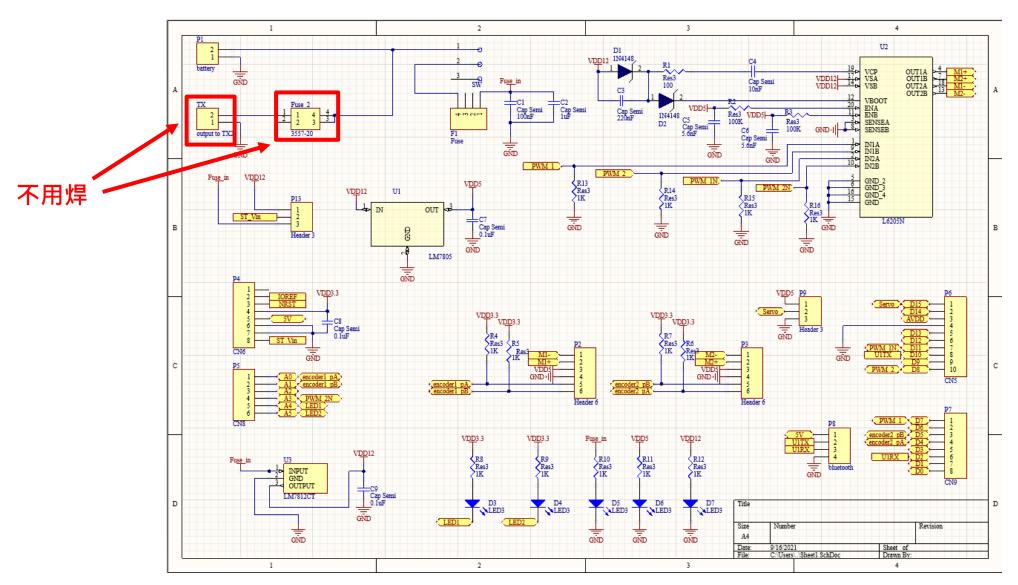
數位控制驅動套件					
名稱/別名	需要?個/套件				
電路板	1				
L6225N(數控用)	1				
20PIN IC插座	1				
LM7805CT 線性電壓穩壓器	1				
LM7812CT 線性電壓穩壓器	1				
保險絲座(4pin)	1				
251/253 Series 2A fuse	1				
一極體 1N4148	2				
2.54排針[兩端長(11mm)/25mm等長]	32				
2.54排針[一長9mm一短2mm/不等長(14.2mm)]	22				
SMD 0603電容 10nF	1				
SMD 0603電容 5.6nF	2				
SMD 0603電容 100nF	4				
SMD 0603電容 220nF	1				
SMD 0603電容 1uF	1				
SMD 0603電阻 100歐姆	1				
SMD 0603電阻 1k歐姆	13				
SMD 0603電阻 100k歐姆	2				
SMD 1210 LED	5				
電源pin (90度)	1				
開關	1				

(或L6205N)

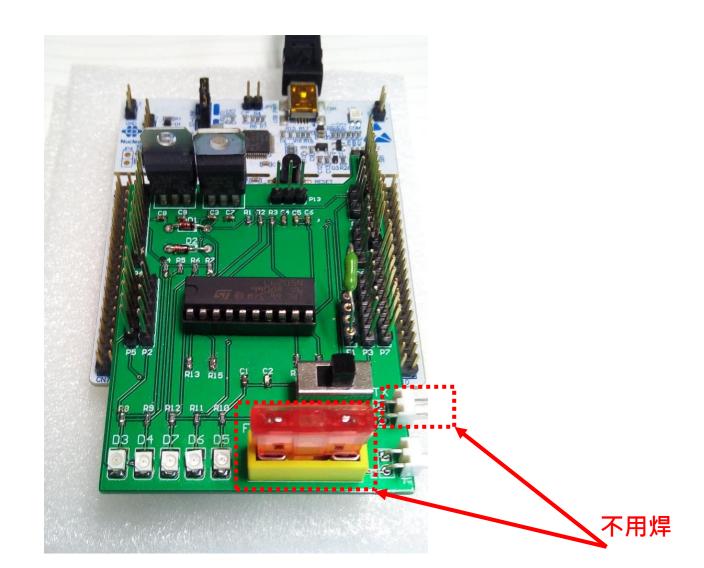


需自備一條USB A to mini B

## 2-2. Circuit Layout

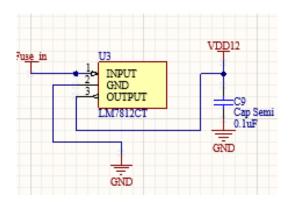


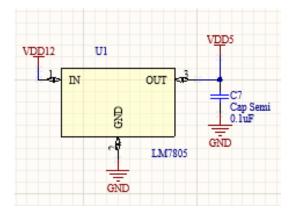
## 2-2. Circuit Layout



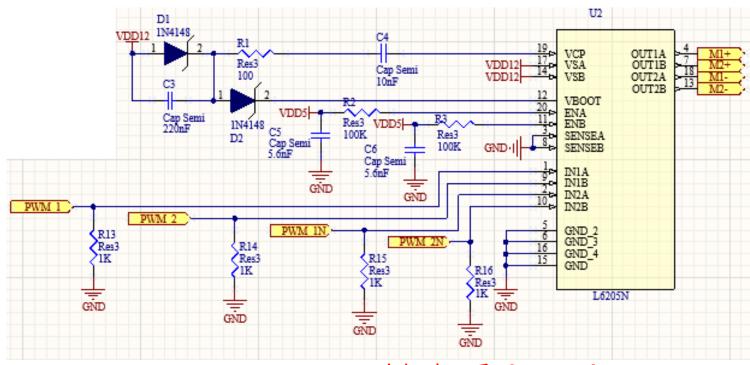
## 2-3. Description

• 穩壓/降壓元件





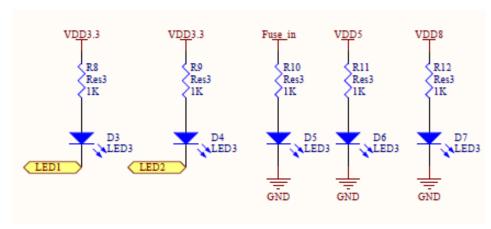
• 驅動器



請查看datasheet

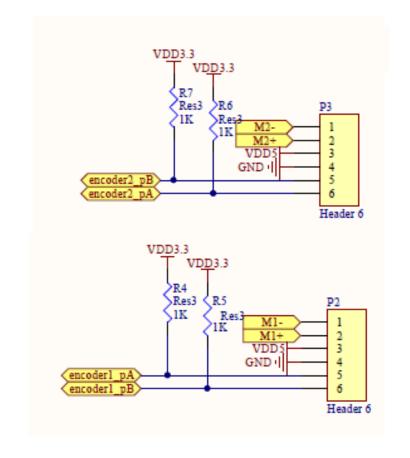
## 2-3. Description

• LED



這裡是pull up, 寫程式的時候要注意

#### • 連接馬達



## 2-4. Reminders

- 由低(貼片電容、電阻、LED)而高(排針座、IC等)
  - ▶ 貼片電容焊接參考: Link
  - ▶ 排針焊接參考: Link
- 邊焊邊檢查是否短路、假焊
- 請在針腳下墊絕緣物預防短路





## 3. Acceptance Check

- Deadline
- Soldering (Req1)
- Serial Communication (Req2)
- LED Control (Req3)

## Deadline

2023/10/25之前,至R503找助教驗收

## Soldering

• 先不要接上ST

• (Req1)接上電源(20V, 1A)後確認D5、D6、D7發亮



LM7812線性穩壓器的工作區間

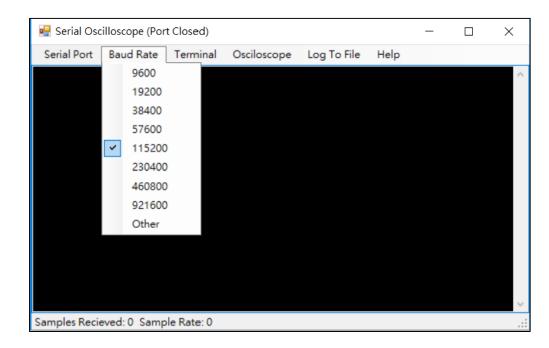
6.7 LM340 / LM7812 Electrical Characteristics,  $V_0 = 12 \text{ V}, V_1 = 19 \text{ V}$ 

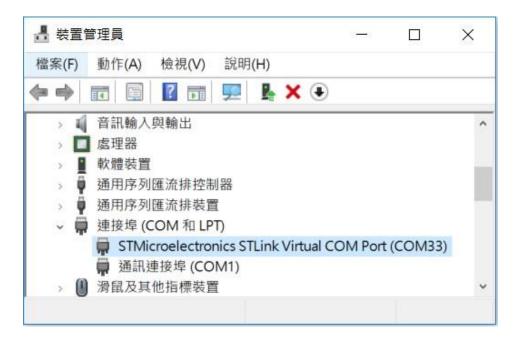
 $0^{\circ}\text{C} \le \text{T}_{\text{J}} \le 125^{\circ}\text{C}$  unless otherwise specified<sup>(1)</sup>

o o - 1j - 120 o amos outormos oposmos								
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
V <sub>O</sub> Output voltage		$T_J = 25^{\circ}C$ , 5 mA $\leq I_O \leq$ 1 A	11.5	12	12.5	V		
	$P_D \le 15 \text{ W}, 5 \text{ mA} \le I_O \le 1 \text{ A}$	11.4		12.6	<i>y</i>			
		$14.5 \text{ V} \leq \text{V}_{\text{IN}} \leq 27 \text{ V}$				•		

## **Serial Communication**

- Download Serial Oscilloscope: Link
- 接上STM32開發板,再至裝置管理員確認連接埠編號
- 開啟Serial Oscilloscope, 選取適當的serial port及baud rate
- 挖洞的程式請上elearn下載





## **Serial Communication**

- (Req2)按下鍵盤(例如按 'a'),在Scope印出程式運行了幾秒(如下圖)
- 會用到的函式:

serial.getc()

serial.readable()

```
Serial Oscilloscope (COM33, 115200) — 

Serial Port Baud Rate Terminal Osciloscope

UART OK

UART OK

This program runs since 5 seconds.

This program runs since 9 seconds.

This program runs since 12 seconds.

This program runs since 16 seconds.
```

## **LED Control**

- 練習使用Timer Interrupt, Memory
- (Req3)使驅動板上的LED持續閃爍:
  - ➤ D3 (亮0.5秒,暗0.5秒)
  - ➤ D4 (亮0.5秒,暗1.5秒)