

Education

KTH Royal Institute of Technology , Machine Learning	Sweden
• Thesis: AI for Networked Robotics	2023 – 2026
• Courses: Artificial Intelligence, Machine Learning, Deep Learning, Computer Vision, Robotics, Computer Graphics, Multi-Agent Systems, Statistical Methods	
University of Surrey , Computer Science	UK
• Thesis: RoboKinesis	2019 – 2023
• Controlling Robotic Arm with Computer Vision	
• Courses: Programming, Algorithms, Software and Web Engineering, Artificial Intelligence, Deep Learning, Natural Language Processing	

Experience

Computational Imaging and Vision Laboratory, National Institute of Informatics , Research Exchange Student	Japan
Temporal Motion Magnification	2025 – 2026
• Supervisor: Dr. Imari Sato	1 year
Ericsson Research , Master's Thesis Student	Sweden
Towards Adaptive Reinforcement Learning for Network-Aware Robotics via Quantization Techniques	2025 – 2025
• Supervisor: Dr. Christos N. Mavridis	1 year
Visualization Course, KTH Royal Institute of Technology , Teaching Assistant (Visualization course)	Sweden
	2024 – 2024
	1 year
Centre for Vision, Speech and Signal Processing, University of Surrey , Summer Research Internship Student	UK
• Supervisor: Dr. Oscar Mendez Maldonado	2023 – 2023
	1 year
Hawk-Eye Innovations , Machine Learning Engineer (Placement)	UK
	2022 – 2023
	1 year

Publications

Genetically Modified Wolf Optimization with Stochastic Gradient Descent for Optimising Deep Neural Networks
Novel optimization approach combining metaheuristic algorithms and SGD to balance exploration and exploitation for training Deep Neural Networks.
Manuel Bradicic, Michal Sitarz, Felix Sylvest Olesen
arxiv.org/abs/2301.08950

Skills

Programming Languages

ML/AI Frameworks

Tools & Infrastructure

3D/Simulation

Languages

Polish

Native speaker

English

Fluent

Serbo-Croatian

Fluent