

# Systemy Komputerowe w Sterowaniu i Pomiarach

## Laboratorium 2

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## Praca domowa

### Uruchomienie i skonfigurowanie OpenWRT dla maszyny wirtualnej i uruchomienie na qemu

#### Użyte komendy

```
wget https://downloads.openwrt.org/releases/22.03.5/targets/armvirt/64/openwrt-22.03.5-armvirt-64-Image
-O openwrt.Image

wget https://downloads.openwrt.org/releases/22.03.5/targets/armvirt/64/openwrt-22.03.5-rootfs-ext4.img.gz
-O openwrt-rootfs-ext4.img.gz

gzip -d openwrt-rootfs-ext4.img.gz

qemu-system-aarch64 -M virt -cpu cortex-a57 -nographic -smp 4 -kernel openwrt.Image
-append "root=/dev/vda console=ttyAMA0" -drive file=./openwrt-rootfs-ext4.img,if=none,format=raw,id=hd0
-device virtio-blk-device,drive=hd0

opkg update

opkg install python3
```

Pobranie najnowszej wersji maszyny z armvirt

Pobranie systemu ext4

Rozpakowanie systemu

Uruchomienie qemu na żądanych ustawieniach

Aktualizacja menedżera pakietów

Pobranie pythona 3

### Implementacja w języku Python oraz uruchomienie w OpenWRT / qemu dwóch programów generujących sygnał PWM

```
1 import sys
2
3 def pwm_with_alternating_frequencies(duty_cycle, frequency):
4     period = 1/frequency
5     on_time = (duty_cycle/100) * period
6     off_time = period - on_time
7     return (on_time, off_time)
8
9 duty_cycle = float(sys.argv[1])
10 for frequency_arg in sys.argv[2:]:
11     frequency = float(frequency_arg)
12     on_time, off_time = pwm_with_alternating_frequencies(duty_cycle, frequency)
13     print(f'Frequency: {frequency} Hz, duty cycle: {duty_cycle}, 1: {on_time:.4f} s, 0: {off_time:.4f} s')
```

Listing 1: Pwm ze zmiennymi częstotliwościami

```
1 import sys
2
3 def pwm_with_alternating_duty_cycles(duty_cycle, frequency):
4     period = 1/float(frequency)
5     on_time = (float(duty_cycle)/100) * period
6     off_time = period - on_time
7     return (on_time, off_time)
8
9 frequency = float(sys.argv[1])
10 for duty_cycle in sys.argv[2:]:
11     on_time, off_time = pwm_with_alternating_duty_cycles(duty_cycle, frequency)
12     print(f'Frequency: {frequency} Hz, duty cycle: {duty_cycle}%, 1: {on_time:.4f} s, 0: {off_time:.4f} s')
```

Listing 2: Pwm ze zmiennym wypełnieniem

## Komendy uruchamiające programy

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```
python3 pwm_with_alternating_frequencies.py 50 10 20 30
Frequency: 10.0 Hz, duty cycle: 50.0, 1: 0.0500 s, 0: 0.0500 s
Frequency: 20.0 Hz, duty cycle: 50.0, 1: 0.0250 s, 0: 0.0250 s
Frequency: 30.0 Hz, duty cycle: 50.0, 1: 0.0167 s, 0: 0.0167 s
python3 pwm_with_alternating_duty_cycles.py 10 25 50 75
Frequency: 10.0 Hz, duty cycle: 25%, 1: 0.0250 s, 0: 0.0750 s
Frequency: 10.0 Hz, duty cycle: 50%, 1: 0.0500 s, 0: 0.0500 s
Frequency: 10.0 Hz, duty cycle: 75%, 1: 0.0750 s, 0: 0.0250 s
```

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