

LVC 1 - Glossary of Notations

\mathcal{X} = A vector of categorical data

y = Outcome class (categorical)

$f: \mathcal{X} \rightarrow y$ = Decision Rule i.e. f is a function that is mapping the independent features with the target values

x_i = i^{th} row of the vector \mathcal{X}

y_i = i^{th} row of vector y

N = Natural number

\in = Belongs to

Σ = The summation

\neq = Not equal to

$R(f)$ = Empirical Error (generalization error) of a Decision Rule

$R^*(f)$ = Probabilistic Error of a Decision Rule

$\frac{1}{N} \sum_i^N I(f(x_i) \neq y_i)$ = The average number of misclassifications. The $I()$ function is 1 in case

of a misclassification and 0 otherwise

C = It is a sub class that maps with a function f to predict the y along with probability maximization

k = subset of all feature indices in the sub class

Z = Random Variable

$X, Y = X, \text{and } Y$ are the random variables

$P(Z) = Z$ is a random variable with the probability mass function

E = Expectation value

$P(x, y)$ = It represents the joint distribution of X and Y

$H(Z)$ = Entropy

$H(X, Y)$ = Joint Entropy of random variables X and Y

$H(X|Y)$ = Conditional Entropy of Y given X

$IG(Y | X)$ = Information Gain of Y given X

$X \perp Y = X$ is perpendicular to Y

$X(m)$ = a feature from the X

$S_1 = \{(y_i \mid x_i(m) = 0\}$ = Splitting outcome based on class 0

$S_2 = \{(y_i \mid x_i(m) = 1\}$ = Splitting outcome based on class 1