

# MICHALIS IAKOVIDES

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## EDUCATION

**University of Manchester** - Master of Science, Robotics

**Sep 2023 - Present**

**Relevant Classes** - Foundations of Machine Learning, Software for Robotics, Cognitive Robotics and Computer Vision, Autonomous Mobile Robots

**University of Manchester** - Bachelor of Engineering, Mechatronic Engineering

**Sep 2020 - Jun 2023**

**Relevant Classes** - C Programming, Microcontroller Engineering, Data Networking, Embedded Systems Project, Numerical Analysis, Concurrent Systems, Mobile Robots & Autonomous Systems, Sensors & Instrumentation

## TECHNICAL SKILLS

**Languages** | Python, C, C++, MATLAB, VHDL, Assembly

**Frameworks / Libraries** | ROS, ROS2, OpenCV, Tensorflow, PyTorch

**Developer Tools** | VSCode, PyCharm, Git, Jupyter Notebook, CodeBlocks, Arduino IDE

**Project Management Tools** | Trello

## PROJECTS

### Self-Driving Car navigation in a Mini Town with a Web Application

*Python / ROS / Tensorflow / OpenCV / Flask / HTML / CSS*

- Trained a traffic sign recognition CNN model with 98% accuracy
- Implemented a lane and traffic light detection algorithm to navigate the vehicle in a mini town
- Experience with ROS and computer vision techniques
- Tested and tuned the algorithms on a simulated vehicle in Gazebo simulator
- Designed and built a web application GUI to visualize real-time vehicle data
- Assembled the hardware components for a mini vehicle running on Nvidia Jetson Nano with a Raspberry Pi camera

### Lidar Simulation for Simultaneous Localisation and Mapping (SLAM)

*C++ / SFML*

- Developed a Lidar simulation software to emulate a robotic mapping and navigation system
- Implemented Lidar sensor modeling, including angle resolution and range settings
- Designed a dynamic graphical interface for real-time visualisation of Lidar scans
- Employed collision detection algorithms to identify obstacles in a simulated environment

## CERTIFICATES

- Learn Python 3 | Codecademy
- Learn C++ | Codecademy
- Simulink Onramp | MathWorks

## COMPETITIONS

- |   |                 |
|---|-----------------|
| • UoM Robotics Society Hack-A-Bot2023 (Best Engineered Award)   Communications Software | <b>Mar 2023</b> |
| • UniCS Great Uni Hack 2022   Backend Team - API  | <b>Nov 2022</b> |
| • American Astronautical Society (AAS) CanSat   Sensor Subsystem Team                   | <b>Jun 2022</b> |
| • American Astronautical Society (AAS) CanSat   Sensor Subsystem Team                   | <b>Jun 2021</b> |
| • Robotex Cyprus Enhanced Line Following Challenge   Software/Hardware Team Lead        | <b>Jul 2019</b> |
| • Robotex Cyprus Maze Solving Challenge (2nd Place)   Software Team - PID algorithm     | <b>Jul 2019</b> |
| • FIRST Lego League Hydrodynamics Estonian Open International   Software Team           | <b>Jun 2018</b> |
| • FIRST Lego League Hydrodynamics Cyprus (1st Place)   Software Team                    | <b>Mar 2018</b> |

## HOBBIES/INTERESTS

- FPV Drone Pilot
- Machine Learning / AI Generated Art
- 3D Printing

## LANGUAGES

- English
- Greek