Contents

1	Basic Test Results	2
2	README	3
3	Barrier.h	4
4	Barrier.cpp	5
5	Makefile	6
6	MapReduceFramework.cpp	7

1 Basic Test Results

```
1
    ======= Tar Content Test =======
    found README
    found Makefile
3
   tar content test PASSED!
4
    ====== logins =======
    login names mentioned in file: kawabanga, michal. maayan
    Please make sure that these are the correct login names.
9
10
    ====== make Command Test =======
    g++ -Wall -std=c++11 -g -I. -c -o MapReduceFramework.o MapReduceFramework.cpp g++ -Wall -std=c++11 -g -I. -c -o Barrier.o Barrier.cpp
11
12
    ar rv libMapReduceFramework.a MapReduceFramework.o Barrier.h
    a - MapReduceFramework.o
14
15
    a - Barrier.o
    a - Barrier.h
16
    ranlib libMapReduceFramework.a
17
    MapReduceFramework.cpp: In function void* threadLogic(void*):
19
    MapReduceFramework.cpp:111:21: warning: comparison between signed and unsigned integer expressions [-Wsign-compare]
20
21
         while (oldValue < tc->inputVec->size()) {
22
23
    MapReduceFramework.cpp:131:41: warning: comparison between signed and unsigned integer expressions [-Wsign-compare]
                 for (int i = FIRSTTHREAD; i < tc->MT; ++i) {
24
25
26
    MapReduceFramework.cpp:159:37: warning: comparison between signed and unsigned integer expressions [-Wsign-compare]
             for (int i = FIRSTTHREAD; i < tc->MT; ++i) {
27
28
29
    MapReduceFramework.cpp:172:19: warning: comparison between signed and unsigned integer expressions [-Wsign-compare]
             if (index < tc->Queue->size()) {
30
31
32
    MapReduceFramework.cpp: In function void runMapReduceFramework(const MapReduceClient&, const InputVec&, OutputVec&, int):
    MapReduceFramework.cpp:218:55: warning: narrowing conversion of i from int to unsigned int inside { } [-Wnarrowing]
33
34
                            &Queue, &mutexQueue, &fillCount};
35
    ar: creating libMapReduceFramework.a
36
37
    stderr: b'MapReduceFramework.cpp: In function \xe2\x80\x98void* threadLogic(void*)\xe2\x80\x99:\nMapReduceFramework.cpp:111:
38
39
    make command test FAILED!
40
    Pre-submission Test FAILED!
41
42
    Check info above.
```

2 README

```
1 kawabanga, michal.maayan
2 Yaron Scherf (305758211), Michal Maayan (203348776)
3 EX: 3
4
5 FILES:
6 MapReduceFramework.c -- Our main code file, an implementation of the
7 required code.
8 Barrier.h -- school implementation
9 Barrier.cpp -- school implementation
10
11 REMARKS:
12 Hope you have enjoyed from our implementation, we have done our best :)
```

3 Barrier.h

```
#ifndef BARRIER_H
2
   #define BARRIER_H
3 #include <pthread.h>
4
    // a multiple use barrier
    class Barrier {
8
    public:
      Barrier(int numThreads);
9
       ~Barrier();
10
11
       void barrier();
12
   private:
13
     pthread_mutex_t mutex;
14
        pthread_cond_t cv;
15
16
       int count;
       int numThreads;
17
   };
18
19
20 #endif //BARRIER_H
```

4 Barrier.cpp

```
#include "Barrier.h"
    #include <cstdlib>
    #include <cstdio>
4
    Barrier::Barrier(int numThreads)
     : mutex(PTHREAD_MUTEX_INITIALIZER)
      , cv(PTHREAD_COND_INITIALIZER)
      , numThreads(numThreads)
9
10
    { }
11
12
13
    Barrier::~Barrier()
14
         if (pthread_mutex_destroy(&mutex) != 0) {
15
             fprintf(stderr, "[[Barrier]] error on pthread_mutex_destroy");
16
             exit(1);
17
18
         if (pthread_cond_destroy(&cv) != 0){
19
             fprintf(stderr, "[[Barrier]] error on pthread_cond_destroy");
20
21
             exit(1);
22
    }
23
24
25
26
    void Barrier::barrier()
27
         if (pthread_mutex_lock(&mutex) != 0){
28
29
             fprintf(stderr, "[[Barrier]] error on pthread_mutex_lock");
             exit(1);
30
31
32
         if (++count < numThreads) {</pre>
             if (pthread_cond_wait(&cv, &mutex) != 0){
33
                 fprintf(stderr, "[[Barrier]] error on pthread_cond_wait");
34
35
                 exit(1);
             }
36
        } else {
37
             count = 0;
38
             if (pthread_cond_broadcast(&cv) != 0) {
39
40
                 fprintf(stderr, "[[Barrier]] error on pthread_cond_broadcast");
41
                 exit(1);
             }
42
43
        if (pthread_mutex_unlock(&mutex) != 0) {
44
45
             fprintf(stderr, "[[Barrier]] error on pthread_mutex_unlock");
46
             exit(1);
        }
47
    }
48
```

5 Makefile

```
CC=g++
1
    CXX=g++
    RANLIB=ranlib
4
    LIBSRC=MapReduceFramework.cpp Barrier.cpp Barrier.h
   LIBOBJ=$(LIBSRC:.cpp=.o)
6
8
    INCS=-I.
   CFLAGS = -Wall -std=c++11 -g $(INCS)
9
   CXXFLAGS = -Wall -std=c++11 -g $(INCS)
11
   OSMLIB = libMapReduceFramework.a
12
    TARGETS = $(OSMLIB)
14
    TAR=tar
15
16
   TARFLAGS=-cvf
    TARNAME=ex3.tar
17
    TARSRCS=$(LIBSRC) Makefile README
18
19
   all: $(TARGETS)
20
21
    $(TARGETS): $(LIBOBJ)
22
        $(AR) $(ARFLAGS) $@ $^
23
24
        $(RANLIB) $@
25
26
27
        $(RM) $(TARGETS) $(OSMLIB) $(OBJ) $(LIBOBJ) *~ *core
28
29
        makedepend -- $(CFLAGS) -- $(SRC) $(LIBSRC)
30
31
        $(TAR) $(TARFLAGS) $(TARNAME) $(TARSRCS)
33
```

6 MapReduceFramework.cpp

```
#include <cstdlib>
    #include <cstdio>
3 #include "Barrier.h"
   #include "MapReduceClient.h"
    #include <atomic>
   #include <iostream>
   #include <algorithm>
                             // std::sort
    #include <semaphore.h>
    #define FIRSTTHREAD 0
10
11
    typedef struct ThreadContext{
12
        unsigned int threadId;
        unsigned int MT:
14
        Barrier * barrier;
15
      std::atomic<int>* atomicIndex;
16
       std::atomic<int> *outAtomicIndex;
17
18
        std::atomic<int> *reduceAtomic;
        const InputVec* inputVec;
19
        OutputVec* outputVec;
20
21
        std::vector<IntermediateVec> *arrayOfInterVec;
       const MapReduceClient* client;
22
23
       std::vector <IntermediateVec> *Queue;
        sem_t *mutexQueue;
24
        sem_t *fillCount;
25
26
   }ThreadContext;
27
    typedef struct MapContext{
28
29
        IntermediateVec *interVector;
    }MapContext;
30
31
    typedef struct ReduceContext{
        OutputVec *outVector;
33
34
        std::atomic<int> *outAtomicIndex;
    }ReduceContext;
35
36
37
    void safeExit(ThreadContext* tc)
38
        if(tc == nullptr){
39
40
            exit(-1);
41
42
        tc->Queue->clear();
43
44
45
    void printErr(std::string msg, ThreadContext *tc){
        std::cerr<<msg<<std::endl;</pre>
46
47
        safeExit(tc);
48
49
50
    //void printInterVector(IntermediateVec** array, int numOfThreads){
51
         printf("++++++++\n");
52
53
          for (int i = 1; i < numOfThreads; ++i){
             printf("thread id: %d:\n",i);
54
              for (unsigned long j = 0; j < (*(array[i])).size(); ++j){
55
                  //printIntermediatePair((\mathfrak{C}(*(array[i])).at(j)));
   //
57
              printf("~~~~\n");
58
```

```
60
     //}
 61
     void emit2 (K2* key, V2* value, void* context){
 62
          auto* tc = (MapContext*) context;
 63
          tc->interVector->emplace_back(key, value);
 64
     }
 65
     void emit3 (K3* key, V3* value, void* context){
 66
          auto* tc = (ReduceContext*) context;
 67
 68
          int oldValue = (*(tc->outAtomicIndex))++ ;
          auto iterator = (*(tc->outVector)).begin();
 69
          (*(tc->outVector)).emplace(iterator+(oldValue), key, value);
 70
 71
     }
 72
     bool comperator(IntermediatePair &p1, IntermediatePair &p2){
 73
 74
          return (*p1.first < *p2.first);</pre>
 75
 76
      // check the IntermediateVec isn't empty, in case it doesn't find the next max key
 77
     bool check_empty_find_max(std::vector<IntermediateVec> *arr, int MT, K2 **max){
 78
          bool isEmpty = true;
 79
          for (int i = FIRSTTHREAD; i < MT; ++i) {</pre>
 80
              if (not((arr)->at(i)).empty()) {
 81
                  isEmpty = false;
 82
                  if(*max == nullptr){
 83
                      *max = ((arr)->at(i)).back().first;
 84
 85
                  else{
 86
 87
                      if((**max) < *((arr)->at(i)).back().first)
                      {
 88
 89
                           *max = ((arr)->at(i)).back().first;
 90
                  }
 91
              }
 92
 93
          }
          return isEmpty;
 94
 95
     }
 96
     bool is_eq(K2 *max, IntermediatePair &p){
 97
          if(not(*max < *p.first)){</pre>
 98
              if(not(*p.first < *max)){</pre>
 99
100
                  return true;
101
          }
102
103
          return false;
104
105
106
     void* threadLogic (void* context) {
          auto *tc = (ThreadContext *) context;
107
108
          int oldValue = (*(tc->atomicIndex))++;
109
          //map logic
110
111
          while (oldValue < tc->inputVec->size()) {
112
              auto k1 = tc->inputVec->at(oldValue).first;
113
              auto v1 = tc->inputVec->at(oldValue).second;
              MapContext mapContext = {(&tc->arrayOfInterVec->at(tc->threadId))};
114
              tc->client->map(k1, v1, &mapContext);
115
              oldValue = (*(tc->atomicIndex))++;
116
          }
117
118
119
          //sort
          auto tempVec = &(tc->arrayOfInterVec->at(tc->threadId));//[tc->threadId];
120
121
          std::sort(tempVec->begin(), tempVec->end(), comperator);
122
          tc->barrier->barrier();
123
124
          //shuffle
          if(tc->threadId == FIRSTTHREAD) {
125
              // initial K2
126
127
              K2* max = nullptr;
```

```
128
              bool isEmpty = check_empty_find_max(tc->arrayOfInterVec, tc->MT, &max);
              while(not isEmpty){
129
                  IntermediateVec sameKey = {};
130
                  for (int i = FIRSTTHREAD; i < tc->MT; ++i) {
131
                      // in case the vector isn't empty
132
133
                      if (not(tc->arrayOfInterVec->at(i).empty())) {
                          while(is_eq(max, (tc->arrayOfInterVec->at(i).back()))) {
134
                               (sameKey).emplace_back(((tc->arrayOfInterVec->at(i))).back());
135
136
                               ((tc->arrayOfInterVec->at(i))).pop_back();
                               //check emptyness again
137
                              if (((tc->arrayOfInterVec->at(i))).empty()){
138
139
140
                          }
141
142
                       }
                  }
143
144
                  max = nullptr;
                  isEmpty = check_empty_find_max(tc->arrayOfInterVec, tc->MT, &max);
145
146
                  //add to queue using semaphore
                  if (sem_wait(tc->mutexQueue) != 0){
147
                      printErr("sem_wait err",tc);
148
                  }
149
150
                  tc->Queue->push_back(sameKey);
                  if (sem_post(tc->mutexQueue) != 0){
151
152
                      printErr("sem_post err",tc);
153
                  if (sem_post(tc->fillCount) != 0){
154
155
                      printErr("sem_post err",tc);
156
157
             }
158
              //wakeup all the threads who went down
              for (int i = FIRSTTHREAD; i < tc->MT; ++i) {
159
160
                  if (sem_post(tc->fillCount) != 0){
                      printErr("sem_post err",tc);
161
162
163
             }
         }// end of shuffle
164
165
          //reduce
166
         while(true){
167
168
             if (sem_wait(tc->fillCount) != 0){
                  printErr("sem_wait err",tc);
169
170
171
              auto index = (*(tc->reduceAtomic))++ ;
              if (index < tc->Queue->size()) {
172
173
                  if (sem_wait(tc->mutexQueue) != 0){
174
                      printErr("sem_wait err",tc);
175
176
                  auto pairs = &(tc->Queue->at(index));
                  ReduceContext reduceContext = {tc->outputVec, tc->outAtomicIndex};
177
                  tc->client->reduce(pairs, &reduceContext);
178
179
                  if (sem_post(tc->mutexQueue) != 0){
180
                      printErr("sem_post err",tc);
181
                  7
              } else{
182
                  break:
183
184
185
         return nullptr;
186
187
     }
188
189
190
     void runMapReduceFramework(const MapReduceClient& client,
                                  const InputVec& inputVec, OutputVec& outputVec,
191
192
                                  int multiThreadLevel){
          if(multiThreadLevel < 1){</pre>
193
             printErr("multiThreadLevel isn't legal", nullptr);
194
195
```

```
196
          pthread_t threads[multiThreadLevel];
          ThreadContext contexts[multiThreadLevel];
197
198
          Barrier barrier(multiThreadLevel):
199
          std::atomic<int> atomicIndex(0);
          std::atomic<int> outAtomicIndex(0);
200
          std::atomic<int> reducetAtomic(0);
201
          std::vector<IntermediateVec> arrayOfInterVec = {};
202
          std::vector <IntermediateVec> Queue;
203
204
          sem_t mutexQueue;
          sem_t fillCount;
205
          if (sem_init(&mutexQueue, 0, 1) != 0){
206
207
              printErr("sem_init failed\n", nullptr);
208
          if (sem_init(&fillCount, 0, 0) != 0){
209
210
              printErr("sem_init failed\n", nullptr);
211
          for (int i = FIRSTTHREAD; i < multiThreadLevel; ++i) {</pre>
212
              arrayOfInterVec.push_back({});
213
214
215
          for (int i = FIRSTTHREAD; i < multiThreadLevel; ++i) {</pre>
216
              contexts[i] = {i, (unsigned int)multiThreadLevel, &barrier, &atomicIndex, &outAtomicIndex, &reducetAtomic,
                             &inputVec, &outputVec, &arrayOfInterVec, &client,
217
218
                              &Queue, &mutexQueue, &fillCount};
219
          for (int i = FIRSTTHREAD+1; i < multiThreadLevel; ++i) {</pre>
220
              if (pthread_create(threads + i, NULL, threadLogic, contexts + i) != 0){
221
                  printErr("pthread_create failed\n",contexts + i);
222
223
          }
224
225
          threadLogic(contexts);
226
          for (int i = FIRSTTHREAD+1; i < multiThreadLevel; ++i) {</pre>
              if (pthread_join(threads[i], NULL) != 0){
227
                  printErr("pthread_join failed\n",contexts + i);
228
229
230
231
     }
232
```