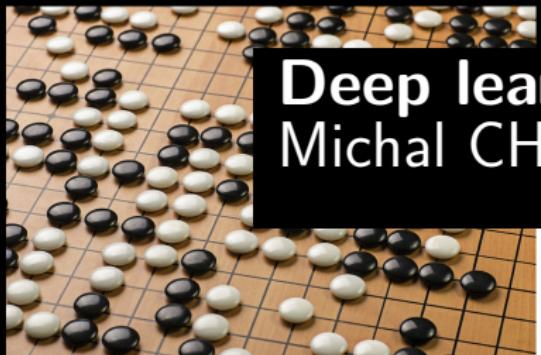


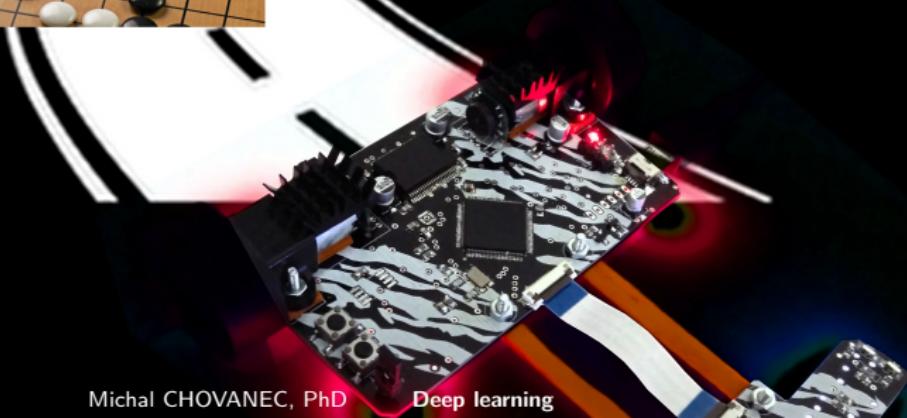
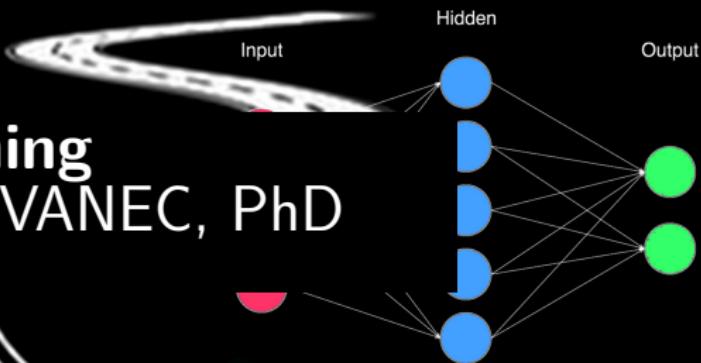
$$Q(s_t, a_t) \leftarrow Q(s_t, a_t) + \alpha [r_{t+1} + \lambda \max_a Q(s_{t+1}, a) - Q(s_t, a_t)]$$

(The New Action Value = The Old Value) + The Learning Rate \times (The New Information — the Old Information)



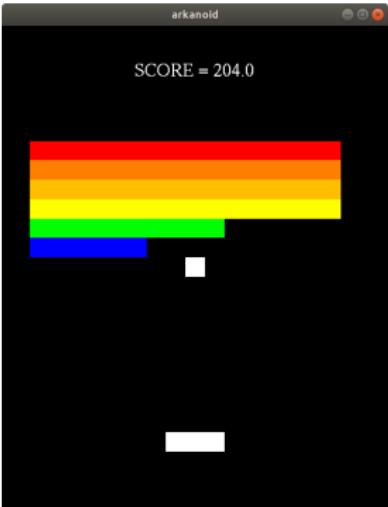
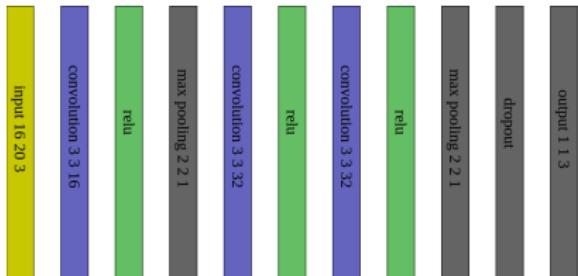
Deep learning

Michal CHOVANEC, PhD



Playing Atari games on super human level

(video)



- neurons count **10 000**
 - 500 000 parameters
 - 16 000 parameters
- ant neurons count 250 000
- bee neurons count 960 000

Applications

- self driving cars - Tesla model S
- healthcare, biomedical engineering - Cell in fluid
- voice search, control - Google, Amazon Echo
- machine translation - Google translator
- image recognition - Huawei Mate 10
- game bots, robotics - DeepMind, Boston Dynamics



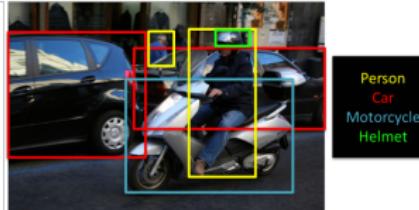
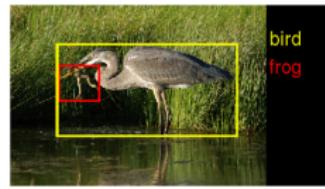
Speech Recognition



Reduced word errors by more than 30%

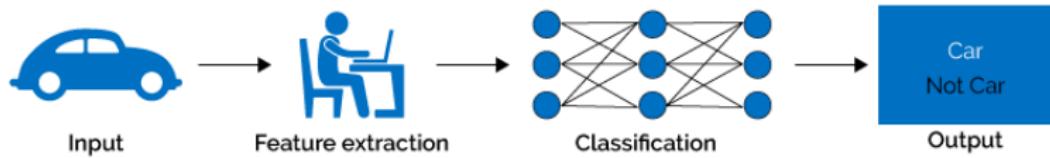
Google Research Blog - August 2012, August 2015

Research at Google

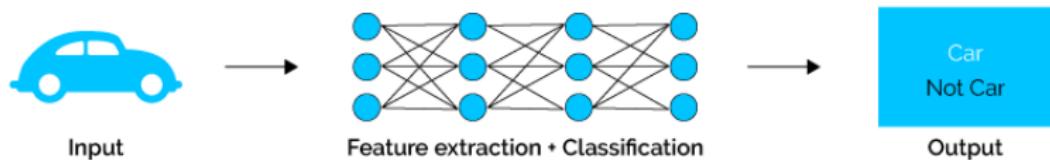


Deep learning¹

Machine Learning

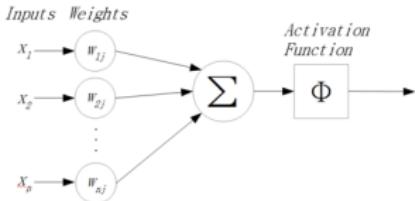


Deep Learning

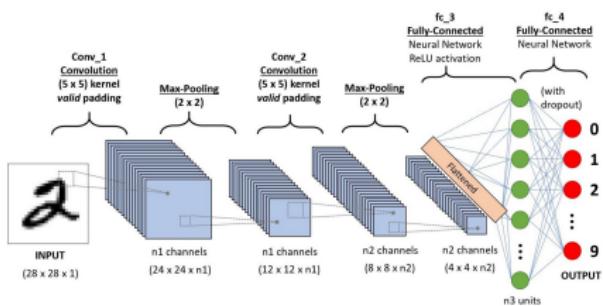
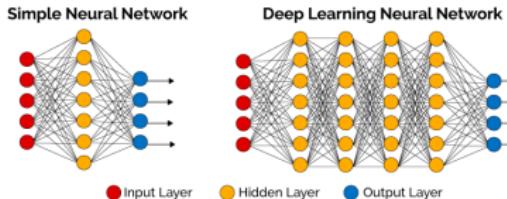


¹<https://medium.com/datamob/clearing-the-buzzwords-in-machine-learning-e395ad73178b>

Neural network

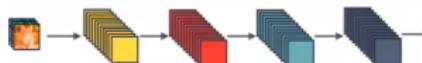


$$y(X) = f\left(\sum_i X_i W_i + b\right)$$

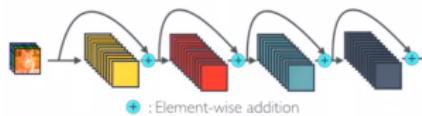


Deep neural network

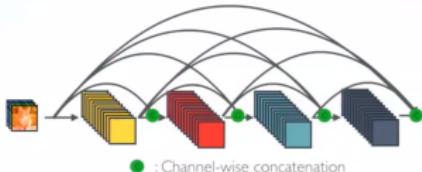
- Old methods (before NN) - 2011, 25.8%
- Convolutional, AlexNet - 2012, 16.4%
- Google inception - 2013, 6.7%
- Microsoft ResNet - 2015, 6.1%
- DenseNet - 2018, 5.17%
- CNN



- ResNET



- DenseNet



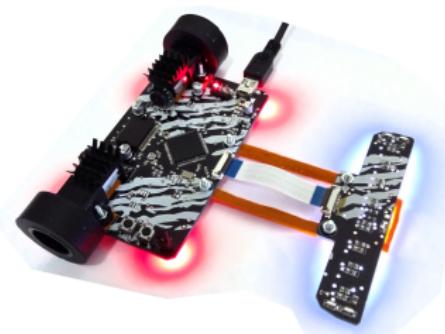
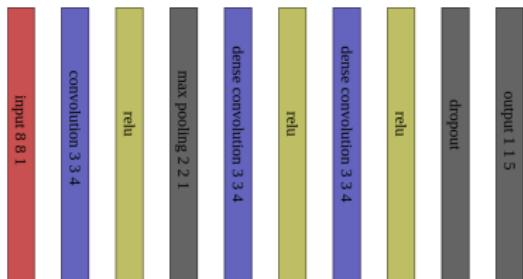
My research

- Robotics - hobby
- Red blood cells trajectory prediction
- Deep reinforcement learning

Robotics - line follower

Curve shape classification

- stm32f303 (72MHz),
stm32f746 (216MHz)
- 8x 500nm line sensors
- pololu motors, 1:30
- network input : 8 last line
sensors results (8x8 matrix)
- response 4..5ms



Robotics - line follower



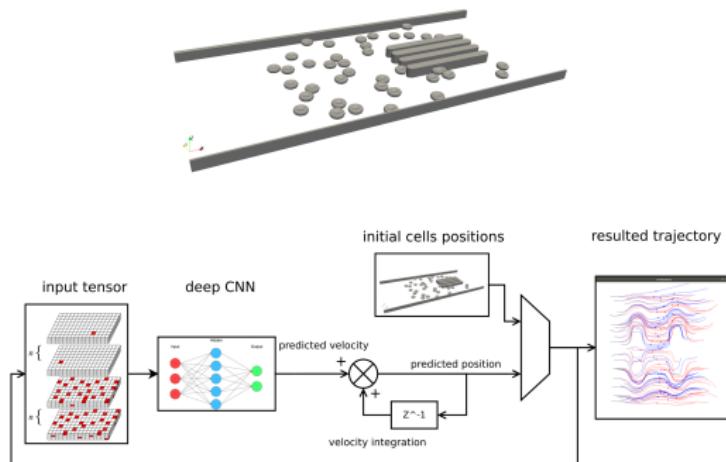
(video)

Red blood cells trajectory prediction

Research group **Cell in fluid**

Mgr. Katarína Jasenčáková, PhD thesis

- train DNN to predict RBC trajectory from past
- 15 conv layers network (6hours training on GTX1080ti)
- input : RBC position + 7 past frames + other cells position
- output: RBC predicted velocity

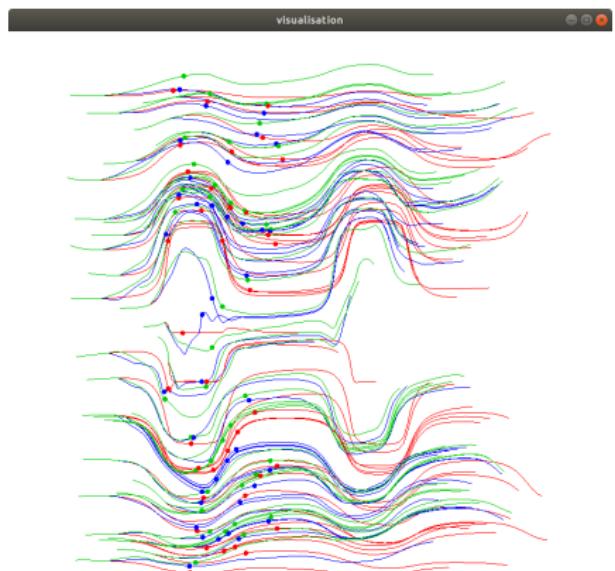


Networks

layer	net 0	net 1	net 2	net 3	net 4	net 5	net 6	net 7
0	fc 256	conv 3x3x32	dense conv 3x3x8					
1	fc 64	fc 64	dense conv 3x3x8					
2	fc 32	fc 32	dense conv 3x3x8					
3	fc 3	fc 3	dense conv 3x3x8					
4			conv 1x1x32	conv 1x1x16	conv 1x1x32	conv 1x1x16	conv 1x1x16	conv 1x1x32
5			fc 3	dense conv 3x3x8	fc 3	dense conv 3x3x8	dense conv 3x3x8	dense conv 3x3x8
6				dense conv 3x3x8		dense conv 3x3x8	dense conv 3x3x8	dense conv 3x3x8
7				dense conv 3x3x8		dense conv 3x3x8	dense conv 3x3x8	dense conv 3x3x8
8				dense conv 3x3x8		dense conv 3x3x8	dense conv 3x3x8	dense conv 3x3x8
9				conv 1x1x32		conv 1x1x32	conv 1x1x16	conv 1x1x32
10				fc 3		fc 3	dense conv 3x3x8	dense conv 3x3x8
11							dense conv 3x3x8	dense conv 3x3x8
12							dense conv 3x3x8	dense conv 3x3x8
13							dense conv 3x3x8	dense conv 3x3x8
14							conv 1x1x32	conv 1x1x64
15							fc 3	fc 3

Results

(video)



Results

ID	total error			
	mean [um]	sigma [um]	rms [um]	rms relative [%]
0	-9.8	38.88	40.1	7.23
1	-36.99	215.02	218.18	39.32
2	-3.85	23.11	23.43	4.22
3	-0.32	16.09	16.09	2.9
4	-1.26	11.44	11.51	2.07
5	-0.25	11.27	11.28	2.03
6	-0.85	12.26	12.29	2.22
7	-1.67	11.9	12.02	2.17

Playing GO



- **supervised training** - train game using Masters games
- **reinforcement learning** - let play two networks against each other

Network architecture

we need to go much deeper for GO

- **28, 35 layers**

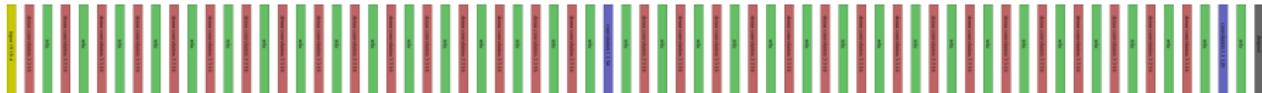
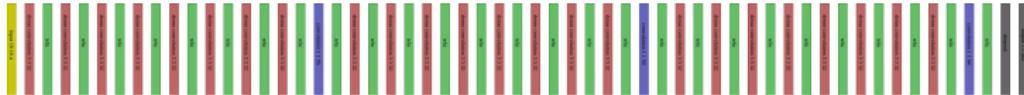
dense blocks + feature pooling layer

- **input**

4 matrices 19×19 : black stones, white stones, empty fields, active player

- **output**

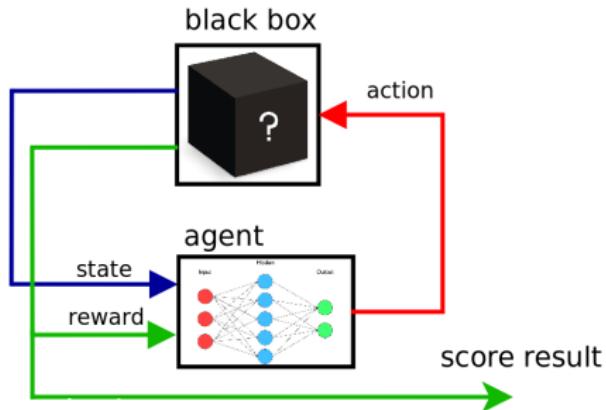
recommended moves $19 \times 19 + 1$ for pass = 362 outputs



Reinforcement learning

- learn from punishment and rewards
- learn to play a game with unknown rules
- obtain **state**, s
- choose **action**, a
- **execute** action
- obtain **reward**, R
- learn from **experiences**, $Q(s, a) = R + \gamma \max_{\alpha'} Q(s', \alpha')$

$$Q(s, a) \approx \hat{Q}(s, a; w)$$



FRI deep learning projects

- machine learning summer school
<https://mlss.sk>
- masters projects
 - Ing. Peter Tarábek, PhD. - Inteligentná analýza obrazku,
Tvorba UI pre počítačové hry
 - doc. Mgr. Ondrej Šuch, PhD. - Aplikácie strojového učenia pre
Big Data
- AI seminars - monday, prof. Ing. Martin Klimo, PhD.
- robotics competition
 - Irobot www.robotika.sk
 - Robotický den robotickyden.cz
- Learning systems - methods and applications
Ing. Michal Chovanec, PhD., 5II140, AMUS

Usefull links

-  CHRISTOPHER J.C.H. WATKINS : Q-learning
<http://www.gatsby.ucl.ac.uk/~dayan/papers/cjch.pdf>
-  Richard S. Sutton : Reinforcement Learning: An Introduction
<https://www.amazon.com/Reinforcement-Learning-Introduction-Adaptive-Computation/dp/0262193981>
-  Google DeepMind : Playing Atari with Deep Reinforcement Learning
<https://arxiv.org/pdf/1312.5602.pdf>
-  Google DeepMind : Dueling Network Architectures for Deep Reinforcement Learning
<https://arxiv.org/pdf/1511.06581.pdf>
-  Google DeepMind :Mastering the Game of Go without Human Knowledge
https://deepmind.com/documents/119/agz_unformatted_nature.pdf
-  Andrej Karpathy : Pong from pixels
<http://karpathy.github.io/2016/05/31/r1/>
-  Maxim Lapan : Deep reinforcement learning
<https://www.amazon.com/Practical-Reinforcement-Learning-Maxim-Lapan/dp/1788834240>
-  Mohit Sewak : Practical Convolutional Neural Networks
<https://www.amazon.com/Practical-Convolutional-Neural-Networks-Implement/dp/1788392302>
-  Densely Connected Convolutional Networks
<https://arxiv.org/pdf/1608.06993.pdf>

Q&A



michal chovanec (michal.nand@gmail.com)
www.youtube.com/channel/UCzVvP2ou8v3afNiVrPAHQGg
github <https://github.com/michalnand>