Realistic Camera Model

Shan-Yung Yang

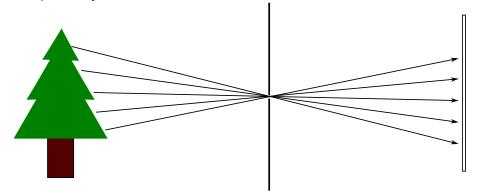
November 2, 2006

Outline

- Introduction
- Lens system
- Thick lens approximation
- Radiometry
- Sampling
- Assignment #2

Introduction

Until now we have only discussed the pinhole camera model, which is not phisically correct.



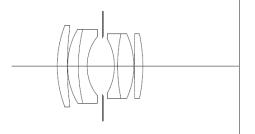
Why We Need Realistic Model

- Phisical correctness is our goal.
- Combining real images with synthetic ones is very common in digital visual effects.
- Machine vision and scientific applications need to simulate camera correctly.
- Users of 3D graphics system are familiar with cameras.

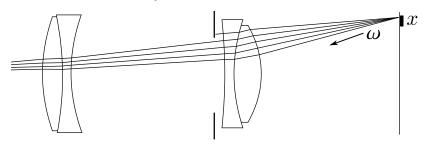
Lens Systems

Lens systems are typically constructed from a series of individual spherical lenses.

radius	thick	n_d	V-no	ap
58.950	7.520	1.670	47.1	50.4
169.660	0.240			50.4
38.550	8.050	1.670	47.1	46.0
81.540	6.550	1.699	30.1	46.0
25.500	11.410			36.0
	9.000			34.2
-28.990	2.360	1.603	38.0	34.0
81.540	12.130	1.658	57.3	40.0
-40.770	0.380			40.0
874.130	6.440	1.717	48.0	40.0
-79.460	72.228			40.0



Measurement Equation

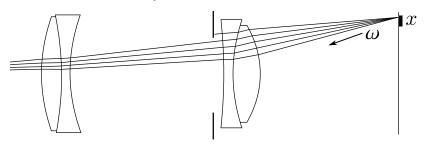


$$R = \iiint \int \int \int L(T(x,\omega,\lambda);\lambda)S(x,t)P(x,\lambda)\cos\theta \ dx \ d\omega \ dt \ d\lambda$$

L: radiance T: image to object space transformation

S: shutter function P: sensor response characteristics

Measurement Equation



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Solving the Integral

Problem: given a function f and domain Ω , how to calculate

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Solution: Monte Carlo method:

$$\int_{\Omega} f(x)dx \approx \left[\frac{1}{N} \sum_{i=1}^{N} f(x_i)\right] \cdot \int_{\Omega} dx$$

where x_1, x_2, \ldots, x_N are uniform distributed random samples in Ω .

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8 / 25

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- 3 Shoot the ray according to the result of $T(x_i, \omega_i)$ into the scene, and calculate the radiance.
- Set the pixel value to the average of radiance.

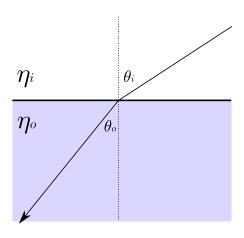
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 - Ompute the new direction by Snell's law if the medium is different.

9 / 25

Snell's Law



$$\eta_i \sin \theta_i = \eta_o \sin \theta_o$$

• In some situations we need an ideal lens approximation.

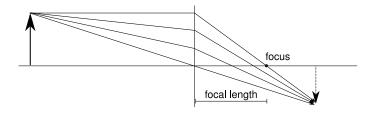
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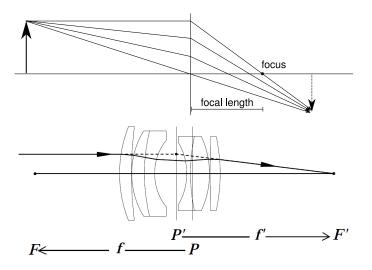
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- Thick lens approximation has additional parameter of thickness.

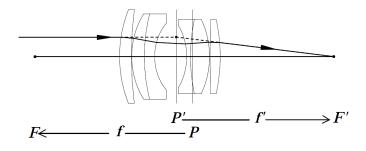
Thin Lens and Thick Lens



Thin Lens and Thick Lens

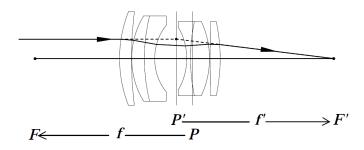


Finding Thick Lens Approximation



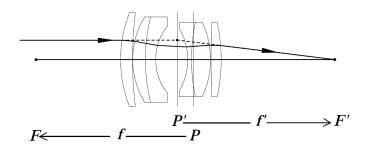
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- Find the principal plane by intersecting the refracted ray and parallel one.
- Find the secondary principal plane by tracing from another side.

Application of Thick Lens Approximation

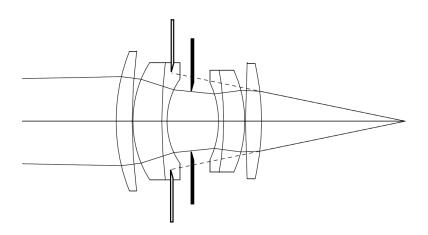
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- Calculate the **exit pupil**.



The exit pupil is the effective aperture stop in the image space which allows ray incindence.

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- You may also use the aperture of the nearest lens as the exit pupil.

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• Assume that the irradiance is constant over the exposure period:

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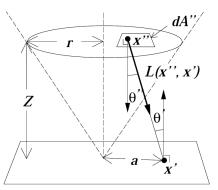
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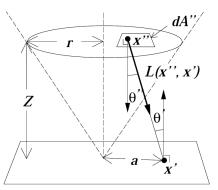
- In practice, we only need to integrate over the exit pupil instead of the whole semisphere.
- Let

$$E(x') = \int L(T(x', \omega)) \cos \theta' d\omega$$
$$R = \Delta t \cdot \int E(x') dx'$$

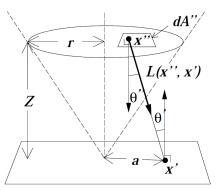




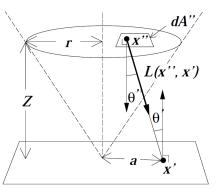
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$$E(x') = \int_{x'' \in D} L(x'', x') \frac{\cos \theta' \cos \theta''}{||x'' - x'||^2} dA''$$



$$E(x') = \frac{1}{Z^2} \int_{x'' \in D} L(x'', x') \cos^4 \theta' \ dA''$$

Sampling a Disk Uniformly

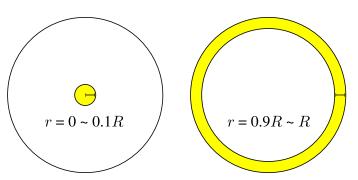
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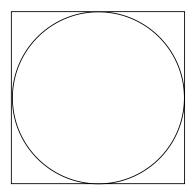
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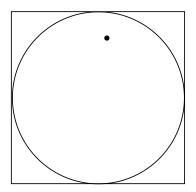
- Now we need to obtain random samples on a disk uniformly.
- How about uniformly sample r in [0,R] and θ in $[0,2\pi]$ and let $x=r\cos\theta,y=r\sin\theta$?
 - ▶ The result is not uniform due to coordinate transformation.



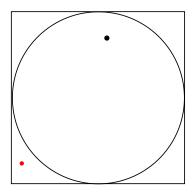
- Uniformly sample a point in the bounding square of the disk.
- If the sample lies outside the disk, reject it and sample another one.



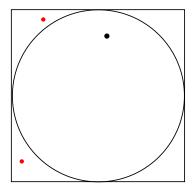
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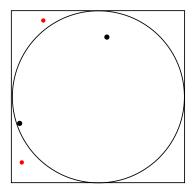
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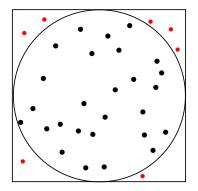
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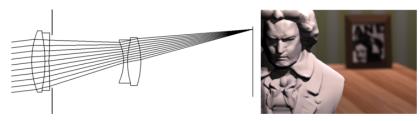
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 This produce uniform samples on a disk after coordinate transformation. We will prove it later in chapter 14 "Monte Carlo integration".



200mm Telescope



50mm General



35mm wide-angle



16mm Fisheye

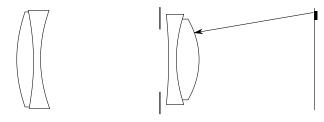
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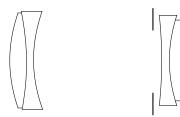
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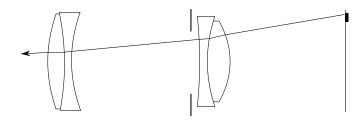
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 - You need to fill the content of ray and return a value for its weight.



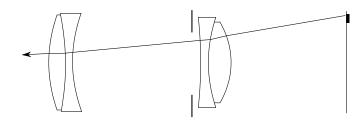
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- **③** Fill ray with the result and return $\frac{\cos^4 heta'}{Z^2}$ as its weight.

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- Your source code.
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- My email address:

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littleshan@cmlab.csie.ntu.edu.tw
littleshan@gmail.com
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