

signalHsmm - a novel semi-Markov model of eukaryotic signal peptides

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ABSTRACT

The proper localization of proteins in a cell is essential to maintain their desired function. Information about the protein destination is included within the very protein in the form of short peptides called targeting signals. Ones of them are signal peptides, diverse N-terminal sequences, which are responsible for targeting of proteins to endomembrane system and their export outside the cell. Proteins equipped with signal peptides play crucial roles in metabolism, maintenance of tissue structure, immune response and regulation of other organismal functions. Moreover, the transport of proteins through the endomembrane system is important for their correct folding and posttranslational modifications.

A common model of classical signal peptides assumes that they start with a positively charged n-region, followed by a hydrophobic h-region and a c-region ended with a cleavage site recognised by a signal peptidase. However, our studies of many protein sequences representing the wide range of diversified taxonomic organisms indicate a variability of signal peptides. Therefore, we designed a new, more universal probabilistic model for eukaryotic signal peptides, which includes knowledge about their organisation, amino acid composition and variation.

The proposed model is based on hidden semi-Markov models (HSMMs) and use intrinsic knowledge about signal peptides. The big advantage of the algorithm is its extensibility. Using the n-grams (k-mers) we point how the general model can be attuned to yield not only better results, but also more information about signal peptides.

Our model was validated a signal peptide predictor. It has showed the largest AUC=0.98 in comparison to other software and appeared very stable in the recovery of signal peptides after training even on very small data sets. Thanks to that, our model does not need to be permanently retrained with the continuous expansion of sequence databases. It should be emphasised that our model describes signal peptides from medically significant malaria parasites *Plasmodium* and their relatives (AUC = 0.92) more accurately than popular programs (0.84).

Keywords: signal peptide prediction; n-gram; hidden semi-Markov models

INTRODUCTION

Signal peptides

Proteins of eukaryotes are encoded in nuclear genomes and are synthesized in ribosomes located in the cytosol or bounded by the endoplasmic reticulum. After the translation process, proteins have to be targeted to specific subcellular compartments or exported outside the cell to the extracellular environment. The proper localization of proteins is essential to perform their desired function. Information about protein destination is included within the very protein in the form of short peptides or stretches of amino acid residues called targeting or sorting signals. Ones of them are signal peptides, which are located at the N-terminus of proteins.

Signal peptides are responsible for targeting of proteins via the Sec61 translocation channel (Rapoport, 2007) to endomembrane system, which includes endoplasmic reticulum, Golgi apparatus and endosomes. Such proteins can stay inside of these compartments, or can be inserted into cellular membranes or exported outside the cell. Proteins equipped with signal peptides constitute a substantial fraction of the whole proteome. They play crucial roles in metabolism (β galactosidase, pepsins) (Hofmann and Schultz, 1991), maintenance of tissue structure (collagen) (Chan et al., 2001), immune response (interferons, interleukins) (Zhang et al., 2005) and regulation of other organismal functions (prolactin, glucagon) (Huang et al., 2010). Moreover, passing proteins through the endomembrane system is important for their correct folding and posttranslational modification such as glycosylation and phosphorylation.

Although signal peptides are quite variable, some general architecture were proposed (Izard and Kendall, 1994; Voss et al., 2013) - Fig. 1. It is assumed that signal peptides start with a positively charged sequence of amino acid residues, called the n-region with the length of about 5-8 residues. They probably enforce a proper topology on the polypeptide during translocation through membrane based on the positive-inside rule (von Heijne and Gavel, 1988). The first region is followed by a stretch of hydrophobic amino acids (h-region) with the length of about 8-12 residues. It constitutes a core region of signal peptide and has a tendency to form α -helix. The third part of a signal peptide, usually 6 residues long, is a polar, but uncharged c-region ended with a cleavage site recognized by the signal peptidase. The amino acid composition and the length of these regions vary between signal peptides, which influences the efficiency of protein secretion (Hegde and Bernstein, 2006).



Figure 1. The organization of signal peptide.

During or after translocation of the protein into the lumen of endoplasmic reticulum, the typical signal peptide is cleaved by a signal peptidase (Paetzel et al., 2002) and next degraded by specific proteases, whereas the rest (mature) part of protein stays in the lumen or is passed to other compartments. The cleavage site is characterized by a very variable amino acid composition. It typically contains small and neutral residues at -3 and -1 positions (Palzkill et al., 1994). The site is, however, absent from some membrane proteins in which the first transmembrane-domain acts both as signal peptides and signal anchor (Szczesna-Skorupa et al., 1988).

Some data indicate that signal peptides may be universal. It was found, for example, that even bacterial signal peptides targeted correctly transgenic proteins to the plant (Moeller et al., 2009) or mammalian secretory system (Nagano and Masuda, 2014). On the other hand, signal peptides show great variation and the description presented above (Fig. 1) refers to the most 'typical' signal peptides. There are also exceptionally long signal peptides, which fulfil more sophisticated roles (Hiss and Schneider, 2009). For example, the fragment of signal peptide from prolactin probably takes part in the regulation of prolactin secretion. Other examples are signal peptides of MHC class I, which inhibit activity of NK cells. Interesting functions have signal peptides of viral origin, which are involved in the immune evasion or viral life cycle (Kapp, 2000). Such diverse functions are restricted not only to the long signal peptides. The peptides from midkine, a protein contributing to the tumor progression, contains epitopes recognized by CD4+ T cells (Kerzerho et al., 2013). It indicates that the signal peptide may participate in a tumor immunity. The functional significance of these targeting signals makes that the prediction of signal peptide-containing proteins is also an important step in the drug development (Zhang et al., 2005; Neto Ade et al., 2012; Moeller et al., 2010).

Signal peptide predicting software

Although many experimental methods determining the subcellular localization of proteins were devised, they are time consuming and laborious. Therefore, the development of new approaches in the field of computational biology and bioinformatics is desirable. They are not only a good support, complement or alternative for the experimental methods but also enable to understand rules encoding information about protein targeting, which is contained in the predicted targeting signals. However, many of the present predictors disregard full biological information carrying by signal peptides.

Having functional importance and specific features, signal peptides became the subject of many programs to their prediction based on different methods. The state of the art software for predicting the presence of signal peptides often incorporates 'black-box' models, as neural networks (Petersen et al., 2011), support vector machines (Zhang et al., 2014), Bayesian networks (Zheng et al., 2012) or k-nearest neighbours (Shen and Chou, 2007). Such models neither utilize biological information about signal peptides nor work properly on atypical signal peptides.

The other type of software incorporates into the prediction process theoretical knowledge about the structure of signal peptides. Although these programs do not share innate flaws of 'black-box' models, they also demand an improvement. Some of them are based on position matrices or their more abstract variants (Zhang et al., 2014; Hiller et al., 2004). Others (Phobius, Philius and not supported SignalP 3.0) use hidden Markov models (HMMs) (Käll et al., 2004; Reynolds et al., 2008;

Bendtsen et al., 2004), which reflect regions of signal peptides without realizing limitations of this probabilistic framework. However, the HMMs imply geometric distribution for duration of region length. We replicated the rules for extracting regions' boundaries from the first work utilizing HMMs in prediction of signal peptides (Nielsen and Krogh, 1998) and found that the mentioned assumption is not in concordance with the reality because every region revealed the length distribution other than geometric (Fig. 2). Moreover, the commonly used rigid region scheme (Fig. 1) does not describe extremely long or short signal peptides. Theoretically, HMMs that describe the atypical signal peptides could be developed to consider also unusual structures, but such probabilistic frameworks have not still been implemented.



Figure 2. A) Distribution of lengths of signal peptides. B) Distribution of the lengths of signal peptide regions. The measure of the length is a number of amino acids in the subsequence. The data was extracted from 2 589 signal peptide sequences derived from UniProt database (see **Data selection** in **Methods**).

Another feature, shared by majority of the signal peptide predicting software, is the orthogonal encoding of amino acids, in which a vector of 20 digits represents every amino acid. This method of encoding, however, does not preserve relationships between amino acids. The distance between residues is the same regardless of the similarity of their physicochemical properties. Such behaviour is especially undesired in signal peptides models because their regions are defined by specific features of amino acid residues and not by the simple occurrence of specific amino acids. In addition to this, such sparse encoding enforces larger data sets, which hinders their management and analysis (Lin et al., 2002).

All programs used in signal peptide recognition are trained on real protein sequences. Therefore, they succeed in the recognition of peptides similar to those in the learning set, but fail in the case of artificial signal peptides. Such peptides are designed to increase effectiveness of protein secretion (Futatsumori-Sugai and Tsumoto, 2010). They are especially important in industrial applications to increase yield of proteins. Therefore, only explicit knowledge about the organization of signal peptides allows creating sequences that will be the most efficient in the export of proteins (Ng and Sarkar, 2013). Signal peptides have also an important application in gene therapy. Mimicking the natural mechanism of protein export, artificial signal peptides with tumor epitopes increase the antitumor immune response (He et al., 2003). Such epitopes must be properly inserted into a signal peptide without decreasing its secretion properties through disruption of the regional structure. Instead of time-consuming and expensive laboratory experiments, it would be very useful to survey *in silico* many artificial peptides to select the ones that would fulfil the designed role.

METHODS

Overview

The functionality of a signal peptide depends not on exact sequence of specific amino acids, but on the physicochemical properties of residues in a given region. Henceforth, the usage of raw amino acid sequences is superfluous and introduces unnecessary information. To utilize this property of signal peptide recognition, we cluster amino acids into several groups based on the physicochemical

properties of residues.

The pre-processed sequences are further analyzed by the heuristic algorithm, which determines borders between three characteristic signal peptide regions, the enhanced version of algorithm presented in Nielsen and Krogh (1998). Using the current information from experimentalists, we refined the region recognition criteria.

Next, two models are trained to recognize proteins with and without a signal peptide. The first one is a hidden semi-Markov model, in which each of three signal peptide regions is represented by a different hidden state. The additional fourth hidden state represents mature protein. Each state is described by the frequencies of amino acid groups within that state. The distribution of hidden states durations, the number of amino acids related to each hidden state in signal peptide, is based on the empirical density of region lengths from the training set.

The second model is a simple probabilistic approach in which no association between amino acids was assumed, and probability of amino acids groups occurrence was determined by their frequencies in mature proteins.

Data selection

Eukaryotic protein sequences and their annotations were properly prepared according to the literature of the subject and downloaded from UniProt database release 2015_06. The positive set contained 2 589 sequences with an experimentally confirmed signal peptide and its cleavage site. Sequences with more than one cleavage site were excluded from the final data set. The negative set comprised 152 272 sequences without any signal peptide annotation. Protein sequences with ambiguous symbols: X, J, Z and B were removed from the final sets. Proteins with selenocysteine (U) were also excluded from data set, because there are no records of signal peptides containing this amino acid.

Clustering of amino acids

Amino acids were clustered using several criteria relevant for the architecture of signal peptide: hydrophobicity, frequency in alpha-helices, polarity and size. High values of hydrophobicity are required in the h-region, the core of signal peptides. Alpha-helix, the secondary structure of this region, is probably induced by the positively charged n-region. Polarity as well as size are important especially in the cleavage site (Palzkill et al., 1994).

Criterion name	Property name
Size	Size
Size	Molecular weight
Size	Residue volume (Goldsack and Chalifoux, 1973)
Size	Bulkiness (Zimmerman et al., 1968)
Hydrophobicity	Normalized hydrophobicity scales for alpha-proteins (Cid et al., 1992)
Hydrophobicity	Consensus normalized hydrophobicity scale (Eisenberg, 1984)
Hydrophobicity	Hydropathy index (Kyte and Doolittle, 1982)
Hydrophobicity	Surrounding hydrophobicity in alpha-helix (Ponnuswamy et al., 1980)
Polarity	Polarity (Grantham, 1974)
Polarity	Mean polarity (Radzicka et al., 1988)
Frequency in alpha-helices	Signal sequence helical potential (Argos et al., 1982)
Frequency in alpha-helices	Normalized frequency of N-terminal helix
Frequency in alpha-helices	Relative frequency in alpha-helix (Prabhakaran, 1990)

Table 1. Properties used in clusterization.

We selected 13 properties from AAIndex database (Kawashima et al., 2008) (see Table 1), each attributed to a single criterion. Considering all combinations of single properties for every criterion, we created 96 possible clusterings of amino acids using Euclidean distance and Ward's method.

To compare encodings we performed a 5-fold cross-validation training a new instance of signalHsmm on every encoding. We created balanced data sets by subsampling a number of proteins without a signal peptide equal to the number of proteins with signal peptide. The cross-validation was repeated XXX times, to ensure that every negative protein was tested at least once with XXX probability.

Hidden semi-Markov model

Let us first define Hidden Markov Model (HMM). Suppose you have a sequence of observations e.g. amino acids. What is of interest is understanding underlying cause of their occurrence. HMM

aims to answer that by assuming a specific yet flexible structure of the problem. HMM consists of two stochastic processes. First is discrete Markov chain $X_{t=1}^T$ on the set of so called hidden states $\{S_1, \dots, S_n\}$. These are "the cause" for the observations. At every step, hidden state might change according to transition matrix $A = (a)_{i,j=1}^n$, where $a_{i,j} = \mathcal{P}(X_{t+1} = S_j | X_t = S_i)$. In our application hidden states are signal peptide regions. Second process $E_{t=1}^T$ is observation process, defined on the set of possible observations $\{O_1, \dots, O_m\}$. Observations are assumed to occur independently. Their distribution depends only on hidden state which emits it. Probabilities are given by a matrix B , $b_{i,k} = \mathcal{P}(E_t = O_k | X_t = S_i)$. In our case, observations are (degenerated) amino acids. Main goal in signalHsmm is to find, for a given peptide, most probable regions boundaries. This is achieved with Viterbi algorithm. For a good reference on HMM see (Rabiner, 1989).

In regular HMM, hidden state duration – number of observations emitted by the hidden state, has geometric distribution. (Durbin et al., 1998) shows how to extend it for some different distributions without significant increase in computational complexity. Similar ideas were used for signal peptide recognition, for example in (Käll et al., 2004). It is However still not flexible enough. Empirical regions length distributions (see figure 2) are difficult to capture in that way.

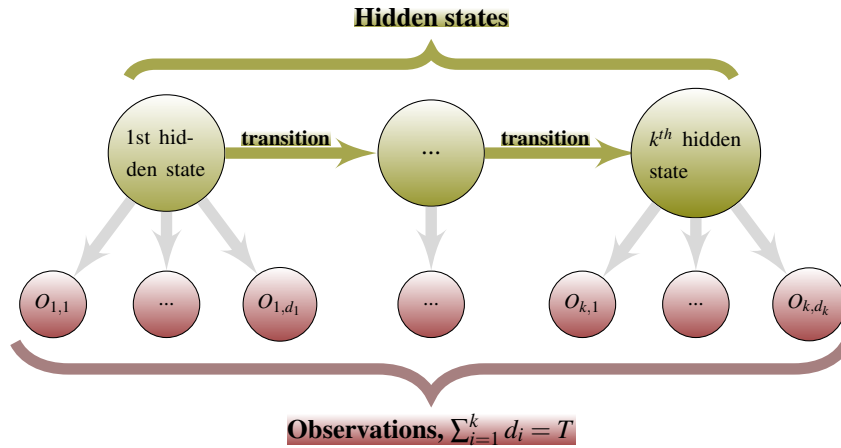


Figure 3. Hidden semi-Markov Model scheme

The model we use is Hidden semi-Markov Model(HSMM) (Yu, 2010). It extends HMM by allowing any given hidden state length distribution. Scheme is shown in figure 3. Model is given by matrices A and B as before, as well as probabilities of duration length in hidden states.

$$\mathcal{P}(\text{duration in state} = d | \text{state is } S_i), \quad i = 1, \dots, n, \quad d = 1, \dots, D$$

D is maximal allowed duration. As our datasets are of reasonable size, D is small – around 30, computational effort is not much higher than in the regular HMM.

The gain is not only a better fit to the data but also, as model structure (see figure 4) is straightforward, easier interpretation for researcher without mathematical background.

n-gram extension

HSMM can be further extended to use some specific motives that might occur in proximity of cleavage site. Such an extension requires defining additional hidden states. To find such motives we analyze n-grams (k-mers) – vectors of n characters derived from input sequences. The rigid structure of n-grams may mirror cleavage sites, which are more conservative than other parts of signal peptide (Hiller et al., 2004). Scheme of extended HSMM can be seen in figure 5.

Using the biogram software (BIOGRAM CITATION) we extracted n-grams from cleavage sites of signal peptides. XXX n-grams were further used in the analysis

RESULTS

DISCUSSION

Despite the presence of signal peptide predicting software, there are no exhaustive studies devoted to the analysis of the signal peptide structure and taxonomical variability. Our research focuses on a transparent model of signal peptide instead of a 'black-box' solution.

Figure 4. Scheme of signalHsmm

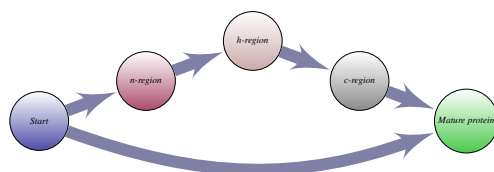


Figure 5. Scheme of signalHsmm with cleavage site motives

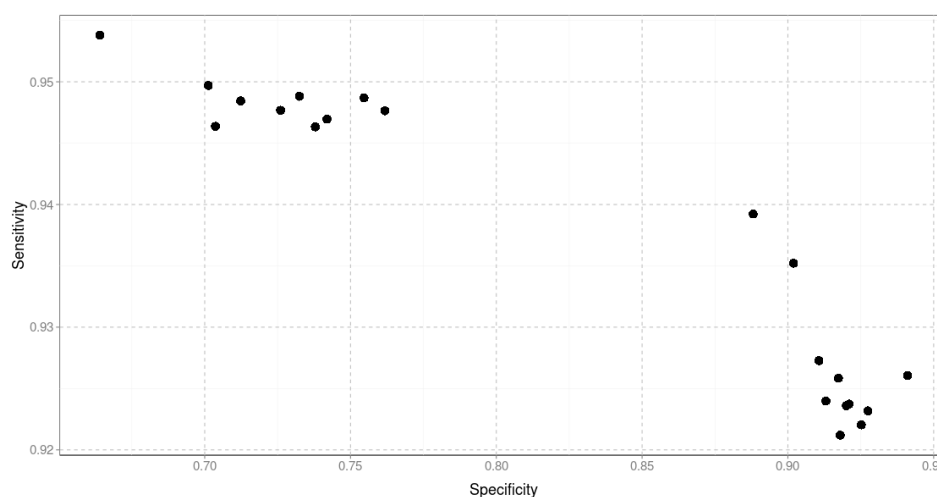
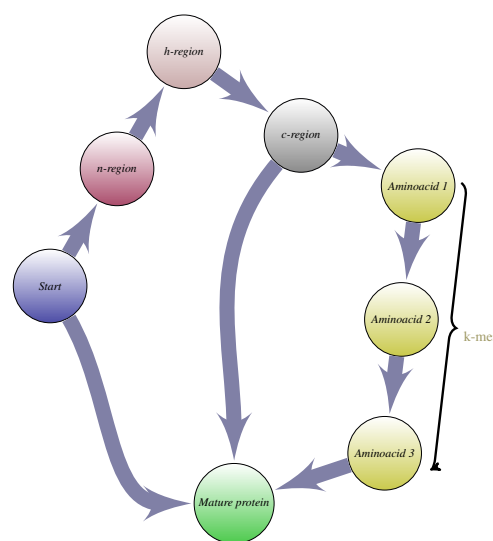


Figure 6. Results of cross-validation for 15 best performing amino acid encodings.

The proposed algorithm recognizing various signal peptides will reduce costs and speed up searching appropriate artificial signal peptides designed for protein secretion in expensive and time-consuming laboratory experiments. Moreover, the algorithm can be applied in recognition any sequence types on the nucleotide and amino acid levels, represented by small sets. Accessible as a stand-alone and browser-based software, its useful both for researches interested in the analysis of signal peptides.

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PS and PB devised the HSMM model of signal peptide. MB and PS co-wrote the software. MB gathered data and carried the analysis. MB, PS and PM drafted the manuscript. All authors revised the manuscript and approved the final version.

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