

ML in Action

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DFS
problem def.
abstract DT
concrete DT
aux stuff
dfs

ML in Action

Graph Coverage

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# Depth First Search (DFS) Abstract Datatypes

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## To solve the problem we need:

- a tree datatype to represent the result of the visit

type 'a tree = Leaf of 'a | Tree of ('a \* 'a tree list);;

- a graph datatype to support the obvious needing

```
module type GraphADT =
sig
  type 'a graph

val empty : unit -> 'a graph

val add_node : 'a -> 'a graph -> 'a graph
val add_arc : 'a -> 'a -> 'a graph -> 'a graph
val adjacents : 'a -> 'a graph -> 'a list
val node_is_in_graph : 'a -> 'a graph -> bool
val is_empty : 'a graph -> bool
exception TheGraphIsEmpty
exception TheNodeIsNotInGraph
end;;
```



# Depth First Search (DFS) Problem Definition

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DFS

Problem def.

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concrete DT

aux stuff

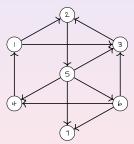
dfs

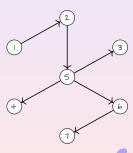
result

result

#### Depth First Search

 is an algorithm for traversing graph starting from a given node and exploring as far as possible along each branch before backtracking.





#### Note.

- DFS depends on how out edges are ordered (in the case above they are sorted by value).
- we focus on acyclic direct graphs

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#### Depth First Search (DFS)

Graph Implementation

DFS
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References

```
module Graph : GraphADT =
struct
  type 'a graph = Graph of ( 'a list ) * ( ( 'a * 'a ) list )
  let empty() = Graph([], [])
  let is.empty = function
        Graph(nodes, _) -> (nodes = [])
  exception TheGraphIsEmpty
  exception TheNodeIsNotInGraph
  (* checks if an element belongs to the list *)
  let rec is_in_list ?(res=false) x = function
        [] -> res
  | h::tl -> is_in_list ~res: (res || (x=h)) x tl
        (* checks if a node is in the graph *)
  let node_is_in_graph n = function
        Graph(nodes, _) -> is_in_list n nodes
    ...
end
```

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#### Depth First Search (DFS)

Graph Implementation (Follows)

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```
(* adds an element to a list if not present *)
let rec add_in_list ?(res=[]) x = function
 [] -> List.rev x::res
| h::tl when (h=x) -> List.rev_append tl (h::res)
                 -> add_in_list ~res: (h::res) x tl
(* operations to add new nodes and arcs (with their nodes) to the graph, respectively *)
let add_node n = function
 Graph([], []) -> Graph([n], [])
| Graph( nodes, arcs ) -> Graph( (add_in_list n nodes), arcs )
let add arc s d = function
 Graph(nodes, arcs) ->
    Graph( (add_in_list d (add_in_list s nodes)), (add_in_list (s,d) arcs) )
let adjacents n =
 let adjacents n = List.map snd (List.filter (fun x -> ((fst x) = n)) l)
in function
 Graph(_-, arcs) -> adjacents n arcs
```

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# AND TO RUM AND TO REAL PROPERTY.

## Depth First Search (DFS)

DFS Implementation

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```
open Graph
let dfs g v =
   let rec dfs g v g' = function
   [] -> g'
   | hd::tl when (node_is_in_graph hd g') -> dfs g v g' tl
   | hd::tl -> dfs g v (add_arc v hd (dfs g hd (add_node hd g') (adjacents hd g))) tl
   in
   if (is_empty g) then raise TheGraphIsEmpty
   else if not (node_is_in_graph v g) then raise TheNodeIsNotInGraph
        else graph_to_tree (dfs g v (add_node v (empty())) (adjacents v g)) v
```





#### Depth First Search (DFS) Ancillary Operations on Graphs

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TAK!

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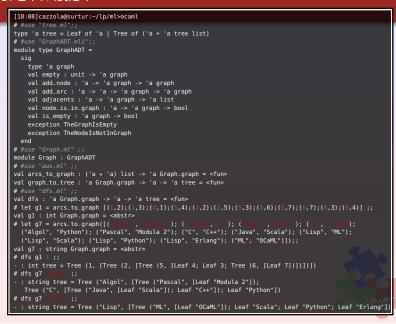
# Depth First Search (DFS) DFS in Action

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.f. DT DT



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### References

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