

Michele Maria Ciciolla

Graduating in Robotics and Artificial Intelligence

I consider myself a genuine robotics and artificial intelligence enthusiast with a strong goal oriented thinking and team working attitude. **I'm interested in R&D, Robotics, Artificial Intelligence, Automotive, Space/Defence context.**



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UNIVERSITY EDUCATION

Master in Artificial Intelligence and Robotics (EN)

Università La Sapienza

09/2018 - 05/2021

Rome, Italy

- Relevant exams : Autonomous and Mobile Robotics, Artificial Intelligence, Vision and Perception, Medical Robotics
- Thesis Project : Developing an automated calibration process for machine vision cameras carried by industrial robots for precision measurements.

Bachelor in Automation and Computer Science Engineering (IT)

Università Roma Tre

09/2014 - 03/2018

Rome, Italy

- Relevant exams : SCADA and PLC Automation Systems, Project Management.
- Thesis Project : Mobile Robot Navigation and Mapping (ROS, Turtlebot)

WORK EXPERIENCE

Internship – Robotics Software Engineering

STAR srl - ICAP Group

01/2021 - 05/2021

Latina (RM), Italy

- Thesis Topic : Developing an automated process for calibrating cameras carried by industrial anthropomorphic robotics arm.
- Tools: VB.NET, ABB RobotStudio, LMI HexSight

Advanced training course in Collaborative Robotics

Experis (Manpower) and Universal Robot A/S

09/2020 - 11/2020

Practical Applications of Lean robotics using Universal Robot Software Environment, Robotic Cell tasks examples and BUS remote control

- Main topics: Collaborative Robotics Process design, Siemens PLC fundamentals, Project Management. Case Study Projects.

reference program: <https://bit.ly/3j7hk4o>

Promoter/sales

Save The Children - Telethon

05/2018 - 09/2018

Promoting and sales activity for popular NGOs

- Team Leading, Team Coordination, Team Working, Marketing, Sales, Customer Communication

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SKILLS

Python, VB.NET, Java

Artificial Intelligence (TensorFlow)

MATLAB, OpenCV

Robotics Software (URSim, RobotStudio, HexSight, RoboDK)

ROS

OS (Linux, Windows)

Version Control (GIT)

Reliability

Adaptability and Flexibility

Team Working

ACADEMIC PROJECTS PORTFOLIO

Neural Network Classifier of COVID RX images (07/2020 - 09/2020)

- Topics: Fine Tuning of ResNet network to classify Positive/Negative patient RX images from large worldwide dataset (CNN, TensorFlow, Transfer Learning, Python)

Consensus Strategy for Platooning of Autonomous Vehicles (09/2020)

- Topics : Cruise velocity control, Safety Distance, Platoon of Autonomous vehicles, MATLAB/Simulink.

Visual/Force Control of Surgical Robot (Da Vinci)

- Topics: Developing the Inverse Kinematics and Visual Servoing Control of a Surgical Medical Robot. (Robotics Kinematics, MATLAB, VREP)

Simulation of a One-Legged Hopping Robot

- Topics : Underactuated Robots, (MATLAB/Simulink)

Simulation of a Industrial Brewing Process

- Topics: PLC, Industry Process Simulation, Events management, (VB.NET, iFix, PLC)

Coding challenges : NextBattle, Pi Campus, Codemotion

- Topics: Logic and problem solving challenges (Python)

LANGUAGES

English



Spanish



INTERESTS

Green Technology

Electric Automotive

Guerrilla Marketing

Sport

Solo Traveling