

# MICHELE MARIA CICIOLLA

Software Engineer

# **REACH ME**

Mobile:

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#### Website:

https://micheleciciolla.github.io/

## Location:

Rome

#### **ABOUT ME**

I consider myself a genuine robotics and artificial intelligence enthusiast with a strong goal oriented thinking and team working attitude

My interests are Robotics, Computer Vision and Artificial Intelligence

#### UNIVERSITY

#### Università La Sapienza Roma

**Master** of Science in Artificial Intelligence and Robotics

- Sept. 2018 to May 2021
- Specialized in robotics, computer vision and deep learning
- Thesis in computer vision applied to industrial robotics for camera calibration

#### Università Roma Tre

**Bachelor** in Computer Science Engineering

- Sept. 2014 to March 2018
- Specialized in automation control and project management
- Thesis in mobile robotics navigation and mapping (SLAM)

# **ACADEMIC PROJECTS**

**Detection** of COVID patients based on their X-Ray images using a neural network

· Python, TensorFlow, CNN

Design of a **controller** for a platoon of autonomous vehicles

MATLAB

Implementation of a **SLAM** algorithm for a simulated robot geared with a range sensor

· Octave, ICP

# **LANGUAGES**

Italian: NATIVE Spanish: BEGINNER

English: FLUENT

# **WORK EXPERIENCE**

#### **Software Engineer for Machine Control**

Leica Geosystems October 2022 - now

- Developing and maintaining software for paving machines
- C++, Qt

# Mobile Robotics and Computer Vision Engineer

<u>Pixies UrbanLab</u> - Startup September 2021 - September 2022

- Developing and maintaining software of an autonomous sweeper for outdoor cleaning
- ROS, C++, Python, OpenCV, Docker

# Intern - Robotics Software Engineer

ICAPGROUP January 2021 - May 2021

 Master thesis for autonomous camera calibration in industrial robotics

# **SKILLS**

#### **Coding Languages:**

C++, Python

## Frameworks/Systems:

Qt, ROS, OpenCV, Docker, GIT, Matlab/Simulink, TensorFlow

#### **Soft Skills:**

Decision Making, Team Player

#### **COURSES**

#### **ETH Robotics Summer School**

ETH University Zürich (Switzerland) 07/2021

- Tutorials and hands-on sessions on a real mobile robot
- SLAM, Path planning, Mission planning, State Estimation
- ROS, C++

# Advanced training course in collaborative robotics

Experis Academy (Manpower) 09-11/2020

 Universal Robots programming software kit using RoboDK and URSIM

#### PRIVACY CONSENT

I hereby authorize the use of my personal data in accordance to the GDPR 679/2016 "European regulation on the protection of personal data"