Modelation and simulation

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Demonstration examples

- Model freefall body in a vacuum
 - □ From physics we know:

$$a = g = konst.$$
 $v = a \cdot t$ $s = v \cdot t$

$$v = a \cdot t$$

$$s = v \cdot t$$

Prefer:

$$a = g = \frac{d v(t)}{dt} \qquad v(t) = -\frac{d h(t)}{dt}$$

differential equations - the description of the model

v

Demonstration examples - freefall

- DE Solutions: $a = g = \frac{dv(t)}{dt}$ $v(t) = -\frac{dh(t)}{dt}$
 - Analytical :

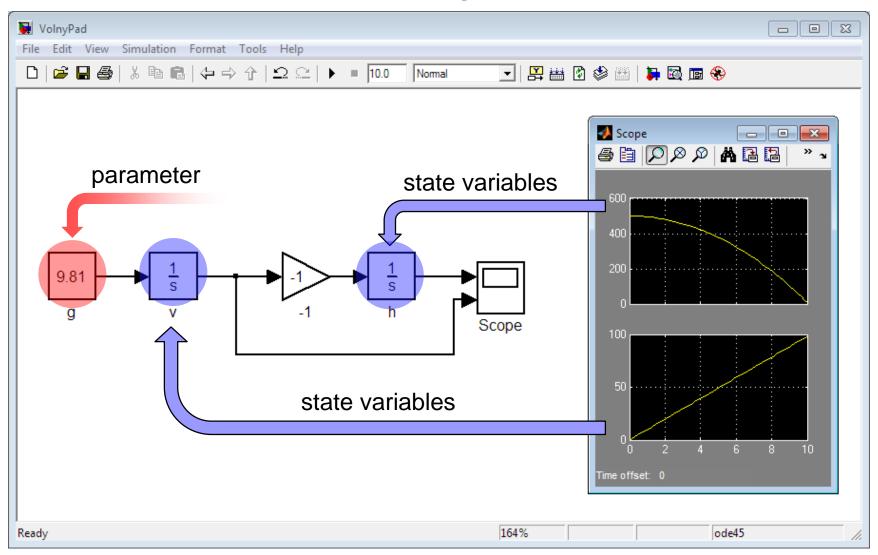
$$v(t) = v_0 + \int_0^t g \, dt = \underbrace{v_0 + gt}_{}$$

$$h(t) = h_0 - \int_0^t v(t) dt = h_0 - \int_0^t (v_0 + gt) dt =$$

$$h_0 - \int_0^t v_0 dt - \int_0^t gt dt = h_0 - v_0 t - \frac{gt^2}{2}$$

Numerical example using Simulink

Demonstration examples - freefall





Practice 1 - task

- The mathematical model freefall skydiver
 - □ In Simulink implement mathematical model freefall skydiver
 - Analytically determine the relationship of the limit rate of fall, the rate at which a skydiver due to air resistance already not accelerate
 - □ The parameter (s) to specify the drag so that the speed limit was 180 km / h (with units!)
 - Using simulation to verify its calculation
 - From the simulation results, estimate the time and covered distance than a skydiver reaches 95% of the speed limit

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Practice 1 – freefall skydiver

- Gravitational force and the aerodynamic drag force act on skydriver
 - \Box The gravitational force F_q is considered constant

$$|F_g| = mg$$

 \square Size of the resistive force F_o is a function of velocity

$$\left| F_o \right| = \frac{1}{2} C S \rho v^2$$

The forces are oppositely oriented, the resultant F is oriented to the ground $|F| = |F_g| - |F_o| = mg - \frac{1}{2} CS\rho v^2$



Practice 1 – freefall skydiver

□ 2laws of motion says:

$$F = am \implies a = \frac{F}{m}$$

□ therefore

$$a(t) = \frac{mg - \frac{1}{2}CS\rho v(t)^2}{m} = g - \frac{1}{2}\frac{CS\rho}{m}v(t)^2 = \frac{dv(t)}{dt}$$

□ therefore

1. DE of model
$$\frac{dv(t)}{dt} = g - kv(t)^2$$



Practice 1 – freefall skydiver

☐ Still applies 2. DE:

$$\frac{d h(t)}{dt} = -v(t)$$
2. DE of model

 When you reach the speed limit are active forces in equilibrium - magnitude of the velocity does not change.
 Its derivative is thus zero.

applies
$$\frac{d v(t)}{dt} = 0 \text{ m.s}^{-2}$$



Practice 1– desired output

- Model file *. mdl with correctly described blocks
- Short paper in *. pdf containing
 - □ The differential equation model
 - ☐ General calculation of the parameter of drag, substituting into equation and numerical result with units
 - □ Table of all model parameters with columns: symbol, importance, value, unit
 - □ Table of all state variables of the model with columns: symbol, meaning the initial value, unit
 - □ Graphical representation of the simulation results with marked estimates of time and distance while achieving a 95% limit rate