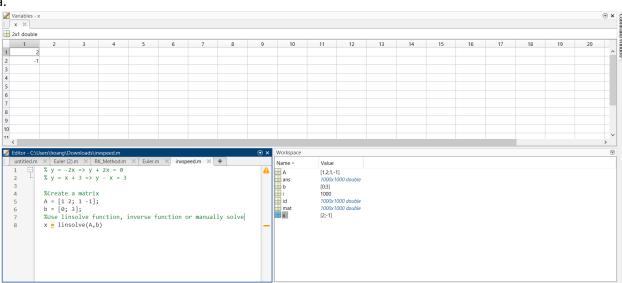
Michael Dang - 16257750

MATH434

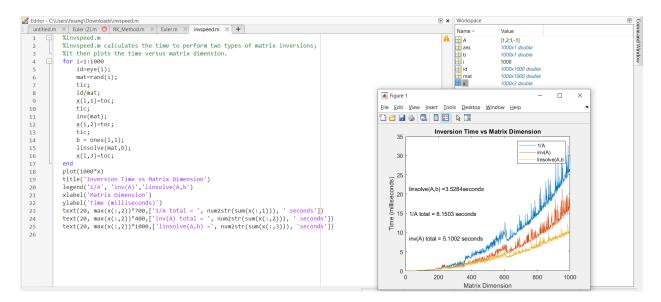
Lab2

```
1.
           A
ans
b
i
                                                                                                                                                                                                                        [1,2;1,-1]
                                                                                                                                                                                                                       1000x1000 double
[0;3]
1000
                                                                                                                                                                                                                        1000x1000 double
                                                                                                                                                                                                                        1000x1000 double
1000x2 double
                             x(i,1)=toc;
tic;
inv(mat);
x(i,2)=toc;
                                                                                                                                                           Figure 1
                                                                                                                                                                                                                                          П
                                                                                                                                                           File Edit View Insert Tools Desktop Window Help
                                                                                                                                                           end
plot(1900*x)
title('Inversion Time vs Matrix Dimension')
legend('1/A', 'inv(A)')
xlabel('Matrix Dimension')
ylabel('Time (milliseconds)')
text(20, max(x(:,2))*700,['1/A total = ', num2str(sum(x(:,1))), ' seconds'])
text(20, max(x(:,2))*400,['inv(A) total = ', num2str(sum(x(:,2))), ' seconds'])
                                                                                                                                                                                    Inversion Time vs Matrix Dimension
                                                                                                                                                                  35
                                                                                                                                                                   30
                                                                                                                                                              30 Lime (milliseconds)
                                                                                                                                                                         1/A total = 8.9978 seconds
                                                                                                                                                                   10
                                                                                                                                                                        inv(A) total = 6.1206 seconds
                                                                                                                                                                                  200
                                                                                                                                                                                                 400
                                                                                                                                                                                                                600
                                                                                                                                                                                                                               800
                                                                                                                                                                                                                                             1000
```

2. a.



b.



3. a.

```
Z Editor - C:\Users\hoang\Downloads\lot.m
RK_Method.m × Euler.m × lot.m × +
        function lot(N, R)
                                                                                      Your lottery numbers are: 80 248 253
        %lot picks lottery numbers. N numbers from 1 to R are chosen.
                                                                                      >> lot(3,600)
       if (N <= R & R > 0)
tot = randperm(R);
                                                                                      Your lottery numbers are: 49 105 157
 4
                                                                                      >> lot(3,600)
        % returns a row vector containing a random permutation of the in
                                                                                     Your lottery numbers are: 315 580 310
       %repeating %elements.
                                                                                    >> lot(3000,600)
 6
            x = tot(1:N);
            disp(['Your lottery numbers are: ', num2str(x)])
```

b.

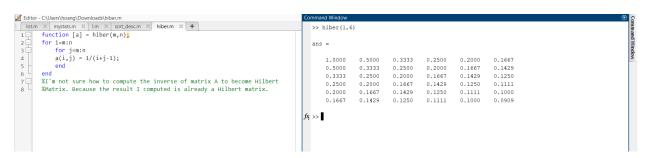
```
Z Editor - C:\Users\hoang\Downloads\mystats.m
RK_Method.m × Euler.m × lot.m × mystats.m × +
                                                                                                           >> x = rand(1,300);
          function [avg, med] = mystats(x)
                                                                                                           >> mystats(x)
         n = length(x);
avg = mymean(x,n);
med = mymedian(x,n);
         end
                                                                                                               0.4658
 6 📮
         function a = mymean(v,n)
 7
8
9
         \ensuremath{\text{\%}} MYMEAN Example of a local function.
                                                                                                       fx >>
         a = sum(v)/n;
         function m = mymedian(v,n)
% MYMEDIAN Another example of a local function.
 10 🗆
 11
         w = sort(v);
if rem(n,2) == 1
 12
 13
 14
              m = w((n + 1)/2);
         else
 15
             m = (w(n/2) + w(n/2 + 1))/2;
16
17
         end
18
         end
```

```
Z Editor - C:\Users\hoang\Downloads\l.m
       lot.m × mystats.m × l.m × +

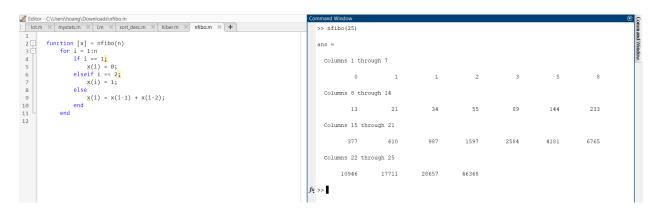
1 %matrix A and vector b
4.
                 function [x1, x2] = l(A,b)
                                                                                                                  A =
                x1 = A \setminus b;
                x2 = inv(A)*b;
                                                                                                                        2
                 end
                                                                                                                                      0
                                                                                                                        4
                                                                                                                              -1
                                                                                                                  >> h
                                                                                                                        2
                                                                                                                  >> 1(A,b)
                                                                                                                        1
                                                                                                               fx >>
```

```
Editor - C:\Users\hoang\Downloads\sort_desc.m
5.
      >> data = [9 11 3 0 -7 5];
                                                                                                    >> sort desc(data)
               % sort_desc Sort in descending order.
               \% res = sort_desc(data) sorts the elements of the vector
                                                                                                    ans =
              % data in descending order. [res,index] = sort(data) also % returns an index vector index, i.e., res = data(index).
                                                                                                                   5 3
                                                                                                        11
                                                                                                               9
                                                                                                                                  0
               % When data is complex, the elements are sorted by
               % abs(data).
                                                                                                 fx >>
               % check usage
              error(nargchk(1,1,nargin));
% sort data in ascending order using the MATLAB built-in
       9
       10
               % function sort
               [res,index] = sort(data);
       12
               % reorder the data
       13
       14
               [m,n] = size(data);
               if (m <= n)
  res = fliplr(res);</pre>
       15
       16
       17
                 index = fliplr(index);
               else
       18
       19
                res = flipud(res);
       20
                index = flipud(index);
       21
               end
```

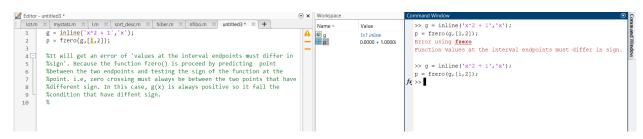
6.



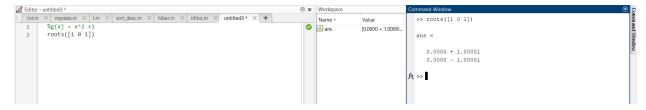
7.



8.



9.



10.

This computation of eigenvalues in MATLAB can determine as the root() function for polynomial. As the professor demonstrated in class, the result shows the same. i.e, we can use root() to find the eigenvalues of the matrix as long as we can get the characteristic equation.

11.

