Systemy Kontrolno-Pomiarowe laboratorium

Raport z projektu Stacja pogodowa – pomiar temperatury oraz wilgotności

Projekt wykonali: Michał Woźniak Jakub Pisarczyk

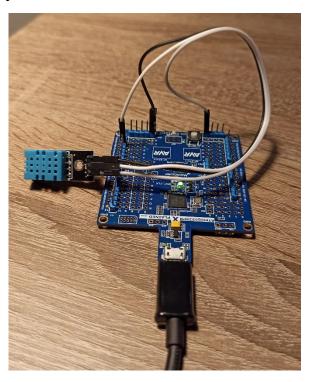
Prowadzący: dr inż. Jakub Sorocki

1. Założenia projektu

Pomiar temperatury oraz poziomu wilgotności przy użyciu czujnika DTH11, zaprogramowanie płytki ATmega328PB do komunikacji z czujnikiem oraz komputerem przy użyciu programu Microchip Studio, zaprojektowanie interfejsu graficznego do odczytu danych przy użyciu programu LabVIEW.

2. Udokumentowanie poszczególnych etapów

a) Połączenie fizyczne



Rys 1. Czujnik DHT11 podpięty do płytki ATmega328PB

Czujnik podpięty do zasilania 5V, GND oraz wyjście danych OUT do pinu PD2.

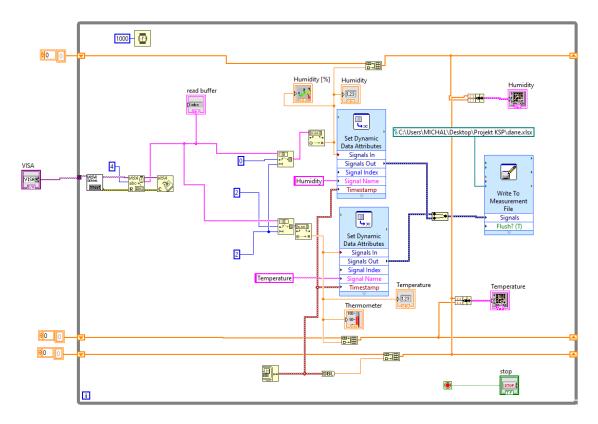
b) Kod obsługujący czujnik DHT11

```
#define F_CPU 16000000UL // Clock Speed ATmega328PB 16 MHz
#include <avr/io.h>
#include <stdlib.h>
#include <util/delay.h>
#include "usart.h"
#define BAUD 9600
#define MYUBRR F_CPU/16/BAUD-1
                                  // PIN PD2
#define DHT11 PIN PORTD2
uint8_t c=0,I_RH,D_RH,I_Temp,D_Temp,CheckSum;
void Request()
                                          /* MCU wysyła impuls startowy */
{
        DDRD |= (1<<DHT11_PIN);</pre>
        PORTD &= ~(1<<DHT11_PIN);
                                          /* Ustawienie pinu na stan niski*/
                                          /* czeka 18ms */
        _delay_ms(18);
        PORTD |= (1<<DHT11 PIN); /* ustawia pin na stan wysoki */
}
void Response()
                                          /* gdy otrzyma odpowiedź z czujnika DHT11 */
        DDRD &= ~(1<<DHT11_PIN);
        while(PIND & (1<<DHT11 PIN));</pre>
        while((PIND & (1<<DHT11_PIN))==0);</pre>
        while(PIND & (1<<DHT11_PIN));</pre>
}
uint8_t Receive_data()
                                          /* odbiór danych */
        for (int q=0; q<8; q++)</pre>
        {
                 while((PIND & (1<<DHT11 PIN)) == 0); /* sprawdzenie stanu odebranego bitu danych */</pre>
                 _deLay_us(30);
                if(PIND & (1<<DHT11_PIN))/* jeśli impuls służszy niż 30us to stan logiczny "0" */</pre>
                 c = (c << 1) | (0x01);
                                          /* w innym wypadku stan logiczny "1" */
                 else
                 c = (c << 1);
                 while(PIND & (1<<DHT11_PIN));</pre>
        return c;
}
int main(void)
{
        USART_Init(MYUBRR);
        char data[5];
        _delay_ms(1000); //stabilizacja zasilania
        while(1)
        {
                                          /* impuls startowy */
                 Request();
                 Response();
                                          /* otrzymanie odpowiedzi */
                                         /* zapisuje pierwsze 8 bitów w I_RH */
                 I_RH=Receive_data();
                                         /* zapisuje kolejne 8 bitów w D_RH */
                 D_RH=Receive_data();
                I_Temp=Receive_data(); /* zapisuje kolejne 8 bitów w I_Temp */
D_Temp=Receive_data(); /* zapisuje kolejne 8 bitów w D_Temp */
                 CheckSum=Receive_data();/* zapisuje kolejne 8 bitów w CheckSum */
                }
                 else
                 {
                         itoa(I_RH,data,10);
                         USART_PutS(data);
                         itoa(I_Temp,data,10);
                         USART PutS(data);
                 _delay_ms(1000);
        }
}
```

c) Kod definiujący funkcje połączenie USART

```
#include <avr/io.h>
#include <stdlib.h>
#include <util/delay.h>
#include "usart.h"
void USART_Init( unsigned int ubrr) // Inicjalizacja USART
      /* Ustawia bitrate */
      UBRR0H = (unsigned char)(ubrr>>8);
      UBRROL = (unsigned char)ubrr;
      /* odbieranie i wysyłanie */
      UCSR0B = (1 << RXEN0) | (1 << TXEN0);
      /* format ramki 8 bitów danych i 1 bit stopu */
      UCSROC = (3 < UCSZOO);
}
void USART_PutC( char data ) // ZNAK CHAR
      /* oczekiwanie na dane */
      while ( !( UCSR0A & (1<<UDRE0)) );</pre>
      /* wkłada dane do bufora */
      UDR0 = data;
}
void USART_PutS( char * s) // STRING - CIAG CHAR'ÓW
{
      while( *s ) USART_PutC( *s++ );,
}
unsigned char USART_Receive( void )
      /* oczekiwanie na dane */
      while ( !(UCSR0A & (1<<RXC0)) );</pre>
      /* otrzymuje i zwraca dane z bufora*/
      return UDR0;
}
```

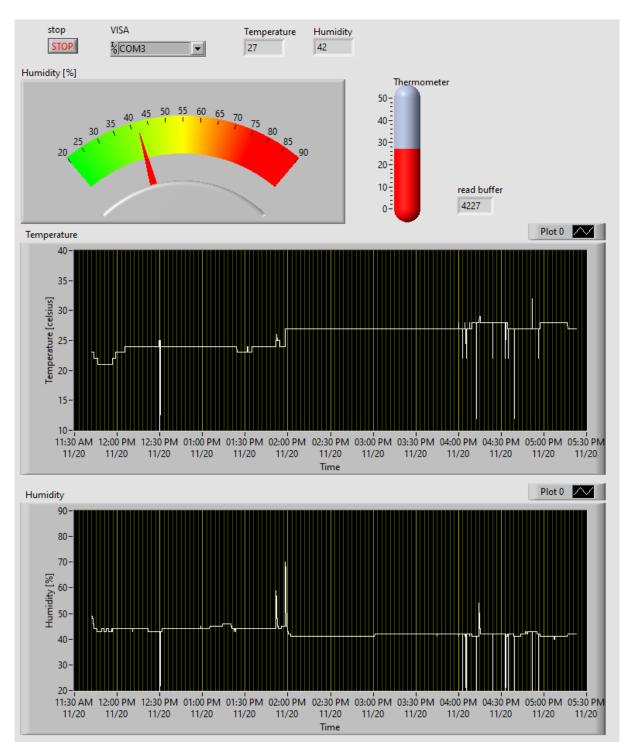
d) Diagram blokowy projektu stacji pogodowej w LabVIEW



Rys 2. Diagram blokowy

Układ otrzymuje dane z płytki na porcie COM3, zlicza 4 bity, wysyła dane w postaci "string" do kolejnych modułów. String dzielony jest po 2 znaki na część reprezentującą dane temperaturowe w postaci jednostki stopni Celsjusza, oraz procentowej wartości wilgotności w powietrzu. Następnie wartości te zamieniane są na zmienne liczbowe. Wartości w takiej postaci wyświetlane są na wykresie oraz w okienku w postaci cyfr. Dodatkowy etap to połączenie wyników w 2 wymiarowe tablice razem z wartością czasu rzeczywistego, oraz wyświetlenie na wykresach. Dane te są także zapisywane do pliku .xlsx który możemy otworzyć za pomocą np. Excela. Program pracuje w nieskończonej pętli while, konfigurowanej przez możliwość zmiany czasu ponownego wykonania pętli, podanego w ms.

e) Interfejs graficzny projektu stacji pogodowej w LabVIEW



Rys 3. Interfejs graficzny

(Podczas 6 godzinnego pomiaru, skoki pomiarowe wywołane przez ingerencje człowieka w celu zmiany właściwości środowiska pogodowego w jakim znajdował się czujnik)

f) Zapis odczytanych pomiarów do pliku .xlsx

1 Time Temperature Humidity 2 20.11.2021 19:54:20,204 28 42 3 20.11.2021 19:54:21,441 28 42 4 20.11.2021 19:54:22,720 28 42 5 20.11.2021 19:54:23,992 28 42 6 20.11.2021 19:54:25,330 28 42 7 20.11.2021 19:54:26,604 28 42 8 20.11.2021 19:54:27,878 28 42 9 20.11.2021 19:54:30,471 28 47 10 20.11.2021 19:54:30,471 28 47 11 20.11.2021 19:54:31,831 28 50 12 20.11.2021 19:54:33,147 28 53 13 20.11.2021 19:54:33,147 28 57 14 20.11.2021 19:54:37,036 28 63 15 20.11.2021 19:54:38,326 28 63 16 20.11.2021 19:54:39,618 28 68 18 20.11.2021 19:54:40,917 28 70 19 20.11.2021 19:54:43,568 29 72 20	1	Α	В	С
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21 20.11.2021 19:54:44,858 29 75 22 20.11.2021 19:54:46,189 29 76 23 20.11.2021 19:54:47,485 30 76 24 20.11.2021 19:54:48,782 30 78 25 20.11.2021 19:54:50,071 30 79 26 20.11.2021 19:54:51,364 30 79 27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	19	20.11.2021 19:54:42,250	29	72
22 20.11.2021 19:54:46,189 29 76 23 20.11.2021 19:54:47,485 30 76 24 20.11.2021 19:54:48,782 30 78 25 20.11.2021 19:54:50,071 30 79 26 20.11.2021 19:54:51,364 30 79 27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	20	20.11.2021 19:54:43,568	29	72
23 20.11.2021 19:54:47,485 30 76 24 20.11.2021 19:54:48,782 30 78 25 20.11.2021 19:54:50,071 30 79 26 20.11.2021 19:54:51,364 30 79 27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	21	20.11.2021 19:54:44,858	29	75
24 20.11.2021 19:54:48,782 30 78 25 20.11.2021 19:54:50,071 30 79 26 20.11.2021 19:54:51,364 30 79 27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	22	20.11.2021 19:54:46,189	29	76
25 20.11.2021 19:54:50,071 30 79 26 20.11.2021 19:54:51,364 30 79 27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	23	20.11.2021 19:54:47,485	30	76
26 20.11.2021 19:54:51,364 30 79 27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	24	20.11.2021 19:54:48,782	30	78
27 20.11.2021 19:54:52,649 30 81 28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	25	20.11.2021 19:54:50,071	30	79
28 20.11.2021 19:54:53,949 31 82 29 20.11.2021 19:54:55,258 31 82	26	20.11.2021 19:54:51,364	30	79
29 20.11.2021 19:54:55,258 31 82	27	20.11.2021 19:54:52,649	30	81
-	28	20.11.2021 19:54:53,949	31	82
30 20.11.2021 19:54:56,580 31 81	29	20.11.2021 19:54:55,258	31	82
	30	20.11.2021 19:54:56,580	31	81

Rys 4. Zapis danych do pliku

Trzy kolumny zawierające aktualny czas wykonania pomiaru, temperaturę oraz poziom wilgotności.