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Prn:2020BTECS00090

SUB:DAA

Ass no:9

Title of assignment: Dynamic Programming

Q1. From a given vertex in a weighted connected graph, Implement shortest path finding

Bellman-Ford algorithm.

- Algorithm: (Pseudocode)

.....

STEP 1 : distance[], previous[], V->vertex , G->Graph

STEP 2 : for each vertex V in G

 distance[V] <- infinite

 previous[V] <- NULL

STEP 3 : distance[S] <- 0

STEP 4 : for each vertex V in G

 for each edge (U,V) in G

 tempDistance <- distance[U] + edge_weight(U, V)

 if tempDistance < distance[V]

 distance[V] <- tempDistance

 previous[V] <- U

STEP 5 : for each edge (U,V) in G

 If distance[U] + edge_weight(U, V) < distance[V]

 return Negative Cycle Exists

```
return distance[], previous[].
```

- **Code snapshots of implementation**

```
• #include <bits/stdc++.h>
• using namespace std;
• #define pii pair<int, int>
• const int N = 1000005;
• int n, m;
•
• struct node
• {
•     int u;
•     int v;
•     int wt;
•     node(int first, int second, int weight)
•     {
•         u = first;
•         v = second;
•         wt = weight;
•     }
• };
•
• signed main()
• {
•     ios_base::sync_with_stdio(false);
•     cin.tie(NULL);
•
•     #ifndef ONLINE_JUDGE
•         freopen("C:\\Users\\Teknath\\Desktop\\code\\input.txt",
"r", stdin);
•         freopen("C:\\Users\\Teknath\\Desktop\\code\\output.txt",
"w", stdout);
•     #endif
•     vector<node> edges;
•     vector<int> dis(N, INT_MAX);
•     cin >> n >> m;
•     for (int i = 1; i <= m; i++)
•     {
•         int u, v, wt;
```

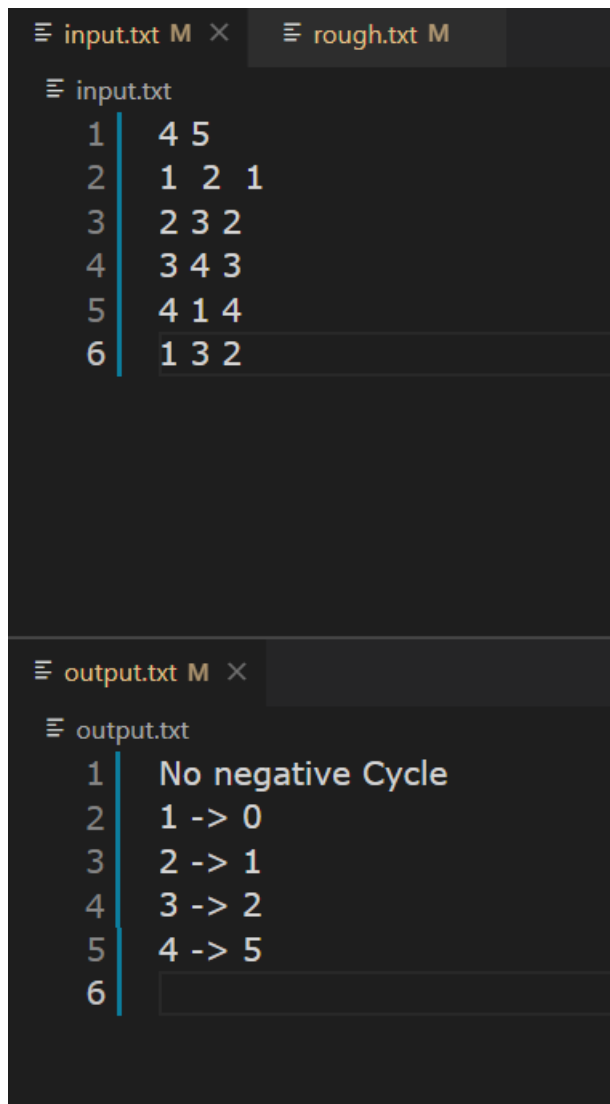
```
•         cin >> u >> v >> wt;
•         edges.push_back(node(u, v, wt));
•     }
•     for(int i=1;i<=n;i++)
•         dis[i]=INT_MAX;
•
•     //let source is 1
•     dis[1] = 0;
•
•     //traverse for n-1 time
•     for (int i = 1; i <= n - 1; i++)
•     {
•         for (auto it : edges)
•         {
•             if (dis[it.u] + it.wt < dis[it.v])
•                 dis[it.v] = dis[it.u] + it.wt;
•         }
•     }
•
•     int fl = 0;
•     for (auto it : edges)
•     {
•         if (dis[it.u] + it.wt < dis[it.v])
•         {
•             cout << "Negative Cycle is here \n";
•             fl = 1;
•         }
•     }
•
•     if (fl == 0)
•     {
•         cout << "No negative Cycle \n";
•         for (int i = 1; i <= n; i++)
•         {
•             cout << i << " -> " << dis[i] << '\n';
•         }
•     }
• }
```

.....

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OUTPUTS :



The screenshot shows a code editor with two tabs: 'input.txt' and 'rough.txt'. The 'input.txt' tab is active and contains the following text:

```
1 4 5
2 1 2 1
3 2 3 2
4 3 4 3
5 4 1 4
6 1 3 2
```

Below this, the 'output.txt' tab is visible and contains the following text:

```
1 No negative Cycle
2 1 -> 0
3 2 -> 1
4 3 -> 2
5 4 -> 5
6
```

.....

- Complexity of proposed algorithm (Time & Space)

.....

Space Complexity :

As here I have used minimum priority queue so fetching is done in $\log V$ time and we are doing for all Edges E so time complexity is $O(V \log V)$

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Time Complexity :

Only distance array is extra space for all vertex So space complexity is $O(V)$

.....

- **Your comment (How your solution is optimal?)**

.....

In this algorithm as we have relax $n-1$ time each node so at n th relaxation we got our result , thus it optimal than Dijkstra algorithm.

.....

Q) Show that Dijkstra's algorithm doesn't work for above graph

Ans-> As applying Dijkstra algorithm we end up with a infinity while loop as shown in pic

Because priority queue never gets empty

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```
≡ input.txt M ×  ≡ rough.txt M
≡ input.txt
1 5 10
2 1 2 6
3 2 3 5
4 3 2 -2
5 4 3 7
6 5 4 9
7 5 3 -3
8 2 4 -4
9 4 1 2
10 2 5 8

≡ output.txt M ×
≡ output.txt
26843541 67108852
26843542 67108854
26843543 67108857
26843544 67108859
26843545 67108862
26843546 67108864
26843547
```

Given a weighted, directed graph $G = (V, E)$ with no negative-weight cycles, let m be the maximum over all vertices $v \in V$ of the minimum number of edges in a shortest path from the source s to v . (Here, the shortest path is by weight, not the number of edges.) Suggest a simple change to the Bellman-Ford algorithm that allows it to terminate in $m + 1$ passes, even if m is not known in advance.

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ANS ->

We can simply implement this optimization of **BELLMAN-FORD** algorithm by remembering if v was relaxed or not.

If v is relaxed then we wait to see if v was updated (which means being relaxed again).

If v was not updated, then we would stop
