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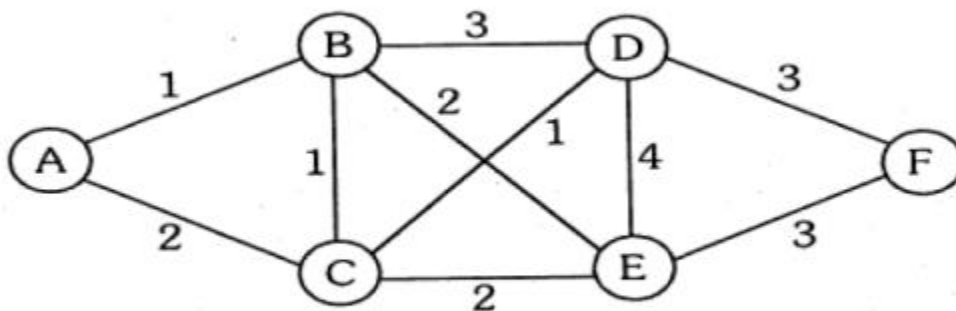
Prn: 2020BTECS00090

Title: Greedy method

Sub: DAA

Ass no: 8

- 1) From a given vertex in a weighted connected graph, implement shortest path finding Dijkstra's algorithm.



- Q) Show that Dijkstra's algorithm doesn't work for graphs with negative weight edges
Q) Modify the Dijkstra's algorithm to find shortest path.

1. Algorithm: (Pseudocode)

.....

STEP 1 : initialize a distance array as positive infinity to all the vertices

STEP 2 : put the distance from source to itself as 0 $dis[source]=0$

STEP 3 : take a min heap and insert $\{src, 0\}$

STEP 4: LOOP while heap is not empty

 Temp \leftarrow heap top

 Pop top of heap

 Traverse each neighbour of temp in graph

 Check if $(dis[Child] > (wt + dis[node]))$

 Then relax this node and insert into the min heap

STEP 5 : Print distance array .

→Code Implementation:

```
#include <bits/stdc++.h>
using namespace std;
#define N 100005
#define pii pair<int, int>

// adjacency list
vector<pii> adj[N];
// distance array
int dis[N];
// nodes and edges
int n, m;

// Dijkstra's algorithm for shortest path
void bfs(int src)
{
    // min heap
    priority_queue<pii, vector<pii>, greater<pii>> pq;
    pq.push({0, src});

    // distance from source to itself
    dis[src] = 0;

    while (!pq.empty())
    {
        pii temp = pq.top();
        pq.pop();
        int node = temp.second;
        int wt = temp.first;

        // traversing each neighbour of node temp
        for (auto child : adj[node])
        {
            int nChild = child.first;
            int nwt = child.second;

            // relaxing nodes

            if (dis[nChild] > (nwt + dis[node]))
            {
                dis[nChild] = nwt + dis[node];
                pq.push({dis[nChild], nChild});
            }
        }
    }
}
```

```

    }
    for (int i = 1; i <= n; i++)
        cout << "A"
            << " to " << char(i + 64) << " -> " << dis[i] << "\n";
}

signed main()
{
    cout << "Enter the number of nodes and the number of edges: ";

    cin >> n >> m;

    for (int i = 0; i < N; i++)
    {
        adj[i].clear();
        dis[i] = INT_MAX;
    }
    cout << "Edges " << endl;
    // storing graph
    for (int i = 1; i <= m; i++)
    {
        char a, b;
        cin >> a >> b;
        int u = a - 64, v = b - 64, wt;
        cin >> wt;
        adj[u].push_back({v, wt});
        adj[v].push_back({u, wt});
    }
    bfs(1);
}

```

OUTPUT:→

```

PS C:\vis-clg+ass+all\DAA\All_assignments\ass8> cd "c:\vis-
clg+ass+all\DAA\All_assignments\ass8\" ; if ($?) { g++ q1.cpp -o q1 } ; if ($?) {
.\q1 }

```

Enter the number of nodes and the number of edges: 6 10

Edges

A B 1

A C 2

B D 3

B E 2

B C 1

C E 2

D E 4

```

C D 1
D F 3
E F 3
A to A -> 0
A to B -> 1
A to C -> 2
A to D -> 3
A to E -> 3
A to F -> 6
-----

```

Q2:Ans→

For negative cyclic graph while loop went in infinite loop as due to negative cycle value from node a to b is reducing continuously so here Dijkstra algorithm fails for negative cyclic graph.

```

PS C:\vis-clg+ass+all\DAA\All_assignments\ass8> cd "c:\vis-clg+ass+all\DAA\All_assignments\ass8\"
Enter the number of nodes and the number of edges: 4 4
Edges
A B 5
B C -6
C D 2
D A 8

```

Here on above of -ve weight this algorithm is Stucked.

Q3:Ans→

If there is no negative cycle then it is Working properly:

```

PS C:\vis-clg+ass+all\DAA\All_assignments\ass8> cd "c:\vis-clg+ass+all\DAA\All_assignments\ass8\" ; if ($?) { g++ q1.cpp -o q1 } ; if ($?) { .\q1 }
Enter the number of nodes and the number of edges: 4 4
Edges
A B 5
B C 2
C D 1
D A 3

```

```
A to A -> 0
A to B -> 5
A to C -> 4
A to D -> 3
PS C:\vis-clg+ass+all\DAA\All_assignments\ass8>
```

2. Complexity of proposed algorithm (Time & Space)

Space Complexity :

As here I have used minimum priority queue so fetching is done in $\log V$ time and we are doing for all Edges E so time complexity is $O(E \log V)$

Time Complexity :

Only distance array is extra space for all vertex So space complexity is $O(V)$.

3. Your comment (How your solution is optimal?)

In first naive implementation where complexity is $O(V^2)$ but after using min heap we reduced time complexity to $O(E \log V)$.
