Lecture Notes Statistic for Astronomy

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1 Statistics basics

1.1 Cox's rules

The first rule states that the probability of something happening, let's call the event X, plus that of X not happening is one:

$$P(X) + P(\bar{X}) = 1 \tag{1}$$

The second rule (the product rule) states that the probability of events X and Y happening is given by:

$$P(X, Y) = P(X|Y) \cdot P(Y) \tag{2}$$

Where $P(X|Y)$ is the probability of X given Y happening.

1.2 Bayes' theorem

Bayes' theorem gives us the probability of the hypothesis H being true given the data D.

$$P(H|D) = \frac{P(D|H) \cdot P(H)}{P(D)} \tag{3}$$

Where $P(H|D)$ is called the posterior, $P(D|H)$ the likelihood, $P(H)$ the prior, and $P(D)$ the evidence.

1.3 Marginalization

Suppose you have a range of hypotheses $\{H_i\}$, where $i = 0, 1, 2, 3, \ldots$. Then

$$\sum_{i=0}^{N-1} P(H_i) = 1 \tag{4}$$

Then suppose we have some nuisance parameter X (quantities of no intrinsic interest, that sadly enter our analyses), then

$$\sum P(H_i, X) = \sum P(H_i|X) \cdot P(X) \tag{5}$$

$$= P(X) \sum P(H_i|X) \tag{6}$$

$$= P(X) \tag{7}$$

Which could also be written as

$$P(X) = \int_{-\infty}^{\infty} P(X, Y)\, dY \tag{8}$$

Suppose we now have some continuous case. Then we dive into the realm of probability density functions:

$$\text{pdf}(X, Y = y) = \lim_{\delta y \to 0} \frac{P(X, y \leq Y < y + \delta y)}{\delta y} \tag{9}$$

Then the probability that the value of Y lies between y_1 and y_2 is given by

$$P(X, y_1 \leq Y < y_2) = \int_{y_1}^{y_2} \text{pdf}(X, Y)\, dY \tag{10}$$

Where

$$\int_{-\infty}^{\infty} P(Y|X)\, dY = 1 \tag{11}$$