• Let h_j denote the increment in H_0 in interval j, that is,

$$h_j = H_0(s_j) - H_0(s_{j-1}), \quad j = 1, \ldots, J.$$

Assuming $H_0 \sim \mathcal{GP}(c_0H^*, c_0)$, we know h_j are **independent** and

$$h_j \stackrel{indep}{\sim} \mathsf{Gamma}(\alpha_{0,j} - \alpha_{0,j-1}, c_0),$$

where $\alpha_{0,j} = c_0 H^*(s_j)$.

• Consider the piecewise constant baseline hazard with $h_j = (s_j - s_{j-1}) (\lambda_j) \Rightarrow$ Observe a great similarity.

3,23 (ICS) Relationship to Partibellihedihood

· Cox model under a GP for Holt), GP (GH*, G)

lim.
$$\pi(\beta \mid data) \approx \frac{n}{17} \left[\frac{\exp(x \cdot \beta)}{\sum_{k \in R_{\beta}} \exp(x \cdot \beta)} \right]^{\gamma}$$
:

= Cox partial likelihood

3.24 Geamma process on baseline hazard ho(E)



More on Covariates

- **(fixed-time covariates)** Covariates may be constant (or fixed) values known at time 0.
 - e.g. initial disease status.

 $\chi(t)$

- (time-dependent covariates) Covariates may be time dependent, i.e., their value changes over time.
 - e.g. A covariate takes on the value 0 until some intermediate event occurs. It becomes 1 when the event occurs.
 - ** Observe time to the intermediate event is random.

more e.g. current disease status, serial blood pressure measurements.

More on Time-Dependent Covariates (KM p307):

Kalbfleisch and Prentice (1980) distinguish between two types of time-dependent covariates.

- ** **Type 1:** An <u>external</u> covariate is one that is <u>not directly</u> related to the failure mechanism.
 - O Case 1: Their value is completely under the control of the investigator.
 - e.g. a planned schedule of treatments under the control of the investigator
 - O Case 2: Ancillary time-dependent covariates are the output of a stochastic process external to the failure process
 - e.g. daily temperature as a predictor of survival from a heart attack

- ** **Type 2:** An *internal* covariate is a value over time generated by the individual under study. These covariats are measured only as long as the individual is still under observation.
 - e.g. blood pressure, and CD4 counts measured over the course of the study
 - \Rightarrow The distribution of theses covariates carries information about the failure process.

- What does the difference between the two types imply?
 - ** Type 1: Consider the survival probability

$$S(t \mid X(t)) = P(T > t \mid X(t))$$

$$= \exp\left(-\int_0^t h(u \mid X(t))du\right)$$

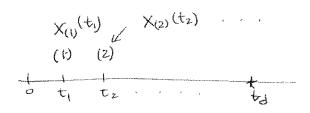
$$= \exp\left(-\int_0^t h_0(u)e^{\beta X(t)}du\right).$$

- ** **Type 2:** $S(t \mid X(t)) = 1$ provided that X(t) does not indicate that the individual has died (must be alive and at risk of failure).
 - ⇒ For internal covariates, the partial likelihood construction is still valid, but it is not possible to estimate the conditional survival function.

- Set-up for time-dependent covariates
 - ** T: time to some event
 - ** $\mathbf{X}(t) = (X_1(t), \dots, X_p(t))'$: a set of covariates at time t which may affect the survival distribution of $-\mathbf{y}$.

Assume:

- ** Given $X_i(t)$, the event and censoring time for subject i is independent.
- ** The value of $X_i(t)$ is known for any time at which the subject is under observation.
- ** The value of the covariate is known at an instant just prior to time t (that is, their values are predictable)



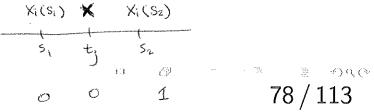
- Consider an extension of the proportional hazards model
 - ** The event times are distinct and $t_1 < \ldots < t_d$ denote the ordered event times.
 - ** $\mathbf{X}_{(j)}(t_j)$: the covariate associated with the individual whose failure time is t_j .
 - ** R_j : the risk set at time t_j
- The partial likelihood is

$$PL(\beta) = \prod_{j=1}^{d} \frac{\exp\left(\sum_{k=1}^{p} \beta_{k} X_{(j)k}(t_{j})\right)}{\sum_{\ell \in R_{j}} \exp\left(\sum_{k=1}^{p} \beta_{k} X_{\ell k}(t_{j})\right)}.$$

The partial likelihood is

$$PL(\beta) = \prod_{j=1}^{d} \frac{\exp\left(\sum_{k=1}^{p} \beta_{k} X_{(j)k}(t_{j})\right)}{\sum_{\ell \in R_{j}} \exp\left(\sum_{k=1}^{p} \beta_{k} X_{\ell k}(t_{j})\right)}.$$

- ** It is assumed that at each uncensored time t_j , the values of the covariates are observed for all the subjects who are at risk at time t_j .
- ** If X varies its value continuously over time and is measured only at certain time intervals.
 - $\Rightarrow X_i(t_i)$ may not be available.
- ** To overcome the issue, a possible approach is some interpolation between repeated measurements.



- * Revisit Acute Leukemia Example (Example 9.1 of KM)
 - Bone marrow transplants are a standard treatment for acute leukemia.
 - A total of 137 patients are treated.
 - ▶ Several risk factors were measured at the time of transplantation.
 - ▶ One of them is the disease group (fixed covariate); patients were grouped into three risk categories based on their status at the time of transplantation;
 - ► ALL (38 patients)
 - ▶ AML low-risk first remission (54 patients)
 - ▶ AML high-risk second remission or untreated first relapse (15 patients) or second or greater relapse or never in remission (30 patients).

- * Example 9.1 of KM (contd):
 - An individual is said to be disease-free at a given time after transplant if that individual is alive without the recurrence of leukemia.
 - ▶ The event indicator for disease-free survival is $\nu=1$ if the individual has died or has relapsed.
 - ► The days on study for a patient is the smaller of their relapse or death time.
 - ► There is an intermediate event that occurs during the transplant recovery process
 - ▶ Return of the patient's platelet count to a self-sustaining level (platelet recovery):

 $X_P(t) = 1$ if platelet recovery occurs prior to time t



- * Example 9.1 of KM (contd):
 - ▶ The time of the intermediate event, if it occurs, is random.
 - ► Goal:

 | Compariates (risk categories , poxp)
 - Examine the relationship of to the disease-free survival time
 - ▶ See how the effects of the fixed covariates change when their intermediate events occur.

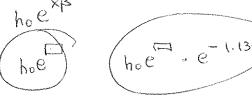
* X: fixed factors & Platelets

High

```
> mySurv <- Surv(t1, t2, d)
> myCPH <- coxph(mySurv ~ as.factor(g) +(j)
> myCPH
Call:
coxph(formula = mySurv ~ as.factor(g) + i)
               coef exp(coef) se(coef)
as.factor(g)2 -0.494
                        0.610
                                0.289 - 1.71 0.08773
1.450
                                0.269
                                      1.38 0.16743
             -1.130
                        0.323
                                0.329 -3.44 0.00059
Likelihood ratio test=22.6 on 3 df, p=4.82e-05
n= 256, number of events= 82
        having the platelet recovery
```

- * Interpretation of the time-dependent covariate coefficient.
- ☼ The estimate of coefficient of platelet recovery is -1.130, which suggests that a patient whose platelets has recovered at a given time has a better chance of survival than a patient who, at that time, has yet to have platelets recover.
- \circlearrowleft The relative risk of $\exp(-1.130) = 0.323$ suggests that the rate at which patients are relapsing or dying after their platelets recover is about one-third the rate prior to the time at which their platelets

recover.



 How about Bayesian approaches to accommodate time-dependent covariates? (ICS 10.1.3)

$$h(t \mid x(t)) = h_0(t)\psi(x(t)).$$

$$\Rightarrow S(t \mid x(t)) = \exp\left\{-\int_0^t h_0(u)\psi(x(u))du\right\}.$$

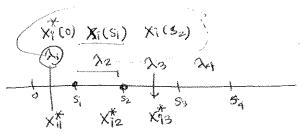
$$\Rightarrow f(t \mid x(t)) = h_0(t)\psi(x(t)) \exp\left\{-\int_0^t h_0(u)\psi(x(u))du\right\}.$$

- ** H_0 and ψ no longer separate into a product.
- ** Furthermore, H_0 does not even appear!

- What does this imply?
- ** We need to compute

$$A(t \mid x(t)) = \exp\left\{-\int_0^t h_0(u)\psi(x(u))du\right\}.$$

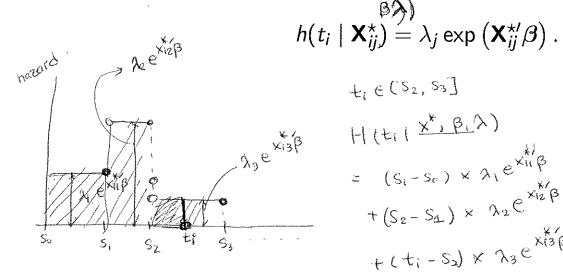
- ** In other words, each likelihood evaluation requires n numerical integrations.
- ** Sampling from the resulting posterior distribution is very challenging.



- Ex: Consider a Cox <u>piecewise exponential hazard</u> model (Bradshaw et al, 2010)
 - ** Construct a finite partition of the time axis, $0 < s_1 < s_2 < \ldots < s_J$ with $s_J > \max(y_i)$.
 - \Rightarrow we have the J intervals, $(0, s_1]$, $(s_1, s_2]$,..., $(s_{J-1}, s_J]$.
 - ** The measurement times for the covariate vector are assumed to fall at the boundaries of the intervals.
 - ** Each subject provides a series of longitudinal measurements for p covariates by \mathbf{X}_{ik} measured at time v_{ik} for $k=1,\ldots,K_i$, $K_i \geq 1$.
 - ** Thus, it is possible for a measurement to span multiple intervals.
 - e.g. if measurements on **X** are taken every 2 years but the intervals $(s_{j-1}, s_j]$ correspond to 1 year each. $\Rightarrow K_i \leq J$.



- Consider a Cox piecewise exponential hazard model (Bradshaw et al, 2010)
 - ** For subject i within interval j, we define \mathbf{X}_{ij}^* , which may represent
 - * the previous observation of the variable carried forward into the current interval, or,
 - * for continuous variables, an interpolated value between two observations.
 - ** The hazard function under the piecewise constant hazards model, for $t_i \in (s_{j-1}, s_j]$,



$$= \frac{\{(S_2, S_3)\}}{\{(t_1 \mid \frac{x^*, \beta_1 \lambda}{\lambda})\}}$$

$$= \frac{\{(S_1 - S_2) \times \lambda_1 e^{x_1^* \beta}\}}{\{(S_2 - S_1) \times \lambda_2 e^{x_1^* \beta}\}}$$

$$= \frac{\{(t_1 \mid \frac{x^*, \beta_1 \lambda}{\lambda})\}}{\{(t_1 \mid \frac{x^*, \beta_1 \lambda}{\lambda})\}} du$$

- Shall we write down the likelihood?
 - ** Define censoring indicator ν_i as

$$u_i = \begin{cases} \emptyset \text{ if subject } i \text{ failed (observed survival time),} \\ \mathbf{0} \text{ otherwise.} \end{cases}$$

** Define δ_{ij} as

$$\delta_{ij} = \begin{cases} \emptyset & \text{if subject } i \text{ failed or censored in interval } j \\ 0 & \text{otherwise} \end{cases}$$

** The likelihood function of (β, λ) is

$$\Sigma_{i} = \frac{J}{\Pi} \left(\lambda_{j} e^{x_{ij}^{*}\beta} \right)^{\sqrt{187}} \cdot \exp \left\{ -\sum_{j=1}^{N} S_{ij} \left(\sum_{S_{ij}}^{N} (S_{ij} - S_{j+1}) \lambda_{j} \cdot e^{x_{ij}^{*}\beta} \right) + (y_{i} - S_{3}) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{J}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right) \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i} \left(y_{i} - S_{3} \right) \lambda_{j} e^{x_{ij}^{*}\beta} \right\}$$

$$\Sigma_{i} = \frac{N}{\Pi} \left\{ \lambda_{i}$$

Possible Error?

of coefficients on the vector of covariates \mathbf{z}_{ij}^* . The density for the observed failure time y_i within interval j is then:

$$p_{y,j}(y_i|\mathbf{x}_{ij}^*,\mathbf{z}_{ij}^*,\beta_1,\beta_2,\lambda_j) = (\lambda_j \exp(\mathbf{x}_{ij}^{*'}\beta_1 + \mathbf{z}_{ij}^{*'}\beta_2))^{\delta_i} (\exp(-\Lambda_i(y_i)))^{\exp(\mathbf{x}_{ij}^{*'}\beta_2)^{\delta_i}}$$

for $y_i \in (s_{j-1}, s_j]$ with cumulative hazard function:

with cumulative hazard function:
$$\Lambda_{j}(y_{i}) = \left((y_{i} - s_{j-1})\lambda_{j} \exp(\mathbf{x}_{ij}^{*'}\beta_{1} + \mathbf{z}_{ij}^{*'}\beta_{2}) + \sum_{g=1}^{j-1} (s_{g} - s_{g-1})\lambda_{g} \exp(\mathbf{x}_{ig}^{*'}\beta_{1} + \mathbf{z}_{ig}^{*'}\beta_{2}) \right).$$

We further let $\lambda = (\lambda_1, ..., \lambda_J)'$ denote the $J \times 1$ vector of baseline hazards λ_j and let Δ_{ij} be an indicator of if subject i died or was censored in interval j (i.e. $y_i \in (s_{j-1}, s_j]$). The ith contribution to the complete data likelihood for the piecewise exponential model is then:

$$p_{y}(y_{i}|\mathbf{x}_{i},\mathbf{z}_{i},\beta_{1},\beta_{2},\lambda) = \prod_{j=1}^{J} (\lambda_{j} \exp(\mathbf{x}_{ij}^{*'}\beta_{1} + \mathbf{z}_{ij}^{*'}\beta_{2}))^{\Delta_{ij}\delta_{i}} \exp\{-\Delta_{ij}[\Lambda_{j}(y_{i})] \exp(\mathbf{x}_{ij}^{*'}\beta_{1} + \mathbf{z}_{ij}^{*'}\beta_{2})\}$$
(3)

where $\mathbf{x}_{ij}^* = \mathbf{x}_{ik}$ and $\mathbf{z}_{ij}^* = \mathbf{z}_{ik}$ with k and j such that $v_{ik} \leqslant s_{j-1} < v_{i,k+1}$. If we define $t_{ij} = \min(y_i, s_{j+1}) - s_j$ if $y_i \geqslant s_j$ and 0

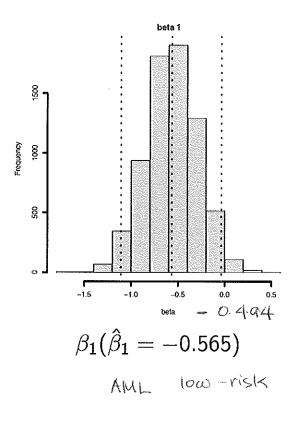
* Revisit Acute Leukemia Example (Example 9.1 of KM)

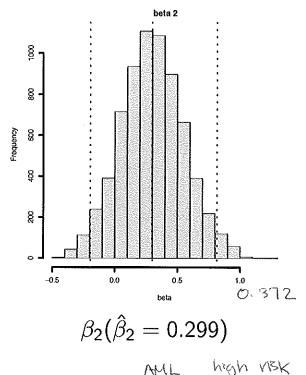
* X: fixed factors & Platelets

```
> ### set up hyperparameters
                                                       \beta \sim N(\bar{\beta}, \Sigma)
> hyper <- NULL
>
> ### Be \sim N_p(Beta_bar, Sig)
> ## fit the frequentist Cox to set hyperparamters
> hyper$Beta_bar <- c(-0.494, 0.372) ## estimate from frequentist cox
> hyper$Sig <- diag(2.0, p)
> hyper$Inv_Sig <- solve(hyper$Sig)</pre>
                                                       Aj ~ Gra (ao, 20)
> hyper$gam_bar <- -1.130 

> hyper$nu2 <- 2 \forall \sim N (\overline{\forall}, \overline{\forall}^2)
> hyper$nu2 <- 2
>
                                                     X:
> ## lambda_j \iid \Ga(a0, lam0)
> hyper$a0 <- 0.1
> hyper$lam0 <- 0.1
```

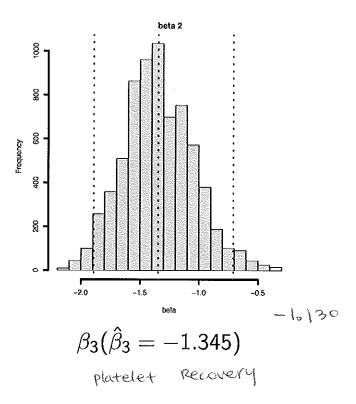
Piecewise Constant Hazard Model with a Time-Varying Covariate



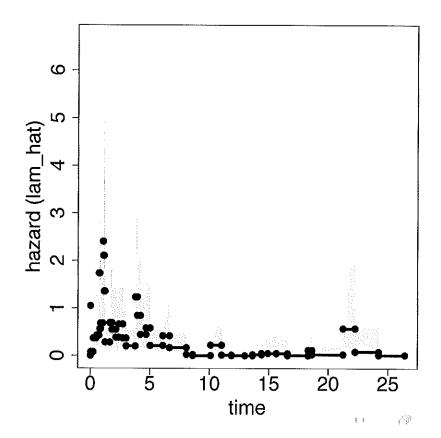


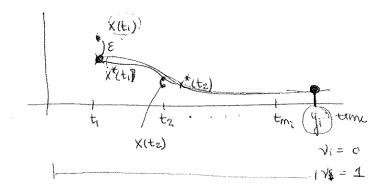
$$eta_2(\hat{eta}_2=0.299)$$
 ALL high VISK

Piecewise Constant Hazard Model with a Time-Varying Covariate



- Piecewise Constant Hazard Model with a Time-Varying Covariate
- \star Posterior mean of λ_j with their 95% credible intervals





$$Xij = \underbrace{X^{*}(tij) + Eij}_{\text{at function of time and } \overline{z}$$

Alternative Approach (ICS Chapter 7)

(f(yi | Xig,j=1,..,mi, Zi,

- (so far) We assume $\mathbf{X}_i(t)$ is known for any time at which the subject is under observation and treat $\mathbf{X}_i(t)$ as fixed variables.
- We treat $X_i(t)$ as observations, representing some function of the true covariate, $X^*(t)$ (referred as the *trajectory function*)
 - \circlearrowleft Often $\mathbf{X}_i(t)$ are incomplete or may be prone to measurement error.
 - Simply including raw measurements in the analysis leads to bias.
 - ⇒ Joint modeling of longitudinal and survival data!

- Health-related quality of life studies (Chapter 7.1.3)
 - ** A quality of life (QOL) survey instrument is typically administered to study participants at a number of prespecified time points during treatment and follow-up.
 - ** Why is it important to study? For a patient, quality of life is at times an even more important factor in treatment decisions than any modest survival benefit.
 - ⇒ Provides more useful information for the decision-making process of both patient and physician.

- Health-related quality of life studies (Chapter 7.1.3 contd)
 - ** Complete QOL data for patients at all of the specified collection times is frequently unavailable due to adverse events such as treatment toxicities or disease progression.
 - O Patients who are very ill when they report to the clinic may be less likely to complete the QOL instrument.
 - O Clinic personnel may feel that it is unethical to ask a patient to complete such a form when the patient feels so poorly.
 - ⇒ The missingness of QOL data is related to the patient's QOL at the assessment time.
 - ⇒ Such nonignorable missingness often leads to serious biases and must be taken into account at the time of analysis.

- Health-related quality of life studies (Chapter 7.1.3 contd)
 - ** Develop a joint model for longitudinal and survival data
 - The longitudinal measure is QOL.
 - The survival component of the model acts as a type of non-ignorable missing data mechanism.