

Alankar Kotwal

CONTACT INFORMATION

Department of Electrical Engineering
Indian Institute of Technology Bombay
#280, Hostel 09, IIT Bombay
Powai, Mumbai, India 400 076

Phone: (+91) 996 967 8123
E-Mail: alankar.kotwal@iitb.ac.in
alankarkotwal13@gmail.com
Webpage: alankarkotwal.github.io

RESEARCH INTERESTS

I am passionate about Computer and Medical Vision (visual recognition, imaging modalities, inverse problems, computational photography), Compressed Sensing (theoretical guarantees, sensing matrix optimization), Machine Learning (graphical models, language processing), Optimization, Astrophysics (stellar structure and evolution) and Cosmology (the Λ CDM model and constituent resolution). I enjoy learning about and experimenting with Robotics (navigation systems, extraterrestrial robotics), Computer Networks and Security, Graphics and applications of these fields in one another.

EDUCATION

Indian Institute of Technology Bombay, Mumbai, India

July 2012 – Present

Final Year, Dual Degree (Bachelor & Master of Technology), Department of [Electrical Engineering](#)
Specialization: *Communication and Signal Processing*

- **Major CGPA:** 9.08/10 ([Detailed List of Courses](#))
- **Minor Degree:** Department of [Computer Science & Engineering](#)

Ratanbai Walbai Junior Science College, Mumbai, India

July 2010 – April 2012

Intermediate Education: Physics, Chemistry and Maths
Specialization: *Electrical Maintenance*

- **Major CGPA:** 9.38/10

Saraswati Vidyalaya High School, Thane, India

July 2000 – April 2010

Matriculation

- **Major CGPA:** 9.53/10

PUBLICATIONS

- Kotwal, A., Bhalodia, R., Awate, S., *Joint Desmoking and Denoising of Laparoscopy Images* (oral), Proc. of the [International Symposium on Biomedical Imaging](#), 2016. Paper [here](#).
- Clarke, J. D. A., Held, J. M., Dahl, A. *et al.*, *Field Robotics, Astrobiology and Mars Analogue Research on the Arkaroola Mars Robot Challenge Expedition*, Proc. of the [14th Australian Space Research Conference](#), 2014. Paper [here](#).

RESEARCH INTERNSHIPS

The AIR Lab, Carnegie Mellon University Robotics Institute

Guide: *Prof. Sebastian Scherer & Stephen Nuske*

Summer 2015

Stereo Odometry From A Downward-Facing Stereo Camera On An Aerial Vehicle

For aerial vehicles, odometry is often done by using sensors like the Pixhawk PX4FLOW, which use a single camera doing correlation-based tracking with a sonar for odometry. This has many disadvantages, like small camera field of view (small maximum speeds), bad sonar readings at low range (during take-off), requirement of an inertial unit for angle measurement and height-dependent camera focus. We aimed to replace this with a small-baseline stereo camera. With the field of view parallel to the baseline, the height of the vehicle is obtained from a robust estimate of horizontal disparity. Alternatively, height, pitch and roll are jointly estimated using a robust gradient-descent homography fit between stereo pairs. Similar, rigid tracking across frames is then used to measure position. We obtained better height estimates, maximum speeds and comparable accuracy without an inertial unit as compared to the PX4FLOW. Code [here](#).

Laboratory for Cosmological Data Mining, University of Illinois, Urbana – Champaign

Guide: *Prof. Robert Brunner, under Google Summer of Code*

Summer 2014

A Pixel-Level Machine Learning Method for Calculating Source Redshifts

Spectrometry is a prominent distance measurement technique in Astrophysics. Here, features in the spectrum (like emission or absorption lines) can be fit with known lines to obtain redshift, which is a measure of distance at cosmologically significant distances. However, there exist sources which are either very far or very dim, so we do not get enough flux from them to measure their spectrum. Broad-band energies from these sources, as an approximation to the entire spectrum, are used as features for a machine learning algorithm to calculate redshifts, or alternatively classify them. Unlike previous work, we calculate features pixel-wise instead of integrating over entire source area, giving benefits like source de-blending and better background separation. Redshift calculation and source classification from the method are reasonably accurate. Code [here](#).

Srujana – Center for Innovation, L. V. Prasad Eye Institute

Guide: *Ashutosh Richhariya, Ophthalmic Biophysics, LVPEI*

Winter 2014

Super-Resolution with Fourier Ptychographic Microscopy

The maximum number of independent samples that an imaging setup can extract from the imaged scene is dictated by the limits set by Fourier optics: if the imaged scene is wide-field, there are limits on how much one can zoom in. However, wide-field, high-resolution images are generally desirable in microscopy, pathology and eye imaging. Traditional methods to achieve this involve mechanical adjustment and require precise control and actuation. Fourier Ptychographic Microscopy was introduced in 2013 as a computational tool to work around this. The idea is to shift, in the Fourier domain, high-frequency information to low frequencies (where the system's optics do not filter it), sense it, and shift it back while reconstructing. We worked on understanding and implementing this method for microscopy slides, and analyzed possible extensions to imaging reflective surfaces like the eye. Code [here](#).

RESEARCH PROJECTS

A Bayesian Framework For Laparoscopic Image Dehazing and Denoising

Guide: *Prof. Suyash Awate, CSE, IITB*

January 2015 – Present

Laparoscopic images in minimally invasive surgery get corrupted by surgical smoke and noise. This degrades the quality of the surgery and the results of further processing for, say, segmentation and tracking. Algorithms for desmoking and denoising laparoscopic images seem to be missing in the medical vision literature. We formulated the problem of joint desmoking and denoising of laparoscopic images as a Bayesian inference problem. This formulation relies on a novel probabilistic graphical model of images, which includes a Markov Random Field (MRF) formulation for color-contrast and another MRF for smoothness on the uncorrupted color image as well as the transmission-map image that indicates color attenuation due to smoke. The results on simulated and real-world laparoscopic images, with clinical expert evaluation, shows the advantages of our method over the state of the art. Code [here](#).

Coded Source Separation for Compressed Video Recovery

Guide: *Prof. Ajit Rajwade, CSE & Prof. V. Rajbabu, EE, IITB*

Dual Degree Thesis

December 2015 – Present

Recent efforts to apply the principles of compressed sensing to video data involve combining frames into coded snapshots while sensing and separating them with an over-complete dictionary. This works well, but needs a dictionary at the same frame-rate and time-smoothness as the video. We try relaxing this constraint using a source-separation approach to this problem where precise error bounds on recovery have been derived. Basis pursuit recovery with Gaussian-random sensing matrices gives excellent results with no ghosting for both similar and radically different images. Unfortunately, the more realizable non-negative sensing matrices don't work as well, because they do not have the nice incoherence properties of Gaussian-random matrices. We aim to design such sensing matrices with low mutual coherence, making them ideal for compressed video. We also aim to design matrices that when rotated circularly, still have low mutual coherence so that they can be tiled for patch-wise reconstruction. Code [here](#).

The IITB Mars Rover Project

May 2013 – Present

The IITB Mars Rover project is a student initiative at IIT Bombay to build a prototype Mars rover capable of extra-terrestrial robotics and to participate in the [University Rover Challenge](#) at the Mars Society's [Mars Desert Research Station](#), Utah. The mechanical subsystem designed and developed a rover with a rocker-bogie suspension and novel air-filled beach tires. The electrical and software team designed power, logic and communication circuits for on-board control. Currently, localization and autonomous navigation are being developed. The role of machine vision for automating rover operations is being explored. One of the design goals for the future is to develop the capability to help astronauts on space missions. We participated in a simulated Martian expedition and tested Rover capabilities in the harsh conditions of the Australian outback, at the [Arkaroola Mars Robot Challenge](#). We participated in a series of exercises in Mars Operations Research, involving test extra-vehicular activities in space-suits (a sample collection task and a rover guidance task) conducted by [Saber Astronautics](#). Details and pictures [here](#).

COURSE PROJECTS

Improved Methods for Compressed Sensing Recovery

CS709: Convex Optimization

Guide: [Prof. Ganesh Ramakrishnan](#), CSE, IITB

Autumn 2015-16

Using convex approximations to the compressed sensing recovery problem, we reconstructed near-exact versions of images at extremely low compressions, with proofs of correctness. Code [here](#).

Hidden Markov Model Part-of-Speech Tagging

EE638: Estimation and Identification

Guide: [Prof. Navin Khaneja](#), EE, IITB

Autumn 2015-16

We implemented part-of-speech tagging with support for unknown words. An error rate of around 5% and capabilities of the system to discern context were observed. Code [here](#).

Laparoscopic Image Dehazing With Dark Channel Prior

CS736: Medical Image Processing

Guide: [Prof. Suyash Awate](#), CSE, IITB

Spring 2014-15

We applied the Dark Channel Prior method for landscape image dehazing to surgical smoke-affected laparoscopic images, accelerated it in time and got good results. Code [here](#).

Stereo Odometry Via Point Cloud Registration

CS763: Computer Vision

Guide: [Prof. Ajit Rajwade](#), CSE, IITB

Spring 2014-15

Maximizing kernel density correlation with gradient-ascent and coherent point drift, we registered pointclouds and observed good convergence behavior for small transformations. Code [here](#).

Gravitational Lens Separation With PCA

CS663: Digital Image Processing

Guide: [Prof. Suyash Awate](#) & [Prof. Ajit Rajwade](#), CSE, IITB

Autumn 2014-15

Gravitationally lensed images of galaxies have rare arc-like artifacts that can be used to calculate the mass of the lens. We used Anscombe denoising followed by PCA to build a basis for galaxy images and used the top few eigengalaxies to subtract sources and detect arcs. Code [here](#).

Processor Design

EE309: Microprocessors

Guide: [Prof. Virendra Singh](#), EE, IITB

Autumn 2014-15

We designed, simulated and implemented (on a DE0-Nano board from Terasic) a [multi-cycle RISC processor](#) following the LC-3b ISA. Following this, we designed and simulated a [pipelined RISC processor](#) using the Little Computer Architecture.

ASTROPHYSICS PROJECTS

Detecting Short γ -Ray Bursts in Astrosat CZTI Data

PH426: Astrophysics

Guide: [Prof. Vikram Rentala](#), PH, IITB and [Prof. A. R. Rao](#), TIFR, Mumbai

Spring 2015-16

We did a literature survey on γ -ray bursts, including open problems in the field. We tackle detecting short γ -ray bursts from data acquired by the CZTI X-Ray Imager on-board Astrosat.

Variability Analysis for Globular Cluster NGC2419

NIUS, Astronomy

Guide: [Prof. Priya Hasan](#), MANUU, Hyderabad

December 2015

We analyzed raw data for the globular cluster NGC2419 taken at the [HCT](#), post-processed it to correct for detector bias and flat-fielding, inverted the effect of atmospheric mass and extracted the variation of magnitudes of stars in the cluster on the scale of a day. Code [here](#).

An X-Ray Study of Black Hole Candidate X Norma X-1

NIUS, Astronomy

Guide: Prof. Manojendu Choudhury, Center for Basic Sciences

December 2013

We analyzed spectral data from the RXTE for the low-mass X-Ray Binary 4U 1630-47, for an outburst in the source. We extracted 3-30 keV spectra and fit them with a model accounting for disk blackbody radiation, non-thermal power-law radiation, and interstellar extinction. We obtained best fit values of system parameters like internal radius and temperature. Report [here](#).

Estimation of Photometric Redshifts Using Machine Learning

NIUS, Astronomy

Guide: Prof. Ninan Sajeeth Philip, IUCAA, Pune

December 2012

Here, we trained a neural network for photometric redshifts, given data for sources whose spectra and redshifts have been measured. We predicted spectra for these objects viewed at various other values of redshifts. Using this expanded dataset, we achieved good predictions for test data.

ACHIEVEMENTS AND AWARDS

Olympiads and Competitive Exams

- Represented India at the [6th International Olympiad on Astronomy and Astrophysics](#), Brazil, 2012. Won a Gold Medal with International Rank 4 and a special prize for Best Data Analysis
- Represented India at the [5th International Earth Sciences Olympiad](#), Italy, 2011. Won a Bronze Medal and prizes for best performance in the Hydrosphere section and the team presentation
- Secured all-India rank 105 in the [IIT-JEE](#) 2012 amongst half a million candidates

Scholarships

- Awarded [KVPY Scholarship](#) 2011 by Dept. of Science and Technology, Govt. of India
- Awarded [NTSE Scholarship](#) 2008 by NCERT, Govt. of India

Competitions

- Secured IIT Bombay the second position by putting on board 72 Messier objects including the entire Virgo cluster of galaxies in the [Inter-IIT Messier Marathon, 2014](#)

KEY TALKS AND SEMINARS

Coded Source Separation for Compressed Video Recovery

Dual Degree Thesis Talk

Department of Electrical Engineering, Indian Institute of Technology Bombay

May 2016

Here, I presented results from the first stage of my dual degree thesis. Presentation [here](#).

Template-Based Stereo Odometry

Invited Talk

The AIR Lab, Carnegie Mellon University

July 2015

Here, I presented results from my 2015 summer internship to my group at Carnegie Mellon University. The talk included a detailed description of the method used, comparisons of the results with ground-truth and stress-tests on the method. Presentation [here](#).

The Cosmic Distance Ladder

Invited Talk

Krittika – The Astronomy Club, IIT Bombay

September 2014, February 2016

This open-to-all popular talk climbs the Cosmic Distance Ladder, a sequence of steps, each building on the previous step's results, for calculating distances in the universe. We begin with solar system distances, and end at enormous distances where the only option is using indirect methods like photometric redshifts. Presentation [here](#).

MENTORING EXPERIENCE

Teaching Assistant for IITB Courses

CS663: Digital Image Processing [Prof. S. Awate](#) & [Prof. A. Rajwade](#)

Autumn 2015-16

CS736: Medical Image Processing [Prof. S. Awate](#)

Spring 2015-16

EE638: Estimation and Identification [Prof. N. Khaneja](#)

Autumn 2016-17

Resource Person, Indian Astronomy Olympiad Programme

May 2013, May 2014

Selected twice as a resource person for Indian Astronomy Olympiad Camps, to mentor students for their selection to the International Astronomy Olympiads. Involved in mentoring students ranging from the 9th to the 12th grades in Astronomy, and in setting up challenging questions and evaluating them.

Technical Mentor*April 2013 – March 2014*

Mentored 1st year students for Robotics Competitions and contributed towards generation of ideas and debugging for Institute Technical Summer Projects. Member of the Electronics club.

**KEY
COURSEWORK**
Computer Sciences and Engineering

Computer Vision, Medical Image Processing, Digital Image Processing, Machine Learning, Convex Optimization, Graphics, Networks, Data Structures, Algorithms, Discrete Mathematics

Electrical Engineering

Estimation and Identification, Adaptive Signal Processing, Digital Signal Processing, Speech Processing, Matrix Computations, Information Theory, Advanced Probability and Random Processes, Communication Networks and Systems, Microprocessors, Signals and Systems, Digital and Analog Systems, Electronic Devices and Circuits, Network Theory

Physics and Mathematics

Astrophysics, The General Theory of Relativity, Electromagnetic Waves, Electricity & Magnetism, Classical Mechanics, Differential Equations, Linear Algebra, Complex Analysis, Calculus

**TECHNICAL
SKILLS**

Programming	C/C++, Python, Bash, Matlab, Verilog, SQL, HTML/CSS, PHP, L ^A T _E X
Software Packages	ROS/Gazebo, OpenCV, The Point Cloud Library, SPICE Circuit Simulation, EAGLE PCB Design, SolidWorks, AutoCAD, LabView
Science Software	Python packages: NumPy, SciPy and Matplotlib, GNUPlot, Scikit-learn, Astropy, SDSS tools
Hardware	<i>Microprocessors:</i> 8051, 8085, AVR and PIC, CPLDs and FPGAs, <i>Embedded Platforms:</i> Arduino, Raspberry Pi, NVIDIA Jetson TK1 <i>standard digital logic families</i>

LANGUAGES

English, Hindi (working knowledge), Marathi (first language), Sanskrit (elementary knowledge)

**OTHER
INTERESTS**

OTHER than my academic interests, I like biking, long walks, trekking, climbing whatever can be climbed, swimming, playing table tennis, socializing, cooking good food and eating it. I especially enjoy classic rock music and people who enjoy my interests. I enjoy design and like making things look and feel good. And finally, I love Origami, the art of paper folding, and building complex, realistic models with Lego blocks.

REFERENCES

Prof. Suyash Awate, CSE
Indian Institute of Technology, Bombay
[E-Mail](#) | [Webpage](#)

Dr. Sebastian Scherer, Robotics Institute
Carnegie Mellon University
[E-Mail](#) | [Webpage](#)

Prof. Mayank Vahia, Astrophysics
Tata Institute of Fundamental Research
[E-Mail](#) | [Webpage](#)

Prof. Rajbabu Velmurugan, EE
Indian Institute of Technology, Bombay
[E-Mail](#) | [Webpage](#)

Prof. Ajit Rajwade, CSE
Indian Institute of Technology, Bombay
[E-Mail](#) | [Webpage](#)

Ashutosh Richhariya, Ophthalmic Biophysics
L. V. Prasad Eye Institute
[E-Mail](#) | [Webpage](#)

Dr. Aniket Sule, Astronomy
Homi Bhabha Center for Science Education
[E-Mail](#) | [Webpage](#)

Dr. Manojendu Choudhury, Astrophysics
Center for Excellence in Basic Sciences
[E-Mail](#) | [Webpage](#)