



GEOSCIENCES
CENTRE DE GÉOSCIENCES

Automnales

October 2017



■ PROBABILITY FOR GEOSTATISTICS

■ Why probability ?



Probability theory \Leftrightarrow mathematical analysis of random experiments

Random experiment

Trial that produces different outcomes when repeated indefinitely under the same controllable conditions



Randomness \approx the uncontrolled, unexplained, unknown

■ Why probability ?



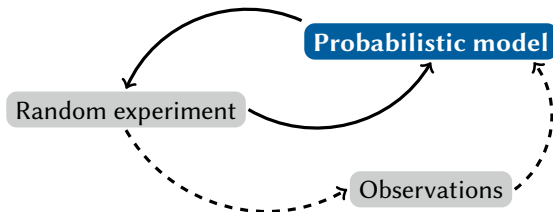
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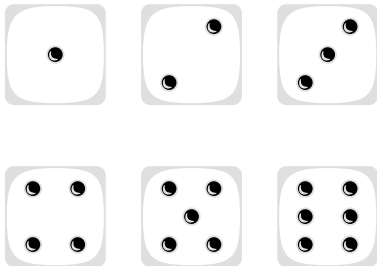
★ Randomness \approx the uncontrolled, unexplained, unknown

In practice :



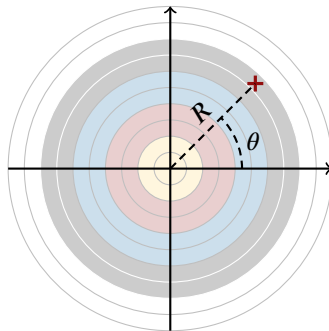
Two examples

Dice roll



Random : resulting number

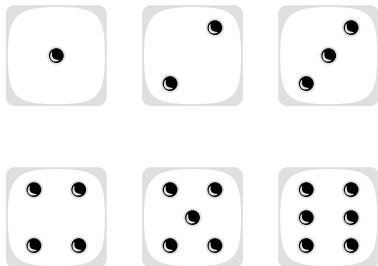
Archery



Random : R and θ

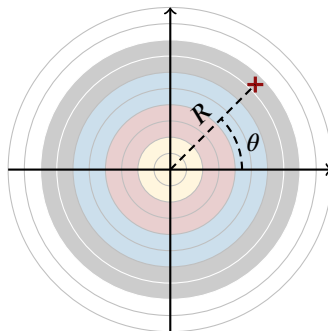
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Random : resulting number

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Random : R and θ

Goal : **measure** the chance of realization of all sets of possible outcomes

1. Measuring the uncertain

- How to construct a probability measure
- Getting started with probability : basic rules
- Getting to the point : random variables

2. How to depict distributions of random variables

- Cumulative distribution functions (cdf)
- Probability density and mass functions (pdf, pmf)
- Dealing with dependence

3. Momentous moments

- Expected value
- Variance and covariance
- Conditional moments



MEASURING THE UNCERTAIN

■ What to we need to measure the uncertain? ■■

Goal Build a function ***P*** that associates a grade to each type of outcome of a random experiment

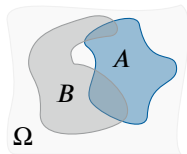
$$\mathbf{P}(\textit{type of outcome}) = \textit{grade}$$

The higher the grade, the more likely the type of outcome

To build this mathematical function we need

- To list all possible outcomes of the experiment
- To specify **which** types of outcomes we want to grade (measure)
- To decide **how** we want to grade (quantify) them

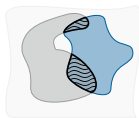
■ Prerequisites - Rudiments of set theory



- Union: $A \cup B := \{x \in \Omega : x \in A \text{ or } x \in B\}$
- Intersection: $A \cap B := \{x \in \Omega : x \in A \text{ and } x \in B\}$
- Relative complement: $A \setminus B := \{x \in \Omega : x \in A \text{ but } x \notin B\}$
- Absolute complement: $A^c := \Omega \setminus A$
- Symmetric difference: $A \Delta B := (A \cup B) \setminus (A \cap B)$



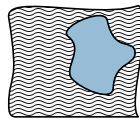
$A \cup B$



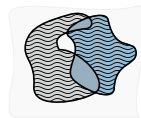
$A \cap B$



$A \setminus B$



A^c



$A \Delta B$

■ Inventory all outcomes - Universe



Universe

The universe (or sample space) is the set made of all theoretically possible outcomes of the studied random experiment; it is denoted by Ω

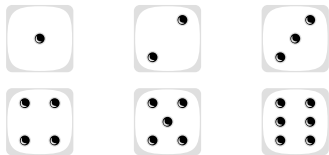
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Dice roll



$$\Omega = \{1, 2, 3, 4, 5, 6\}$$

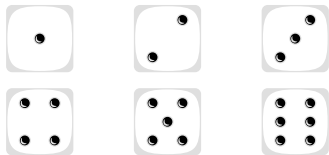
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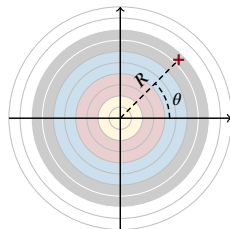
The universe (or sample space) is the set made of all theoretically possible outcomes of the studied random experiment; it is denoted by Ω

Dice roll



$$\Omega = \{1, 2, 3, 4, 5, 6\}$$

Archery



$$\Omega = [0, 122] \times [-\pi, \pi)$$

■ Specify what to measure - Events



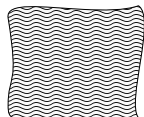
Ω

Set \mathcal{A} made of all that can be measured on Ω ?

■ Specify what to measure - Events

Ω

Set \mathcal{A} made of all that can be measured on Ω ?

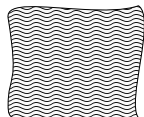


(i) *(Something happens)* $\Omega \in \mathcal{A}$

Specify what to measure - Events

Ω

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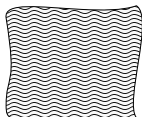
(ii) *(This or that happens)* \mathcal{A} closed under countable unions :

$$\{\forall n \in \mathbb{N} : A_n \in \mathcal{A}\} \Rightarrow \bigcup_{n \in \mathbb{N}} A_n \in \mathcal{A}$$

Specify what to measure - Events

Ω

Set \mathcal{A} made of all that can be measured on Ω ?

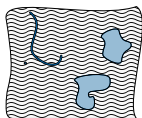


(i) *(Something happens)* $\Omega \in \mathcal{A}$



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$$\{\forall n \in \mathbb{N} : A_n \in \mathcal{A}\} \Rightarrow \bigcup_{n \in \mathbb{N}} A_n \in \mathcal{A}$$



(iii) *(This does not happen)* \mathcal{A} closed under complementation :

$$A \in \mathcal{A} \Rightarrow A^c \in \mathcal{A}$$

■ Specify what to measure - Events



σ -algebra

Any set $\mathcal{A} \subset \mathcal{P}(\Omega)$ (power set of Ω) that fulfills conditions (i) – (iii) is called a σ -algebra or a σ -field ("tribu" in French)



(Ω, \mathcal{A}) called a **measure space**

■ Specify what to measure - Events



σ -algebra

Any set $\mathcal{A} \subset \mathcal{P}(\Omega)$ (power set of Ω) that fulfills conditions (i) – (iii) is called a σ -algebra or a σ -field ("tribu" in French)

★ (Ω, \mathcal{A}) called a **measure space**

Event

Let (Ω, \mathcal{A}) be a measure space, then $A \in \mathcal{A}$ is called an event

Ex. \emptyset : impossible event Ω : sure event $\omega \in \Omega$: elementary/atomic event

★ \mathcal{A} made of subsets of Ω : $A \in \mathcal{A} \Rightarrow A \subset \Omega$

■ Choose how to quantify - Probability



Probability measure

A probability measure on the measure space (Ω, \mathcal{A}) is an application

$$\begin{aligned} \mathbf{P} : \quad \mathcal{A} &\longrightarrow [0, 1] \\ A &\longmapsto \mathbf{P}(A) \end{aligned}$$

such that (i) $\mathbf{P}(\Omega) = 1$ and

(ii) for all sequences $(A_n)_{n \in \mathbb{N}}$ of pairwise disjoint (incompatible) events,

$$\mathbf{P}\left(\bigcup_{n \in \mathbb{N}} A_n\right) = \sum_{n \in \mathbb{N}} \mathbf{P}(A_n) \quad (\sigma\text{-additivity})$$



$(\Omega, \mathcal{A}, \mathbf{P})$ called a **probability space**

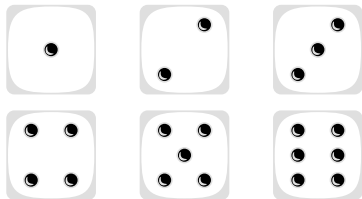


Probability measures cannot be defined on any measure space !

■ Choose how to quantify - Examples



Dice roll



■ $\Omega = \{1, 2, 3, 4, 5, 6\}$

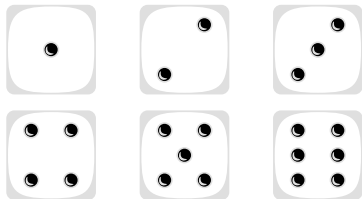
■ $\mathcal{A} = \mathcal{P}(\Omega)$

■
$$P(A) = \frac{\text{Card}(A)}{\text{Card}(\Omega)} \quad A \in \mathcal{A}$$

Choose how to quantify - Examples



Dice roll

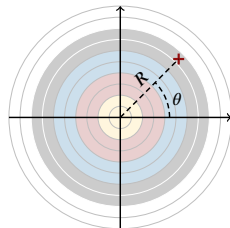


- $\Omega = \{1, 2, 3, 4, 5, 6\}$

- $\mathcal{A} = \mathcal{P}(\Omega)$

- $$P(A) = \frac{\text{Card}(A)}{\text{Card}(\Omega)} \quad A \in \mathcal{A}$$

Archery



- $\Omega = [0, 122] \times [-\pi, \pi)$

- $\mathcal{A} = \mathcal{B}(\Omega)$ (Borel algebra)

- $$P(A) = \frac{\text{Area}(A)}{\text{Area}(\Omega)} \quad A \in \mathcal{A}$$

■ Measuring the uncertain - Summary



We needed

- A list of all possible outcomes ➡ *universe* Ω
- The types of outcomes to grade ➡ *events* listed in the σ -algebra \mathcal{A}
- A function to grade the types of outcomes ➡ *probability measure* \mathbf{P}

We have decided that

- Grades shall be a number between 0 and 1
- There is always something happening: $\mathbf{P}(\Omega) = 1$
- For two *incompatible events* A and B , the probability that either one of them happens is the sum of their probabilities

Given this setting, what else can we say about probability measures ?

■ Getting started - Basic properties



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$A, B \in \mathcal{A}$ events

- Inclusion : $B \subset A \Rightarrow \mathbf{P}(B) \leq \mathbf{P}(A)$
- Intersection : $\mathbf{P}(A \cap B) \leq \mathbf{P}(A) \wedge \mathbf{P}(B)$
- Mutual exclusivity : $A \cap B = \emptyset \Rightarrow \mathbf{P}(A \cap B) = 0$
- Absolute complement : $\mathbf{P}(A^c) = 1 - \mathbf{P}(A)$
- Union : $\mathbf{P}(A \cup B) = \mathbf{P}(A) + \mathbf{P}(B) - \mathbf{P}(A \cap B)$



$$\mathbf{P}(B) \leq \mathbf{P}(A)$$



$$\mathbf{P}(A \cap B)$$



$$\mathbf{P}(A^c)$$



$$\mathbf{P}(B) \quad \mathbf{P}(A)$$

■ Getting started - (In)dependence



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

events $\in \mathcal{A}$

Independent events

Two events A and B are said to be independent iff $\mathbf{P}(A \cap B) = \mathbf{P}(A) \mathbf{P}(B)$



A and B independent $\Leftrightarrow B$ has no influence on A and vice versa

■ Getting started - (In)dependence



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Exercise

Consider a deck of 52 cards.

- Pick one card at random, put it back, shuffle and pick a second one.
 - 1° What would be an adequate probability space for this experiment?
 - 2° Are getting a jack and a queen independent events?
- How would you answer these questions if both cards were picked simultaneously?

■ Getting started - Conditioning



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

events $\in \mathcal{A}$

Conditioning on an event

The conditional probability of an event A given that an event B with non-null probability has occurred is

$$\mathbf{P}(A | B) = \frac{\mathbf{P}(A \cap B)}{\mathbf{P}(B)}$$

■ Getting started - Conditioning



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

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★ $A \in \mathcal{A} \mapsto \mathbf{P}(A | B) \in [0, 1]$ probability measure

★ extension to $\mathbf{P}(A | B)$ when $\mathbf{P}(B) = 0$: disintegration theorem

★ A and B independent $\Rightarrow \mathbf{P}(A | B) = \mathbf{P}(A)$ and $\mathbf{P}(B | A) = \mathbf{P}(B)$
if $\mathbf{P}(A), \mathbf{P}(B) \neq 0$

■ Getting started - Two major theorems



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

events $\in \mathcal{A}$

Law of total probability

Let $(B_n)_{n \in \mathbb{N}}$ be a partition of Ω . For any event A $\mathbf{P}(A) = \sum_{n \in \mathbb{N}} \mathbf{P}(A \cap B_n)$

If in addition $\mathbf{P}(B_n) \neq 0$ for all $n \in \mathbb{N}$, then $\mathbf{P}(A) = \sum_{n \in \mathbb{N}} \mathbf{P}(A | B_n) \mathbf{P}(B_n)$

■ Getting started - Two major theorems



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Bayes' theorem

For any two events A and B such that $\mathbf{P}(A) \neq 0$ and $\mathbf{P}(B) \neq 0$:

$$\mathbf{P}(A | B) = \frac{\mathbf{P}(B | A) \mathbf{P}(A)}{\mathbf{P}(B)}$$

■ Main focus - Random elements



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

events $\in \mathcal{A}$



The experiment is often too complex to make $(\Omega, \mathcal{A}, \mathbf{P})$ explicit
 \Rightarrow **Assume** its existence and focus on the quantities of interest

■ Main focus - Random elements



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

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Random element (RE) - Intuition

Basically, a random element is an object with a priori unpredictable characteristics, e.g.

- *the shape, size and location of a potatoe drawn with closed eyes on a piece of paper,*
- *the color of a future baby cat,*
- *the total number rolled with 2 dices, etc.*

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Mathematically, random elements can be viewed as functions from a complex probability space to a more interesting or convenient one

■ Main focus - Random elements



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

events $\in \mathcal{A}$



The experiment is often too complex to make $(\Omega, \mathcal{A}, \mathbf{P})$ explicit
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Random element (RE) - Formal definition

Let $(\mathcal{X}, \mathcal{B})$ be a measure space. A random element is an application $X : \Omega \rightarrow \mathcal{X}$ such that $\forall B \in \mathcal{B}$ $X^{-1}(B) := \{\omega \in \Omega : X(\omega) \in B\}$ is an event ($\in \mathcal{A}$)

■ Main focus - Random elements



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

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- $\mathcal{X} \subset \mathbb{R}$ countable (ex. $\{0, 1\}, \mathbb{N}, \mathbb{Z}, \mathbb{Q}$): X discrete random variable (RV)
- $\mathcal{X} \subseteq \mathbb{R}$ **uncountable**: X real-valued RV
- $\mathcal{X} \subseteq \mathbb{R}^d$ **uncountable**: X random vector (RVec)

■ Main focus - Random elements



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

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Random elements extract the desired information from $(\Omega, \mathcal{A}, \mathbf{P})$

■ Main focus - Distribution of a RE



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

RE $\Omega \rightarrow \mathcal{X}$

Distribution of a random element

The distribution \mathbf{P}_X of a random element X is the application

$$\begin{aligned} \mathbf{P}_X : \quad \mathcal{B} &\longrightarrow [0, 1] \\ B &\longmapsto \mathbf{P}(X^{-1}(B)) \end{aligned}$$

★ \mathbf{P}_X also called the *pushforward measure* of \mathbf{P} by X

★ $(\mathcal{X}, \mathcal{B}, \mathbf{P}_X)$ probability space

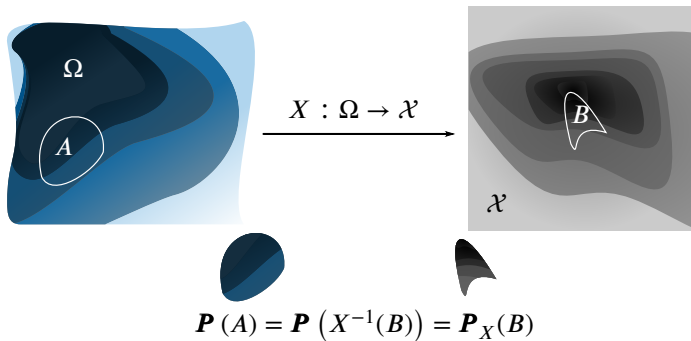
★ **Notation shortcut:** $\mathbf{P}(X \in B) := \mathbf{P}(X^{-1}(B)) = \mathbf{P}_X(B)$

■ Main focus - Pushforward measure

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

RE $\Omega \rightarrow \mathcal{X}$

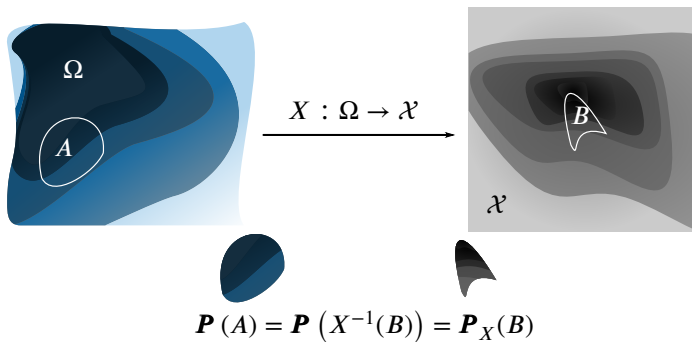


■ Main focus - Pushforward measure

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

RE $\Omega \rightarrow \mathcal{X}$



Exercise

Let X be the random variable that gives the total number rolled with 2 dices. What is the probability that X equals 8 ?



HOW TO DEPICT DISTRIBUTIONS OF RANDOM VARIABLES

■ Cdf - Random variables



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Cumulative distribution function (cdf)

The cdf of a random variable X is the application $F_X :$

$$\begin{array}{lll} \mathbb{R} & \longrightarrow & [0, 1] \\ x & \longmapsto & \mathbf{P}(X \leq x) \end{array}$$

■ Cdf - Random variables



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Cumulative distribution function (cdf)

The cdf of a random variable X is the application $F_X : \mathbb{R} \longrightarrow [0, 1]$
 $x \longmapsto \mathbf{P}(X \leq x)$

■ F_X non-decreasing and càdlàg ("continue à droite, limite à gauche")

■ $F_X(x) \xrightarrow{x \rightarrow -\infty} 0$ and $F_X(x) \xrightarrow{x \rightarrow +\infty} 1$

■ Cdf - Random variables



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

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Exercise

Let X be the random variable that gives the total number rolled with 2 dices.
What is its cdf ?

■ Cdf - Random vectors



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

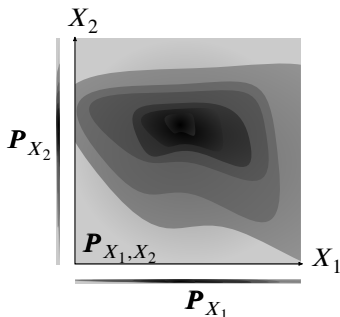
Random vector $\Omega \rightarrow \mathcal{X}$

Let $X = (X_1, \dots, X_d)$ be a RVec ($d \in \mathbb{N}^*$)

■ \mathbf{P}_X joint distribution

■ $\mathbf{P}_{X_1}, \dots, \mathbf{P}_{X_d}$ 1-d marginal distributions

■ $\forall k \in \mathbb{N}^* : \left\{ \mathbf{P}_{X_{j_1}, \dots, X_{j_k}} : (j_1, \dots, j_k) \in \llbracket 1, d \rrbracket^k \right\}$ k -d marginal distributions



★ **Notation:** $\mathbf{P}(X_1 \in B_1, \dots, X_d \in B_d)$
 $= \mathbf{P}(X_1 \in B_1 \text{ and } \dots \text{ and } X_d \in B_d)$
 $= \mathbf{P}(X_1^{-1}(B_1) \cap \dots \cap X_d^{-1}(B_d))$
 $= \mathbf{P}(X \in B) = \mathbf{P}_X(B)$

with $B = \{x_1 \in B_1 \text{ and } \dots \text{ and } x_d \in B_d\}$

■ Cdf - Random vectors



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Cumulative distribution function

The cdf of a RVec $X = (X_1, \dots, X_d)$ is the application

$$F_X : \begin{array}{ccc} \mathbb{R}^d & \longrightarrow & [0, 1] \\ x = (x_1, \dots, x_d) & \longmapsto & \mathbf{P}(X_1 \leq x_1, \dots, X_d \leq x_d) \end{array}$$

■ Cdf - Random vectors



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

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Random vector $\Omega \rightarrow \mathcal{X}$

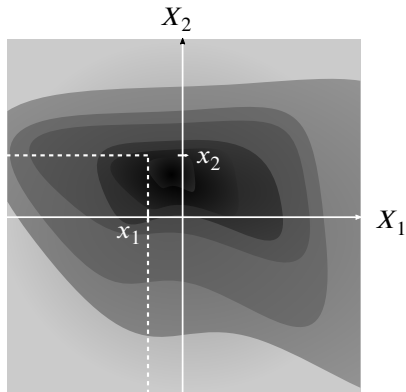
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- F_X non-decreasing and càdlàg for each of its variables
- $\forall j \in \llbracket 1, d \rrbracket : F_X(x) \xrightarrow{x_j \rightarrow -\infty} 0$ and $F_X(x) \xrightarrow{x_1, \dots, x_d \rightarrow +\infty} 1$
- F_{X_1}, \dots, F_{X_d} marginal cdfs

■ Cdf - Random vectors

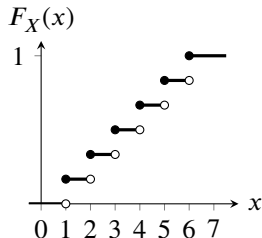


$$F_X(x_1, x_2)$$

Dice roll

If X is the result of a roll then $\forall x \in \mathbb{R}$:

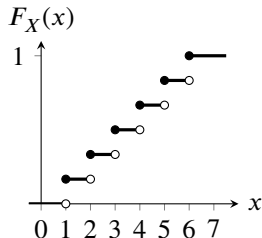
$$F_X(x) = \sum_{k=1}^6 \frac{1}{6} \mathbf{1}\{k \leq x\}$$



Dice roll

If X is the result of a roll then $\forall x \in \mathbb{R}$:

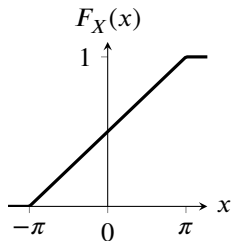
$$F_X(x) = \sum_{k=1}^6 \frac{1}{6} \mathbf{1}\{k \leq x\}$$



Archery

If X is the angle of a blind shot, then $\forall x \in \mathbb{R}$:

$$F_X(x) = \frac{x + \pi}{2\pi} \mathbf{1}\{-\pi \leq x < \pi\} + \mathbf{1}\{x \geq \pi\}$$



■ Pdf/Pmf - Discrete univariate case



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Probability mass function

The probability mass function (pmf) of a discrete RV X is the application

$$p_X : x \in \mathbb{R} \mapsto \begin{cases} \mathbf{P}(X = x) & \text{if } x \in \mathcal{B}, \\ 0 & \text{if } x \notin \mathcal{B}. \end{cases}$$

■ Pdf/Pmf - Discrete univariate case



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$$\blacksquare \quad \forall x \in \mathbb{R} : \quad F_X(x) = \sum_{u \in \mathbb{R}} p_X(u) \mathbf{1}_{\{u \leq x\}}$$

■ Pdf/Pmf - Discrete multivariate case



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Probability mass function

The pmf of a discrete RVec $X = (X_1, \dots, X_d)$ is the application

$$p_X : (x_1, \dots, x_d) \in \mathbb{R}^d \mapsto \begin{cases} \mathbf{P}(X_1 = x_1, \dots, X_d = x_d) & \text{if } (x_1, \dots, x_d) \in \mathcal{B}, \\ 0 & \text{if } (x_1, \dots, x_d) \notin \mathcal{B}. \end{cases}$$

■ Pdf/Pmf - Discrete multivariate case

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Probability mass function

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$$\blacksquare \quad \forall x = (x_1, \dots, x_d) \in \mathbb{R}^d : \quad F_X(x) = \sum_{u \in \mathbb{R}^d} p_X(u) \mathbf{1}\{u_1 \leq x_1, \dots, u_d \leq x_d\}$$

■ p_X exists \Rightarrow its marginals exist and for all $j \in \llbracket 1, d \rrbracket, \forall x \in \mathbb{R} :$

$$p_{X_j}(x) = \sum_{u \in \mathbb{R}^{d-1}} p_X(u_1, \dots, u_{j-1}, x, u_{j+1}, \dots, u_d)$$

■ Pdf/Pmf - Continuous univariate case



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Probability density function

A RV X has a probability density function (pdf) f_X if for all $B \in \mathcal{B}$ we can write

$$\mathbf{P}_X(B) = \int_B f_X(x) dx$$

■ Pdf/Pmf - Continuous univariate case

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Probability density function

A RV X has a probability density function (pdf) f_X if for all $B \in \mathcal{B}$ we can write

$$\mathbf{P}_X(B) = \int_B f_X(x) dx$$

■ $f_X(x)$ gives the marginal weight of the value $x \in \mathbb{R}$ with respect to \mathbf{P}_X

■ $\forall x \in \mathbb{R} : F_X(x) = \int_{-\infty}^x f_X(u) du \quad \text{and} \quad f_X(x) = F'_X(x)$

■ Pdf/Pmf - Continuous multivariate case



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Probability density function

A RVec $X = (X_1, \dots, X_d)$ has a (joint) pdf f_X if for all $B \in \mathcal{B}$ we can write

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■ Pdf/Pmf - Continuous multivariate case

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

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Probability density function

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$$\mathbf{P}_X(B) = \int_B f_X(x) dx$$

$$\blacksquare \quad \forall x = (x_1, \dots, x_d) \in \mathbb{R}^d : \quad F_X(x) = \int_{-\infty}^{x_1} \dots \int_{-\infty}^{x_d} f_X(u_1, \dots, u_d) du_d \dots du_1$$

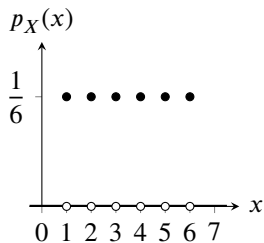
■ f_X exists \Rightarrow its marginals exist and for all $j \in \llbracket 1, d \rrbracket, \forall x \in \mathbb{R} :$

$$f_{X_j}(x) = \int_{\mathbb{R}^{d-1}} f_X(u_1, \dots, u_{j-1}, x, u_{j+1}, \dots, u_d) du_d \dots du_{j+1} du_{j-1} \dots du_1$$

Dice roll

If X is the result of a roll then $\forall x \in \mathbb{R}$:

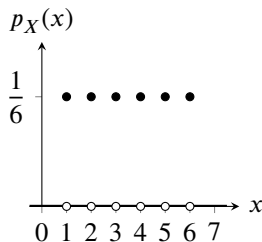
$$p_X(x) = \mathbf{P}(X = x) = \frac{1}{6} \mathbf{1}_{\{x \in \{1, \dots, 6\}\}}$$



Dice roll

If X is the result of a roll then $\forall x \in \mathbb{R}$:

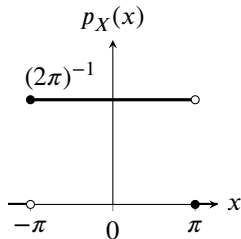
$$p_X(x) = \mathbf{P}(X = x) = \frac{1}{6} \mathbf{1}\{x \in \{1, \dots, 6\}\}$$



Archery

If X is the angle of a blind shot, then $\forall x \in \mathbb{R}$:

$$f_X(x) = \frac{1}{2\pi} \mathbf{1}\{-\pi \leq x < \pi\}$$



■ Conditional distribution



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Conditional pdf

*Assume that the RVec (X, Y) has joint pdf $f_{X,Y}$ with marginals f_X and f_Y .
The conditional pdf of X given that Y equals $y \in \mathbb{R}$ with $f_Y(y) \neq 0$ is defined
for all $x \in \mathbb{R}$ as*

$$f_{X|Y=y}(x) := \frac{f_{X,Y}(x, y)}{f_Y(y)}$$



In the discrete case, replace pdfs by pmfs

■ Conditional distribution



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Conditional pdf

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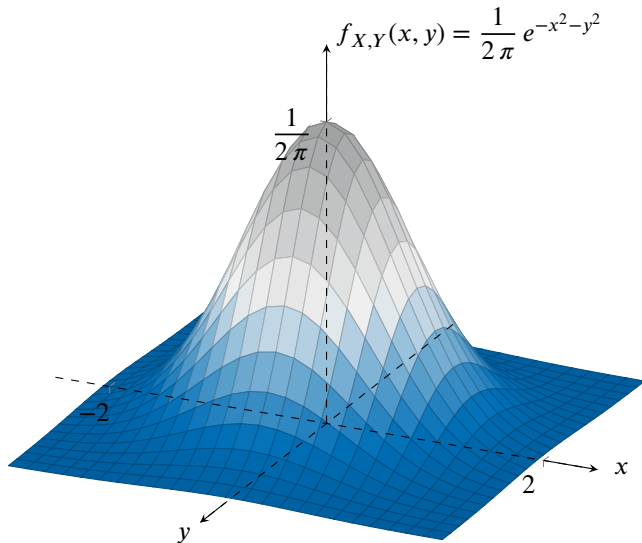
In the discrete case, replace pdfs by pmfs



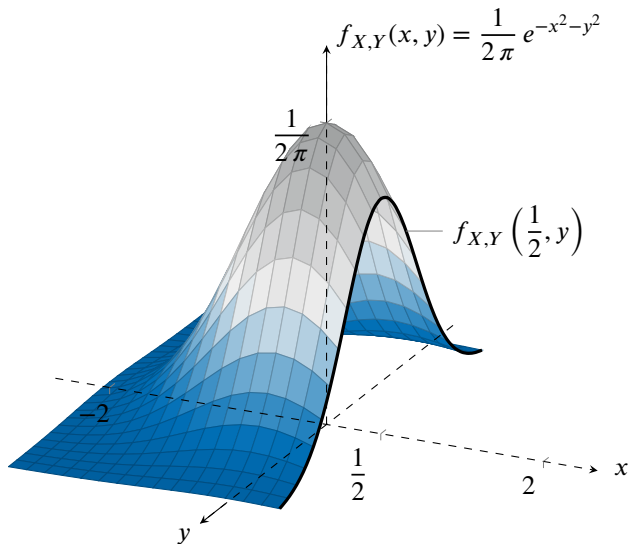
X, Y independent $\Leftrightarrow \forall (x, y) \in \mathbb{R}^2 : f_{X,Y}(x, y) = f_X(x) f_Y(y)$

\Rightarrow when $f_X(x), f_Y(y) \neq 0$: $f_{X|Y=y}(x) = f_X(x)$ and $f_{Y|X=x}(y) = f_Y(y)$

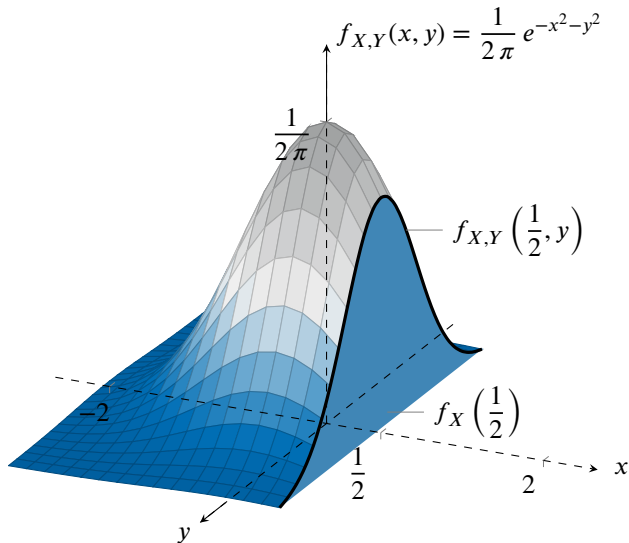
■ Conditional distribution



■ Conditional distribution



■ Conditional distribution



■ Conditional distribution - Discrete case

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Law of total probability

Let X, Y be discrete RVs : $\mathbf{P}(X = x) = \sum_{y \in \mathbb{R}} \mathbf{P}(X = x, Y = y)$ for all $x \in \mathbb{R}$.

If in addition Y is valued in $\mathcal{Y} \subset \mathbb{R}$ and $\mathbf{P}(Y = y) > 0$ for all $y \in \mathcal{Y}$:

$$\mathbf{P}(X = x) = \sum_{y \in \mathcal{Y}} \mathbf{P}(X = x \mid Y = y) \mathbf{P}(Y = y)$$

■ Conditional distribution - Discrete case

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Law of total probability

Let X, Y be discrete RVs : $\mathbf{P}(X = x) = \sum_{y \in \mathbb{R}} \mathbf{P}(X = x, Y = y)$ for all $x \in \mathbb{R}$.

If in addition Y is valued in $\mathcal{Y} \subset \mathbb{R}$ and $\mathbf{P}(Y = y) > 0$ for all $y \in \mathcal{Y}$:

$$\mathbf{P}(X = x) = \sum_{y \in \mathcal{Y}} \mathbf{P}(X = x \mid Y = y) \mathbf{P}(Y = y)$$

Bayes' theorem

Let X, Y be discrete RVs. For all $(x, y) \in \mathbb{R}^2$ such that $\mathbf{P}(X = x), \mathbf{P}(Y = y) \neq 0$:

$$\mathbf{P}(Y = y \mid X = x) = \frac{\mathbf{P}(X = x \mid Y = y) \mathbf{P}(Y = y)}{\mathbf{P}(X = x)}$$

■ Conditional distribution - Continuous case ■

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Law of total probability

Let (X, Y) be a RVec with joint pdf $f_{X,Y} : f_X(x) = \int_{\mathbb{R}} f_{X,Y}(x, y) dy \quad \forall x \in \mathbb{R}.$

If in addition Y is valued in $\mathcal{Y} \subset \mathbb{R}_+$ and $f_Y(y) > 0$ for all $y \in \mathcal{Y}$:

$$f_X(x) = \int_{\mathcal{Y}} f_{X|Y=y}(x) f_Y(y) dy$$

■ Conditional distribution - Continuous case

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space $(\mathcal{X}, \mathcal{B})$ measure space Random variable $\Omega \rightarrow \mathcal{X}$

Law of total probability

Let (X, Y) be a RVec with joint pdf $f_{X,Y} : f_X(x) = \int_{\mathbb{R}} f_{X,Y}(x, y) dy \quad \forall x \in \mathbb{R}.$

If in addition Y is valued in $\mathcal{Y} \subset \mathbb{R}_+$ and $f_Y(y) > 0$ for all $y \in \mathcal{Y} :$

$$f_X(x) = \int_{\mathcal{Y}} f_{X|Y=y}(x) f_Y(y) dy$$

Bayes' theorem

Let (X, Y) be a RVec with joint pdf $f_{X,Y}$. For all $(x, y) \in \mathbb{R}^2$ such that

$$f_X(x), f_Y(y) \neq 0 : f_{Y|X=x}(y) = \frac{f_{X|Y=y}(x) f_Y(y)}{f_X(x)}$$

Three vertical gray bars are positioned in the background, one on the left, one in the center, and one on the right. They are slightly wider at the top and bottom, giving them a stylized appearance.

MOMENTOUS MOMENTS

■ Moments - Expectation



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Expectation

The expectation of a RV X is $\mathbf{E}(X) = \int_{\mathbb{R}} x \mathbf{P}_X(dx) \in \mathbb{R}$ when the integral is absolutely convergent



Expectation \approx average behavior of X

■ Moments - Expectation

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Expectation

The expectation of a RV X is $\mathbf{E}(X) = \int_{\mathbb{R}} x \mathbf{P}_X(dx) \in \mathbb{R}$ when the integral is absolutely convergent



Expectation \approx average behavior of X

■ X has pdf f_X : $\mathbf{E}(X) = \int_{\mathbb{R}} x f_X(x) dx$

■ X has pmf p_X : $\mathbf{E}(X) = \sum_{x \in \mathbb{R}} x p_X(x)$

■ $\forall B \in \mathcal{B}(\mathbb{R}) : \mathbf{E}[\mathbf{1}\{X \in B\}] = \mathbf{P}_X(B) = \mathbf{P}(X \in B)$

■ $X \in \mathbb{R}^d \Rightarrow \mathbf{E}(X) = (\mathbf{E}(X_1), \dots, \mathbf{E}(X_d)) \in \mathbb{R}^d$

Moments - Expectation



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Properties : for any random variables X, Y with existing expectations

$$\blacksquare \quad \forall \alpha, \beta \in \mathbb{R} : \quad \mathbf{E}(\alpha X + \beta Y) = \alpha \mathbf{E}(X) + \beta \mathbf{E}(Y) \quad (\text{linearity})$$

$$\blacksquare \quad X \text{ and } Y \text{ independent} \quad \Rightarrow \quad \mathbf{E}(XY) = \mathbf{E}(X) \mathbf{E}(Y) \quad (\nRightarrow)$$

$$\blacksquare \quad g(X) \text{ valued in a measure space} \quad \Rightarrow \quad \mathbf{E}(g(X)) = \int_{\mathbb{R}} g(x) \mathbf{P}_X(dx)$$

$$\blacksquare \quad \phi \text{ convex function on } \mathbb{R} \quad \Rightarrow \quad \phi(\mathbf{E}(X)) \leq \mathbf{E}(\phi(X)) \quad (\text{Jensen's inequality})$$

$$\blacksquare \quad X \text{ nonnegative, } a > 0 \quad \Rightarrow \quad \mathbf{P}(X \geq a) \leq \frac{\mathbf{E}(X)}{a} \quad (\text{Markov's inequality})$$

■ Moments - Variance



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Variance

The variance of a RV X is $\mathbf{V}(X) = \mathbf{E} \left((X - \mathbf{E}(X))^2 \right)$ when the expectations exist (we can also write $\text{Var}(X)$)



Variance \approx average deviation to the average behavior of X



$\sigma(X) := \sqrt{\mathbf{V}(X)}$ **standard deviation** of X

■ Moments - Variance



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

Variance

The variance of a RV X is $\mathbf{V}(X) = \mathbf{E} \left((X - \mathbf{E}(X))^2 \right)$ when the expectations exist (we can also write $\text{Var}(X)$)

★ Variance \approx average deviation to the average behavior of X

★ $\sigma(X) := \sqrt{\mathbf{V}(X)}$ **standard deviation** of X

■ $\mathbf{V}(X) = \mathbf{E}(X^2) - \mathbf{E}(X)^2$

■ $\forall \alpha, \beta \in \mathbb{R} : \mathbf{V}(\alpha X + \beta) = \alpha^2 \mathbf{V}(X)$

■ $\forall a > 0 : \mathbf{P}(|X - \mathbf{E}(X)| \geq a) \leq \frac{\mathbf{V}(X)}{a^2}$ (Chebyshev's inequality)

■ Moments - Covariance



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Covariance

The covariance of a RVec $X = (X_1, \dots, X_d)$ is defined as the $d \times d$ matrix

$$\Sigma^X := \mathbf{E} \left((X - \mathbf{E}(X)) (X - \mathbf{E}(X))^T \right)$$

when the expectations exist



Covariance \approx average deviation to independence of X

RVs X and Y independent $\Rightarrow \text{Cov}(X, Y) = 0$



■ Moments - Covariance

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random vector $\Omega \rightarrow \mathcal{X}$

Covariance

The covariance of a RVec $X = (X_1, \dots, X_d)$ is defined as the $d \times d$ matrix

$$\Sigma^X := \mathbf{E} \left((X - \mathbf{E}(X)) (X - \mathbf{E}(X))^T \right)$$

when the expectations exist



Covariance \approx average deviation to independence of X

RVs X and Y independent $\Rightarrow \text{Cov}(X, Y) = 0$



- Σ^X positive, semi-definite, symmetric
- $\forall (i, j) \in \llbracket 1, d \rrbracket^2 : \Sigma_{i,j}^X =: \text{Cov}(X_i, X_j)$ and $\Sigma_{i,i}^X = \mathbf{V}(X_i)$
- $\Sigma^X = \mathbf{E}(X X^T) - \mathbf{E}(X) \mathbf{E}(X)^T$

■ Conditional moments



$(\Omega, \mathcal{A}, \mathbf{P})$ probability space

$(\mathcal{X}, \mathcal{B})$ measure space

Random variable $\Omega \rightarrow \mathcal{X}$

X, Y RVs with joint pdf $f_{X,Y}$ plus finite expectations and variances

$y \in \mathbb{R}$ such that $f_Y(y) \neq 0$

■ Conditional moments

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space $(\mathcal{X}, \mathcal{B})$ measure space Random variable $\Omega \rightarrow \mathcal{X}$

X, Y RVs with joint pdf $f_{X,Y}$ plus finite expectations and variances

$y \in \mathbb{R}$ such that $f_Y(y) \neq 0$

Conditional expectation : $\mathbf{E}(X | Y = y) = \int_{\mathbb{R}} x f_{X|Y=y}(x) dx$

■ $\mathbf{E}(X | Y) : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ real-valued RV

■ $\mathbf{E}(X) = \mathbf{E}(\mathbf{E}(X | Y))$ (law of total expectation)

■ Conditional moments

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space $(\mathcal{X}, \mathcal{B})$ measure space Random variable $\Omega \rightarrow \mathcal{X}$

X, Y RVs with joint pdf $f_{X,Y}$ plus finite expectations and variances

$y \in \mathbb{R}$ such that $f_Y(y) \neq 0$

Conditional expectation : $\mathbf{E}(X | Y = y) = \int_{\mathbb{R}} x f_{X|Y=y}(x) dx$

■ $\mathbf{E}(X | Y) : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ real-valued RV

■ $\mathbf{E}(X) = \mathbf{E}(\mathbf{E}(X | Y))$ (law of total expectation)

Conditional variance : $\mathbf{V}(X | Y = y) = \mathbf{E}\left(\left(X - \mathbf{E}(X | Y = y)\right)^2 \mid Y = y\right)$

■ $\mathbf{V}(X | Y) : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ real-valued RV

■ $\mathbf{V}(X) = \mathbf{E}(\mathbf{V}(X | Y)) + \mathbf{V}(\mathbf{E}(X | Y))$ (law of total variance)

■ Conditional moments

$(\Omega, \mathcal{A}, \mathbf{P})$ probability space $(\mathcal{X}, \mathcal{B})$ measure space Random variable $\Omega \rightarrow \mathcal{X}$

X, Y, Z RVs with joint pdf $f_{X,Y,Z}$ plus finite expectations and variances

$z \in \mathbb{R}$ such that $f_Z(z) \neq 0$

Conditional covariance :

$$\text{Cov}(X, Y \mid Z = z) = \mathbf{E} \left((X - \mathbf{E}(X \mid Z = z)) (Y - \mathbf{E}(Y \mid Z = z)) \mid Z = z \right)$$

■ $\text{Cov}(X, Y \mid Z) : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ real-valued RV

■ $\text{Cov}(X, Y) = \mathbf{E}(\text{Cov}(X, Y \mid Z)) + \text{Cov}(\mathbf{E}(X \mid Z), \mathbf{E}(Y \mid Z))$
(law of total covariance)

COMMON DISTRIBUTIONS

- Binomial distribution
- Poisson distribution
- Uniform distribution
- Exponential distribution
- Gaussian distribution
- Multivariate Gaussian distribution

■ Common distributions - Binomial



$$X \sim \mathcal{B}(n, p) \quad (n, p) \in \mathbb{N}^* \times [0, 1] \quad X : (\Omega, \mathcal{A}) \rightarrow ([0, n], \mathcal{P}([0, n]))$$

$$\forall x \in \mathbb{R} : F_X(x) = \sum_{k=0}^{\lfloor x \rfloor} \binom{n}{k} p^k (1-p)^{n-k} \mathbf{1}_{\{x \in [0, n)\}} + \mathbf{1}_{\{x \geq n\}}$$

$$p_X(x) = \binom{n}{x} p^x (1-p)^{n-x} \mathbf{1}_{\{x \in [0, n]\}}$$

$$\mathbf{E}(X) = np$$

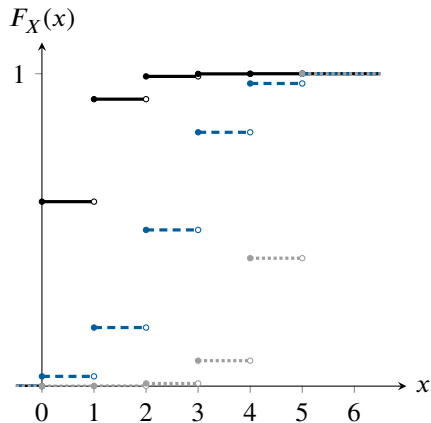
$$\mathbf{V}(X) = np(1-p)$$

$$n = 1 \quad \Rightarrow \quad X \sim \mathcal{B}(p) \text{ Bernoulli distribution}$$

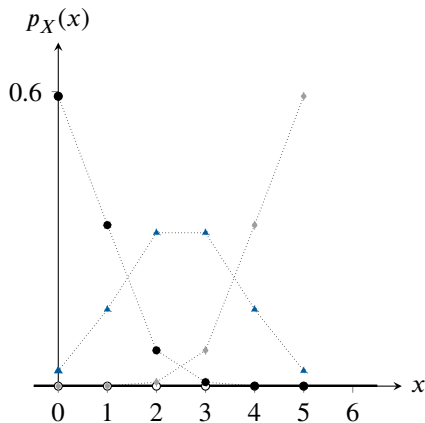
Common distributions - Binomial



$$X \sim B(5, p)$$



— $p = 0.1$ --- $p = 0.5$ $p = 0.9$



● $p = 0.1$ ▲ $p = 0.5$ ◆ $p = 0.9$

■ Common distributions - Poisson



$$X \sim \mathcal{P}(\lambda)$$

$$\lambda \in \mathbb{R}_+^*$$

$$X : (\Omega, \mathcal{A}) \rightarrow (\mathbb{N}, \mathcal{P}(\mathbb{N}))$$

$$\forall x \in \mathbb{R} : F_X(x) = \frac{\Gamma(\lfloor x + 1 \rfloor, \lambda)}{\lfloor x \rfloor!} \mathbf{1}_{\{x \geq 0\}}$$

$$p_X(x) = \frac{e^{-\lambda} \lambda^x}{x!} \mathbf{1}_{\{x \in \llbracket 0, n \rrbracket\}}$$

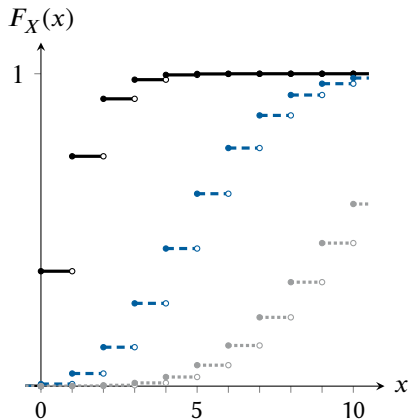
$$\mathbf{E}(X) = \lambda$$

$$\mathbf{V}(X) = \lambda$$

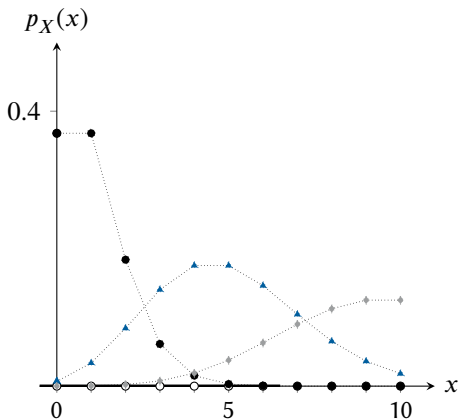
Common distributions - Poisson



$$X \sim \mathcal{P}(\lambda)$$



— $\lambda = 1$ --- $\lambda = 5$ $\lambda = 10$



• $\lambda = 1$ ▲ $\lambda = 5$ ♦ $\lambda = 10$

■ Common distributions - Uniform



$$X \sim \mathcal{U}_{[a,b]}$$

$$(a, b) \in \mathbb{R}^2, a < b$$

$$X : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$$

$$\forall x \in \mathbb{R} : F_X(x) = \frac{x-a}{b-a} \mathbf{1}_{\{x \in [a, b]\}} + \mathbf{1}_{\{x > b\}}$$

$$f_X(x) = \frac{1}{b-a} \mathbf{1}_{\{x \in [a, b]\}}$$

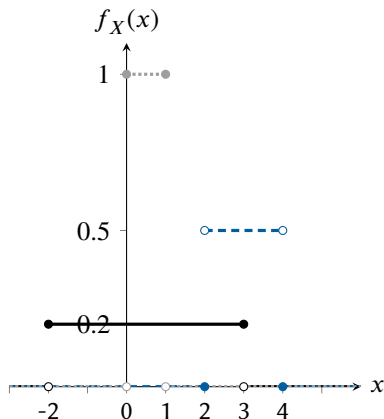
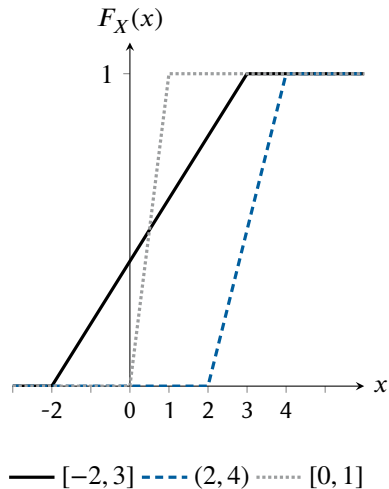
$$E(X) = \frac{a+b}{2}$$

$$V(X) = \frac{(b-a)^2}{12}$$

Common distributions - Uniform



$$X \sim \mathcal{U}_{[a,b]}$$



■ Common distributions - Exponential



$$X \sim \mathcal{E}(\lambda)$$

$$\lambda \in \mathbb{R}_+^*$$

$$X : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}_+, \mathcal{B}(\mathbb{R}_+))$$

$$\forall x \in \mathbb{R} : F_X(x) = 1 - e^{-\lambda x} \mathbf{1}_{\{x \geq 0\}}$$

$$f_X(x) = \lambda e^{-\lambda x} \mathbf{1}_{\{x \geq 0\}}$$

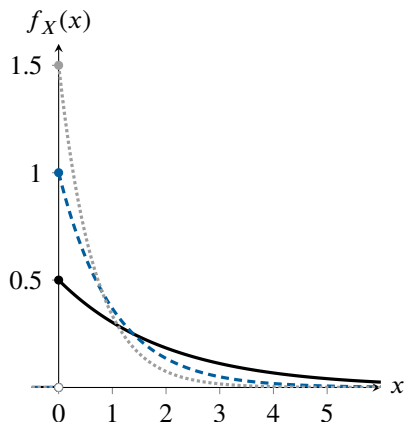
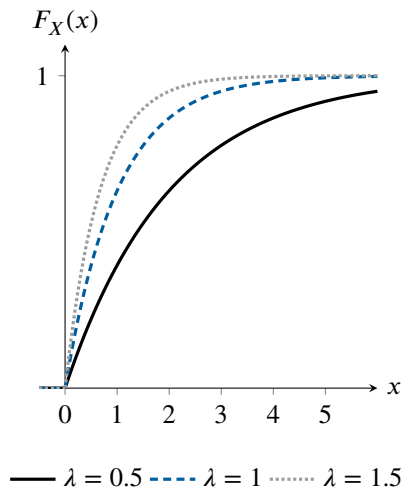
$$\mathbf{E}(X) = \frac{1}{\lambda}$$

$$\mathbf{V}(X) = \frac{1}{\lambda^2}$$

Common distributions - Exponential



$$X \sim \mathcal{E}(\lambda)$$



$$X \sim \mathcal{N}(\mu, \sigma^2) \qquad (\mu, \sigma^2) \in \mathbb{R} \times \mathbb{R}_+^* \qquad X : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$$

$$\forall x \in \mathbb{R} : F_X(x) = \frac{1}{2} \left(1 + \operatorname{erf} \frac{x - \mu}{\sigma \sqrt{2}} \right)$$

$$f_X(x) = \frac{1}{\sigma \sqrt{2\pi}} \exp \left\{ \frac{-(x - \mu)^2}{2\sigma^2} \right\}$$

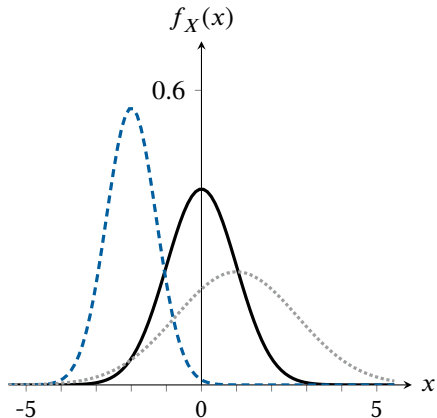
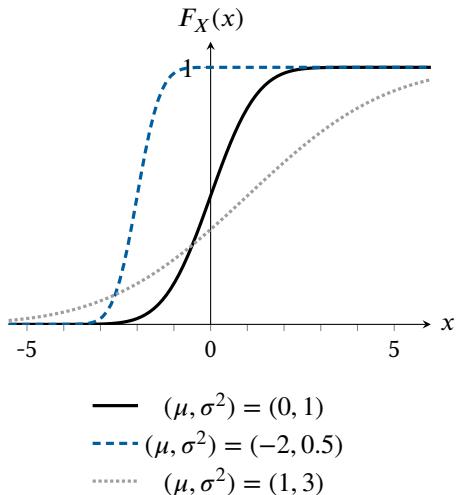
$$\mathbf{E}(X) = \mu$$

$$\mathbf{V}(X) = \sigma^2$$

Common distributions - Gaussian



$$X \sim \mathcal{N}(\mu, \sigma^2)$$



$$X \sim \mathcal{N}(\mu, \Sigma) \quad (\mu, \Sigma) \in \mathbb{R}^d \times \mathcal{M}_{d \times d}(\mathbb{R}_+^*), d \in \mathbb{N}^* \quad X : (\Omega, \mathcal{A}) \rightarrow (\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$$

$$\forall x \in \mathbb{R}^d : f_X(x) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{d/2}} \exp \left\{ \frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

$$\mathbf{E}(X) = \mu$$

$$\mathbf{V}(X) = \Sigma$$

■ Common distributions - Multi. Gaussian



$$X \sim \mathcal{N} \left(\begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 0.25 & 0.3 \\ 0.3 & 2 \end{pmatrix} \right)$$

