

# TMLE for continuous-time survival analysis

## 1 Simulation plan

We consider a setting in which we have observations on a bounded interval of time  $[0, \tau]$  of the following:

- $L_0 \in \mathbb{R}$ , is a uniformly distributed baseline covariate.
- $A \in \{0, 1\}$  is binary baseline treatment.
- $L(t) \in \mathbb{R}^p$  is a time-varying covariate  $L(t) \in \mathbb{R}^p$  with corresponding univariate counting process  $N^\ell(t)$ . We denote the times where  $N^\ell(t)$  jumps by  $T_1^\ell, T_2^\ell, \dots$  (with  $T_0^\ell = 0$ ).
- $C(t) \in \{0, 1\}$  is a censoring indicator: Represented as a binary variable that jumps only once and only at a jump time of the corresponding counting process  $N^c(t)$ . We denote by  $T^c$  the time where  $C(t)$  jumps from 0 to 1.
- $Y(t) \in \{0, 1\}$  is the event indicator: Represented as a binary variable that jumps only once and only at a jump time of the corresponding counting process  $N^y(t)$ . Denote by  $T^y$  the time where  $Y(t)$  jumps from 0 to 1.

Potentially the setting should also include:

- An indicator of death (or other competing risk),  $D(t) \in \{0, 1\}$ , represented as a binary variable that jumps only once and only at a jump time of a corresponding counting process  $N^d(t)$ . Then we also denote by  $T^d$  the time where  $D(t)$  jumps from 0 to 1.

In Section 3 we describe the simulation scheme in detail.

## 2 Statistical estimation problem

## 3 Simulation scheme

We let  $\Delta(T_k) = \mathbb{1}\{T_k = T_k^\ell\} + 2 \cdot \mathbb{1}\{T_k = T^c\}$ , i.e.,  $\Delta(T_k)$  is an indicator, at time  $k$ , of what event happened at time  $T_k$  (a bit odd now, since  $\Delta(T_k) = 0$  indicates event of interest,  $\Delta(T_k) = 1$  indicates monitoring of covariates and  $\Delta(T_k) = 2$  indicates censoring, but whatever, this can of course be changed). Table 1 gives an overview of how the simulations were done. We present more detail in the following. For the simulations we have used  $\tau = 365.24$ . Table 2 shows an example of simulated data for a subject. Figure 1 plots monitoring times (jumps of  $N^\ell(t)$ ), censoring times (jumps of  $N^c(t)$  or  $\tau = 365.24$ ) and event times (jumps of  $N^y(t)$ ).

### 3.1 Baseline variables

We draw the baseline covariate  $L_0$  and the treatment as follows:

$$\begin{aligned} L_0 &\sim \text{unif}(0, 1), \\ A &\sim \text{Bern}(\text{expit}(\beta_0^A + \beta_1^A L_0)). \end{aligned}$$

---

Draw:	$L_0 \sim \text{unif}(0, 1)$ $A \sim \text{Bern}(\text{expit}(\beta_0^A + \beta_1^A L_0))$ $L_1(0) \sim \text{unif}(0, 1)$ $L_2(0) \sim \text{unif}(0, 1)$ $L_3(0) \sim \text{unif}(0, 1)$
Initialize:	$T_0 = 0, \Delta = 1$
From $k$ to $k + 1$ :	$V \sim \text{unif}(0, 1)$ $W_{k+1}   T_k = t \sim \tilde{\Lambda}_t^{-1}(-\log V, A, L_0, L_1(T_k), L_2(T_k), L_3(T_k))$ $T_{k+1} = T_k + W_{k+1}$ $p^y = \phi^y(A, L_0, L_1(T_k), L_2(T_k), L_3(T_k), k)$ $p^\ell = \phi^\ell(A, L_0, L_1(T_k), L_2(T_k), L_3(T_k), k)$ $p^c = \phi^c(A, L_0, L_1(T_k), L_2(T_k), L_3(T_k), k)$ $p' = p^y + p^\ell + p^c$ $\Delta \sim (\{0, 1, 2\}, p = (p^y/p', p^\ell/p', p^c/p'))$
if $\Delta = 1$ :	$L_1(T_{k+1}) \sim N(\mu = 0.05L_0 + L_1(T_k), \sigma = 0.1)$ $L_2(T_{k+1}) \sim N(\mu = 0.02A + 0.025L_0 + L_2(T_k), \sigma = 0.1)$ $L_3(T_{k+1}) \sim N(\mu = 0.04A + 0.0167L_0 + L_3(T_k), \sigma = 0.1)$
if $\Delta \in \{0, 2\}$ :	Stop.
if $\Delta \in \{0, 2\}$ :	Stop.

---

Table 1: Simulation overview.

### 3.2 Weibull intensities

For  $x = \ell, y, c$ , we define,

$$\lambda_k^x(t | \mathcal{F}_{t-}) = \eta \nu t^{\nu-1} \phi^x(t | \mathcal{F}_{t-}), \quad (1)$$

where  $\eta$  is a scale parameter and  $\nu$  is a shape parameter. For instance, the Weibull distribution allows the baseline to increase ( $\nu > 1$ ) or decrease ( $\nu < 1$ ).

For each subject,  $T_k$  denotes the time between the origin and the  $k$ th monitoring. We have that  $T_0 = 0$ . Now define  $W_k = T_k - T_{k-1}$ , the  $k$ th waiting time between two consecutive events. We simulate these waiting times.

Notably, we need the conditional intensity  $\tilde{\lambda}_k$  for  $W_k | T_{k-1} = t$ . This is derived by,

$$\tilde{\lambda}_k(u | T_{k-1} = t) du = \lambda(u + t) du,$$

where  $\lambda$  is the intensity for the original times. The corresponding cumulative hazard is now,

$$\tilde{\Lambda}_k(u | T_{k-1} = t) = \int_0^u \tilde{\lambda}_k(s | T_{k-1} = t) ds = \int_0^u \lambda(s + t) ds = \Lambda(u + t) - \Lambda(t)$$

id	time	$\Delta$	$L_1$	$L_2$	$L_3$	$A$	$L_0$
9	0	1	0.996	0.79	0.566	1	0.556
9	134	1	0.939	0.932	0.577	1	0.556
9	163	0	0.939	0.932	0.577	1	0.556

Table 2: Simulated data for id=9.

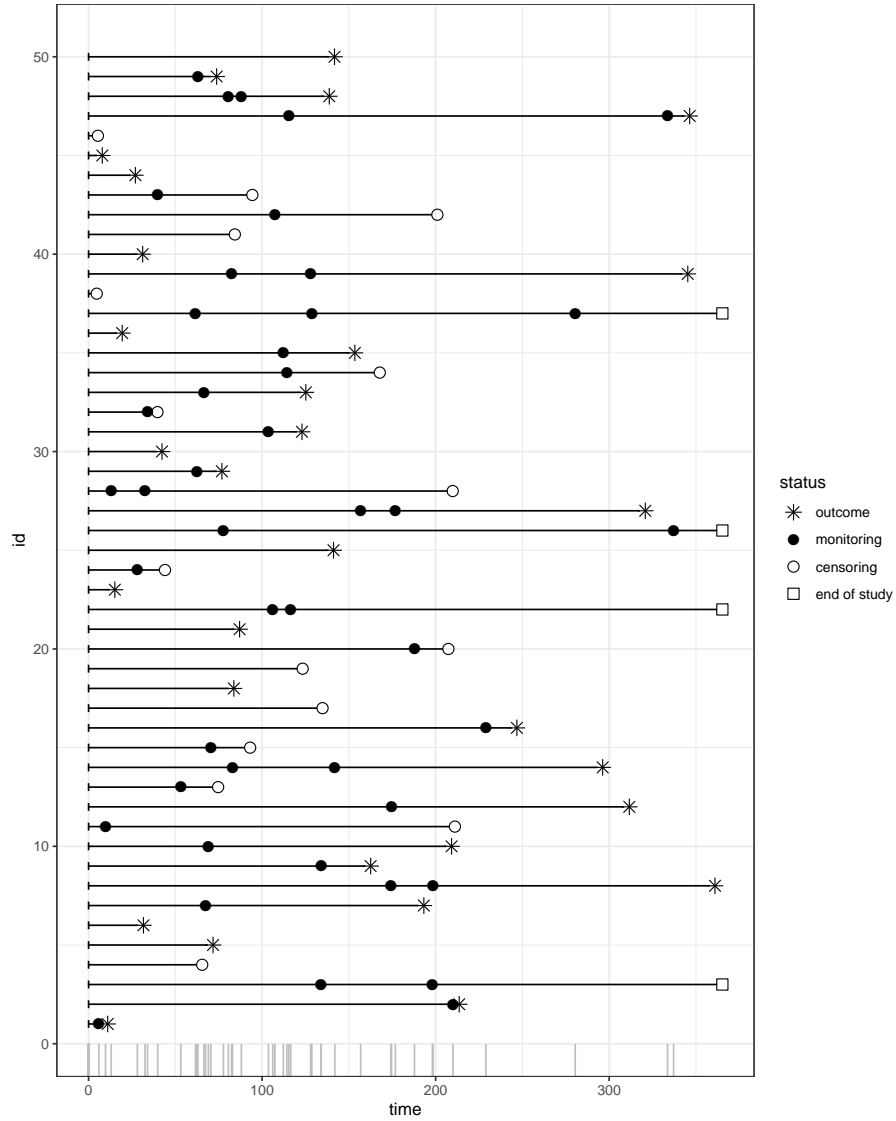


Figure 1: Plot showing simulated data (monitoring and event times).

And then we can use that,

$$W_k | T_{k-1} = t \sim \tilde{\Lambda}_t^{-1}(-\log V),$$

where  $V \sim \text{unif}(0, 1)$ .

The cumulative intensities of the waiting times corresponding to (1) are given as,

$$\tilde{\Lambda}_t^x(u) = \eta \phi^x(t | \mathcal{F}_{t-}) ((t+u)^\nu - t^\nu), \quad (2)$$

so that the cumulative hazard of  $T$  is,

$$\tilde{\Lambda}_t(u) = \tilde{\Lambda}_t^\ell(u) + \tilde{\Lambda}_t^y(u) + \tilde{\Lambda}_t^c(u) = \{\phi^\ell(t | \mathcal{F}_{t-}) + \phi^y(t | \mathcal{F}_{t-}) + \phi^c(t | \mathcal{F}_{t-})\} \eta ((t+u)^\nu - t^\nu) \quad (3)$$

Note that for (2) we have that,

$$\begin{aligned} \tilde{\Lambda}_t^x(u) &= \eta \phi^x(t | \mathcal{F}_{t-}) ((t+u)^\nu - t^\nu), \\ \tilde{\Lambda}_t^{-1}(u) &= \left( \frac{u + \eta t^\nu}{\eta} \right)^{1/\nu} - t, \end{aligned}$$

and similarly for (3) by substituting  $\eta (\phi^\ell(t | \mathcal{F}_{t-}) + \phi^y(t | \mathcal{F}_{t-}) + \phi^c(t | \mathcal{F}_{t-}))$  for  $\eta$ .

We simulate the monitoring times  $T_1, T_2, \dots$ . At each monitoring time we determine the type of event by drawing  $\Delta$  from  $\{0, 1, 2\}$  with probability  $p = (p^y/p', p^\ell/p', p^c/p')$ , where, at the  $k$ th time,

$$\begin{aligned} p^x &= \lambda_k^x(t | \mathcal{F}_{t-}), \quad x = \ell, y, c, \\ p' &= p^\ell + p^y + p^c, \end{aligned}$$

where, notably, the  $(\eta \nu t^{\nu-1})$  factors out. In our simulations, we let,

$$\begin{aligned} \phi^y(A, L_0, L_1(T_k), L_2(T_k), L_3(T_k), k) &= \eta_y \alpha_y^{\mathbb{1}\{k>3\}} \exp(\beta_{y,L_0} L_0 + \beta_{y,L}^\top L(T_{k-1}) + \beta_{y,A} A), \\ \phi^\ell(A, L_0, L_1(T_k), L_2(T_k), L_3(T_k), k) &= \eta_\ell \alpha_\ell^{\min(k, K_{\max})} \exp(\beta_{\ell,L_0} L_0 + \beta_{\ell,A} A), \\ \phi^c(A, L_0, L_1(T_k), L_2(T_k), L_3(T_k), k) &= \eta_c \alpha_c^{\mathbb{1}\{k>3\}} \exp(\beta_{c,L_0} L_0 + \beta_{c,A} A). \end{aligned}$$

Note that we include  $\alpha$  to adjust dependence on the number of previous events ( $\alpha > 1$  ( $\alpha < 1$ ) causes the rate to increase (decrease) with the number of previous events)

### 3.3 Time-varying covariates

At time  $T_0 = T_0^\ell$  we draw:

$$\begin{aligned} L_1(0) &\sim \text{unif}(0, 1), \\ L_2(0) &\sim \text{unif}(0, 1), \\ L_3(0) &\sim \text{unif}(0, 1), \end{aligned}$$

and at all following monitoring times  $T_k^\ell$ ,  $k = 1, 2, \dots$ , we draw covariates  $L_1(T_k), L_2(T_k), L_3(T_k)$  as follows:

$$\begin{aligned} L_1(T_{k+1}) &\sim N(\mu = 0.05L_0 + L_1(T_k), \\ L_2(T_{k+1}) &\sim N(\mu = 0.02A + 0.025L_0 + L_2(T_k), \sigma = 0.1), \\ L_3(T_{k+1}) &\sim N(\mu = 0.04A + 0.0167L_0 + L_3(T_k), \sigma = 0.1). \end{aligned}$$