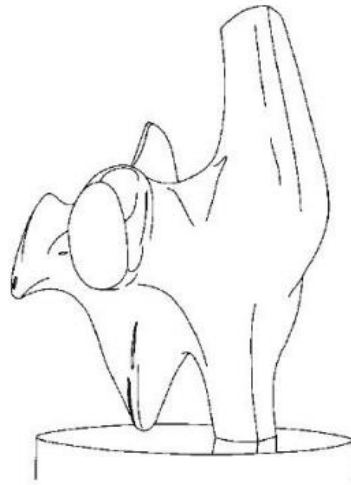


## Canny Edge Detection

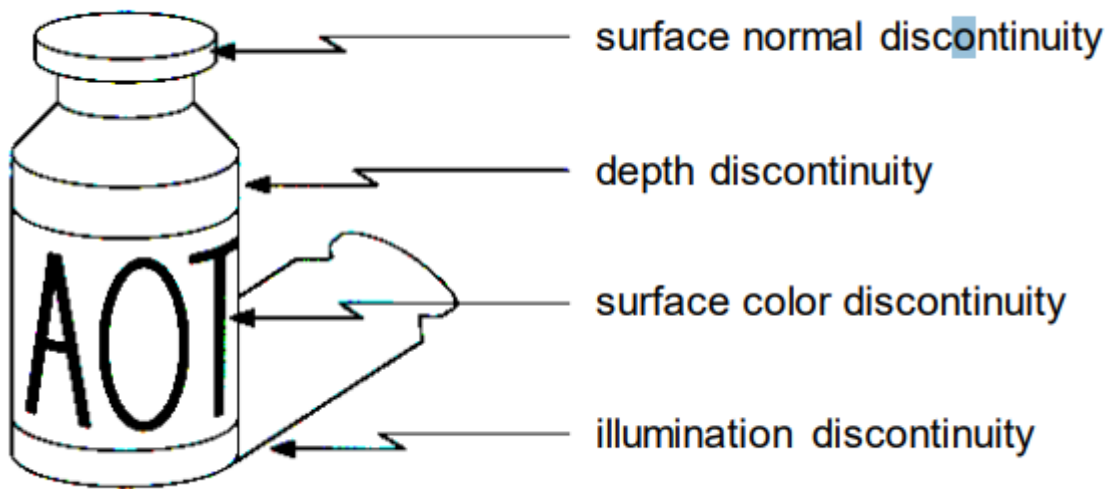
Edge detection



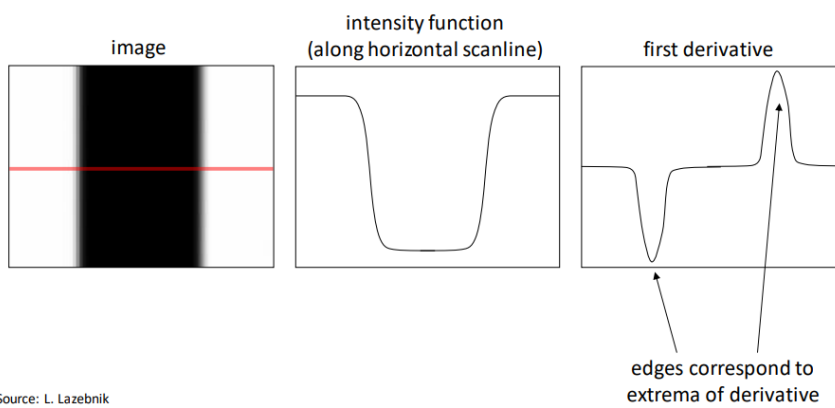
Edge가 왜 중요?

ex) 색깔이 다른 자동차. 같은 자동차인 것을 알아내기 위해서 edge를 이용.





이런 Edge..



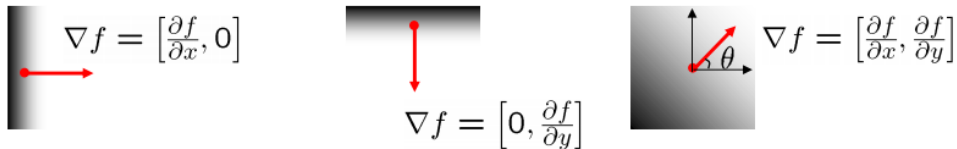
Source: L. Lazechnik

미분을 이용해서 Edge를 찾는다.

# Image gradient

- The *gradient* of an image:  $\nabla f = \left[ \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right]$

The gradient points in the direction of most rapid increase in intensity



The *edge strength* is given by the gradient magnitude:

$$\|\nabla f\| = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2}$$

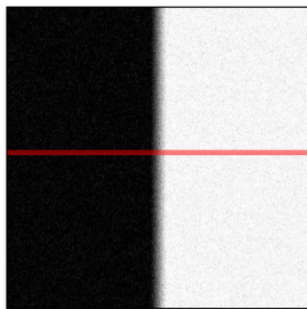
The gradient direction is given by:

$$\theta = \tan^{-1} \left( \frac{\partial f}{\partial y} / \frac{\partial f}{\partial x} \right)$$

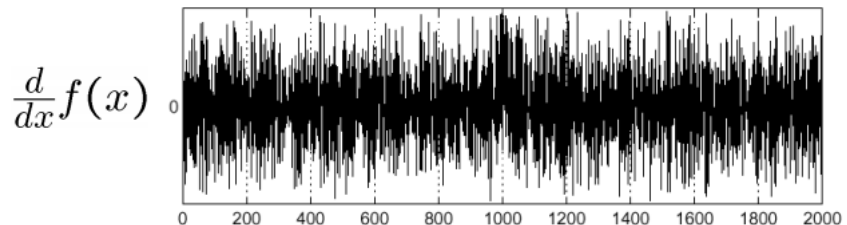
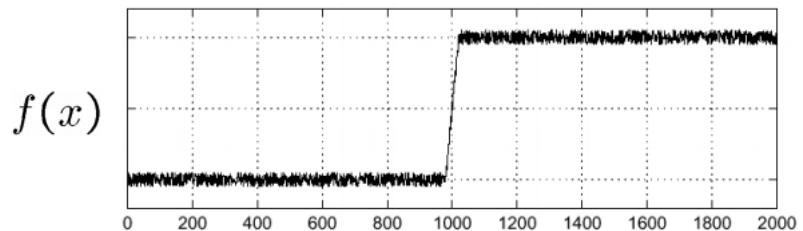
- how does this relate to the direction of the edge?

Source: Steve Seitz

Gradient.

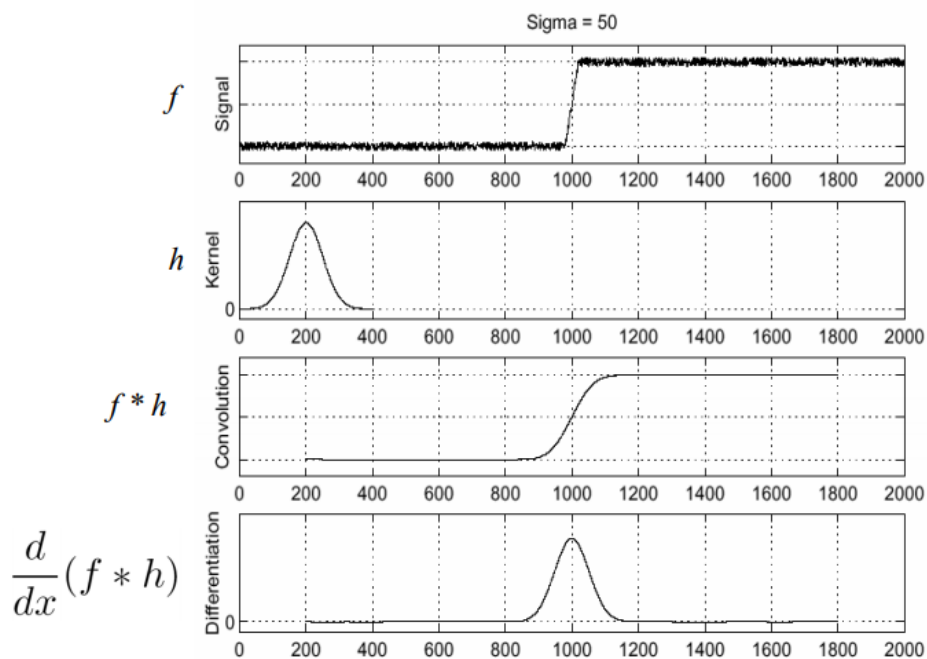


Noisy input image



Where is the edge?

Source: S. Seitz



To find edges, look for peaks in  $\frac{d}{dx}(f * h)$

Source: S. Seitz

- Differentiation is convolution, and convolution is associative:  $\frac{d}{dx}(f * h) = f * \frac{d}{dx}h$
- This saves us one operation:

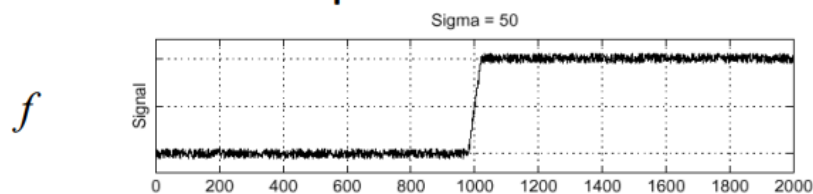
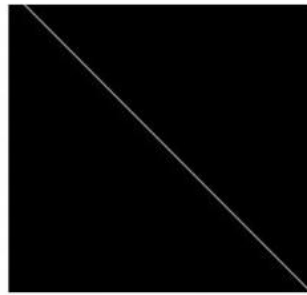




Image with Edge



Edge Location

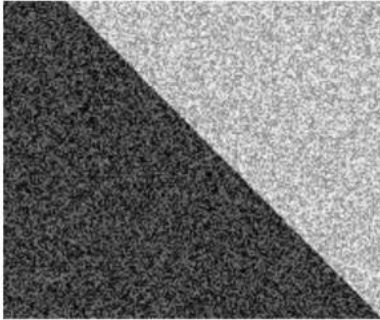
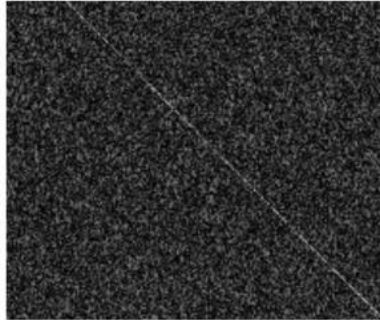
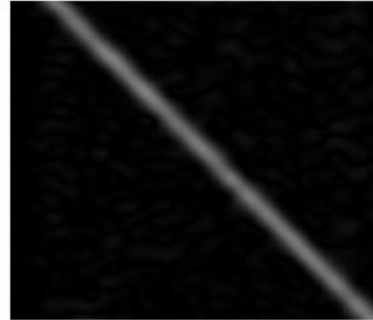


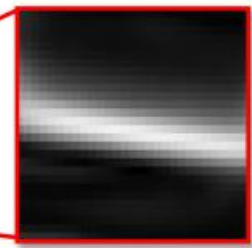
Image + Noise



Derivatives detect edge *and* noise



Smoothed derivative removes noise, but blurs edge

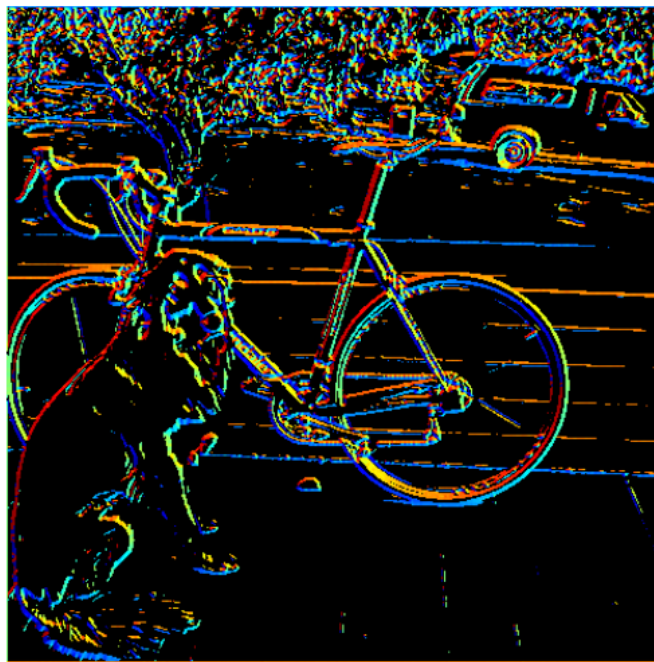


where is the edge?

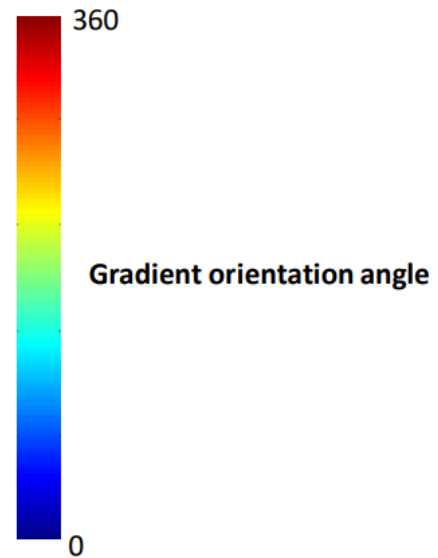
## thresholding

저 굵은 부분을 Edge라고 판단하기 어렵다. 최대한 edge를 가늘게 해줘야 할 필요가 있다.

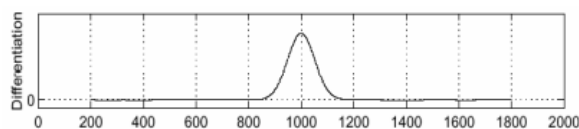
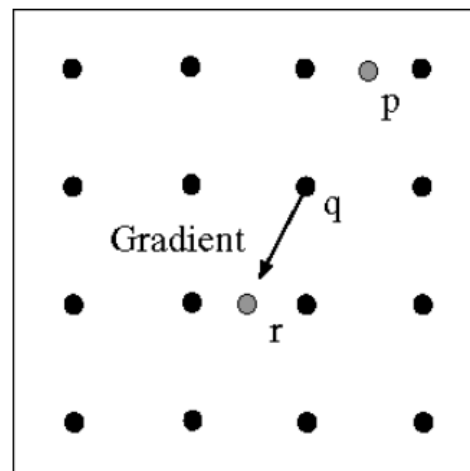
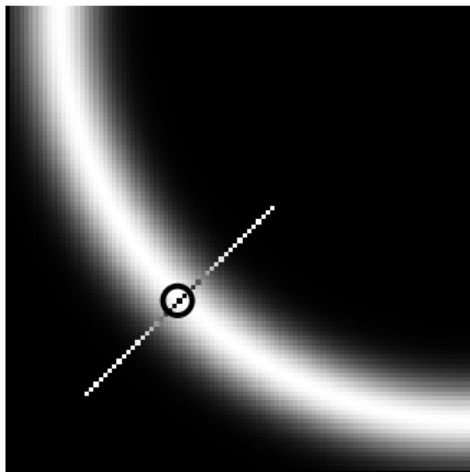
- Get orientation (below, threshold at minimum gradient magnitude)



theta =  
numpy.arctan2(gy, gx)



## Non-maximum suppression



- Check if pixel is local maximum along gradient direction
  - requires *interpolating* pixels p and r

## Before Non-max Suppression



## After Non-max Suppression



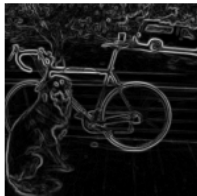
Non-max suppression을 적용함으로써 가늘어진 Edge를 볼 수 있다.



- Still some noise
- Only want strong edges
- 2 thresholds, 3 cases
  - $R > T$ : strong edge
  - $R < T$  but  $R > t$ : weak edge
  - $R < t$ : no edge
- Why two thresholds?



## Canny edge detector



1. Filter image with derivative of Gaussian
2. Find magnitude and orientation of gradient



3. Non-maximum suppression



4. Thresholding and linking (hysteresis):
  - Define two thresholds: low and high
  - Use the high threshold to start edge curves and the low threshold to continue them

Source: D. Lowe, L. Fei-Fei, J. Redmon



# Canny edge detector



original

Canny with  $\sigma = 1$

Canny with  $\sigma = 2$