



MATLAB/Simulink Model for I2C Peripheral Example: Roll and Pitch Angles Estimation using Curiosity Platform Development Board, dsPIC33AK128MC106 Curiosity GP DIM and MPU9250

1. INTRODUCTION

This document describes the setup requirements for demonstration of I2C communication on the hardware platform [EV74H48A](#) "Curiosity Platform Development Board" and [EV02G02A](#) "dsPIC33AK128MC106 General Purpose Dual In-Line Module (DIM)" using MPU9250 sensor on the MPU 9DOF Click Board.

MPU-9250 is a multi-chip module (MCM) with 9-axis Motion Tracking device that combines a 3-axis gyroscope, 3-axis accelerometer, 3-axis magnetometer and a Digital Motion Processor™ (DMP). This example exclusively uses 3-axis gyroscope, and the 3-axis accelerometer to estimate the roll and pitch angles.

2. SUGGESTED DEMONSTRATION REQUIREMENTS

2.1 MATLAB Model Required for the Demonstration

To clone or download this MATLAB model on GitHub,

- MATLAB model can be cloned or downloaded as zip file from the Github repository ([link](#)).

2.2 Software Tools Used for Testing the MATLAB/Simulink Model

- MPLAB® X IDE **v6.25**
- MPLAB® XC-DSC Compiler **v3.21**
- MATLAB R2024b
- Required MATLAB add-on packages
 - Simulink (v24.2)
 - Simulink Coder (v24.2)
 - MATLAB Coder (v24.2)
 - Embedded Coder (v24.2)
 - MPLAB Device blocks for Simulink (v3.62)
 - Motor Control Blockset (v24.2)

NOTE: The software tools used for testing the model during release is listed above. It is recommended to use the version listed above or later versions for building the model.

2.3 Hardware Tools Required for the Demonstration

- Curiosity Platform Development Board ([EV74H48A](#))

- dsPIC33AK128MC106 General Purpose Dual In-Line Module ([EV02G02A](#))
- [MPU 9DOF CLICK](#)

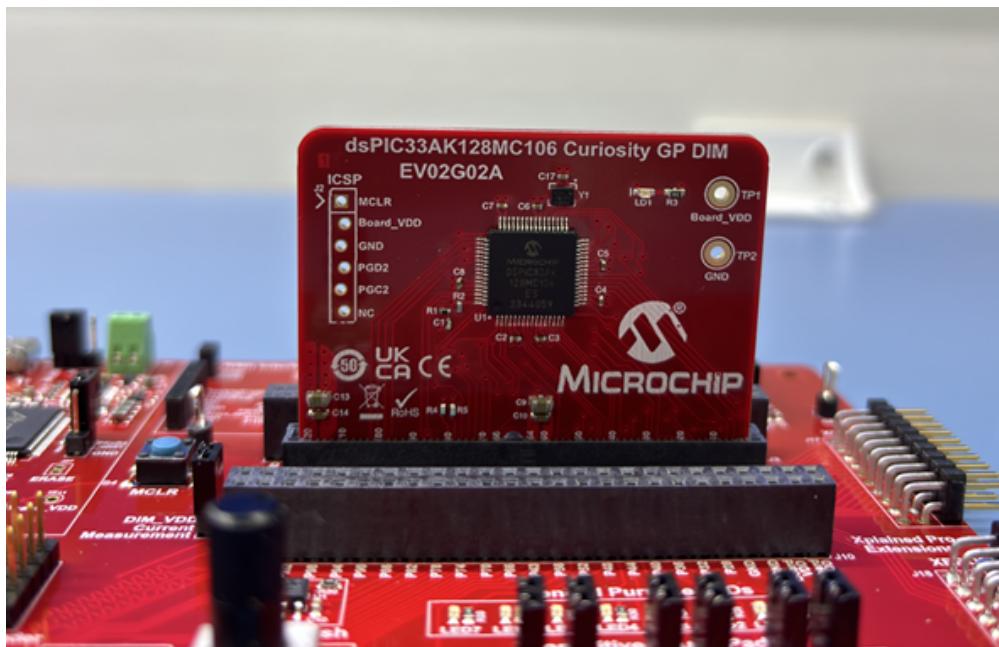
3. HARDWARE SETUP

This section describes the hardware setup required for the demonstration.

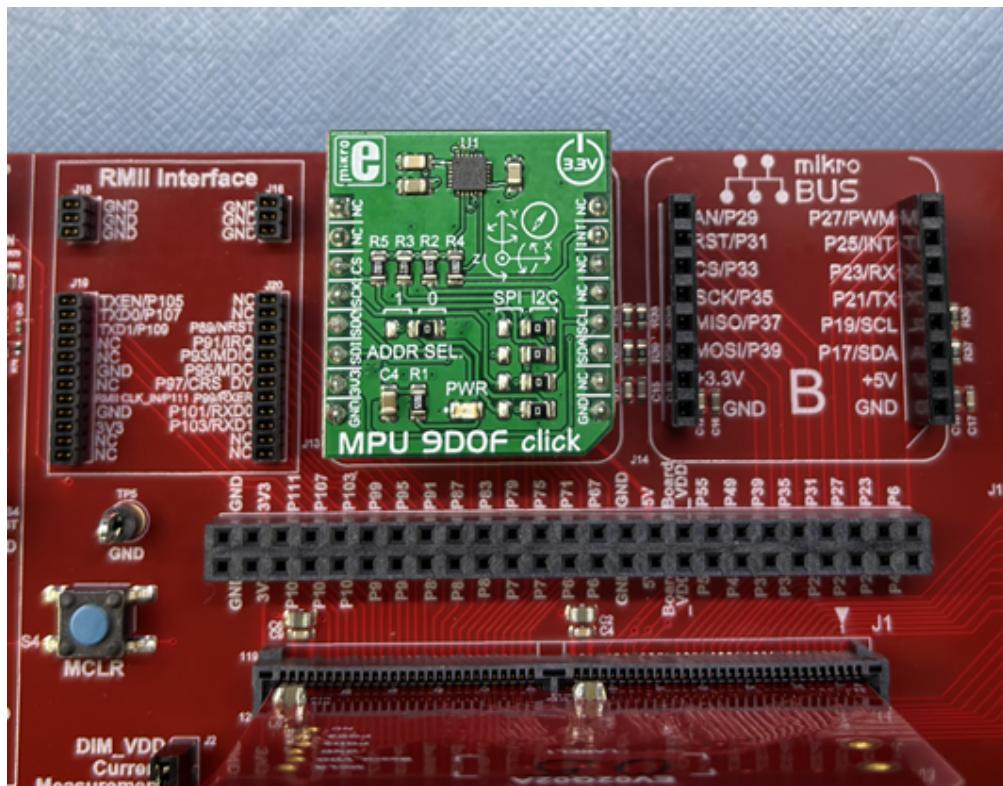
Note:

In this document, hereinafter Curiosity Platform Development Board is referred as **development board**.

1. Insert the **dsPIC33AK128MC106 Curiosity GP DIM** into the DIM Interface **connector J1** on the development board. Make sure the DIM is placed correctly and oriented before going ahead.

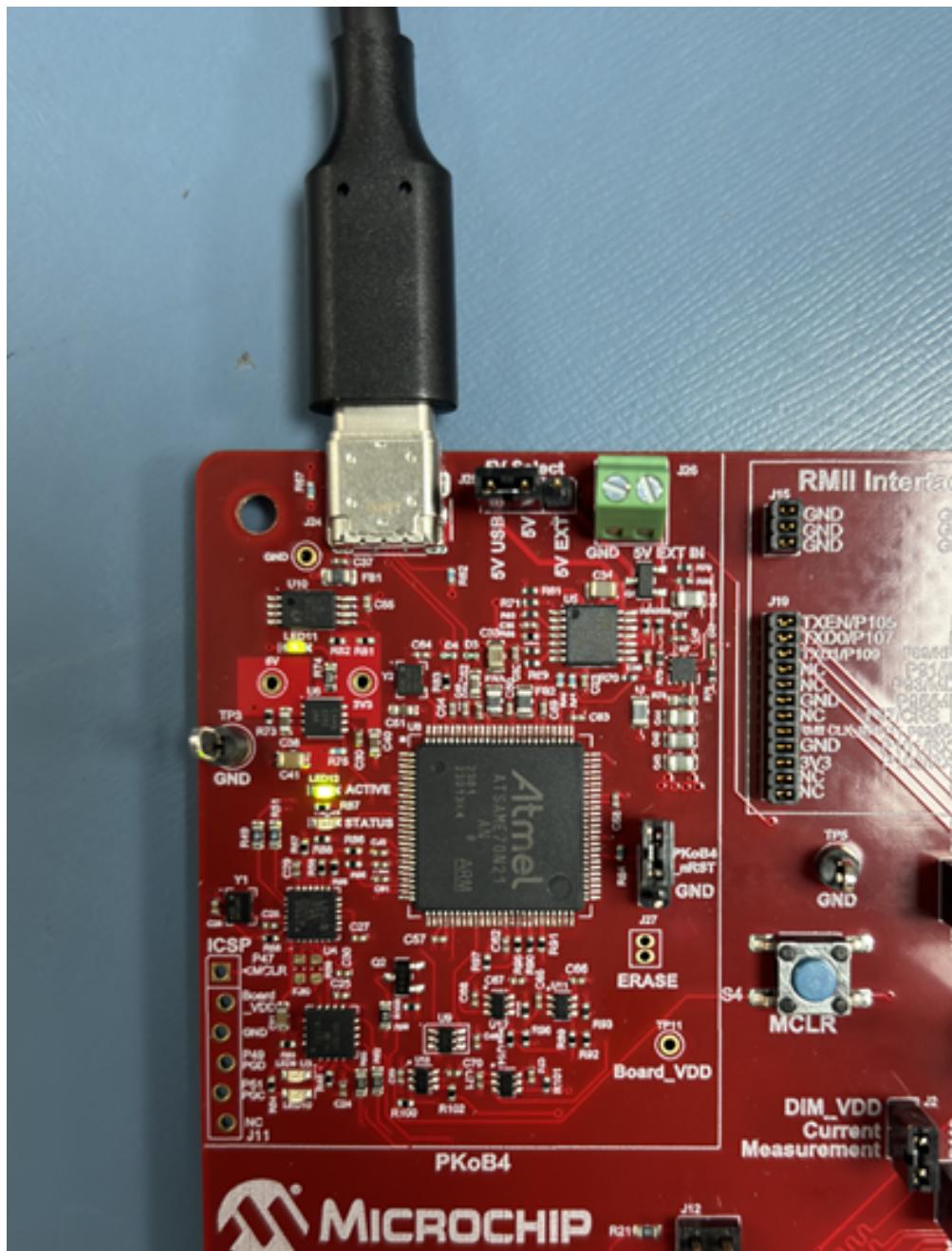


2. Insert the **MPU 9DOF click** into the **mikro BUS A** interface **connector J13** on the development board. Make sure the click board is inserted correctly before going ahead.



3. The development board has an onboard programmer **PICkit™ On Board (PKoBv4)**, which can be used for programming or debugging the microcontroller or dsPIC DSC on the DIM. To use the onboard programmer, connect a Micro-C® cable between the Host PC and **connector J24** on the development board.

The development board is also powered by this USB itself.



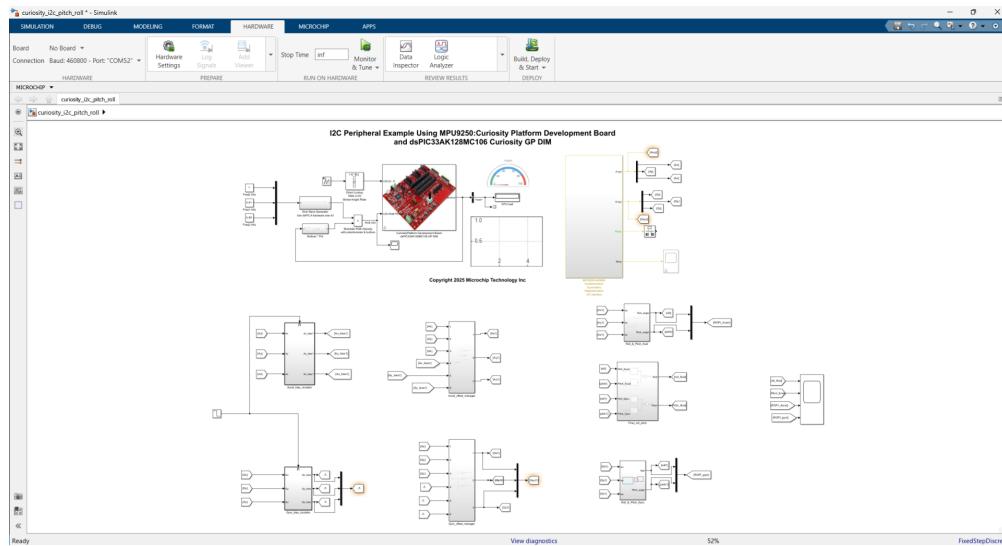
4. BASIC DEMONSTRATION

Follow the below instructions step-by-step, to set up and I2C demo application:

1. Launch MATLAB (refer the section "[2.2 Software Tools Used for Testing the MATLAB/Simulink Model](#)").
 2. Open the folder downloaded from the repository, in which MATLAB files are saved (refer the section "[2.1 MATLAB Model Required for the Demonstration](#)").



3. Double click on the I2C example Simulink model - **curiosity_i2c_pitch_roll.slx**. This opens the Simulink model as shown below.

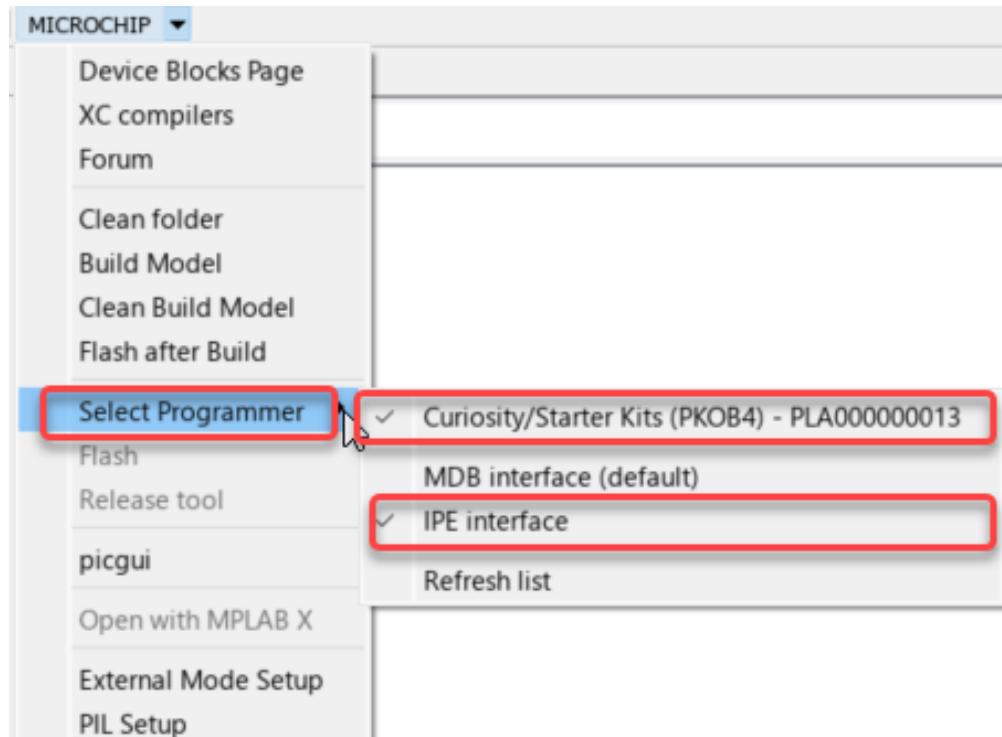


Note:

This example demonstrates only the code generation to demonstrate the I2C communication. The simulation is not possible in this case.

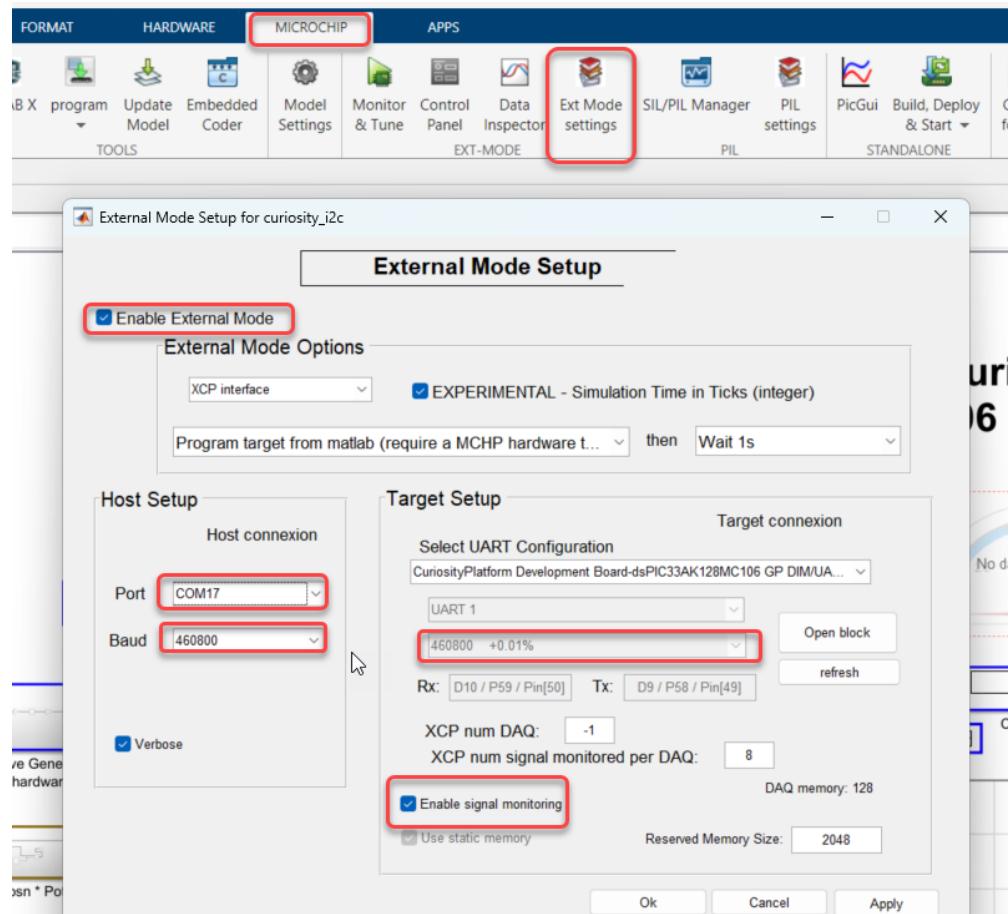
4. From this Simulink model an MPLAB X project can be generated, and it can be used to run the I2C Communication using development board.

To generate the code from the Simulink model, go to the "**MICROCHIP**" tab, and enable the tabs shown in the figure below.



5. This model uses the **External Mode** debug option for real time data visualization. To configure the external mode click on "**Ext Mode Settings**" option under the "**Microchip**" tab.

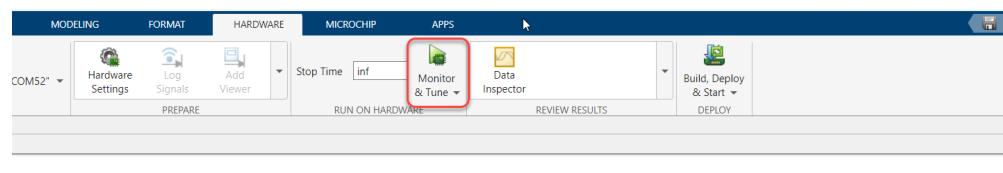
This will open **External Mode Setup** window and enable the checkboxes as shown in the figure. Also select the **COM port** connected to the development board and **Baud Rate**.



Note:

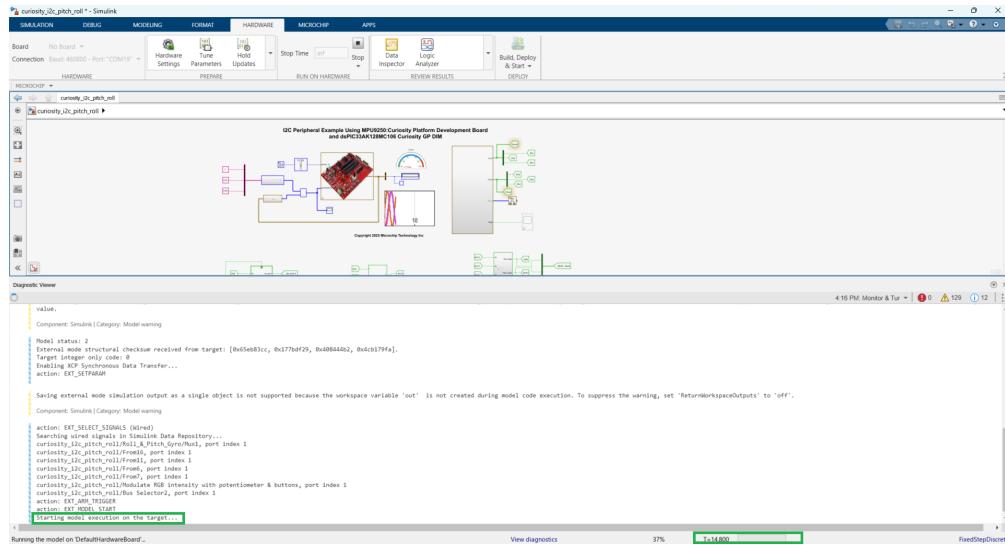
The PKOB4 based USB-UART Channel is used in this example for USB-UART communication. The development board has a 2-port USB hub.

6. To generate the code and run the I2C communication on hardware, click on "**Monitor & Tune**" option under the **Hardware** tab and ensure that "**Stop Time**" is set to "**inf**".

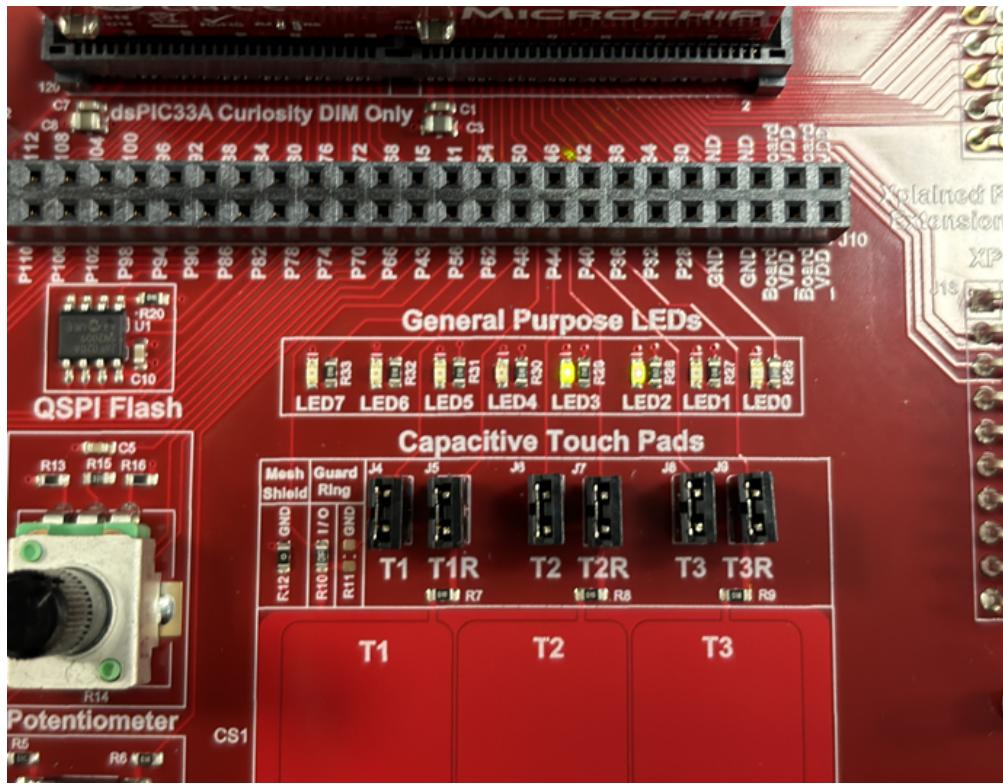


I2C Peripheral Example Using MPU9250:Curiosity Platform Development Board and dsPIC33AK128MC106 Curiosity GP DIM

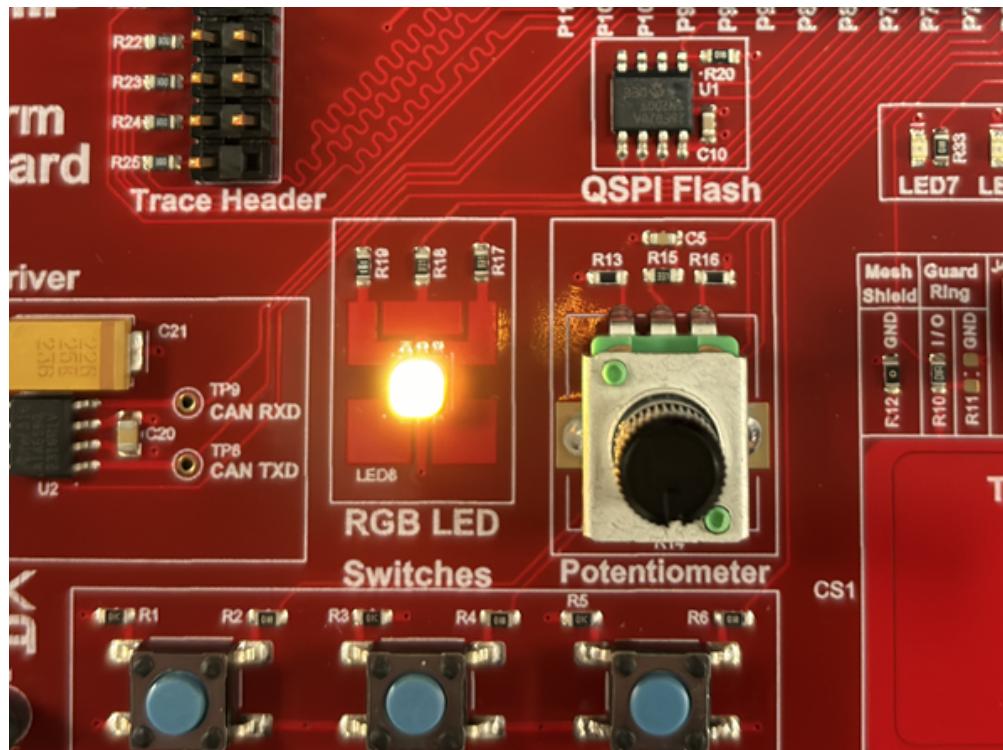
7. After compiling the code and programming the device, External Mode will be activated on the dsPIC DSC.



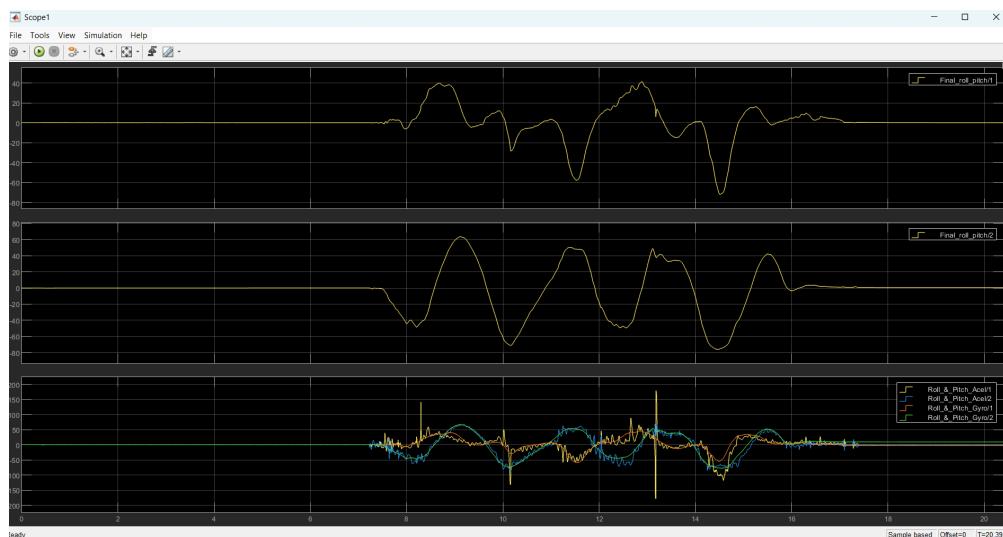
8. The **General Purpose LED's** will be blinking.



9. The **RGB LEB** will be glowing in different colors. To increase the brightness of the RGB LED, vary the **Potentiometer** on the development board.



10. To visualize the estimated roll and pitch angles from the **accelerometer, gyroscope sensors of MPU9250** double click on the scope. This opens the scope view. Tilt or turn the development board by hand to view variations in the roll and pitch angles.



11. Click on the **Stop** button to stop the I2C communication and external mode.

A screenshot of the Microchip Studio interface. The top navigation bar includes 'FORMAT', 'HARDWARE', 'MICROCHIP', 'APPS', 'SCOPE', and 'DEPLOY'. The 'HARDWARE' tab is selected. Under 'HARDWARE', there are buttons for 'Tune Parameters' and 'Hold Updates'. A red box highlights the 'Stop' button, which is part of a dropdown menu labeled 'Stop Time' with options 'inf' and 'Stop'. Below the hardware controls are sections for 'PREPARE', 'RUN ON HARDWARE', 'REVIEW RESULTS', and 'DEPLOY'. A note at the bottom states: '2C Peripheral Example Using MPU9250:Curiosity Platform Development Board and dsPIC33AK128MC106 Curiosity GP DIM'.

Note:

At each startup, the system calibrates the accelerometer and gyroscope of the **MPU 9DOF Click**

board. During this 2-second calibration period, the **development board** and **MPU 9DOF Click board** must remain stationary (do not move/ shake). After calibration, the board can be tilted or rotated to observe angle variations.

REFERENCES:

For more information, refer to the following documents or links.

1. Curiosity Platform Development Board User's Guide ([DS70005562](#))
2. dsPIC33AK128MC106 General Purpose Dual In-Line Module (DIM) Information Sheet ([DS70005556](#))
3. dsPIC33AK128MC106 Family datasheet ([DS70005539](#))
4. MPLAB® X IDE User's Guide ([DS50002027](#)) or MPLAB® X IDE help
5. [MPLAB® X IDE installation](#)
6. [MPLAB® XC-DSC Compiler installation](#)
7. [MPLAB Device Blocks for Simulink :dsPIC, PIC32 and SAM mcu](#)
8. [External Mode Demo](#)