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## AN1017 Demonstration ReadMe for the dsPIC33CK Low Voltage Motor Control Board with the dsPIC33CK256MP508 (MPLAB® X IDE)

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### 1. INTRODUCTION

This document describes the setup requirements for running the Sensored BLDC/PMSM Motor Control Algorithm, which is referenced in AN1017 “Sinusoidal Control of PMSM Motors” using a dsPIC33CK Low Voltage Motor Control Board.

### 2. SUGGESTED DEMONSTRATION REQUIREMENTS

#### 2.1. Motor Control Application Firmware Required for the Demonstration

- AN1017\_dsPIC33CK256MP508\_LVMC.zip

**Note:**

In this document, hereinafter this firmware package is referred as firmware.

#### 2.2. Software Tools Used for Testing the firmware

- MPLAB® X IDE v5.50 or later
- MPLAB® XC16 Compiler v1.70
- MPLAB® X IDE Plugin: X2C-Scope v1.30 or later

**Note:**

The software used for testing the firmware prior to release is listed above. It is recommended to use the version listed above or later versions for building the firmware.

#### 2.3. Hardware Tools Required for the Demonstration

- dsPIC33CK Low Voltage Motor Control Board (DM330031)
- 24V Power Supply (AC002013)
- 24V 3-Phase Brushless DC Motor (AC300020)

### 3. HARDWARE SETUP

**Note:**

All items listed under the section [2.3. Hardware Tools Required for the Demonstration](#) are available at [microchip DIRECT](#).

This section describes hardware setup required for the demonstration. Motor terminals connections and hall effect sensor connections are described here.

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1. Connect the three phase wires from the motor to PHA, PHB & PHC terminals of connector J14, provided on the Development Board as mentioned in the below table.

| LVMC Board | Hurst075 Motor                               |                                        |
|------------|----------------------------------------------|----------------------------------------|
|            | Winding Terminals (Color as per image below) | Molex 39-01-2040<br>(Mating Connector) |
| PHC        | Red                                          | 1                                      |
| PHB        | Black                                        | 2                                      |
| PHA        | White                                        | 3                                      |

2. Connect the hall sensors from the motor to HA, HB and HC terminals of connector J7, provided on the Development Board as mentioned in the below table.

| MCLV2 Board | Hurst075 Motor                               |                                        |
|-------------|----------------------------------------------|----------------------------------------|
|             | Hall Terminals<br>(Color as per image above) | Molex 50-57-9408<br>(Mating Connector) |
| 5V          | Red                                          | 1                                      |
| GND         | Black                                        | 2                                      |
| HA          | White                                        | 4                                      |
| HB          | Brown                                        | 3                                      |
| HC          | Green                                        | 5                                      |



3. Plug in the 24V power supply to connector J1 or J2 provided on the dsPIC33CK Low Voltage Motor Control Board.



4. The board has an on-board programmer 'PICKIT™ On Board (PKOBv4)', which can be used for programming or debugging dsPIC33CK256MP508 device. To use on-board programmer, connect a micro USB cable between Host PC and Connector J13 provided on the dsPIC33CK Low Voltage Motor Control Board.



5. Alternatively, connect the Microchip programmer/debugger MPLAB PICKit 4 In-Circuit Debugger to the Connector J10 of the dsPIC33CK Low Voltage Motor Control Board as shown below and to the Host PC used for programming the device. Ensure that PICKit 4 is connected in correct orientation.



## 4. SOFTWARE SETUP AND RUN

### 4.1. Setup: MPLAB X IDE and MPLAB XC16 Compiler

Install MPLAB X IDE and MPLAB XC16 Compiler versions that support the device dsPIC33CK256MP508 and PKOBv4. The version of the MPLAB X IDE, MPLAB XC16 Compiler and X2C-Scope plug-in used for testing the firmware are mentioned in the section [Software Tools Used for Testing the firmware](#). To get help on

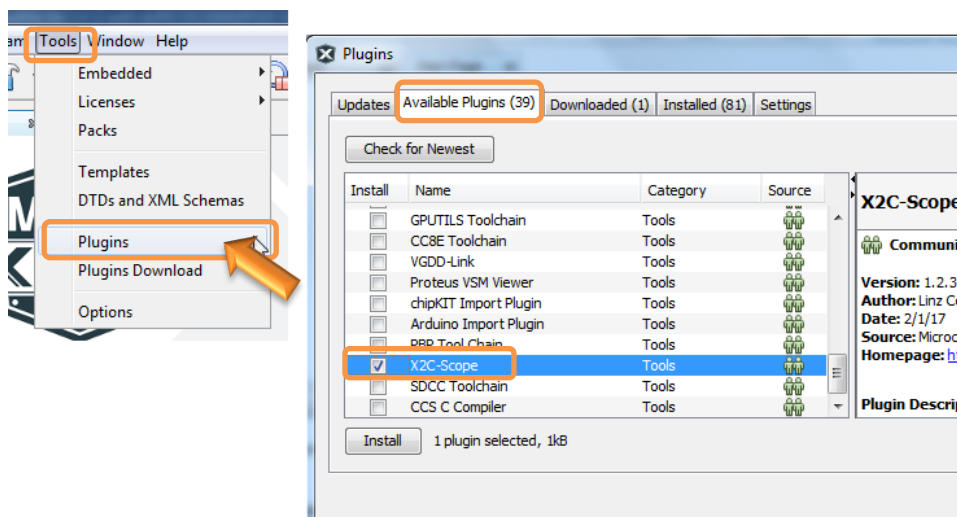
- MPLAB X IDE installation, refer [link](#)
- MPLAB XC16 Compiler installation steps, refer [link](#)

If MPLAB IDE v8 or earlier is already installed on your computer, then run the MPLAB driver switcher (It is installed when MPLAB®X IDE is installed) to switch from MPLAB IDE v8 drivers to MPLAB X IDE drivers. If you have Windows 7 or 8, you must run MPLAB driver switcher in 'Administrator Mode'. To run the Device Driver Switcher GUI application as administrator, right click on the executable (or desktop icon) and select 'Run as Administrator'. For additional details refer MPLAB X IDE help topic *"Before You Begin: Install the USB Device Drivers (For Hardware Tools): USB Driver Installation for Windows Operating Systems"*.

### 4.2. Setup: X2C - SCOPE

X2C - SCOPE is a MPLAB X IDE plugin that allows a developer to interact with an application while the application program is running. X2C-Scope enables you to read, write, and plot global variables (for motor control) in real time. It communicates with the target using the UART. To use X2C, the plugin must be installed:

- In MPLAB X IDE, select **Tools>Plugins** and click on the **Available Plugins** tab.
- Select X2C - SCOPE plug-in by checking its check box, and then click **Install**.
- Look for tool X2C - SCOPE under **Tools>Embedded**.



### 5. BASIC DEMONSTRATION

#### 5.1. Firmware Description

The firmware version required for the demonstration is mentioned under the section [Motor Control Application Firmware Required for the Demonstration](#).

This firmware is implemented to work on Microchip's 16-bit Digital signal controller (dsPIC® DSC) dsPIC33CK256MP508. For more information, see the *dsPIC33CK256MP508 Family datasheet (DS70005349)*.

The Motor Control Demo application uses push button to start or stop the motor and potentiometer to vary speed of the motor.

For more details refer Microchip Application note AN1017 "Sinusoidal Control of PMSM Motors with dsPIC30F / dsPIC33F/ dsPIC33E DSC" available at [Microchip web site](#)

**Note:**

The project may not build correctly in Windows OS if Maximum path length of any source file in the project is more than 260 characters. In case absolute path is exceeding or nearing maximum length, do any (or both) of the following:

- Shorten the name of the directory containing the firmware used in this demonstration. In this case, rename directory AN1017\_dsPIC33CK256MP508\_LVMC to more appropriate shorter name. In case you renamed the directory, consider the new name while reading instructions provided in the upcoming sections of the document.
- Place firmware in a location, such that absolute path length of each file included in the projects does not exceed the Maximum Path length specified.

For details, refer MPLAB X IDE help topic "*Path, File and Folder Name Restrictions*".

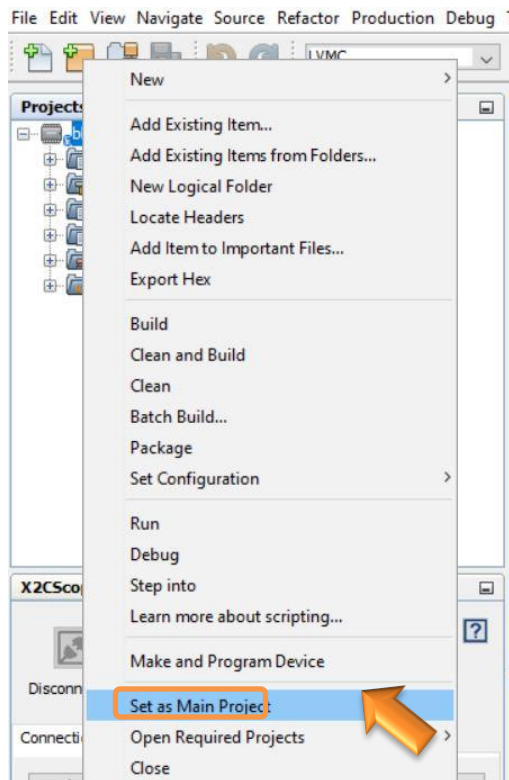
### 5.2 Basic Demonstration

Follow below instructions step by step to setup and run the motor control demo application:

1. Start MPLAB X IDE and open (File>Open Project) the project `bldc.X` (`..\AN1017_dsPIC33CK256MP508_LVMC\bldc.X`) with device selection `dsPIC33CK256MP508`.



2. Set the project `bldc.X` as main project by right clicking on the project name and selecting "Set as Main Project" as shown. The project "**bldc**" will then appear in **bold**.



3. Open `bldc_main.h` (under `bldc.X` -> `headerfiles`) in the project `bldc.X` & define the `OPENLOOP` for Open Loop running & Undefine it for closed loop operation

```
63 // Section: MODE OF OPERATION
64 // *****
65 #undef OPENLOOP
66
```



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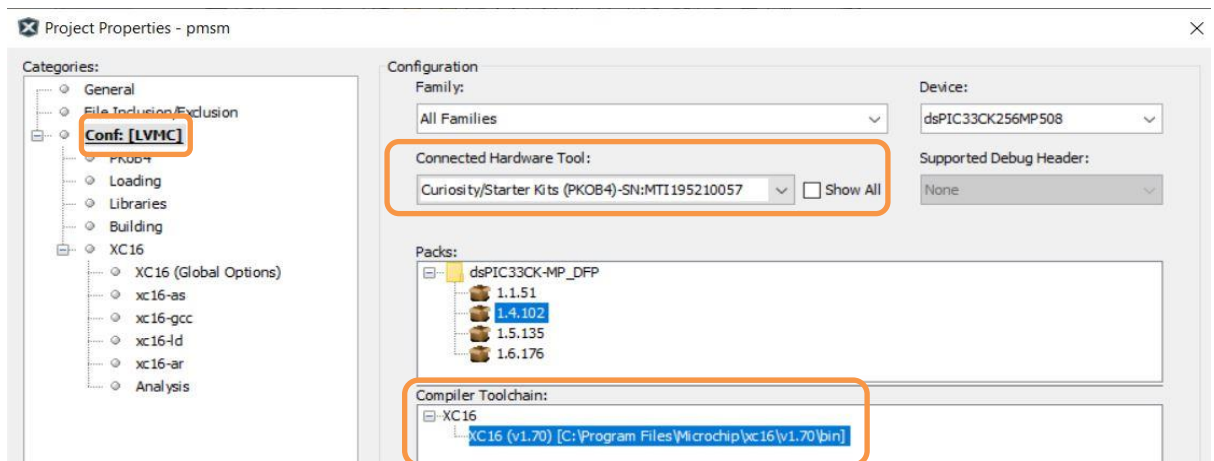
Comment out the `#define PHASE_ADVANCE` for above base speed applications

```
67  /* GLOBAL DEFINES FOR FUNCTIONING MODE */
68  /* undefine for negation */
69  // #define PHASE_ADVANCE    // for extended speed ranges this should be defined
```

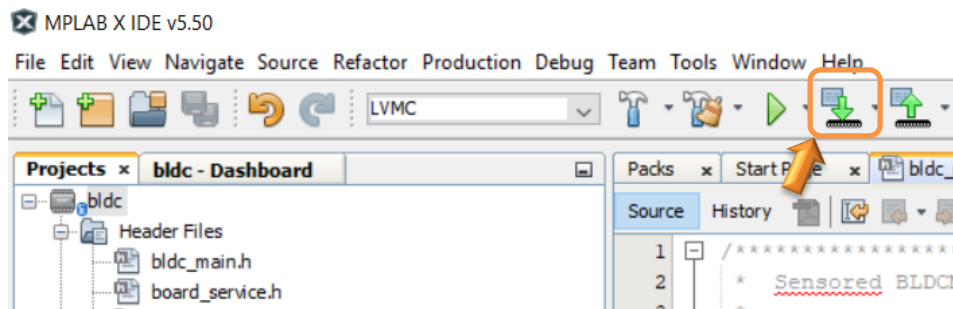
- Right click on the project *pmsm.X* and select “Properties” to open its Project Properties Dialog. Click the “Conf: [default]” category to reveal the general project configuration information.

In the ‘**Conf-LVMC**’ category window:

- Select the specific Compiler Toolchain from the available list of compilers. Please ensure MPLAB® XC16 Compiler supports the device dsPIC33CK256MP508. In this case “XC16(v1.70)” is selected. The compiler used for testing the firmware is listed in the section [2.2 Software Tools Used for Testing the firmware](#).
- Select the Hardware Tool to be used for programming and debugging. In this case, “MPLAB PKoB 4” is the selected programmer.
- After selecting Hardware Tool and Compiler Toolchain, click button **Apply**



- To build the project (in this case *bldc.X*) and program the device dsPIC33CK256MP508, click “**Make and Program Device Main project**” on the toolbar.



- If the device is successfully programmed, **LD10 (‘LED2’)** will be turned ON, indicating that the dsPIC® DSC is enabled.

7. Run or Stop the motor by pressing the push button **SW1**. The function of the pushbutton **SW1** (Run/Stop of the motor) is indicated by turning ON or OFF the **LED1 (LD11)**.



8. If desired, the motor speed can be varied using the potentiometer (labeled "POT1").



9. To reverse the direction of rotation, press the push button **SW2**.
10. Press the push button **SW1** to stop the motor.

**Note:**

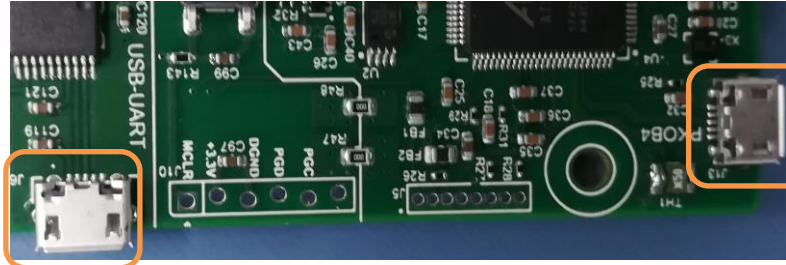
The macro definitions `MAX_MOTORSPEED`, `MAX_MOTORCURRENT`, `POLEPAIRS`, `SECTOR` and `MAX_BOARDCURRENT` are specified in `bldc_main.h` file included in the project `bldc.X`. The definitions `MAX_MOTORSPEED` and `MAX_MOTORCURRENT` are defined as per the specification provided by the Motor manufacturer. *Exceeding manufacturer specification may lead to damage to the motor or (and) the board.*



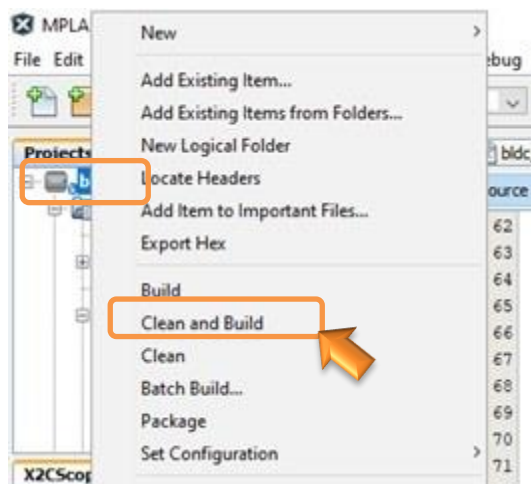
### 6. Data visualization through X2CScope Plug-in of MPLABX

The application firmware comes with initialization required to interface Controller with Host PC to enable Data visualization through X2C Scope plug-in. X2C-Scope is a third-party plugin for MPLAB X which facilitates real-time diagnostics.

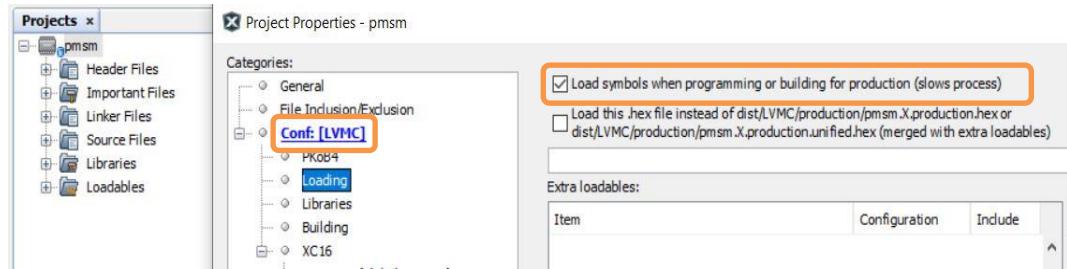
1. Ensure X2C Scope Plug-in is installed. For additional information on how to set up a plug-in refer to <https://microchipdeveloper.com/mplabx:tools-plugins-available>
2. To utilize X2C communication for this demonstration, a micro-USB connection is required between Host PC and dsPIC33CK Low Voltage Motor Control Board. PKob 4 Connector J13 can be used to communicate between Host PC and dsPIC33CK Low Voltage Motor Control Board, alternatively Connect a micro-USB cable from your computer to the J6 connector of the dsPIC33CK Low Voltage Motor Control Board.



3. Ensure application is configured and running as described under Section [5.2 Basic Demonstration](#) by following steps 1 through 11.
4. Build the project *blde.X*. To do that right click on the project *blde.X* and select “Clean and Build”.

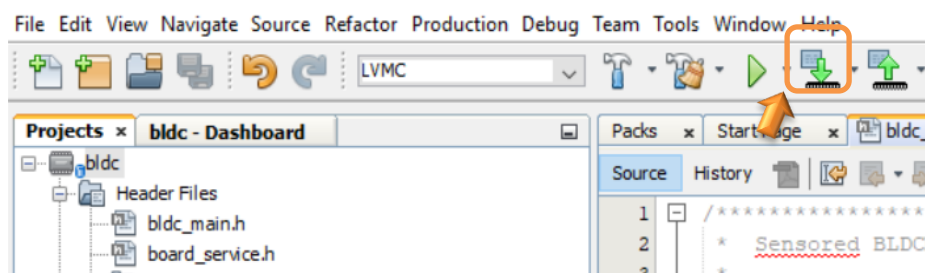


- Please ensure that the checkbox “Load symbols when programming or building for production (slows process)” is checked, which is under the “Loading” category of the Project Properties window

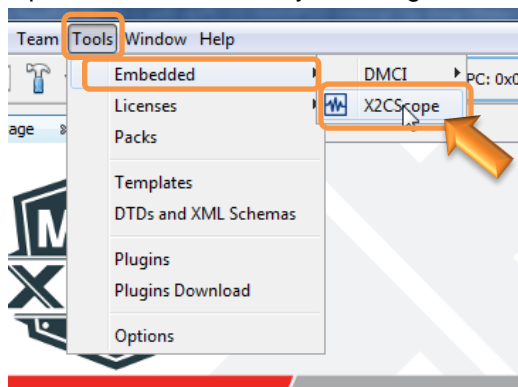


- To build the project (in this case *bldc.X*) and program the device dsPIC33CK256MP508, click “**Make and Program Device Main project**” on the toolbar.

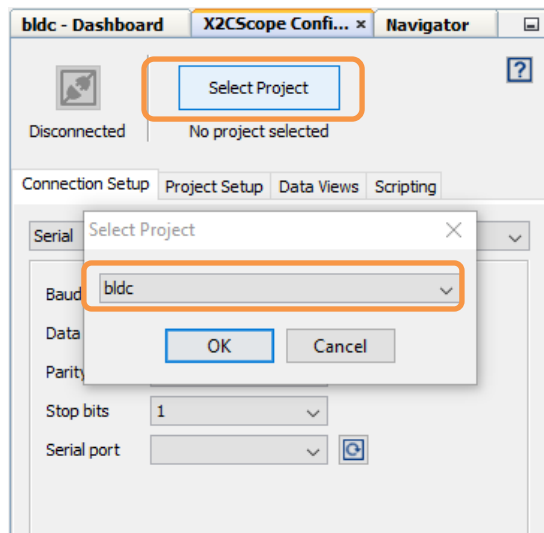
MPLAB X IDE v5.50



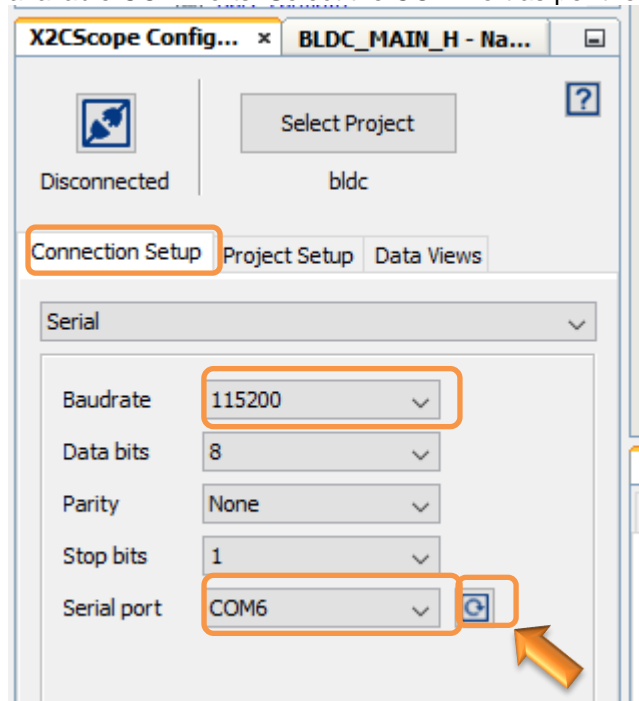
- Open the X2C window by selecting Tools>Embedded>X2CScope.



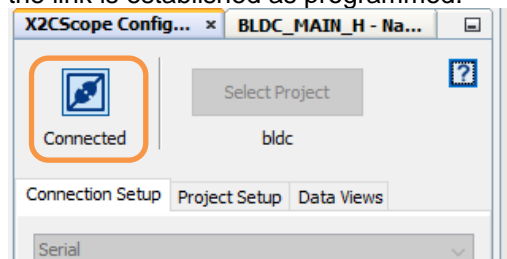
- Open the X2CScope Configuration window and in “Select project” menu, select bldc project as shown.



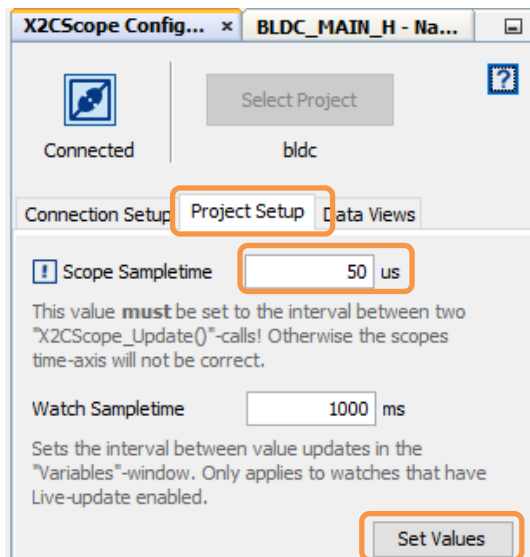
9. Remote Communication needs to be established, as indicated in the following figure. Ensure the communication baud rate is set to 115200 as the same is set in the application firmware, while COM port used depends on the system settings. Refresh button lists the available COM Ports. Select the COM Port as per the connection.



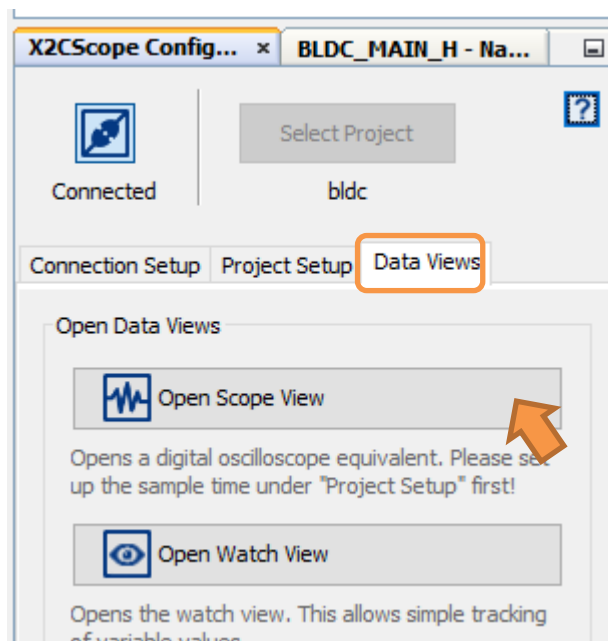
10. Once COM port detected, click on “Disconnected”, and it will be turn into “Connected”, if the link is established as programmed.



11. Set the “Project Setup” as shown below and click “Set Values”. Set Scope sample time as interval at which X2CScopeUpdate() is called. In this application it is every 20kHz (50µs).



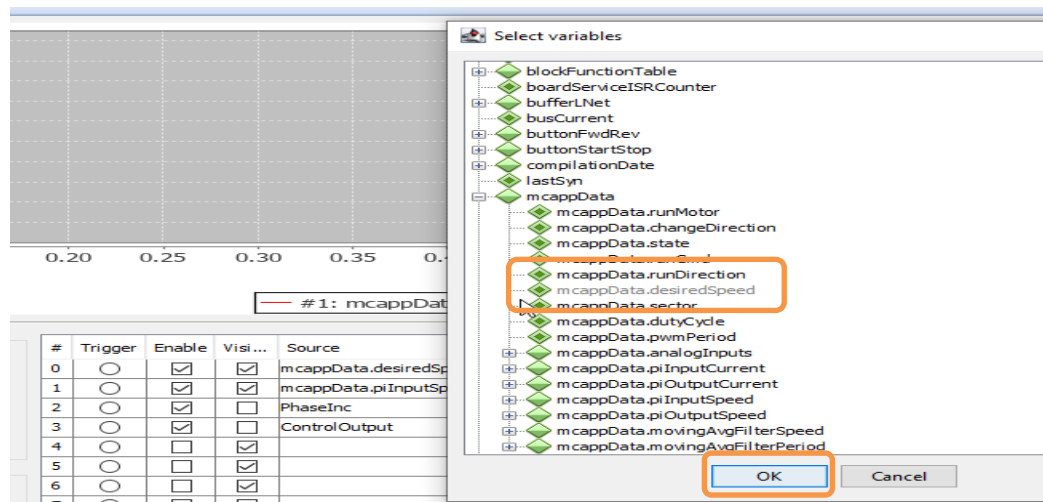
12. When the setup is established, click on open scope View (under sub window “Data Views”), this open Scope Window.



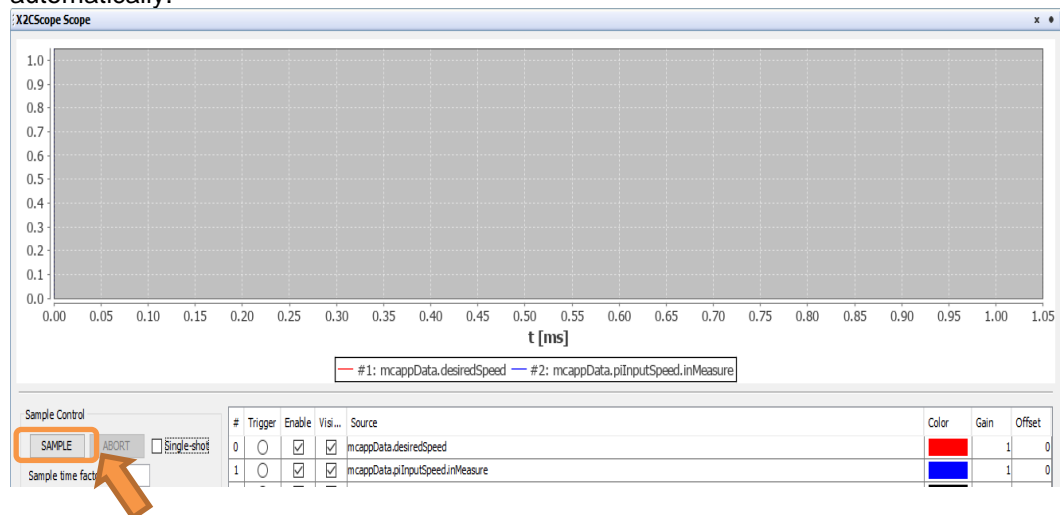
13. In this window, select the variables that needs to be monitored. To do this, click on the source against each channel, a window Select Variables opens upon the screen. From the available list, the required variable can be chosen. Ensure check boxes Enable & Visible are checked for the variables to be plotted

To view data plots continuously, uncheck Single-shot. When Single-shot is checked it captures the data once and stops. The Sample time factor value multiplied with Sample time determines the time difference between any two consecutive data points on the plot.

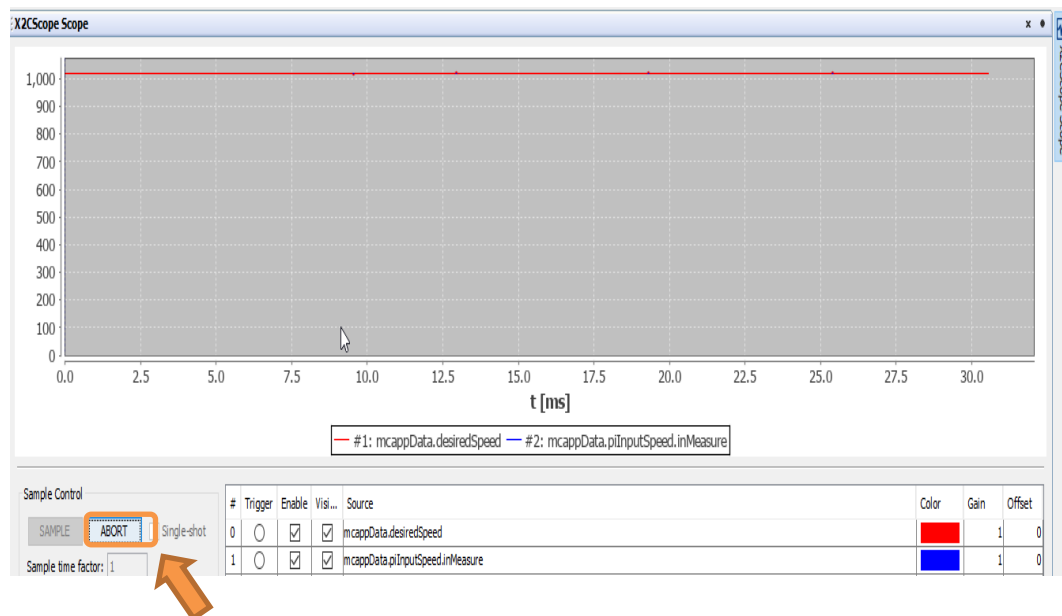
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14. Click on SAMPLE, then X2C scope window shows variables in real time, which is updated automatically.



15. Click on ABORT to stop.



### 7. REFERENCES:

For additional information, refer following documents or links.

1. AN1017 Application Note “Sinusoidal Control of PMSM Motors with dsPIC30F / dsPIC33F/ dsPIC33E DSC”
2. AN957 Application Note “Sensored BLDC Motor Control Using dsPIC30F2010”
3. dsPIC33CK Low-Voltage Motor Control Development Board (DM330031) User's Guide
4. dsPIC33CK256MP508 Family datasheet (DS70005349).
5. Family Reference manuals (FRM) of dsPIC33CK256MP508 family
6. MPLAB® X IDE User's Guide (DS50002027) or MPLAB® X IDE help
7. [MPLAB® X IDE installation](#)
8. [MPLAB® XC16 Compiler installation](#)