

## Contents

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```
function [x,tbl] = SOR(x0,A,b,tol,verbose)
```

```
% Optimal omega
```

## Check the inputs

---

```
narginchk(3,5);  
if nargin<4  
    tol=1e-6;  
end %if  
if nargin<5  
    verbose=false;  
end %if
```

```
Error using SOR00 (line 6)  
Not enough input arguments.
```

## MATLAB Built-in Soln for x

---

```
xsolnmat = A\b;
```

## Setup iterations

---

```
maxit=1000;    %max number of iterations  
n=size(A,1);  %system size  
tbl = [];      % Store the relaxation parameter & corresponding it. #  
kit = 0;       % # of it. for omega  
xsoln = [];  
errr = [];
```

## Perform iterations

---

```
for k = -99 : 1 : 99 % test 0 < omega < 2  
    omega = 1; % relaxation parameter  
    it = 1;  
    kit = kit + 1;  
    omega = omega + k*0.01;  
    residual=10*ones(n,1);  
    difftot=1e3+tol;    %max sure we enter iterations  
    x=x0;  
    while(difftot > tol && it <= maxit)  
        difftotprev = difftot;
```

```

resprev = residual;
xprev = x;
for i=1:n
    residual(i)=b(i);
    for j=1:n
        residual(i) = residual(i) - A(i,j)*xprev(j);
    end %for
    x(i) = xprev(i) + omega*residual(i)/A(i,i);
end %for
difftot=sum(abs(residual-resprev));

%     if (verbose)
%         fprintf('x= ');
%         for i=1:n
%             fprintf('%f  ',x(i));
%         end %for
%         fprintf('\n');
%         fprintf('it=%d; difftot = %e\n',it,difftot);
%     end %if

%     if (difftot>difftotprev & it>2)
%         error('Solution appears to be diverging, check diagonal dominance...')
%     end %if
    it=it+1;
end %while

tbl(1,kit) = omega;      % Store value of omega
tbl(2,kit) = it - 1;     % Store value of it. #
xsoln(:,kit) = x;
err(:,kit) = xsolnmat - x;

end % for

% nit=it-1;
% if (nit==maxit)
%     warning('Solution may not have converged fully...')
% end %if

plot(tbl(1,:),tbl(2,:), 'LineWidth',3)
xlabel('omega (Relaxation Parameter)')
ylabel('# of Iterations Required')
title('Relaxation Parameter vs. # of Iterations Rqd.')

```

```

end %function

```