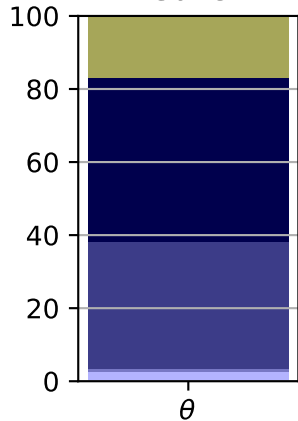
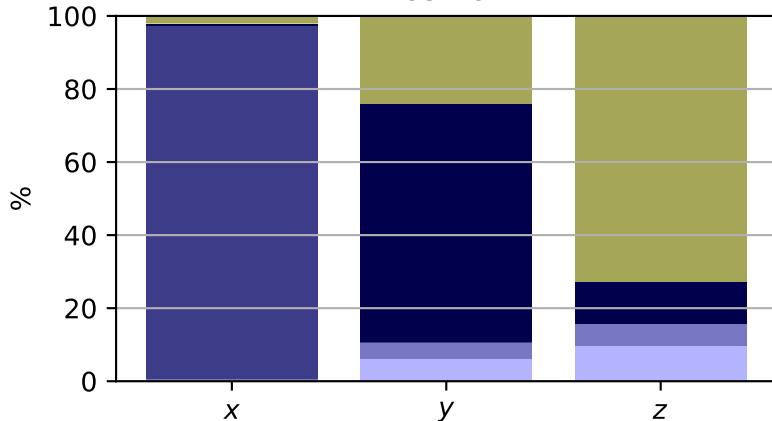


# Standard Deviation of Errors. Contribution from Camera Intrinsics

## Gaze



## Position



- dist. coeff. k2
- dist. coeff. k1
- dist. coeff. k0
- dist. center y
- dist. center x
- focal length y
- focal length x
- principal pt. y
- principal pt. x