

OPA2364

Condition:

$C_L = 100 \text{ pF}$, $V_S = +5 \text{ V}$, $V_{\text{STEP}} = 4 \text{ V}$, $G = +1$

Settling time:

To 0.1% = $1 \mu\text{s}$

To 0.01% = $1.5 \mu\text{s}$

15x
This is 30x
longer than
the time for
the RC filter
to settle to
0.01%.

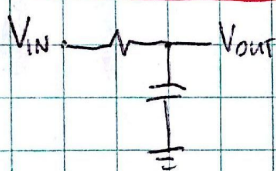
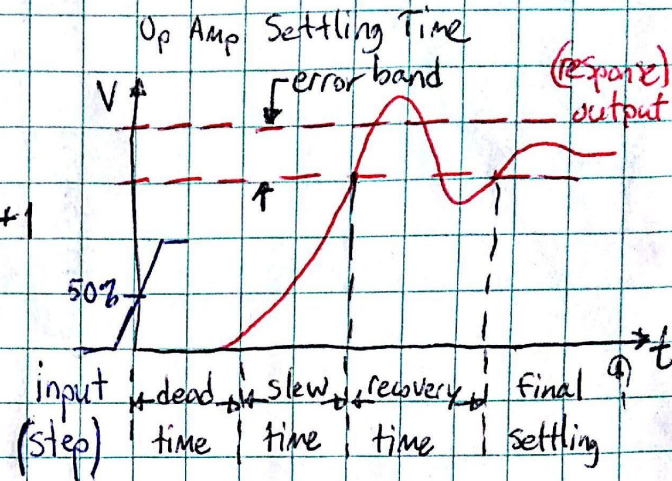
Specify error band: $\frac{1}{4} \text{ LSB}$

$$\frac{2.5 \text{ V}}{2^{16}} = 38 \mu\text{V} \quad \text{error band: } \frac{38 \mu\text{V}}{4} \approx 10 \mu\text{V}$$

$$0.01\% \text{ of } 2.5 \text{ V} = 2.5 \times 10^{-4} \text{ V} = 250 \mu\text{V} = 6.5 \text{ LSB}$$

This is good enough.

See if there is enough time
to take 4 readings per pixel
for increased of 1 bit of
resolution.



$$R = 100 \Omega$$

$$C = 100 \text{ pF}$$

$$\tau = RC = 10 \text{ ns}$$

$$1.5 \mu\text{s} = 150 \text{ ns}$$

$$1.5 \mu\text{s} \text{ is } 150 \tau$$

$V_{\text{IN Step}}$ at $t=0$: initial condition, $V_{\text{OUT}} = 0 \text{ V}$.

$$C = Q/V \quad i_C = \frac{dQ}{dt} \quad i_C = i_R = \frac{V_{\text{IN}} - V_{\text{OUT}}}{R}$$

$$V_C = \frac{1}{C} Q$$

$$\text{KVL: } V_R + V_C = V_{\text{IN}}, \quad V_C = V_{\text{OUT}}$$

$$\frac{dV_C}{dt} = \frac{1}{C} i_C$$

$$(V_{\text{IN}} - V_{\text{OUT}}) \frac{1}{R} = C \frac{dV_{\text{OUT}}}{dt}$$

$$V_{\text{IN}} = V_{\text{OUT}} + RC \frac{dV_{\text{OUT}}}{dt}$$

$$V_{\text{OUT}} \text{ of form } Ae^{st} \quad V'_{\text{OUT}} = sAe^{st} \quad V_{\text{OUT}} = Ae^{st}$$

$$\text{i.c.: } V_{\text{OUT}} = 0 \text{ at } t=0 \quad e^0 = 1 \quad V_{\text{OUT}} = A(1 - e^{-t/RC})$$

$$\text{f.c.: } V_{\text{OUT}} = V_{\text{IN}} \quad \lim_{t \rightarrow \infty} e^{-t/RC} = 0$$

$$A = V_{\text{IN}}$$

$$V_{\text{OUT}} = V_{\text{IN}}(1 - e^{-t/RC})$$

$$\text{Calc } \frac{V_{\text{OUT}}}{V_{\text{IN}}} \text{ @}$$

$$t = 1.5 \mu\text{s}:$$

$$1 - e^{-\alpha}$$

$$\alpha = \frac{1.5 \mu\text{s}}{100 \Omega \cdot 100 \times 10^{-12} \text{ F}} = t/\tau$$