#### CiS Projekt

# Eindimensionale Schrödingergleichung für beliebiges Potential bei periodischen Randbedingungen

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#### **Problemstellung**

• Schrödingergleichung: i

$$i\hbar \frac{d\Psi}{dt} = H\Psi$$

• Hamiltonian:

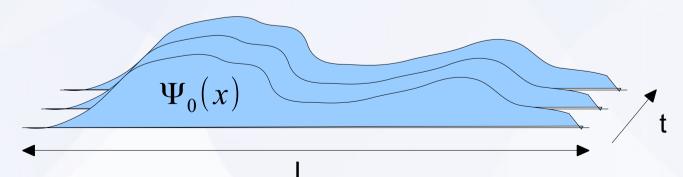
$$H = \frac{-\hbar^2}{2m} \frac{d^2}{dx^2} + V = T + V$$

• Periodische R.B.:

$$\Psi(x,t) = \Psi(x+L,t)$$

$$V(x,t) = V(x+L,t)$$

$$\Psi(x, t=0) = \Psi_0(x), V = V(x, t) : \Psi(x, t) = ?$$

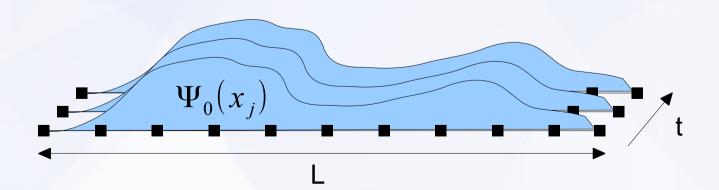


- Programmiersprache: MATLAB
- Ortsdiskretisierung

$$x = j \cdot \Delta x$$
,  $j = 0, \dots, n_x$ 

Matrixrepräsentation

$$H = (H)_{i,j} = (T + diag(V))_{i,j}$$
  
$$\Psi = (\Psi)_{i}$$



Approximation des kinetischen Hamiltonanteils

$$(T\Psi)_{j} = \frac{-\hbar^{2}}{2m} \left( \frac{d\Psi^{2}}{dx^{2}} \right)_{j} \approx \sum_{k} T_{jk} \Psi_{k}$$

- 1.) Fourier-Grid-Hamiltonian Method (D. Tannor)
- 2.) Differenzenquotienten

$$\frac{d\Psi^2}{dx^2} \approx \frac{\Delta \Psi^2}{\Delta x^2} = \frac{\Psi(x - \Delta x) - 2\Psi(x) + \Psi(x + \Delta x)}{\Delta x}$$

- H = konstant:
  - Eigenzustände  $H\Psi_n(x,t=0)=E_n\Psi_n(x,t=0)$
  - Zeitentwicklung  $\Psi(x,t) = \sum_{n} c_n e^{\frac{iE_n t}{\hbar}} \Psi_n(x,t=0)$
- H = H(t):
  - Zeitdiskretisierung  $t_k = k \cdot \Delta t$ ,  $k = 0, ..., n_t$
  - Direkte Zeitentwicklung  $i\hbar \frac{d\Psi(x,t)}{dt} = H(t)\Psi(x,t)$

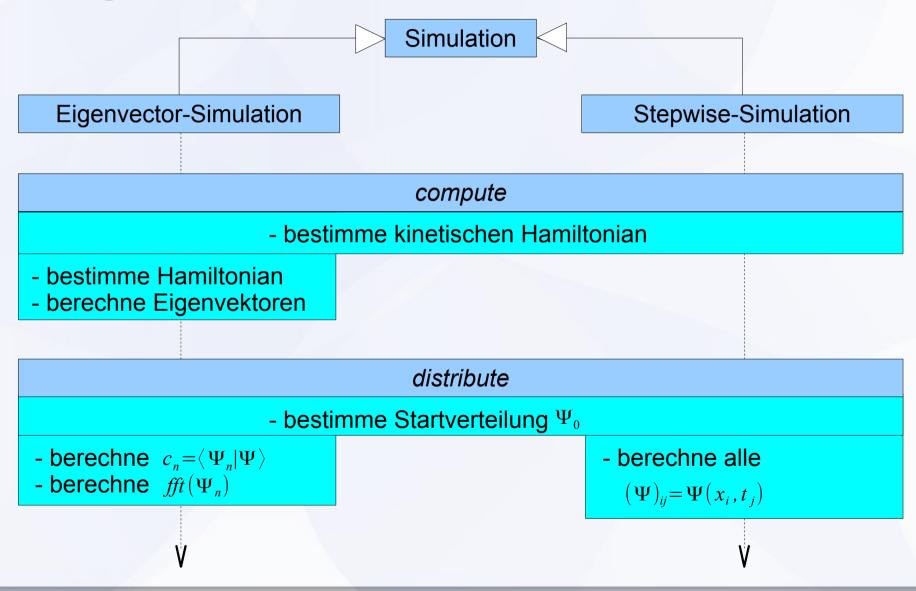
Numerische Zeitentwicklung von Ψ

$$i\hbar \frac{d\Psi(x,t)}{dt} = H(t)\Psi(x,t)$$

Crank-Nicholson-Operator

$$\Psi(x, t + \Delta t) = \frac{1_N + \frac{i}{\hbar} H(x, t)}{1_N - \frac{i}{\hbar} H(x, t)} \Psi(x, t)$$

#### Programmstruktur



## Programmstruktur

Eigenvector-Simulation

Stepwise-Simulation



#### - bestimme t aus Position des Schiebereglers

- berechne  $\Psi(x,t) = \sum_{n} c_{n} e^{\frac{iE_{n}t}{\hbar}} \Psi_{n}(x,t=0)$
- im k-Raum analog
- plotte

$$\Psi(x,t)$$
 ,  $V(x)$  ,  $\Psi_k(x,t)$ 

- diskretisiere t = t
- plotte

$$(\Psi)_{\bullet,j} = \Psi(x, t_j)$$

$$(V)_{\bullet,j} = V(x, t_j)$$

$$fft((\Psi)_{\bullet,j})$$

#### Live-Demo

 $\dots \rightarrow \mathsf{MATLAB}$