

A 3-ingredient recipe for
Accelerating Aerospace Engineering Design:
MDO, **Surrogate** and **Ecodesign**
Prof. Joseph Morlier

AE Seminar at TUD



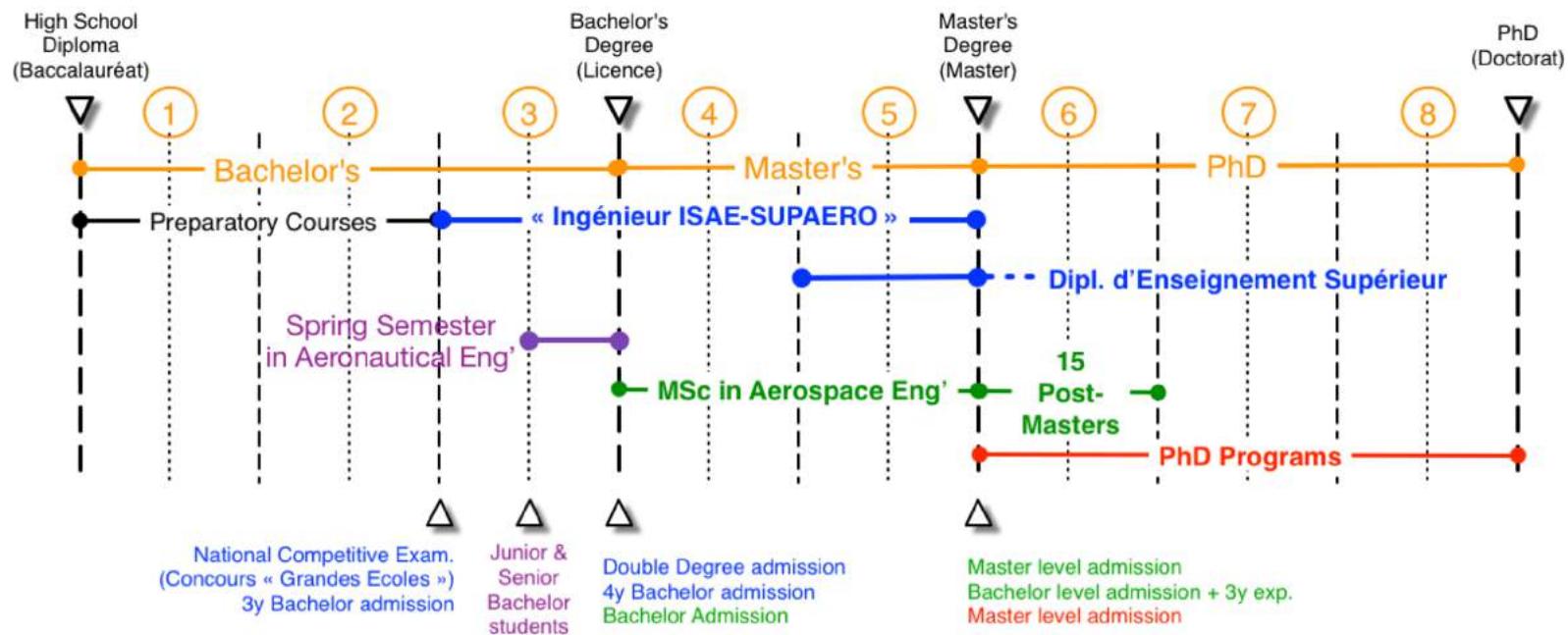
Optimisation
Promo Structures
Technologie HPC
Fondation
Impression Additive
Gift 83 SUPAERO
ISAE Class Aero
Ecodesign
Topologique



Key Figures at a Glance

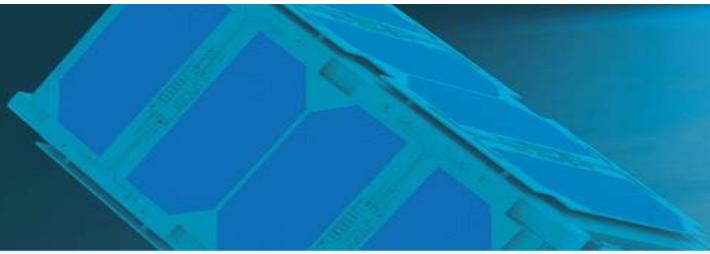


ISAE-SUPAERO Programs & Bologna Process



Toulouse: Aerospace Activities

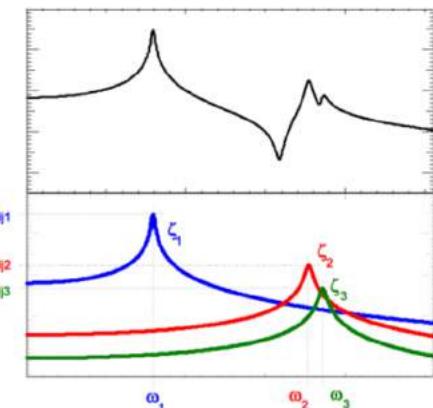
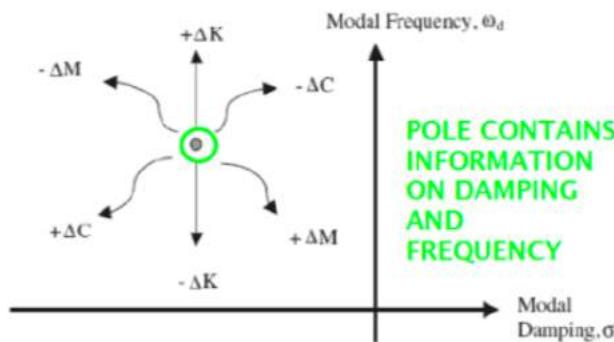
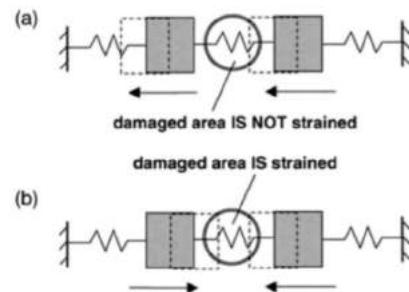




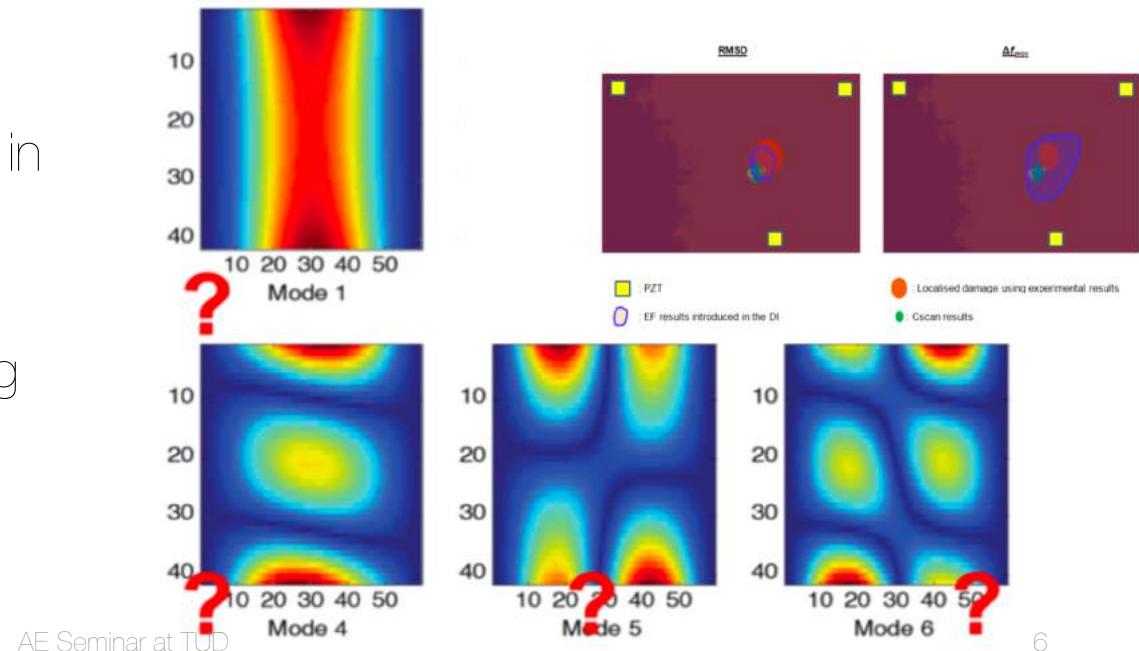
**Thanks to all my Students
and Colleagues**

Before 2012

- SHM on composites (Modal analysis, EMI)



- Detection by change in damping, change in modeshapes
- Methodology for damage recognition using Artificial Neural Networks



Research Experiences

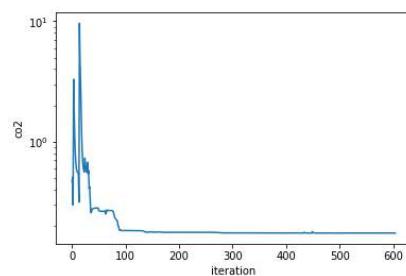
- PhD in Bordeaux SHM of civil engineering structures in 2005
- Ass. Prof in SUPAERO in 2006 SHM of composites structures
- Full Professor in Structural and Multidisciplinary Design Optimization since 2012

As a visiting Researcher

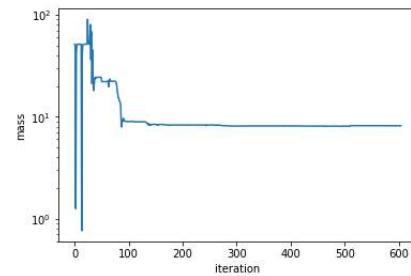
- in Beijing, Sino French lab on Applied Mathematics (summer 2006)
- In University of Michigan @MDOlab (summer 2017)
- **ANR Grant 2021** (French Science Foundation) → TUD in **May 2022** (and also to brainstorm regularly with **Kunal Masania since 1 year**)



CO₂
footprint

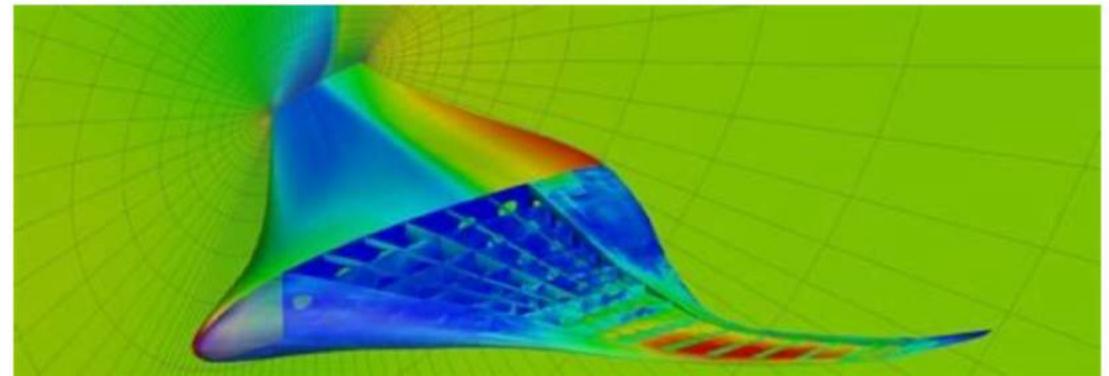


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Vs Mass
minimization

Popularization ONERA-SUPAERO



<http://mdolab.engin.umich.edu>

Optimization [MDO] for connecting people?

Publié le 14 février 2019

[Modifier l'article](#) | [Voir les stats](#)



joseph morlier

Professor in Structural and Multidisciplinary Design Optimization, ... any idea?

[2 articles](#)

74 31 3 0

<https://www.linkedin.com/pulse/optimization-mdo-connecting-people-joseph-morlier/>

Popularization 2

<https://www.linkedin.com/pulse/possible-build-aircraft-wing-lego-joseph-morlier/?articleId=6627240732975480832>



https://www.tripadvisor.fr/LocationPhotoDirectLink-g187529-d574612-i349532022-Museum_of_Natural_Science_Museo_de_Ciencias_Naturales-Valencia_Province_o.html

Is it possible to build an aircraft wing in LEGO® ?

Publié le 17 février 2020

[Modifier l'article](#) | [Voir les stats](#)



joseph morlier

Professor in Structural and Multidisciplinary Design Optimization, ... any
idea?

5 articles

Au programme



| Duration | Description | Agenda |
|----------|-------------|---------------------|
| 10' | MDO | Examples |
| 10' | Surrogate | SMT |
| 10' | Ecodesign | Lighter and Greener |
| 4' | Conclusions | And future works? |

« Tools/Results » oriented presentation

For theoretical background, have a look to

- [1] Bouhlel, M. A., Hwang, J. T., Bartoli, N., Lafage, R., Morlier, J., & Martins, J. R. (2019). A Python surrogate modeling framework with derivatives. *Advances in Engineering Software*, 135, 102662.
- [2] Coniglio, S., Morlier, J., Gogu, C., & Amargier, R. (2019). Generalized Geometry Projection: A Unified Approach for Geometric Feature Based Topology Optimization. *Archives of Computational Methods in Engineering*, 1-38.
- [3] Duriez, E., Morlier, J., Charlotte, M., & Azzaro-Pantel, C. (2021). A well connected, locally-oriented and efficient multi-scale topology optimization (EMTO) strategy. *Structural and Multidisciplinary Optimization*, 1-24.
- [4] Mas Colomer, J., Bartoli, N., Lefebvre, T., Martins, J. R., & Morlier, J. (2021). An MDO-based methodology for static aeroelastic scaling of wings under non-similar flow. *Structural and Multidisciplinary Optimization*, 63(3), 1045-1061.
- [5] Duriez, E., Guadano Martin, Morlier, J. (2022). HALE multidisciplinary ecodesign optimization with material selection, under review
- [6] Duriez, E., Morlier, J., Charlotte, M., & Azzaro-Pantel, C. (2022). Ecodesign with topology optimization. *Procedia CIRP*.

Au programme



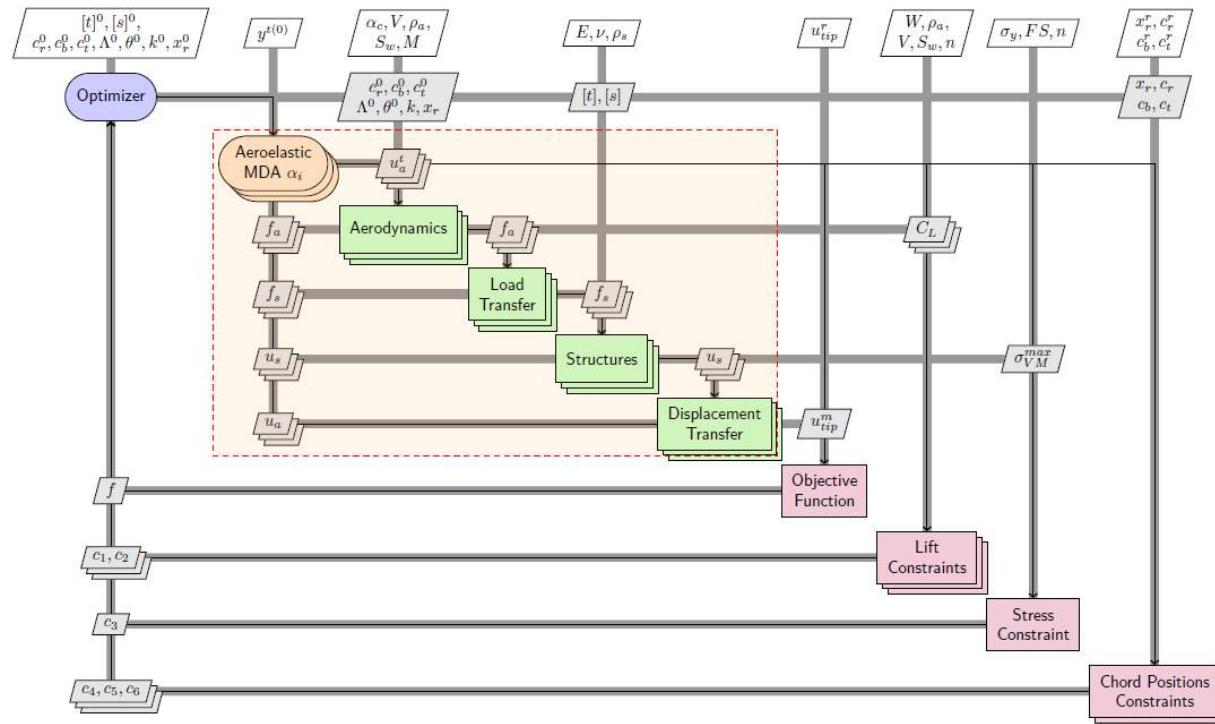
MDO

| Duration | Description | Agenda |
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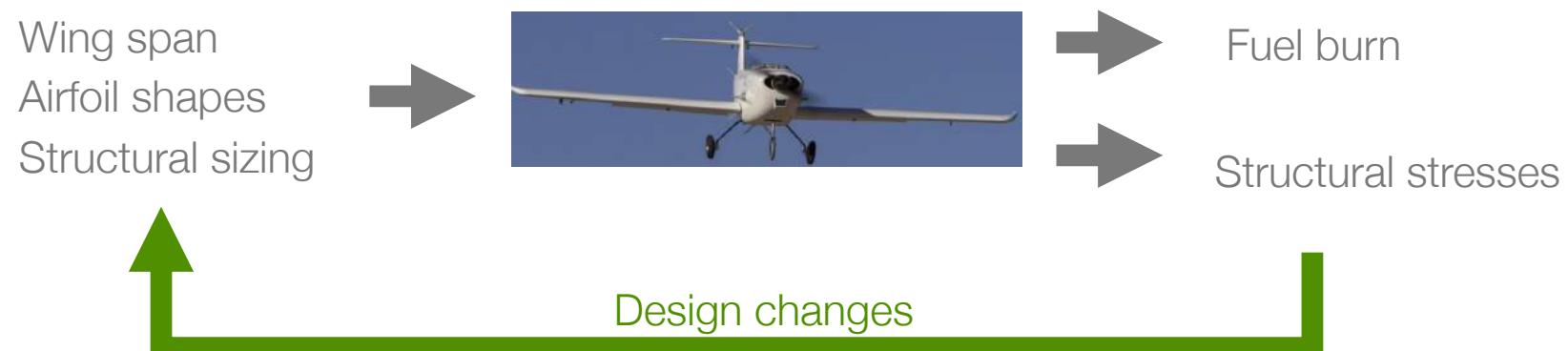


Multidisciplinary Design Optimization

- Multidisciplinary Design Optimization (MDO) focuses on solving optimization problems spanning across multiple interacting disciplines



A way to fully automate the design process

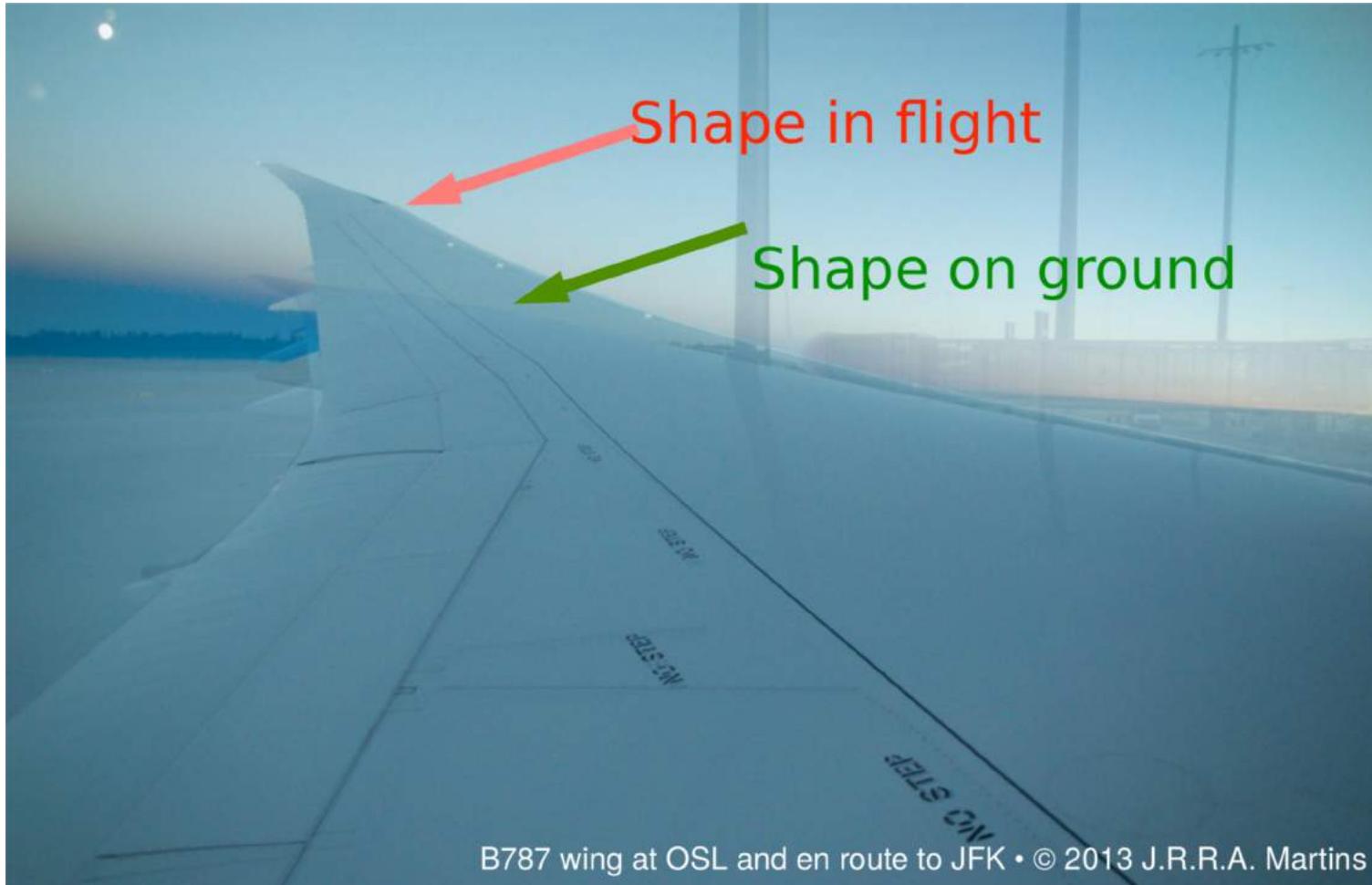


Design
optimization
problem:

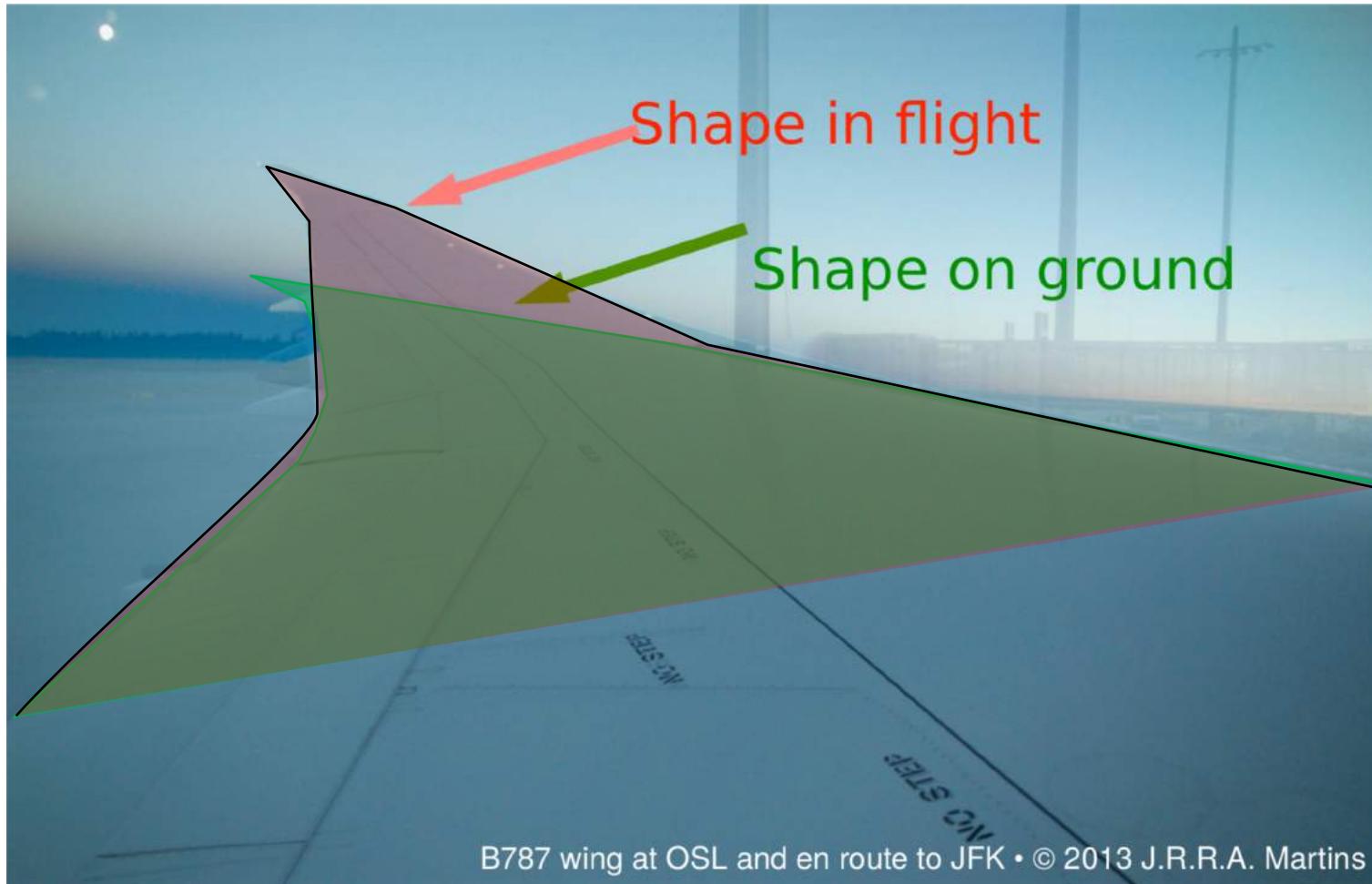
minimize $f(x)$
with respect to x
subject to $c(x) \leq 0$

objective
design variables
constraints

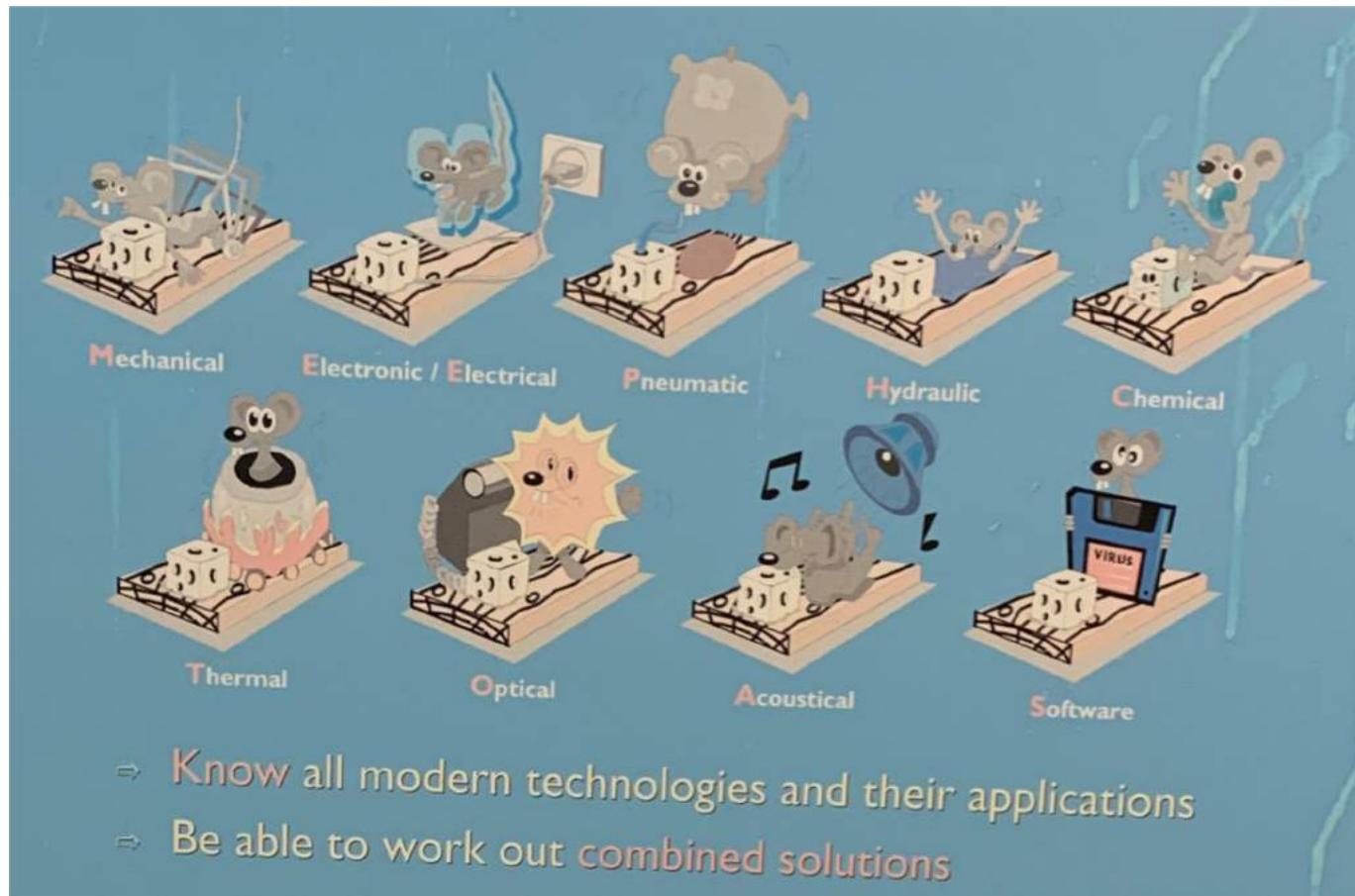
Coupled problem



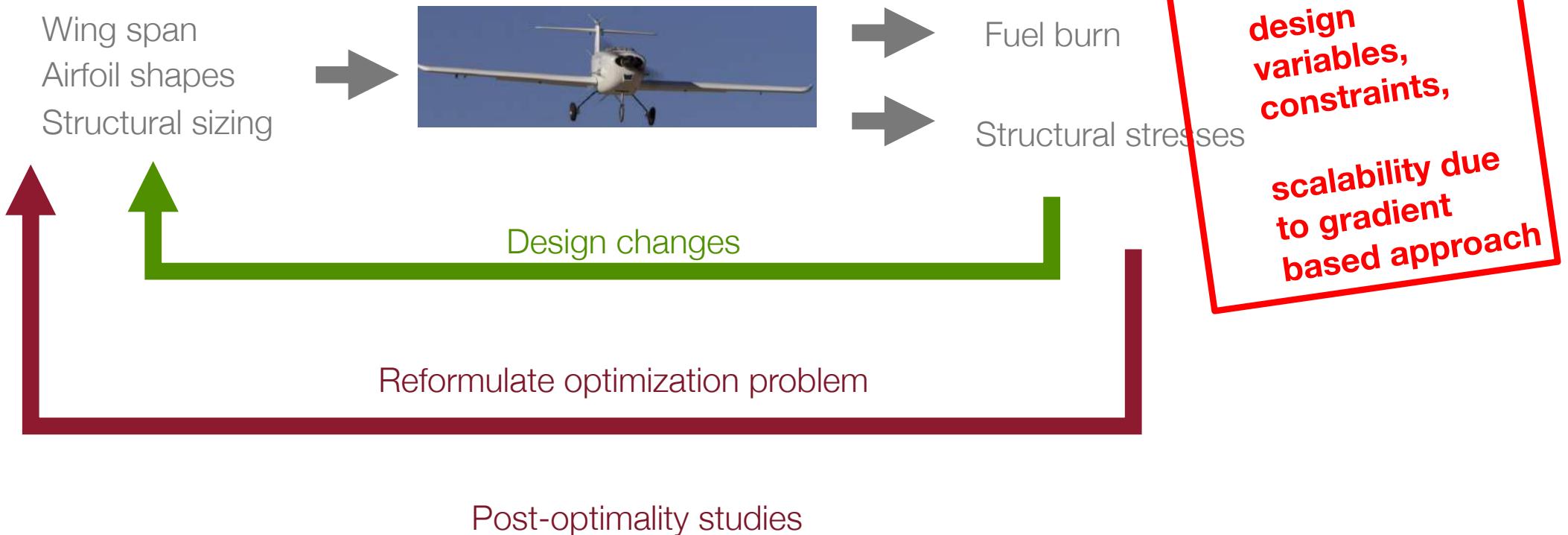
Coupled problem



@Philips : Combining disciplines provides better solutions



Nowadays' Engineering Design Optimization is MDO {M:Multidisciplinary}



MDO for Scaled aircraft aeroelasticity

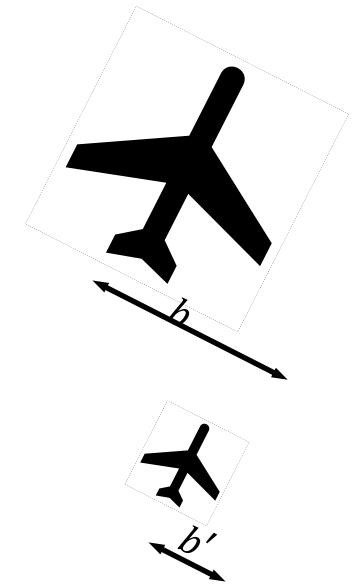


[bombardier.com]

$$\lambda_l = \frac{b'}{b}$$



[MSP, uav.com.pl]



To get experimental data on the **in-flight aeroelastic** behavior of new aircraft concepts while avoiding **costs** and **risks of full-scale** aircraft:

- Development and manufacturing cost
- Operational risk of test aircraft



$$\lambda_l$$

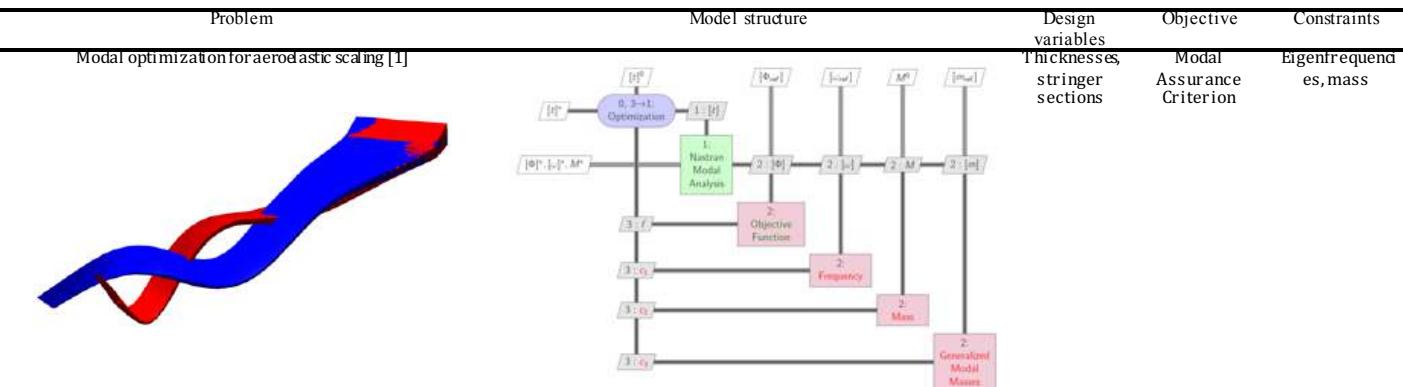


 [Chambers, Modeling Flight, NASA, 2010]

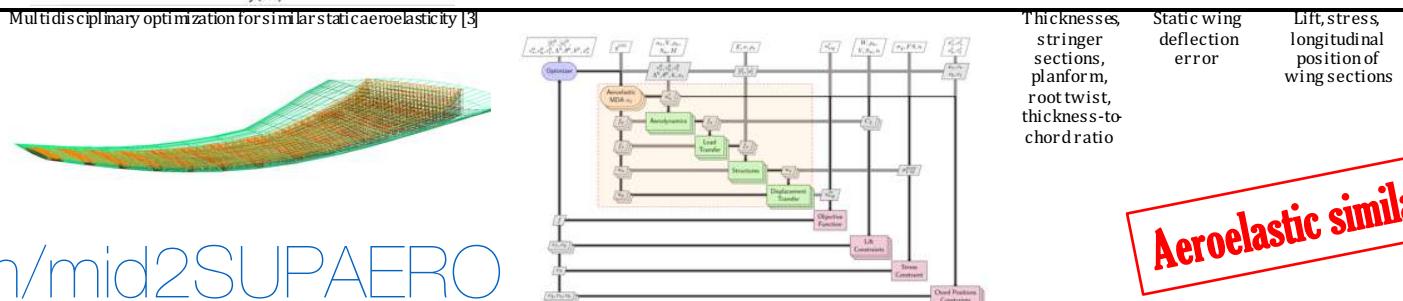
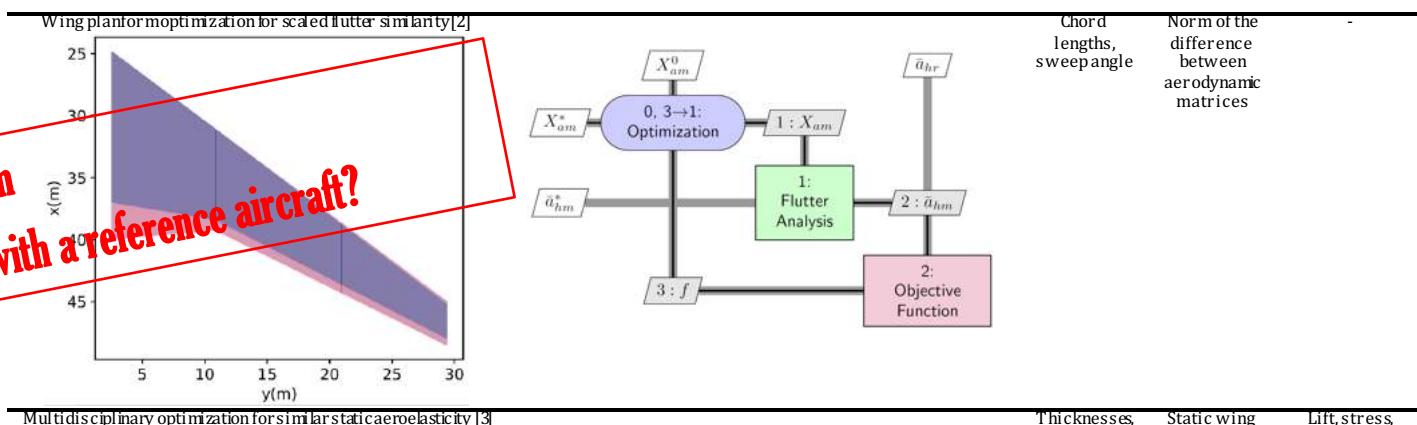
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Joan's thesis

Modal matching



Scaled model's optimal planform
that ensure Flutter similarity with a reference aircraft?



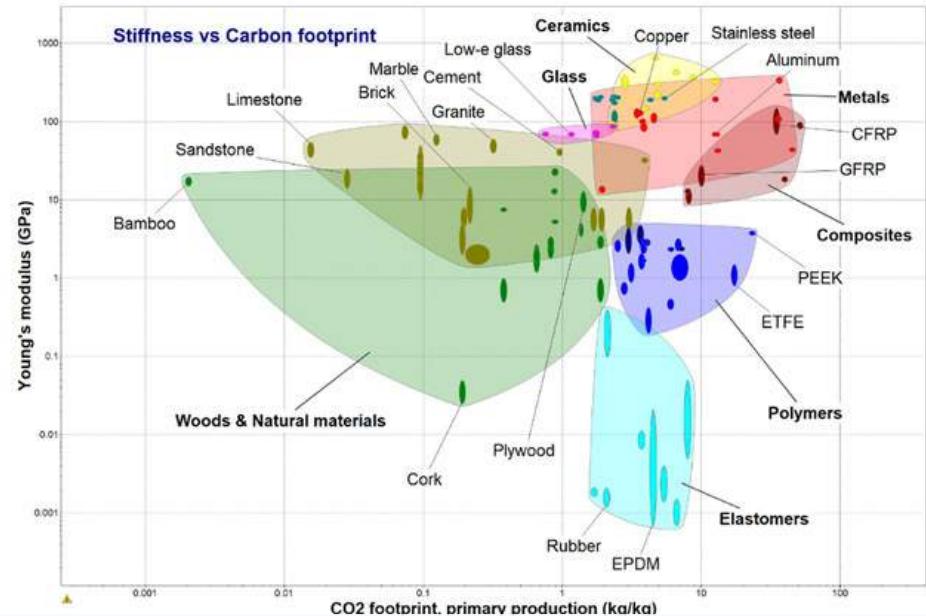
[https://github.com/mid2SUPAERO
/aerostructures](https://github.com/mid2SUPAERO/aerostructures) AES

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MDO for ECOHALE design

- Trade-off between use phase (young's modulus and density) and production phase (CO₂ footprint)



[mdolab / OpenAeroStruct](#)

Watch ▾ 22

Star 57

Fork 63

Code

Issues 33

Pull requests 0

Actions

Projects 8

Wiki

Security

Insights

OpenAeroStruct is a lightweight tool that performs aerostructural optimization using OpenMDAO.

[openmdao](#) [optimization](#) [aerodynamics](#) [open-source](#)

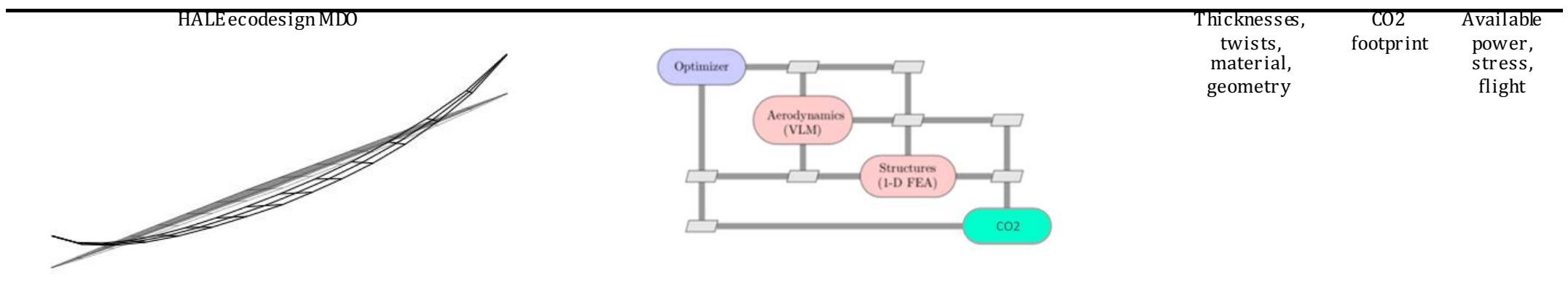
Chauhan, S. S., & Martins, J. R. (2018, September). Low-fidelity aerostructural optimization of aircraft wings with a simplified wingbox model using OpenAeroStruct. In International Conference on Engineering Optimization (pp. 418-431). Springer, Cham.
Jasa, J. P., Hwang, J. T., & Martins, J. R. (2018). Open-source coupled aerostructural optimization using Python. Structural and Multidisciplinary Optimization, 57(4), 1815-1827.

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ECO Hale

Derive OAS 2.0 to treat a HALE pseudo satellite Design problem



Assets: Flexible, repositionable, permanent coverage, cheaper, lower environmental impact?



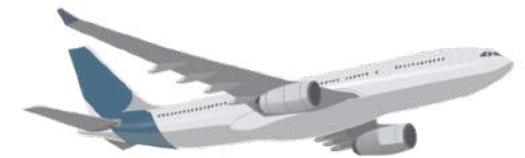
Fig. 1: Airbus-built HALE Zephyr

Discrete variables

Minimize CO₂
w.r.t. thicknesses, twist, geometry,
materials database CES EDUPACK (CFRP-3, GFRP, ALU,...)
Subject to Available solar power, stress,
buckling, flight

From OAS to EcoHale

- Commercial aircraft
- Breguet range equation
- Fuel consumption
- 2.5G manoeuvre
- High Reynolds number
- Fixed structural material
- HALE drones
- Power equilibrium
- Power from batteries and solar panels
- Shear gust wall
- Low Reynolds number
- Material choice optimization



| Discipline | Method | Implementation | Reference |
|---------------|------------------------|----------------|---|
| Aerodynamics | VLM | OAS | Anderson (1991) |
| Structure | Wingbox beams | OAS | Chauhan and Martins (2019) |
| Energy | Simple in-house method | Section 2.1 | data from Colas et al. (2018) |
| Environmental | Proportional to mass | Section 2.3.2 | data from Wetzel and Borchers (2015), Hao et al. (2017) |

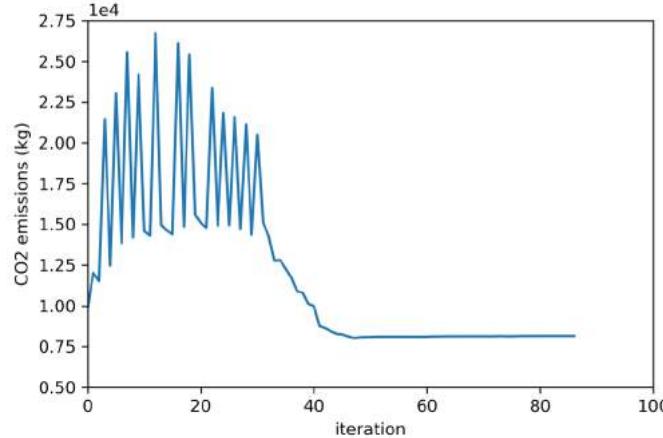
Objective function

- CO₂ emitted by the HALE drone during its life cycle
- No fuel ➤ CO₂ from materials and processing
 - Structure ➤ $CO2_{struct} = M_{spar} \cdot CO2_{mat1} + M_{skin} \cdot CO2_{mat2}$
 - Solar panels ➤ $CO2_{PV} = P_{needed} \cdot CO2_{/W}$
 - Batteries ➤ $CO2_{bat} = P_{needed} \cdot t_{night} \cdot CO2_{/Wh}$
- $CO2_{total} = CO2_{struct} + CO2_{PV} + CO2_{bat}$



CO₂ footprint minimization

(a) Objective function: total CO₂ emitted:



(b) Material density for skins and spars:

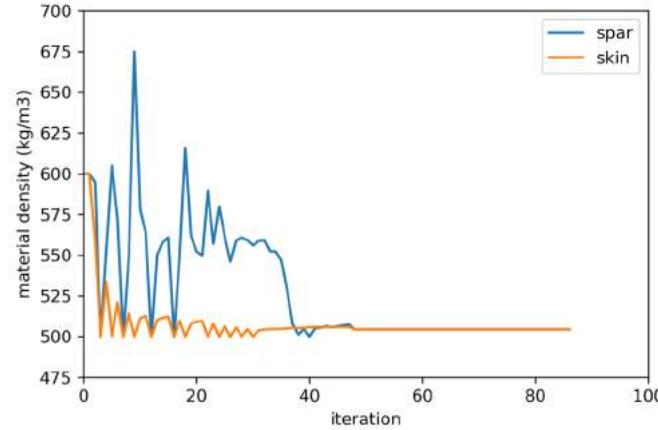


Fig. 8: Convergence graphs

Optimization algorithm ➤ SLSQP

Stopping criteria:

- Convergence accuracy: 10^{-3}
- Maximum number of iterations: 250

| Objective function | Dimension | Bounds |
|--|----------------|-------------------------------|
| CO_2_{tot} | \mathbb{R} | |
| Design variables | | |
| Density | \mathbb{R}^2 | [400, 8000] kg/m ³ |
| Twist control points | \mathbb{R}^4 | [-15, 15] deg |
| Skin thickness (t_{skin}) control points | \mathbb{R}^4 | [0.001, 0.1] m |
| Spar thickness control points | \mathbb{R}^4 | [0.001, 0.1] m |
| Thickness-to-chord ratio control points | \mathbb{R}^4 | [0.01, 0.4] |
| Span | \mathbb{R} | [1, 1000] m |
| Root chord | \mathbb{R} | [1.4, 500] m |
| Taper ratio | \mathbb{R} | [0.3, 0.99] |
| Motor location over semi-span ratio | \mathbb{R} | [0, 1] |
| Constraints | | |
| Mechanical failure $\sigma < \sigma_{max}$ | \mathbb{R}^7 | |
| Buckling $R_s^2 + R_c < 1$ | \mathbb{R}^7 | |
| Skin thickness $2t_{skin} < t_{wing}$ | \mathbb{R}^4 | |
| Power equilibrium $P_{needed}/A_{PV} < S_{wing}$ | \mathbb{R} | |

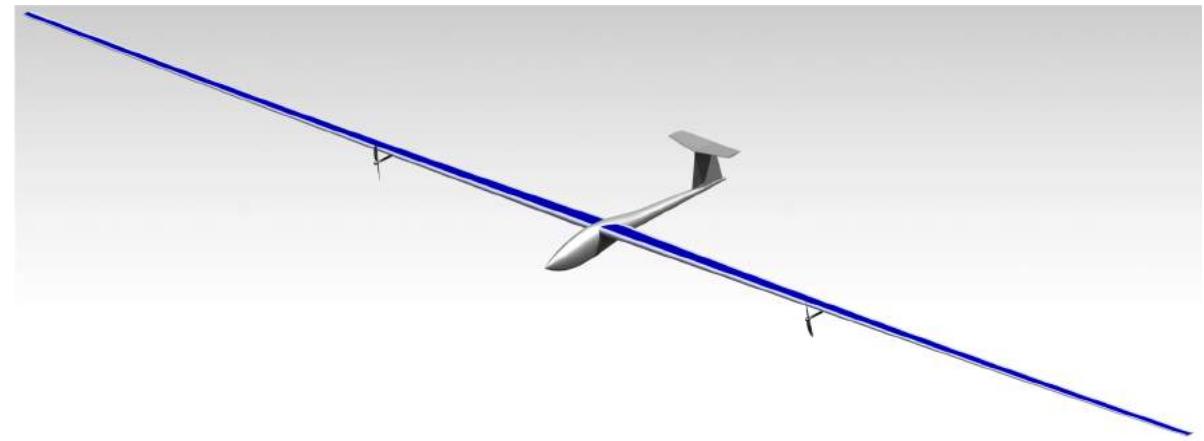


Fig. 9: CAD model of the optimal HALE obtained

Au programme



Surrogate

| Duration | Description | Agenda |
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ML vs Engineering

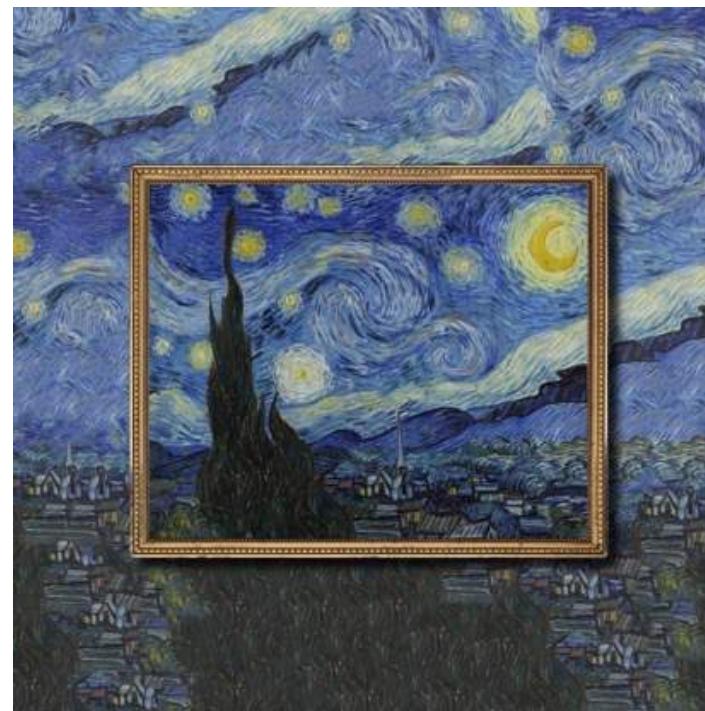
| Kriging (Pioneer) | Gaussian Processes (link with AI) |
|--|---|
| Developed by Daniel Krige – 1951; formalized by Georges Mathéron in the 60's (Mines Paris) | Neural network with infinite neurons tend to Gaussian Process 1994 |

Krige, D. G., 1951, A statistical approach to some basic mine valuation problems on the Witwatersrand: J. Chem. Metal. Min. Soc. South Africa, v. 52, p. 119-139.

Matheron, G., 1963b, Principles of geostatistics: Economic Geol., v. 58, p. 1246-1266.

Neal, R. Priors for infinite networks. Tech. rep., University of Toronto, 1994.

Williams, C. K. I., and Rasmussen, C. E. Gaussian processes for regression. *Advances in Neural Information Processing Systems 8* (1996), 514-520.



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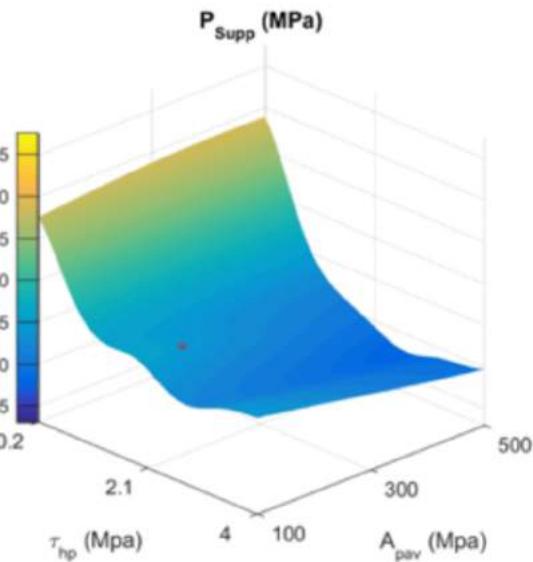
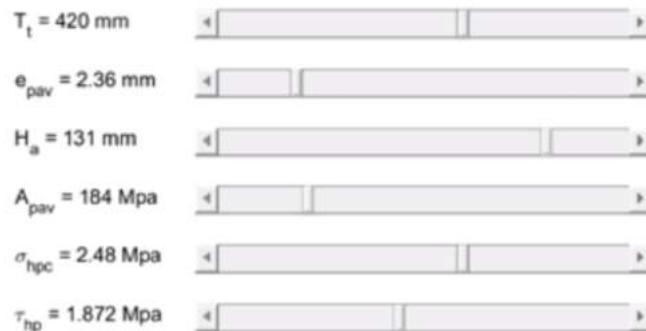
Qualitative claims such as "ML works OK for interpolation but doesn't work for extrapolation" are wrong.

<https://arxiv.org/abs/2110.09485>

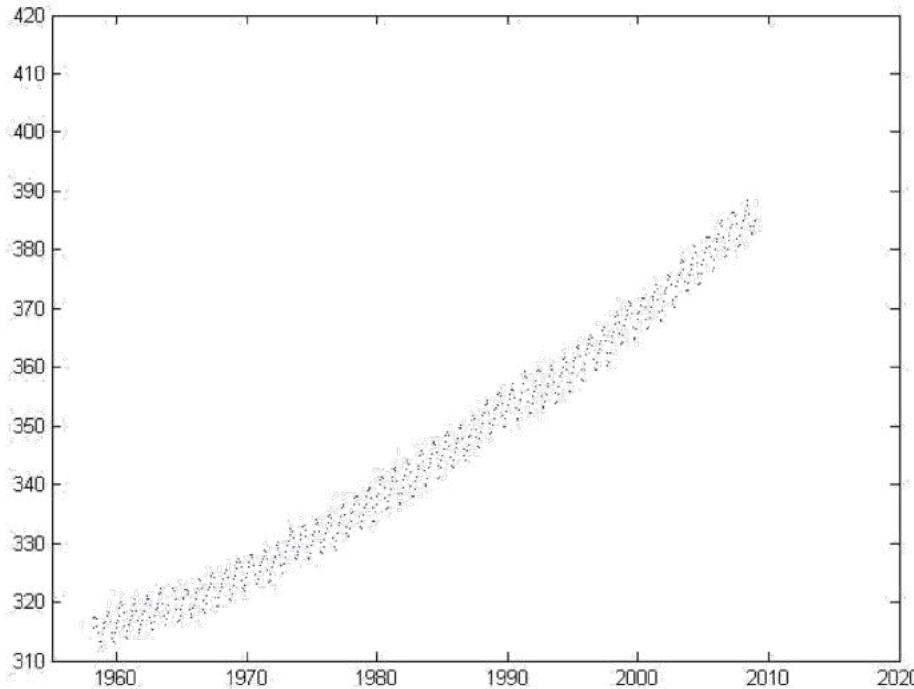
<http://extrapolated-art.com>

Surrogate Models

- A surrogate model of a function is an approximation of the function that is less costly to evaluate
- The surrogate model can then be used to help direct the search for the optimum of the real objective function



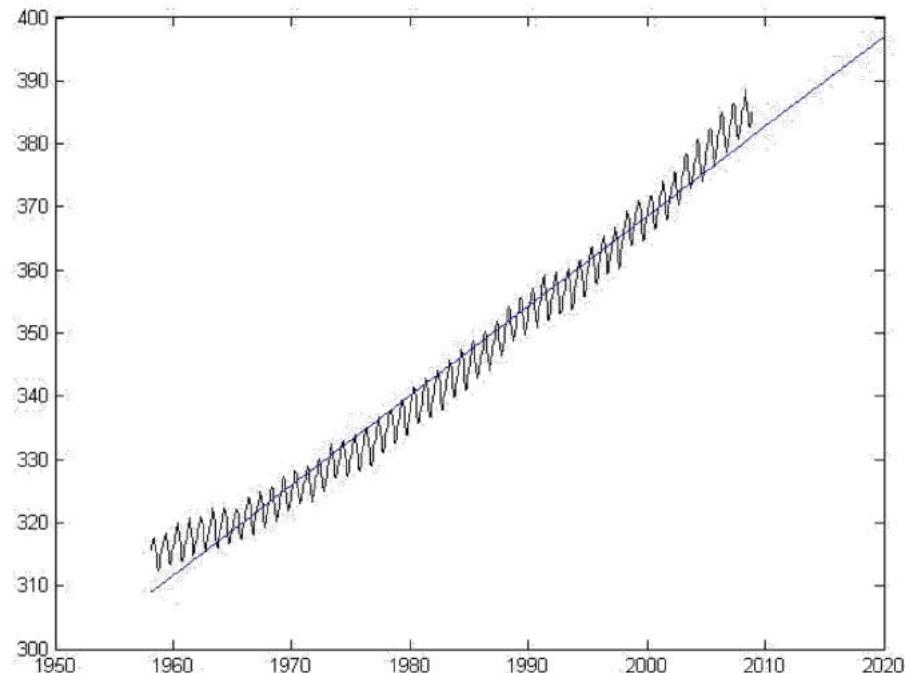
Limit of linear models for prediction



Month-wise data of CO₂ concentration in atmosphere at Hawaii

Image Source: <http://mlg.eng.cam.ac.uk/teaching/4f13/1314/>

Example – Linear Regression



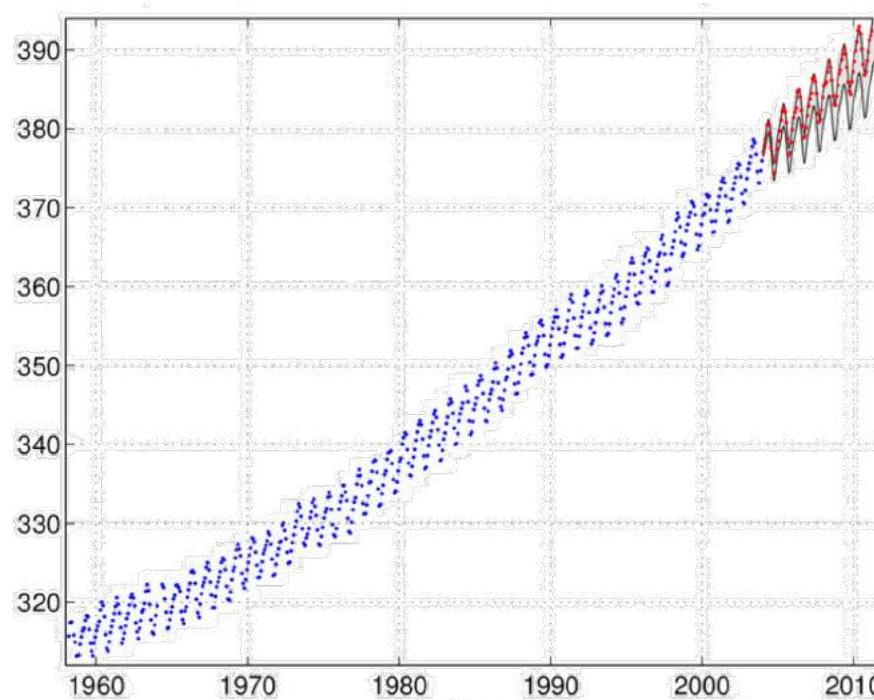
Should we choose a **polynomial**?

What **degree** of polynomial should we choose? (overfitting)

For a given degree, what **parameters** of polynomial should we choose

Image Source: <http://mlg.eng.cam.ac.uk/teaching/4f13/1314/>

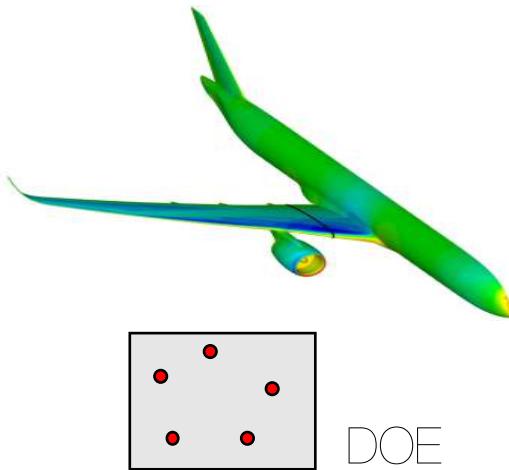
Example – Gaussian Process



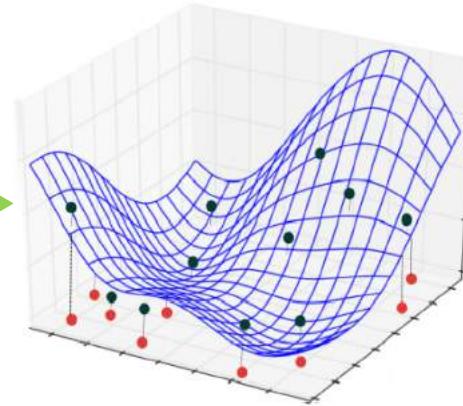
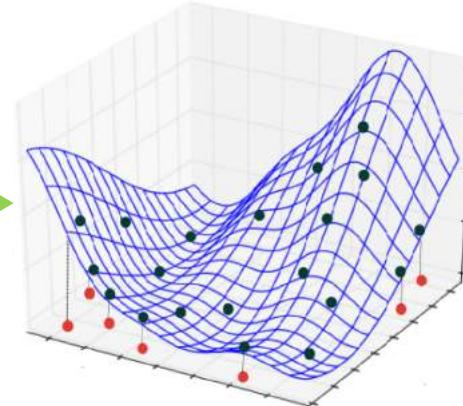
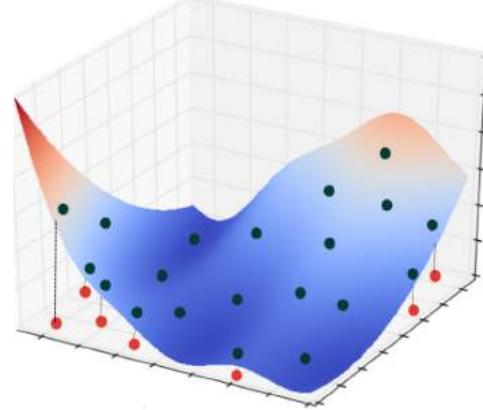
Predicted variance after year 2005 in grey, real data-points in red

Image Source: <http://mlg.eng.cam.ac.uk/teaching/4f13/1314/>

Surrogate modeling Recipes



True Function Evaluation
This is costly!



$$MSE = \frac{1}{n} \sum_{i=1}^n (\hat{y}_i - y_i)^2$$

$$LOF = \frac{MSE}{Var(y)}$$

n is the number of samples
 \hat{y} is the predictions of the n samples
 y is the true outputs of the n samples

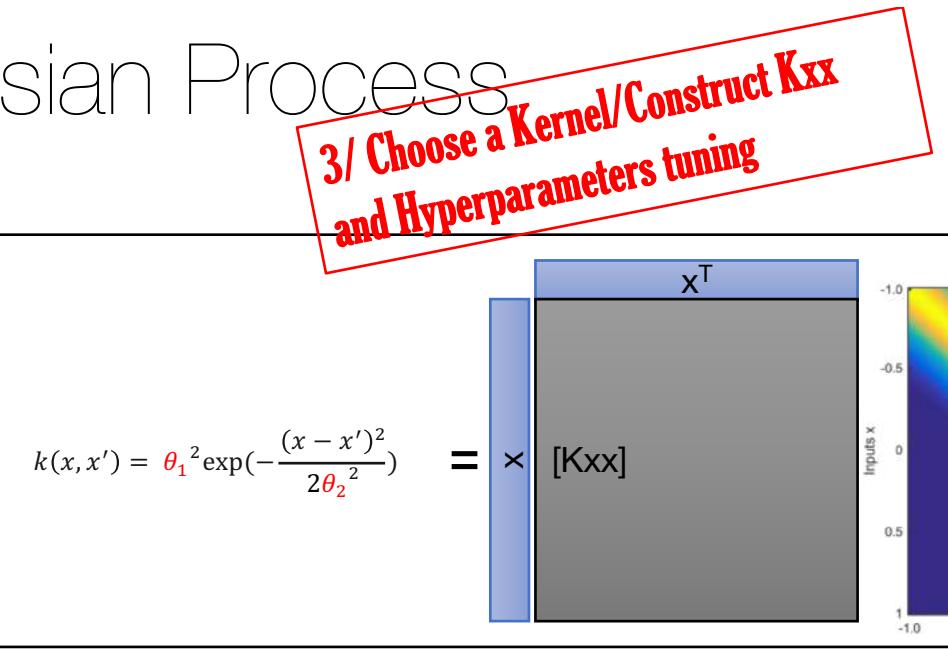
Matrix view of Gaussian Process

1/ Get your inputs/outputs data

$$\begin{bmatrix} x \\ y(x) \end{bmatrix}$$

2/ You wan to predict at x^*

$$x^*$$



$$m(y^*) = [K_{x^*x}] [K_{xx}]^{-1} y(x)$$

$$m(x_*) = K_* [K_{xx}]^{-1} y$$

4/ compute mean

$$\text{cov}(y^*) = [K_{x^*x^*}] - [K_{x^*x}] [K_{xx}]^{-1} [K_{x^*x}]$$

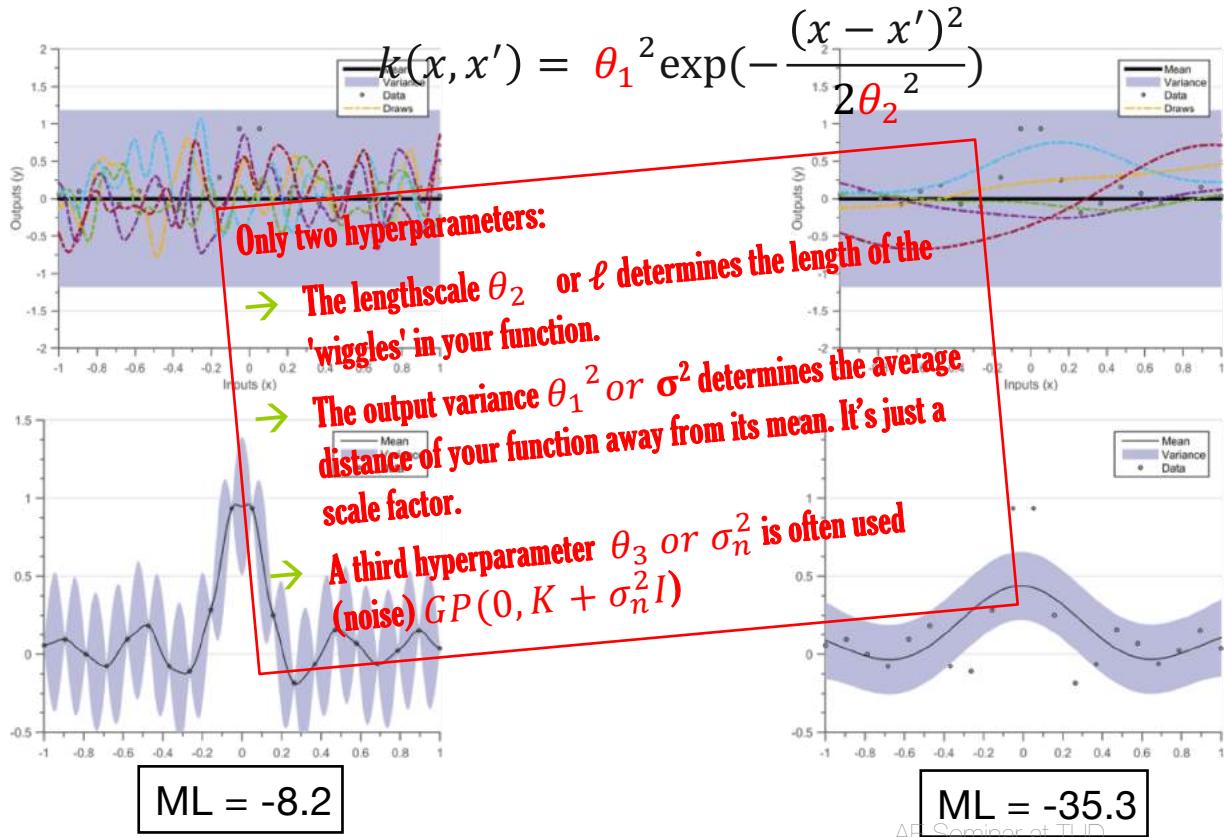
$$[K_{xx}]^{-1} [K_{x^*x}]$$

and variance of estimate
 $\text{var}(x_*, x'_*) = K_{**} - K_*^T [K_{xx}]^{-1} K_*$

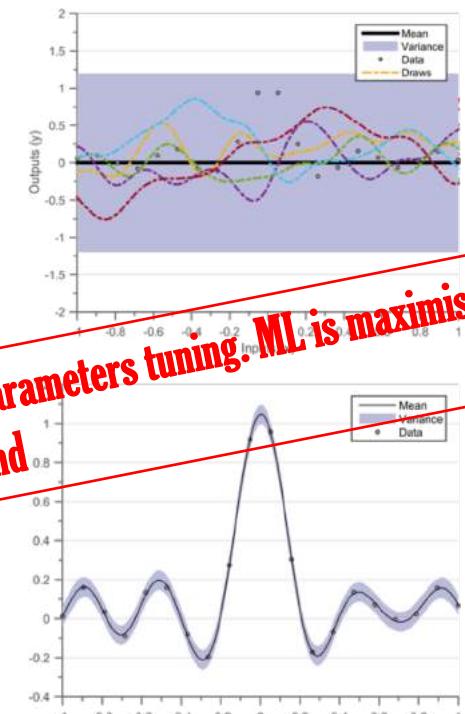
Optimizing Marginal Likelihood (ML)

$$ML = \log(p(y|X, \theta)) = -\frac{1}{2} y^T K^{-1} y - \frac{1}{2} \log|K| - \frac{n}{2} \log(2\pi)$$

- It is a combination of **data-fit term**, a **complexity penalty** term and a **normalization term**



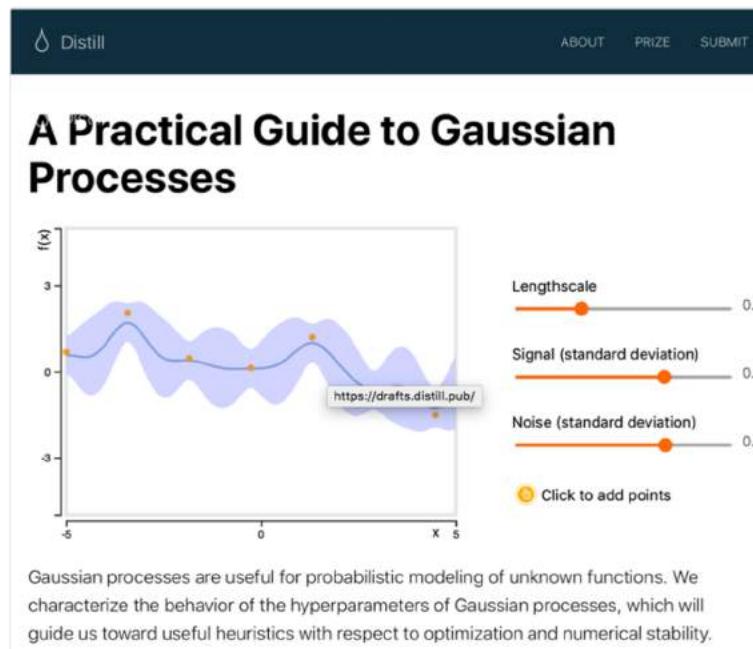
3/ Hyperparameters tuning. ML is maximised,
 θ^* is found



A good starting point x_0 =Rasmussen's book

- <https://drafts.distill.pub/gp/>

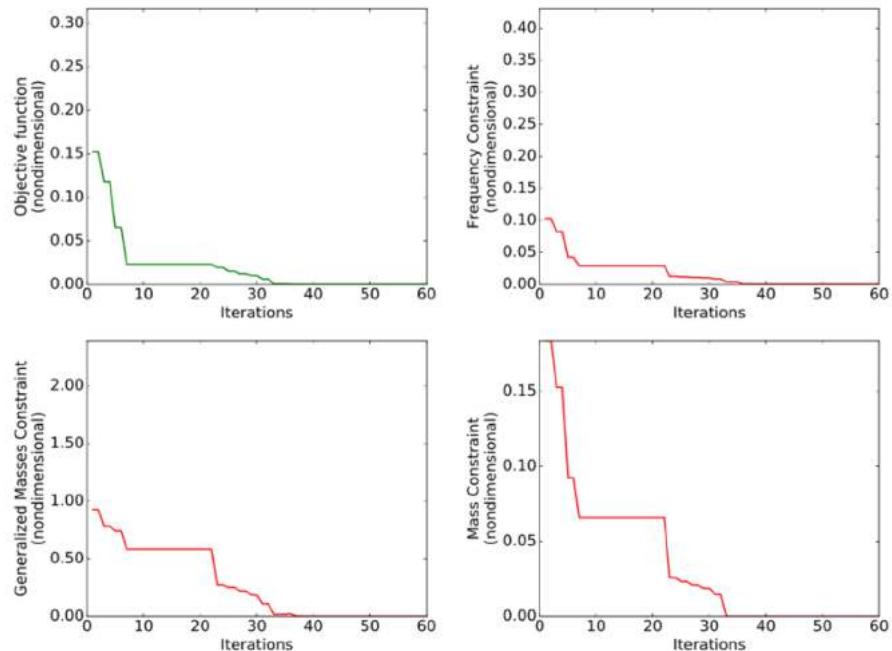
C. E. Rasmussen & C. K. I. Williams, Gaussian Processes for Machine Learning, the MIT Press, 2006, ISBN 026218253X. © 2006 Massachusetts Institute of Technology. www.GaussianProcess.org/gpml



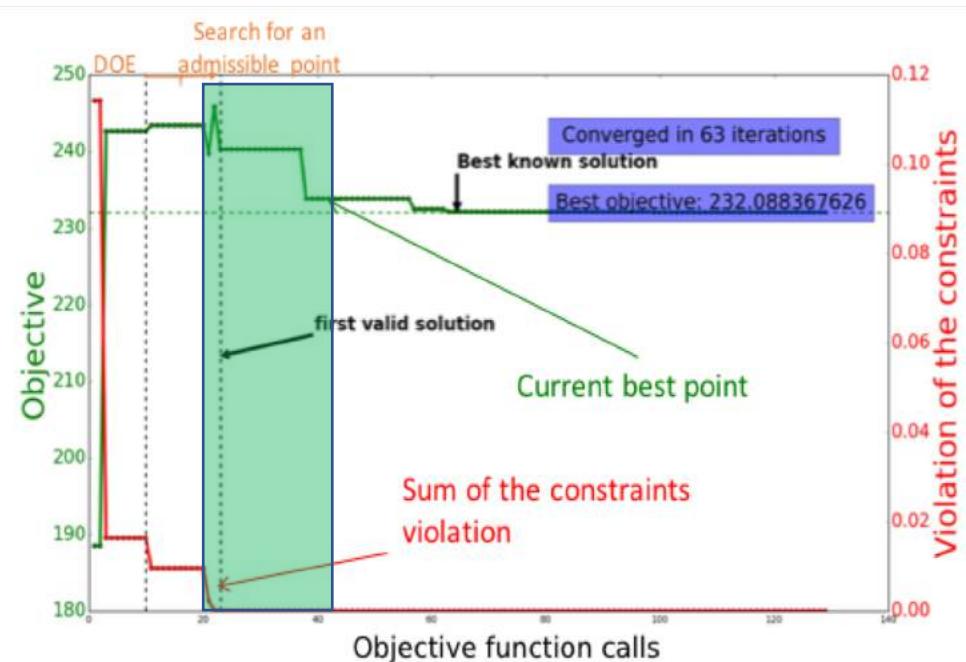
Gaussian Processes for Machine Learning

Convergency graphs

Gradient based Optimality, Feasibility



SBO Exploration, Exploitation



Stopping criteria: tolfun, tolx, maxiter

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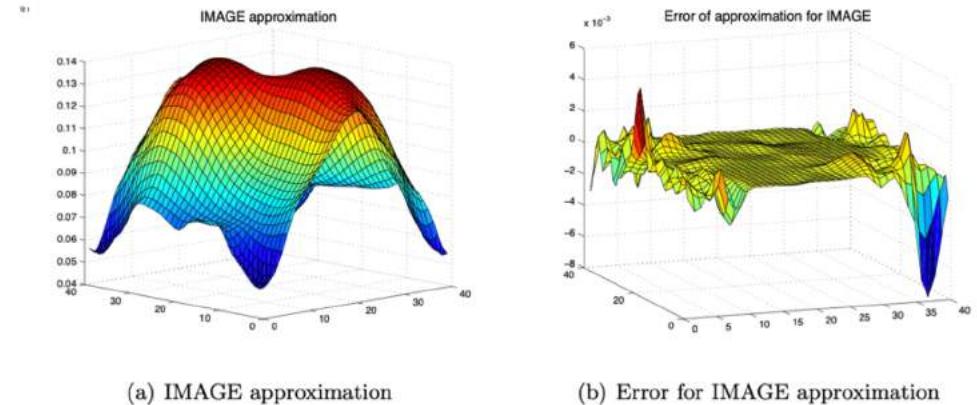
Stopping criteria: Max Budget (Function calls)

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...A long time ago far away

in Onera/Supaero Toulouse

- 2008-2011 D. Bettebghor's PhD first works on Mixture of Experts → How to assemble local surrogates in a global one? IMAGE in matlab
- Results of The PhD of M. Bouhlel (2013-2016) → KPLS trick → treat HD engineer's problem
- M. Bouhlel left to Michigan as postdoc. We decide to unify our forces with UoM, Nasa Glenn, Supaero/Onera → spirit of reproducible research **RR** developed at the MDOLab (Prof Martins)



$$\begin{aligned}
 &\text{Ordinary} \\
 &\text{Kriging} \quad k(x, x') = \sigma^2 \exp\left(-\sum_{i=1}^d \theta_i |x_i - x'_i|^{p_i}\right) \text{ } d \text{ parameters } \theta_i \text{ to evaluate} \\
 &\text{Covariance kernel} \downarrow \\
 &\text{KPLS} \quad k_{PLS}(x, x') = \sigma^2 \exp\left(-\sum_{i=1}^d \eta_i |x_i - x'_i|^{p_i}\right) \text{ with } \eta_i = \sum_{j=1}^h \theta_j |w_{i,j}|^{p_i} \\
 &\text{h parameters } \theta_j \text{ to evaluate}
 \end{aligned}$$

- $|w_{i,j}|_{i=1,\dots,d}$ describes how sensitive the j -th principal component is to each design variable i → PLS
- θ_j describes how sensitive the function is to each principal component ($\max h \approx 4$) → MLE
- If $h = d$ → classical kriging (exponential kernels)

...in 2017 the first SMT version was released



Table of Contents

SMT: Surrogate Modeling Toolbox
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Getting started

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Quick search

SMT: Surrogate Modeling Toolbox

The surrogate modeling toolbox (SMT) is an open-source Python package consisting of libraries of surrogate modeling methods (e.g., radial basis functions, kriging), sampling methods, and benchmarking problems. SMT is designed to make it easy for developers to implement new surrogate models in a well-tested and well-documented platform, and for users to have a library of surrogate modeling methods with which to use and compare methods.

The code is available open-source on [GitHub](#).

Cite us

To cite SMT: M. A. Bouhlel and J. T. Hwang and N. Bartoli and R. Lafage and J. Morlier and J. R. R. A. Martins.

[A Python surrogate modeling framework with derivatives. Advances in Engineering Software, 2019.](#)

```
@article{SMT2019,
    Author = {Mohamed Amine Bouhlel and John T. Hwang and Nathalie Bartoli and Rémi Lafage},
    Journal = {Advances in Engineering Software},
    Title = {A Python surrogate modeling framework with derivatives},
    pages = {102662},
    year = {2019},
    issn = {0965-9978},
    doi = {https://doi.org/10.1016/j.advengsoft.2019.03.005},
    Year = {2019}}
```

Focus on derivatives

SMT is meant to be a general library for surrogate modeling (also known as metamodeling, interpolation, and regression), but its distinguishing characteristic is its focus on derivatives, e.g., to be used for gradient-based optimization.

The paper had to wait until 2019...

Bouhlel, M. A., Hwang, J. T., Bartoli, N., Lafage, R., Morlier, J., & Martins, J. R. (2019). A Python surrogate modeling framework with derivatives. *Advances in Engineering Software*, 135, 102662.

SMT structure – Surrogate

1.1.0 Latest

Compare ▾

self released this 1 hour ago v1.1.0 651df91

- Mixed integer surrogate enhancements (thanks @Paul-Saves)
 - Add number of components estimation in KPLS surrogate models (#325)
 - Add propagate_uncertainty option in MFK method (#320) : when True the variance of lower fidelity levels are taken into account.
 - Add ordered variables management in mixed integer surrogates (#326, #327). Deprecation warning: INT type is deprecated and superseded by ORD type.
 - Update version for the GOWER distance model. (#330)
 - Implement generalization of the homoscedastic hypersphere kernel from Pelamatti et al. (#330)

Svante Wold (1978) Cross-Validatory Estimation of the Number of Components in Factor and Principal Components Models, *Technometrics*, 20:4, 397-405, DOI: [10.1080/00401706.1978.10489693](https://doi.org/10.1080/00401706.1978.10489693)

Useful for low dimensional problem

- Radial basis functions
- Inverse-distance weighting
- Regularized minimal-energy tensor-product splines
- Least-squares approximation
- Second order polynomial approximation
- Kriging
- Kriging with partial least square (KPLS)
- KPLSK
- Gradient-enhanced KPLS
- Gradient-enhanced neural networks
- Marginal Gaussian process

useful for kriging in high dimension

Focus on derivatives

Bouhlel, M. A., Hwang, J. T., Bartoli, N., Lafage, R., Morlier, J., & Martins, J. R. (2019). A Python surrogate modeling framework with derivatives. *Advances in Engineering Software*, 135, 102662.

Focus on derivatives

| Method | Advantages (+) and disadvantages (-) | Derivatives | | |
|---------|---|-------------|-------|------|
| | | Train. | Pred. | Out. |
| Kriging | + Prediction variance, flexible - Costly if number of inputs or training points is large - Numerical issues when points are too close to each other | No | Yes | No |
| KPLS | + Prediction variance, fast construction + Suitable for high-dimensional problems - Numerical issues when points are too close to each other | No | Yes | No |
| KPLSK | + Prediction variance, fast construction + Suitable for high-dimensional problems - Numerical issues when points are too close to each other | No | Yes | No |
| GE-KPLS | + Prediction variance, fast construction + Suitable for high-dimensional problems + Control of the correlation matrix size - Numerical issues when points are too close to each other - Choice of step parameter is not intuitive | Yes | Yes | No |
| RMTS | + Fast prediction + Training scales well up to 10^5 training points + No issues with points that are too close to each other - Poor scaling with number of inputs above 4 - Slow training overall | Yes | Yes | Yes |
| RBF | + Simple, only a single tuning parameter + Fast training for small number of training points - Susceptible to oscillations - Numerical issues when points are too close to each other | No | Yes | Yes |

$$\mathbf{y} = \mathbf{f}(\mathbf{x}, \mathbf{x}\mathbf{t}, \mathbf{y}\mathbf{t})$$

$(\mathbf{x}\mathbf{t}, \mathbf{y}\mathbf{t})$ Training data
 (\mathbf{x}, \mathbf{y}) Prediction data

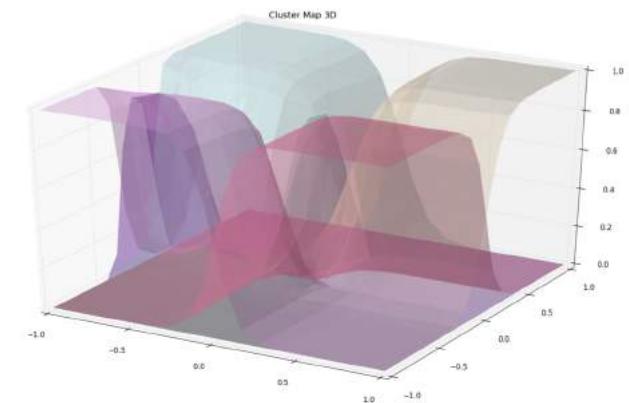
(dyt/dxt) : training derivatives used for gradient-enhanced modeling

(dy/dx) : prediction derivatives

(dy/dyt) : derivatives with respect to the training data

AI4E

- Mixture of experts (MOE) - if 1 expert , comparison of all experts
- Variable-fidelity modeling (VFM)
- Multi-Fidelity Kriging (MFK)
- Multi-Fidelity Kriging KPLS (MFKPLS)
- Multi-Fidelity Kriging KPLSK (MFKPLSK)
- Efficient Global Optimization (EGO)
- Mixed-Integer Sampling and Surrogate (Continuous Relaxation)
- Mixed-Integer Surrogate with Gower Distance



How to approximate highly non linear function?

- Handle heterogeneity and non linearity (all phases in the flight mission, buckling factor for composite fuselage)
- Combine multiple surrogate models divide-and- conquer strategy

AI4E

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How to handle multi-information sources?

- Access to different information sources that approximate $y(x)$ with varying accuracy and cost
Hierarchical relationships among information sources: low-fidelity / high-fidelity

Why multifidelity?

Artificial Intelligence for Engineers, means learning for optimizing a computational design.

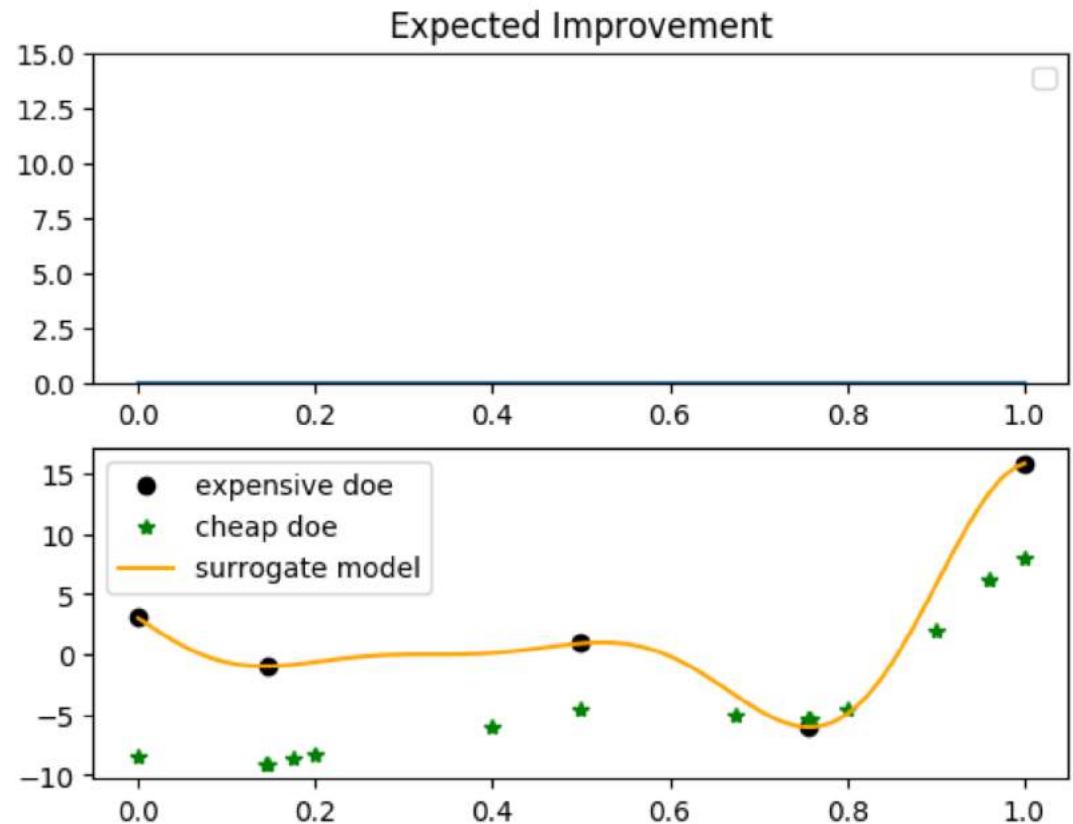
Given a surrogate model with both prediction and confidence parameters, an optimization procedure must balance the search for the expected optimal point and decreasing uncertainty (**Bayesian Optimization**)

What if Several levels of fidelity of the same simulation are available?

(in aerodynamics **multifidelity** means: Lifting line theory, Vortex lattice method, and RANS CFD simulation tools available)

Raw approach use low fidelity for exploration and high fidelity for exploitation

Our approach combine Bayesian optimization with multifidelity



AI4E

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Bayesian optimization (EGO without constraint) for continuous and mixed variables



Included some dedicated Jupyter Notebooks

| |
|------------------------------------|
| .. |
| SMT_EGO_application.ipynb |
| SMT_MixedInteger_application.ipynb |
| SMT_Noise.ipynb |
| SMT_Tutorial.ipynb |

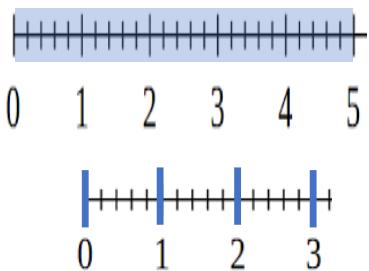
AI4E

- Mixture of experts (MOE)
- Variable-fidelity modeling (VFM)
- Multi-Fidelity Kriging (MFK)
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- Multi-Fidelity Kriging KPLSK (MFKPLSK)
- Efficient Global Optimization (EGO)
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- Mixed-Integer Surrogate with Gower Distance

Focus on mixed integer

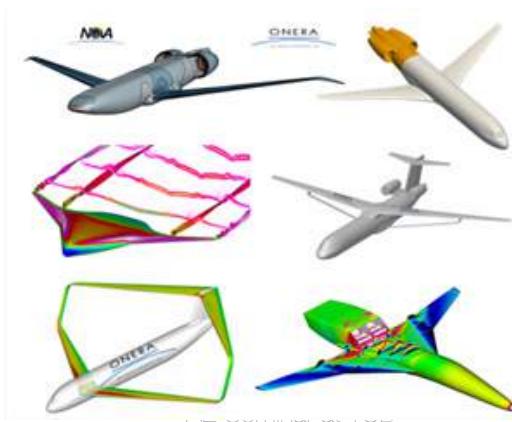
Variables types :

Continuous (x) Ex: wing length



Integer (z) Ex: winglet number

Categorical (u) Ex: Plane shape



Categorical variables: n variables,
n=2
u1= shape
u2= color

Levels: L_i levels for i in 1,...,n,
 $L_1=3$, $L_2=2$.
Levels(u1)= square, circle,
rhombus
Levels(u2)= blue, green

Categories: $\prod_{i=1}^n L_i$, $2^*3=6$

- Blue square
- Blue circle
- Blue rhombus
- Green square
- Green circle
- Green rhombus

Focus on mixed integer

Continuous relaxation

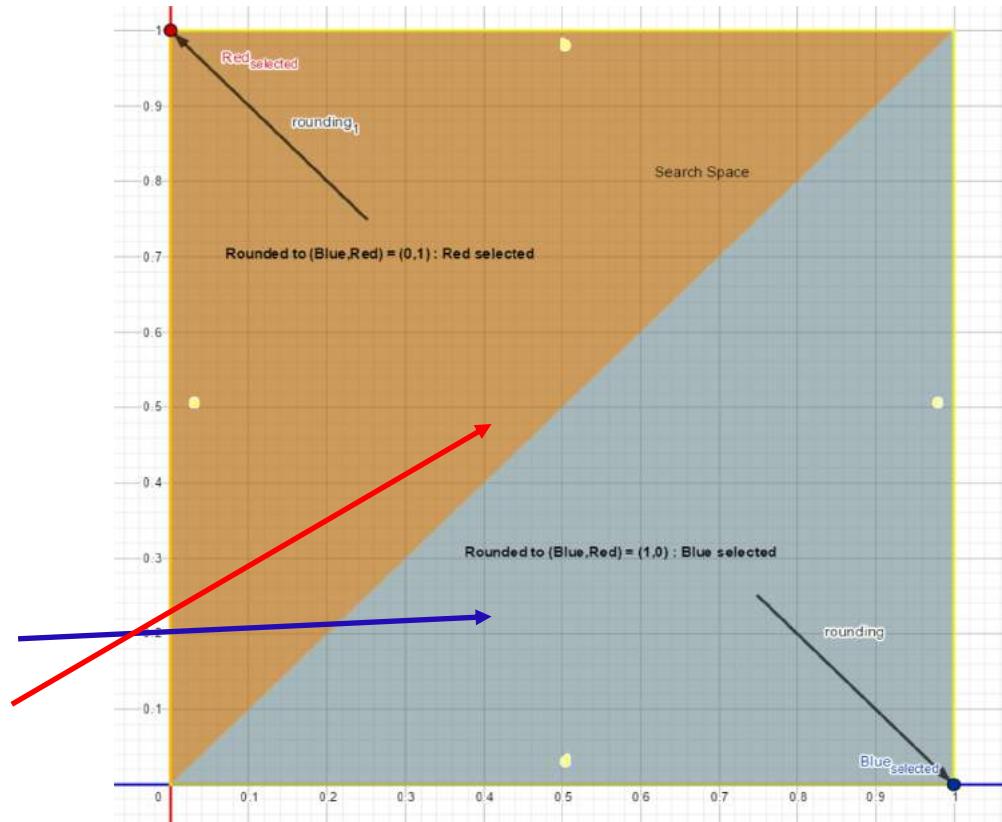
E. C. Garrido-Merchán, and D. Hernández-Lobato. "Dealing with categorical and integer-valued variables in Bayesian Optimization with Gaussian processes". Neurocomputing, vol. 380 (2020), pages 20-35

Example with 1 categorical variable and two levels

- Red color
- Blue color

→ Categorical variable replaced by two continuous variables denoted by X_1 and X_2

- If $X_1 > X_2 \Rightarrow (1., 0.) \Rightarrow$ Blue color
- If $X_1 < X_2 \Rightarrow (0., 1.) \Rightarrow$ Red color



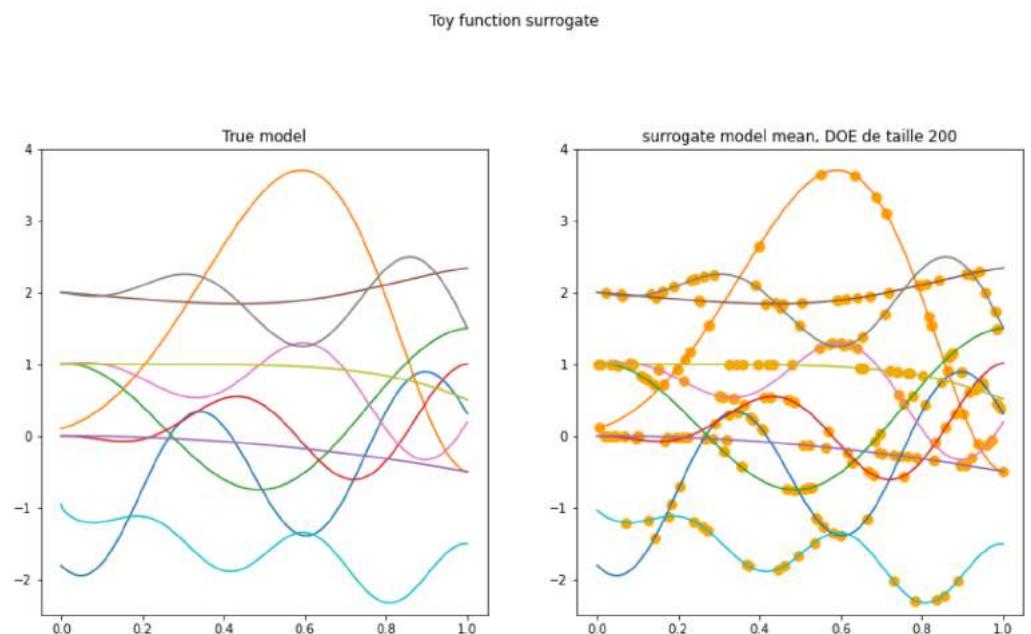
Focus on mixed integer

Continuous relaxation

Validation problem $n_{\text{var}} = 2$

Variable types: continuous and categorical with 10 levels. $n_{\text{var,relaxed}} = 11$

$$f(x, z) = \begin{cases} \cos(3.6\pi(x-2)) + x - 1 & \text{if } z = 1, \\ 2 \cos(1.1\pi \exp(x)) - \frac{x}{2} + 2 & \text{if } z = 2, \\ \cos(2\pi x) + \frac{1}{2}x & \text{if } z = 3, \\ x \left(\cos(3.4\pi(x-1)) - \frac{x-1}{2} \right) & \text{if } z = 4, \\ -\frac{x^2}{2} & \text{if } z = 5, \\ 2 \cos(\frac{\pi}{4} \exp(-x^4))^2 - \frac{x}{2} + 1 & \text{if } z = 6, \\ x \cos(3.4\pi x) - \frac{x}{2} + 1 & \text{if } z = 7, \\ x(-\cos(\frac{7\pi}{2}x) - \frac{x}{2}) + 2 & \text{if } z = 8, \\ -\frac{x^5}{2} + 1 & \text{if } z = 9, \\ -\cos(5\frac{\pi}{2}x)^2 \sqrt{x} - \frac{\ln(x+0.5)}{2} - 1.3 & \text{if } z = 10. \end{cases}$$



SMT installation



On the github website, some instructions are given

- to perform the installation
- to have access to the documentation
- to find some examples

Documentation

<http://smt.readthedocs.io>

Required packages

SMT depends on the following modules: numpy, scipy, scikit-learn, pyDOE2 and Cython.

Installation

If you want to install the latest release

```
pip install smt
```

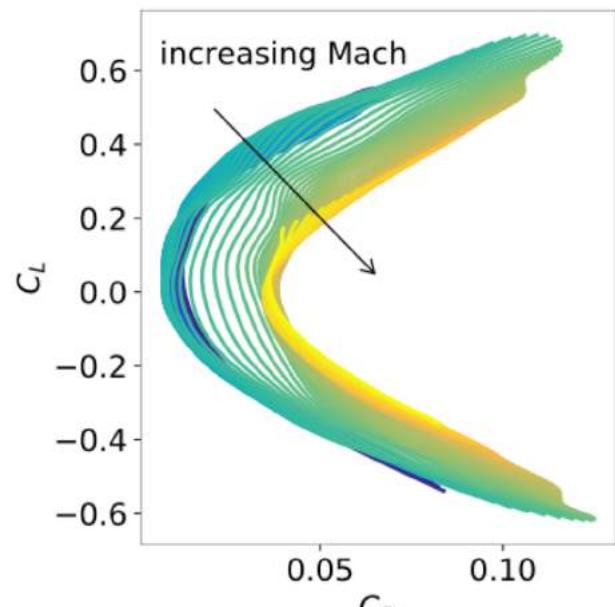
or else if you want to install from the current master branch

```
pip install git+https://github.com/SMTOrg/smt.git@master
```

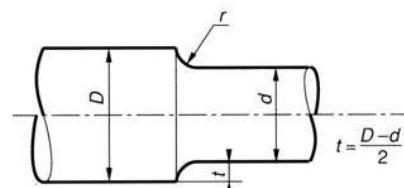
Usage

For examples demonstrating how to use SMT, you can take a look at the [tutorial notebook](#) or go to the 'smt/examples' folder.

Surrogate is the new abacus



Coefficient de concentration de contrainte : K_t .



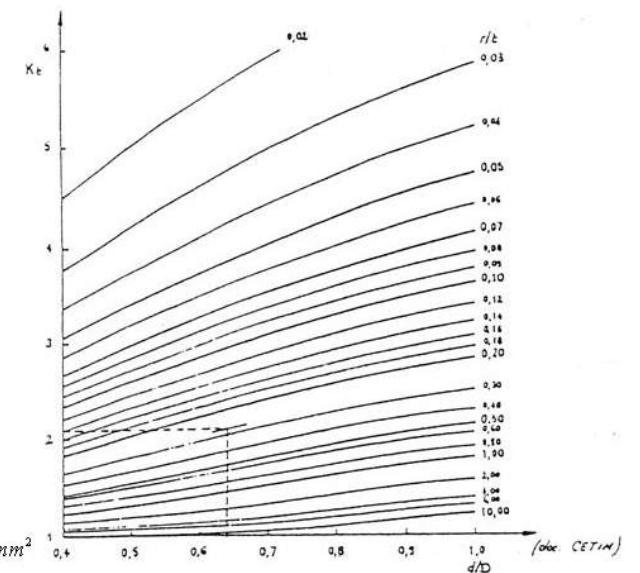
$$\sigma_{\text{min,ale}} = \frac{N}{S} \quad \text{d'où} \quad \sigma_{\text{max,i}} = K_t \cdot \sigma_{\text{min,ale}}$$

Condition de résistance: $\sigma_{\text{max,i}} < R_{pe}$

Exemple: $D = 100$, $d = 64$, $r = 5$
 $N = 5000$ daN

$$\left. \begin{aligned} \frac{d}{D} &= \frac{64}{100} = 0,64 \\ \frac{r}{t} &= \frac{2r}{D-d} = \frac{10}{100-64} = 0,278 \\ \sigma_{\text{min,ale}} &= \frac{4 \times 5000}{\pi \times 64^2} = 1,55 \text{ daN/mm}^2 \\ \sigma_{\text{max,i}} &= K_t \times \sigma_{\text{min,ale}} = 2,1 \times 1,55 = 3,26 \text{ daN/mm}^2 \end{aligned} \right\} K_t = 2,1$$

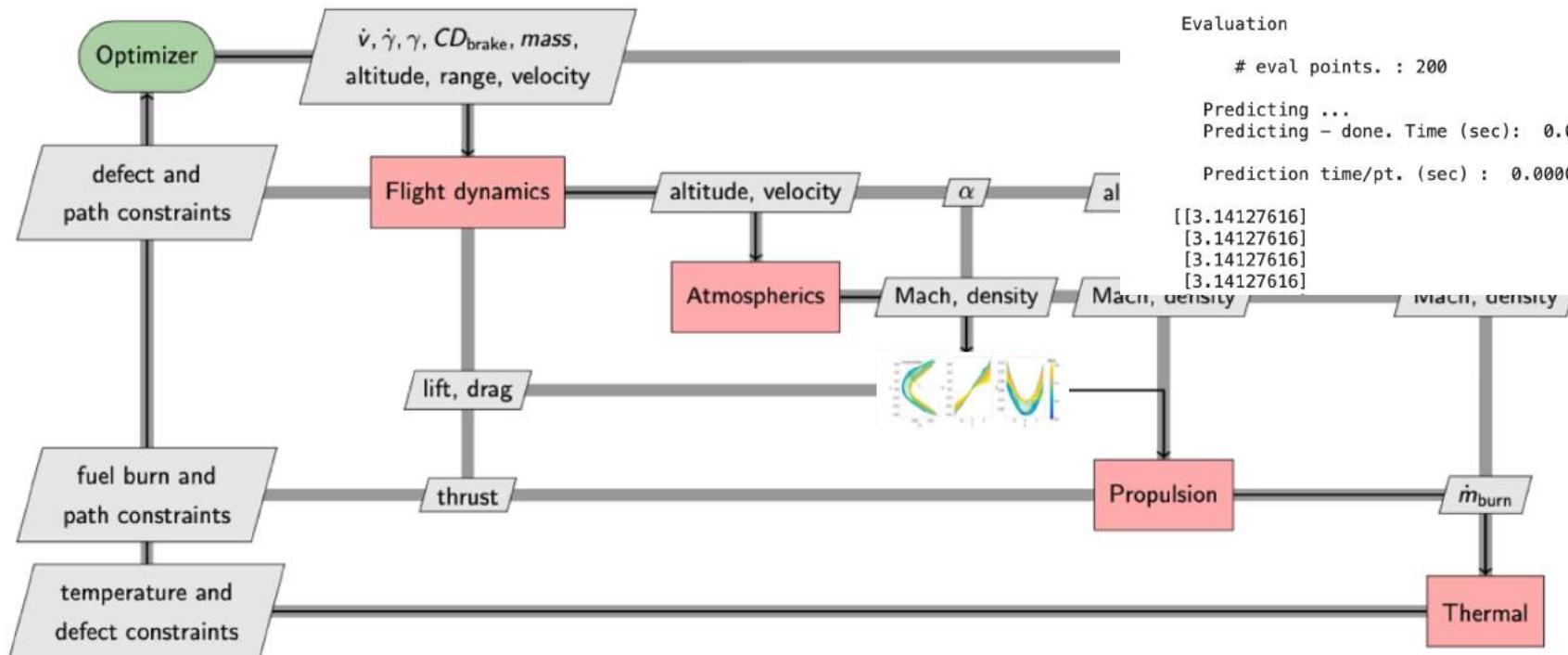
Arbre épaulé en traction



Benefits of Opensource

Coupling with OpenMDAO

Jasa, J. P., Brelje, B. J., Gray, J. S., Mader, C. A., & Martins, J. R. (2020). Large-Scale Path-Dependent Optimization of Supersonic Aircraft. *Aerospace*, 7(10), 152.



```
[ ] import pickle
#For saving models written in Python
filename = "sm.pkl"
with open(filename, "wb") as f:
    pickle.dump(sm, f)
#For loading the model
sm_load = None
with open(filename, "rb") as f:
    sm_load= pickle.load(f)

#to use the surrogate model
y_load = sm_load.predict_values(xtest)
print(y[1:10])
print(y_load[1:10])
```

Evaluation

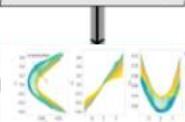
eval points. : 200

Predicting ...

Predicting - done. Time (sec): 0.0008404

Prediction time/pt. (sec) : 0.0000042

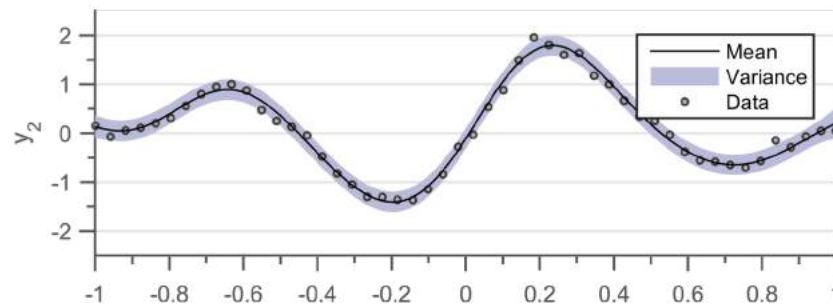
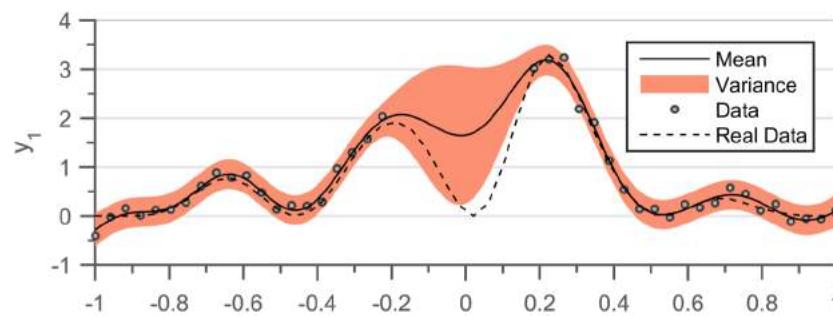
```
[[3.14127616]
 [3.14127616]
 [3.14127616]
 [3.14127616]]
```



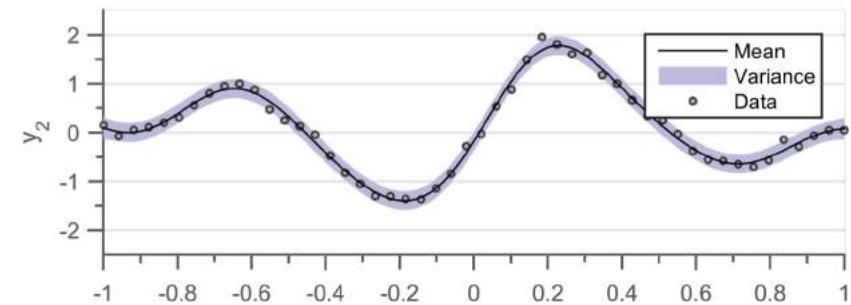
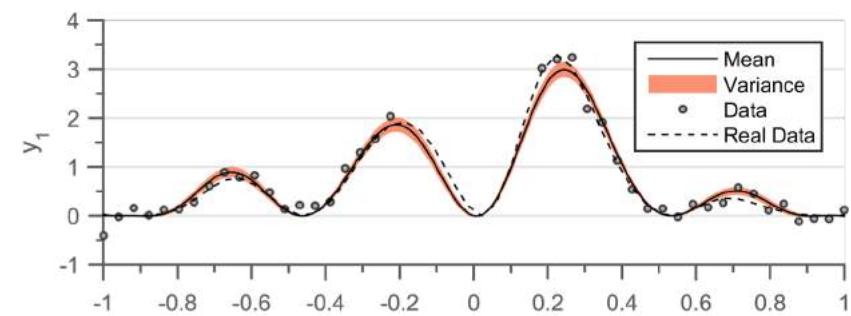
What we did few years ago before PINN and SciML...

https://github.com/ankitchiplunkar/thesis_isae

Faulty sensor



Independent GPs

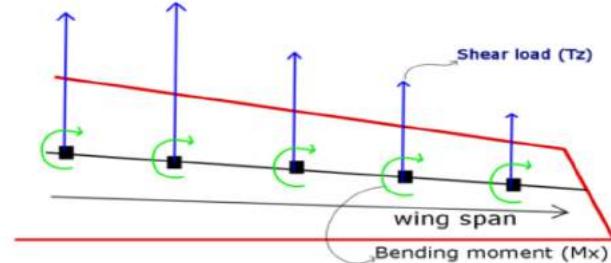


Related GPs

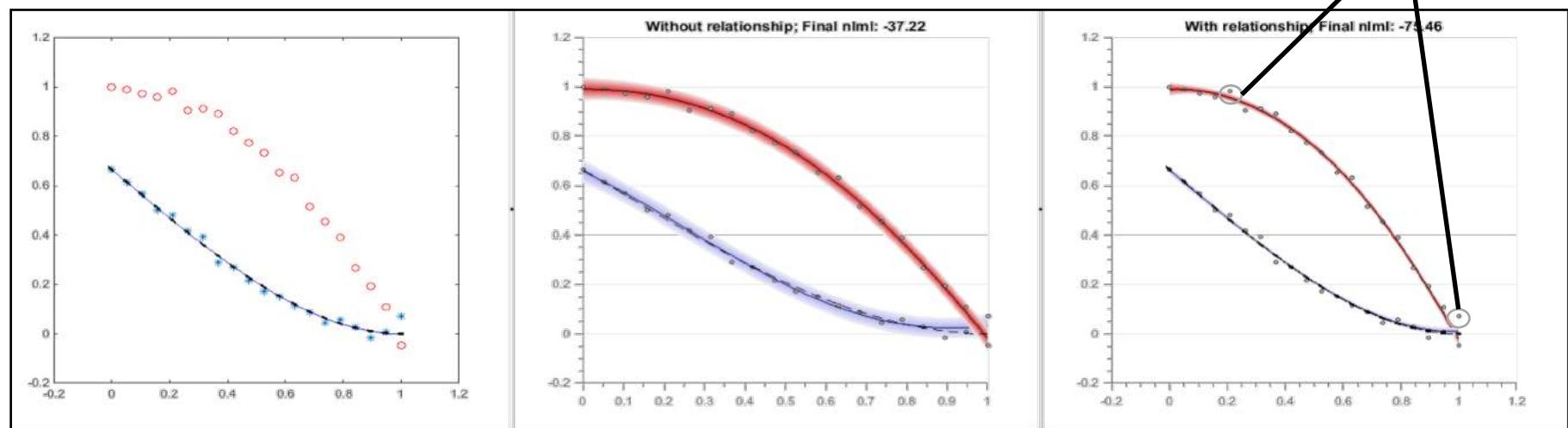
What we did few years ago before PINN and SciML...

https://github.com/ankitchiplunkar/thesis_isae

Flight test - Relationship between T_z and M_x



$$M_x = \int_{\eta}^{\eta_{edge}} (x - \eta) T_z dx$$



Au programme

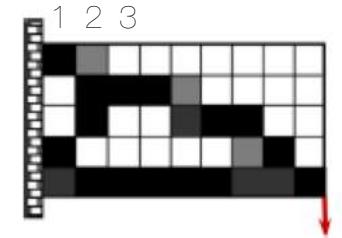


Ecodesign

| Duration | Description | Agenda |
|----------|------------------|---------------------|
| 10' | MDO | Examples |
| 10' | Surrogate | SMT |
| 10' | Ecodesign | Lighter and Greener |
| 2' | Conclusions | And future works? |

Intuitive Problem? Quadratic Form

$$\begin{aligned}x_1 &= 1 \\x_2 &= 0.5 \\x_3 &= 0 \\&\dots\end{aligned}$$



- Objective function; Strain energy

$$\min c(\mathbf{x}) = \mathbf{U}^T \mathbf{F} = \mathbf{U}^T \mathbf{K} \mathbf{U}$$

with

$$\mathbf{K} = \mathbf{K}_0 \sum_{e=1}^N \mathbf{x}_e^p$$

$$\text{with } x_e = \frac{\rho_e}{\rho_0} \quad (4)$$

one can write:

$$\min c(\mathbf{x}) = \sum_{e=1}^N (\mathbf{x}_e)^p \mathbf{u}_e^T \mathbf{k}_0 \mathbf{u}_e \quad \text{Scalar} \quad (5)$$

- Constraints: mass target

$$\frac{V(\mathbf{x})}{V_0} = f = \dot{\underline{const}} \Leftrightarrow \sum_{e=1}^N V_e \mathbf{x}_e = V_0 f = h(\mathbf{x}) \quad \text{Scalar}$$

$$0 < \rho_{\min} \leq \rho_e \leq 1$$

Pixels?

When the size of the FE model is increasing, the SIMP optimization problem is ... increasing

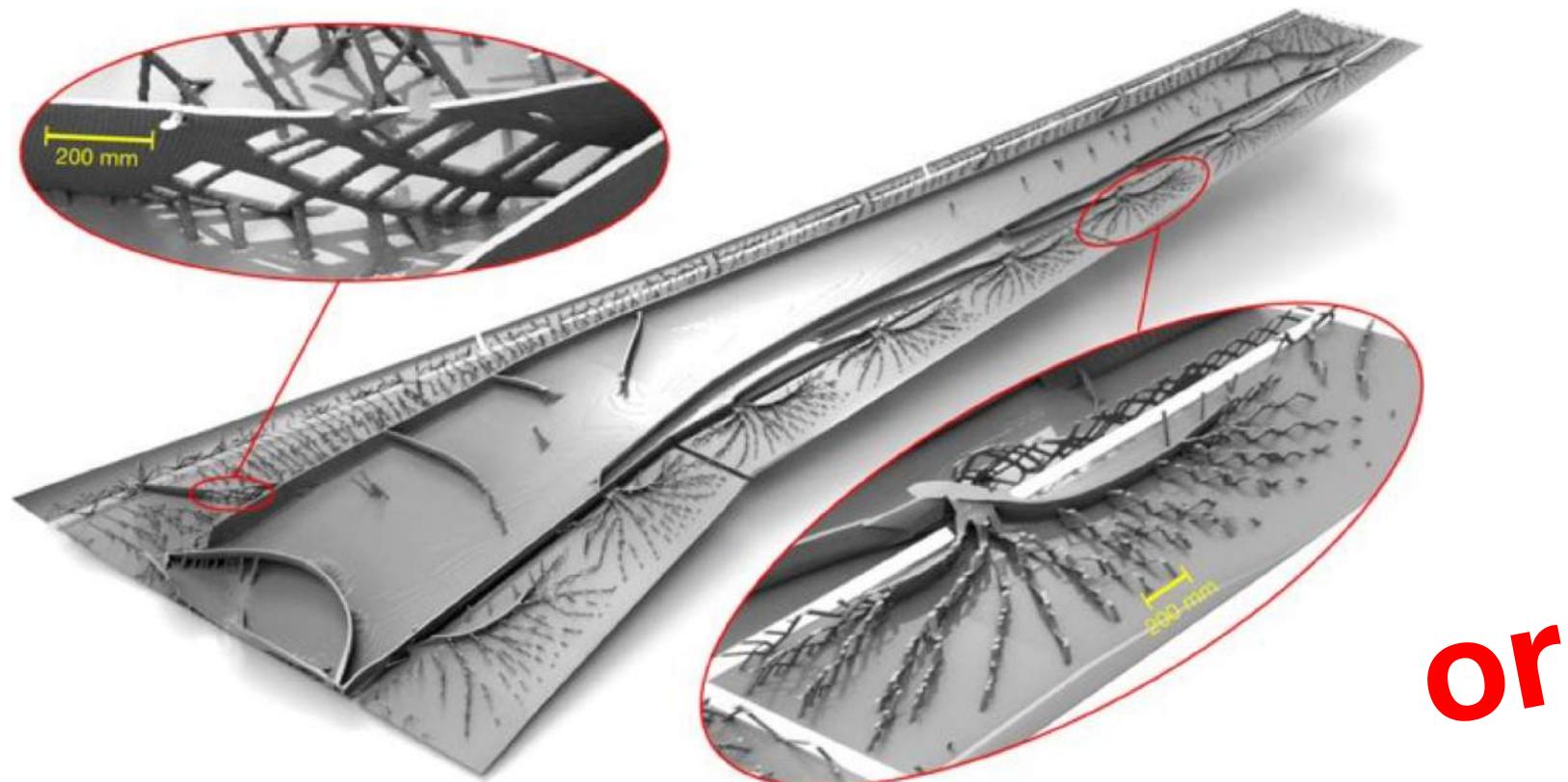


Chris Columbus et al, Pixels, movie 2015



Use HPC and lot of time

Niels Aage, Erik Andreassen, Boyan S Lazarov, and Ole Sigmund. Giga-voxel computational morphogenesis for structural design. *Nature*, 550(7674):84, 2017.

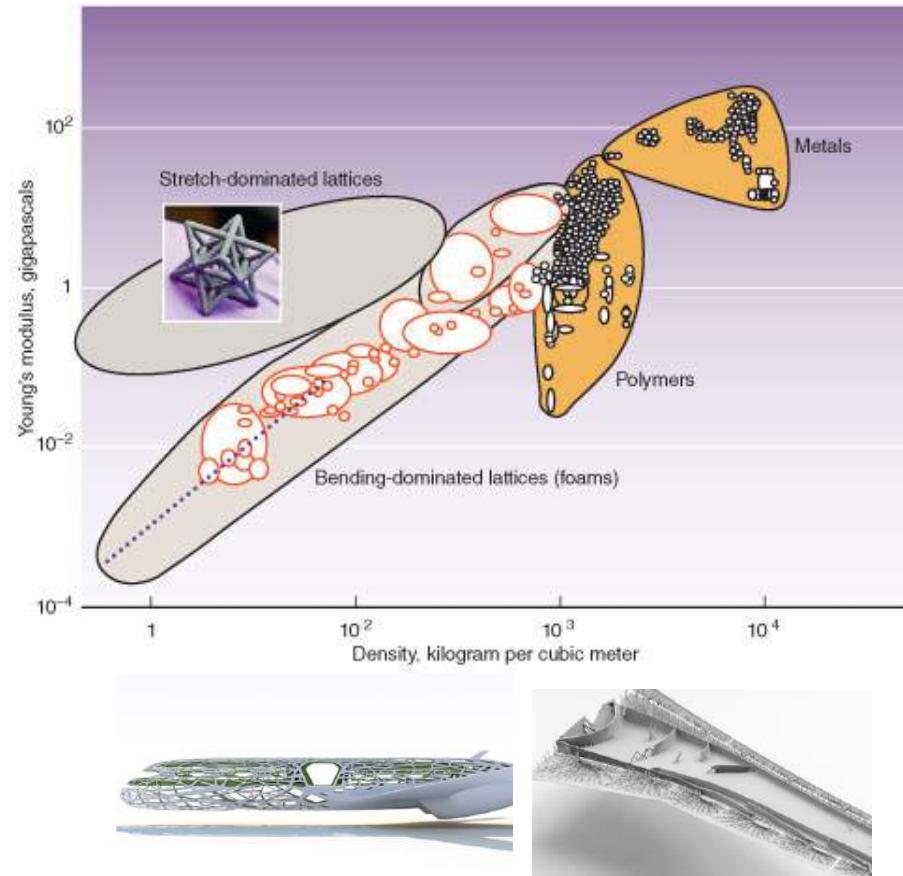


Reproducible Research

- <https://www.topopt.mek.dtu.dk>
- <https://www.top3d.app>



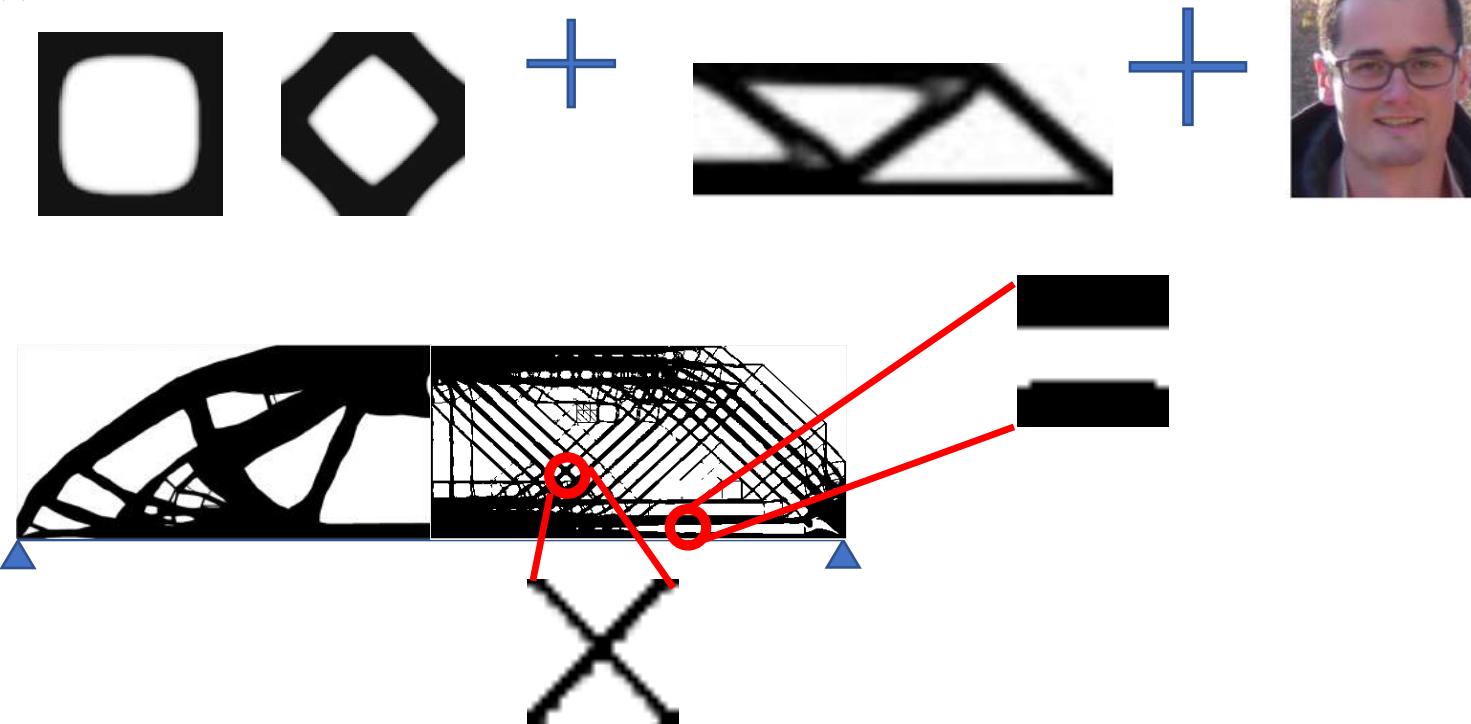
The ERA of DIGITAL MATERIALS



Chris Spadaccini (Inl, USA) "By controlling the architecture of a microstructure, we can create materials with previously unobtainable properties in the bulk form."

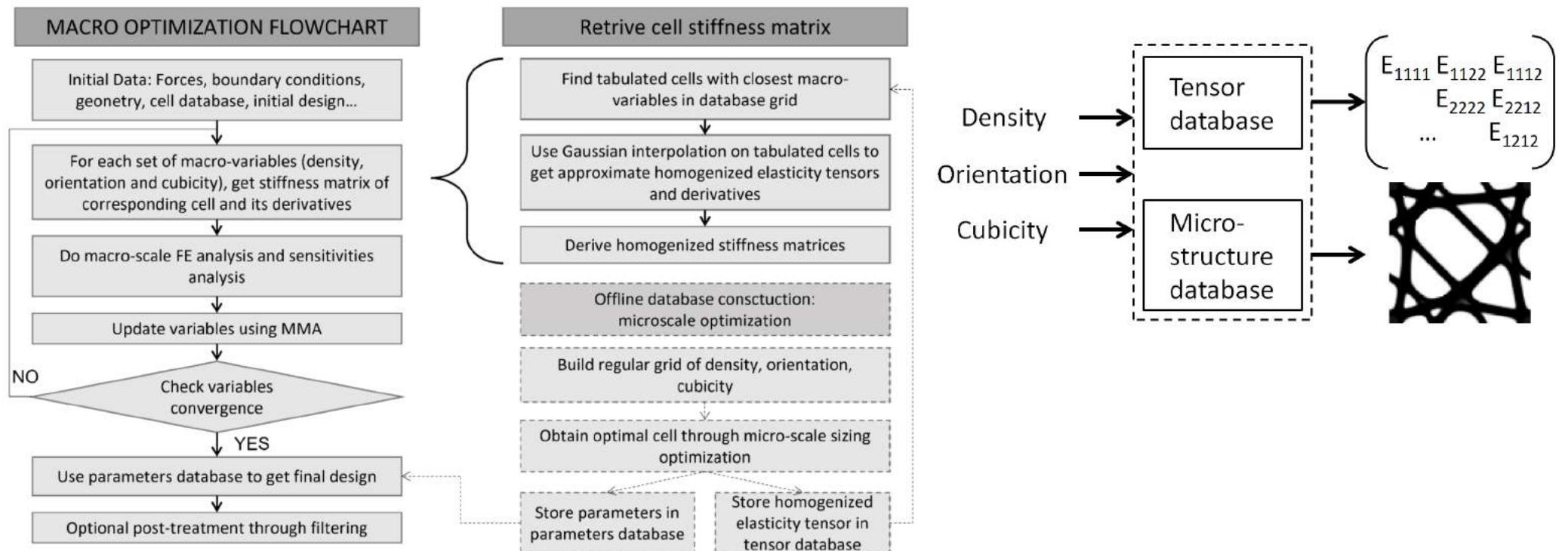
Multi-scale TO

A two level optimization that combines Unit cell design & Topology Optimization

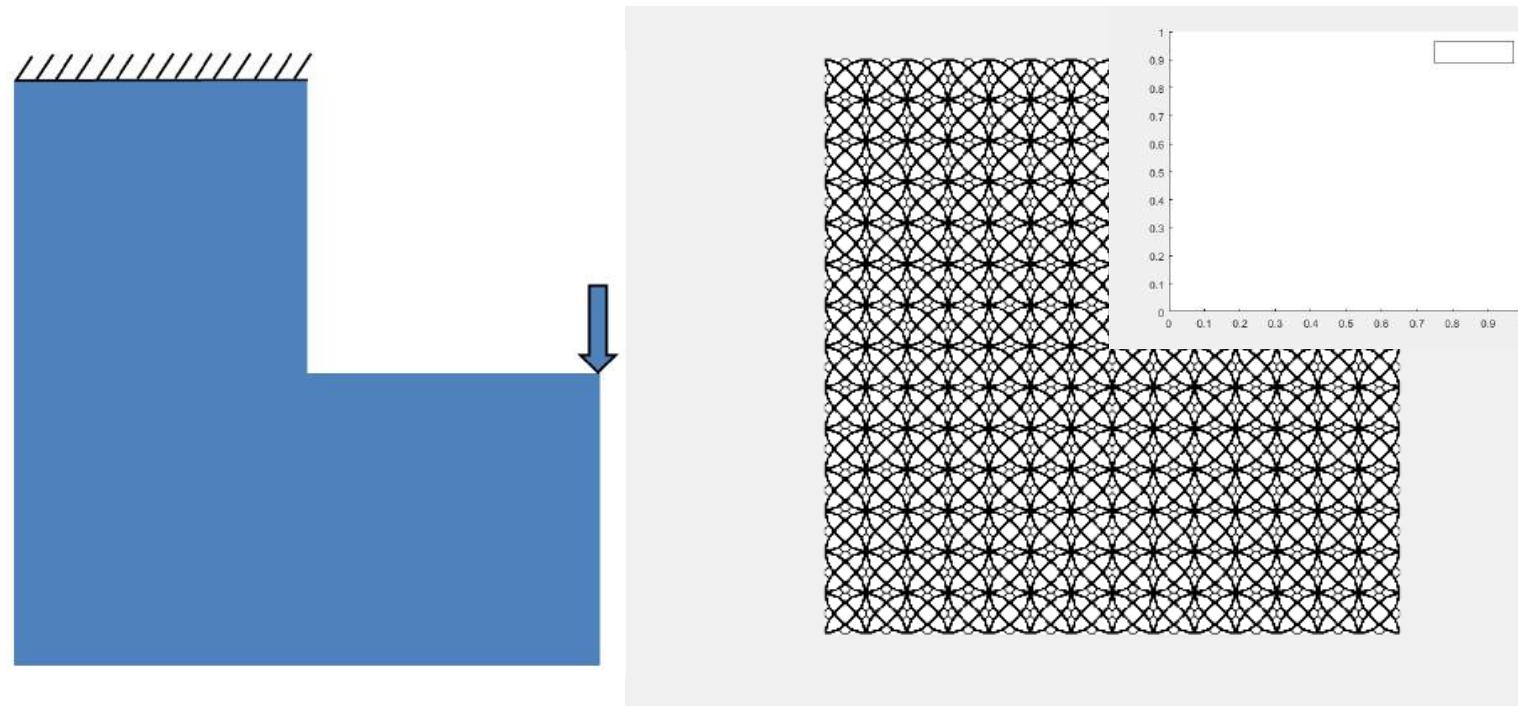


Xia L, Breitkopf P (2015) Design of materials using topology optimization and energy-based homogenization approach in Matlab. Struct Multidisc Optim 52(6):1229–1241. <https://doi.org/10.1007/s00158-015-1294-0>

Acceleration through AI



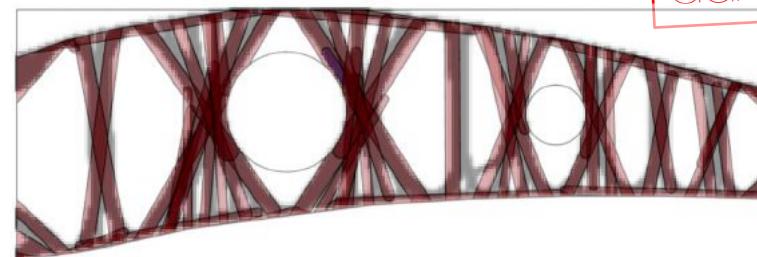
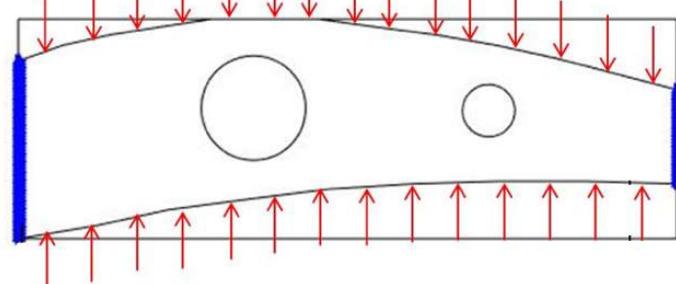
EMTO on L-shape (cellular /digital materials)



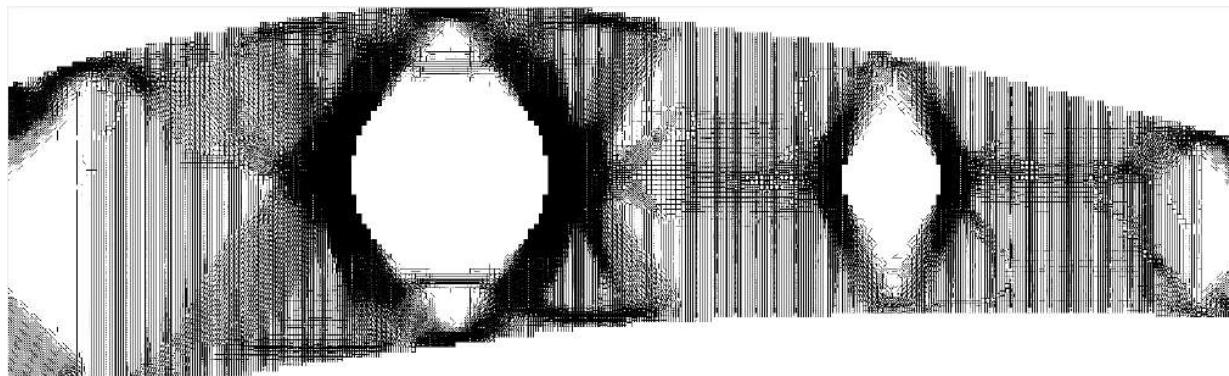
<https://github.com/mid2SUPAERO/EMTO>

Aircraft rib design

- Again Only pressure loads



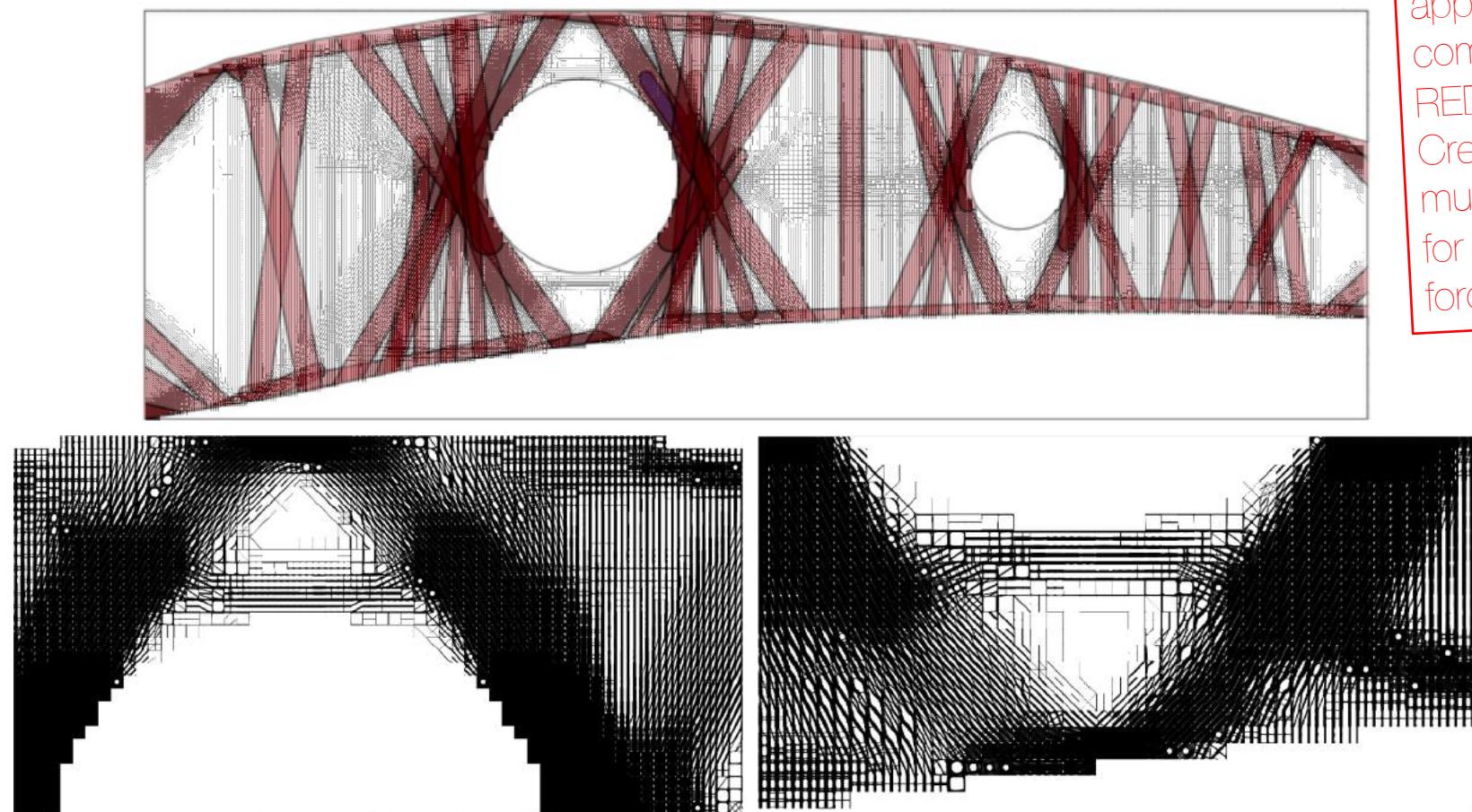
SIMP : $c=0.198$



EMTO : $c=0.172$ (homogenized) $c=0.178-0.206$ (estimate)

GGP := EASY
EXPLORATION of
POTENTIAL DESIGN OF
STRUCTURES
GGP-MNA: $C=0.194$

EMTO vs GGP



Multiscale approach is a complete REDESIGN:
Creation of multiple paths for internal forces

It should be manufactured by machine

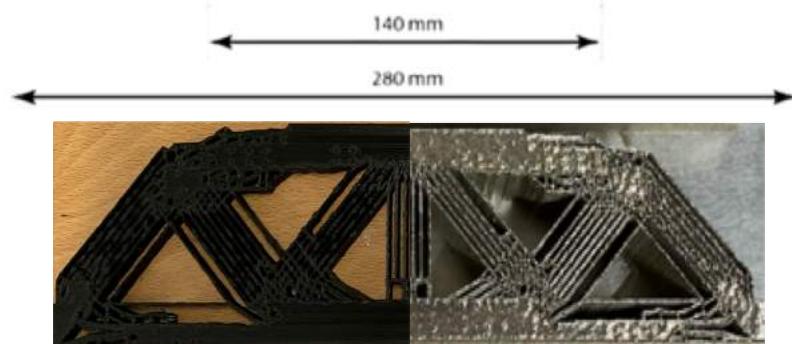
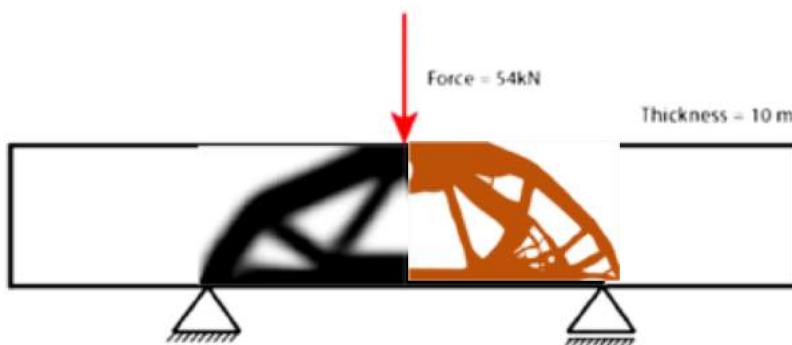
How to **ECO**design tomorrow's structures?

Prof. Joseph Morlier, Edouard Duriez, Miguel Charlotte, Catherine Azzaro-Pantel

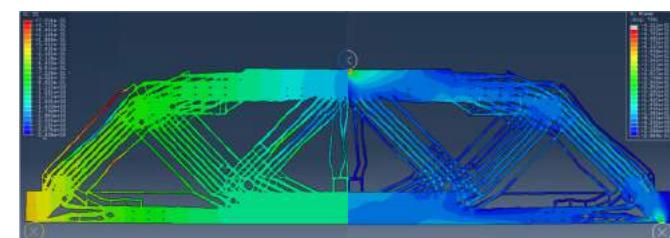
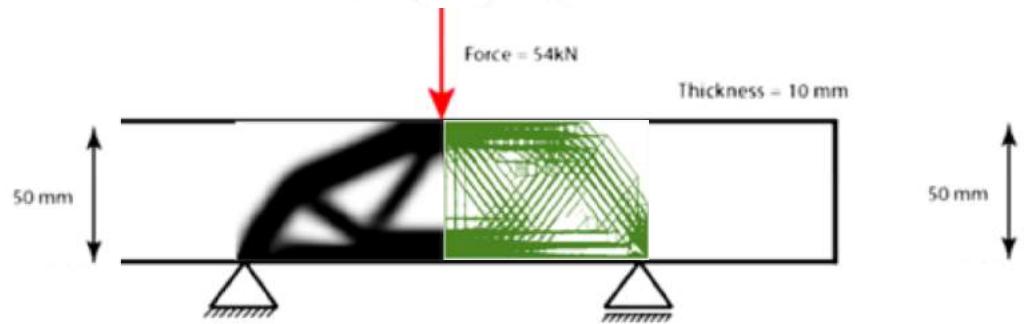
Print it , Test it



EXP +ABAQUS
REANALYSE

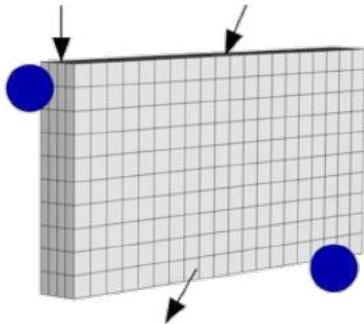


PLA or Selective Laser Melting (SLM)

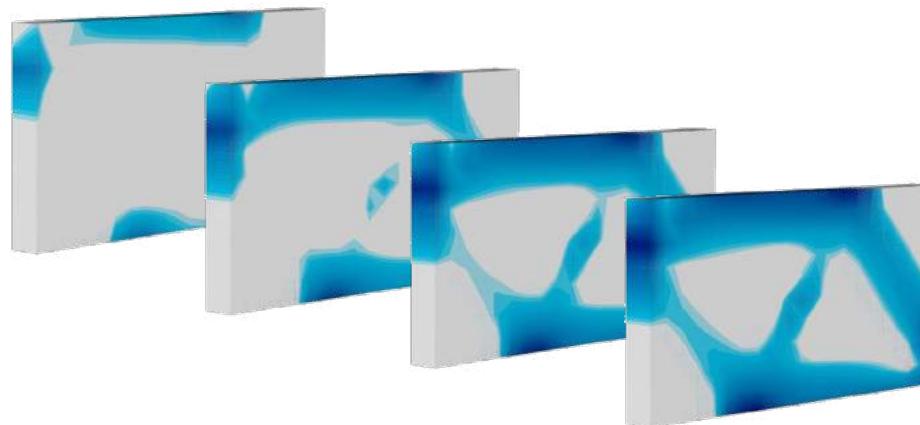


**A simple way to do Ecodesign
with Topology Optimization ?**

Start with Topology Optimization



Inputs: Material, BCs and Loading

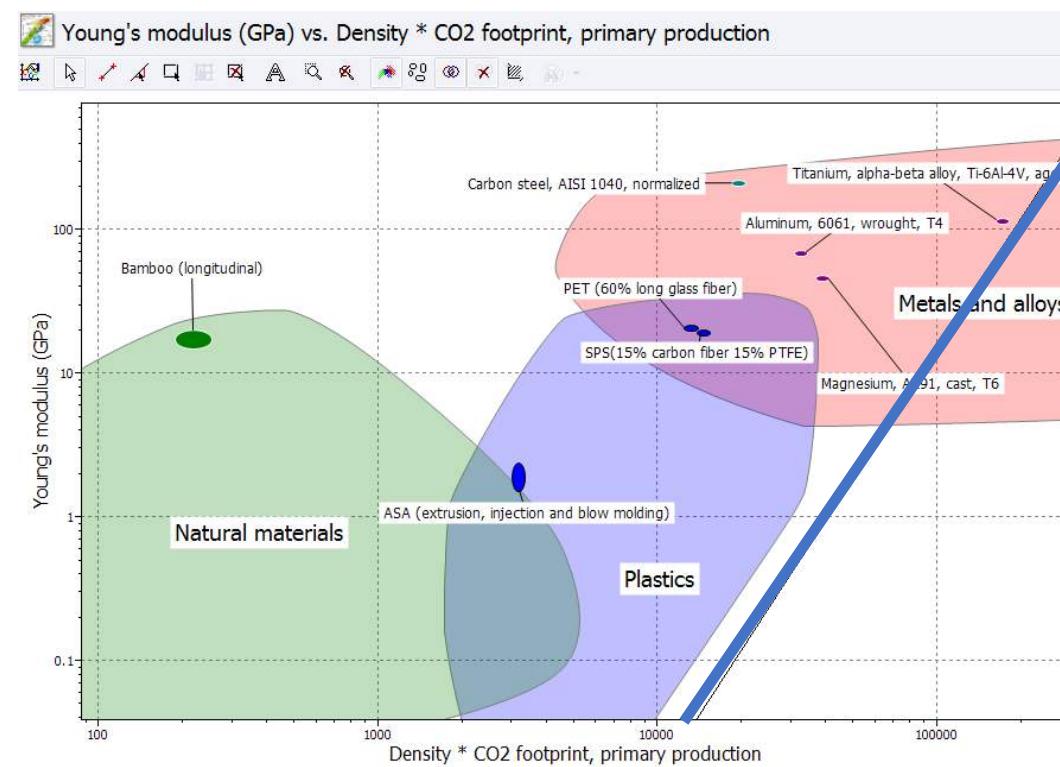


Outputs: design of a „stiff“ bicycle frame



CO₂ footprint minimization (Ashby's method)

Inputs: Type of Structures, default materials



Outputs: Optimal material ([bamboo](#)) with optimal Design

MDO



Available online at www.sciencedirect.com

ScienceDirect

Procedia CIRP 00 (2021) 000–000



www.elsevier.com/locate/procedia

32nd CIRP Design Conference
Ecodesign with topology optimization

Edouard Duriez^{*a}, Joseph Morlier^a, Catherine Azzaro-Pantel^b, Miguel Charlotte^a

#Generalized Ashby's theory
compatible with TopOpt
#All In One problem is a MDO
problem !!!

$$\begin{aligned} & \arg \min_{mat, \mathcal{D}, t} CO_2^{tot}(mat, \mathcal{D}, t) \\ & \text{s.t. } \delta \leq \delta_{max} \\ & mat = \{E, \rho, CO_{2mat}^i\} \in \Phi \\ & 0 < v_f(\mathcal{D}) \leq 1 \end{aligned}$$

Time to conclude



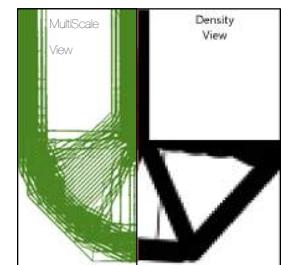
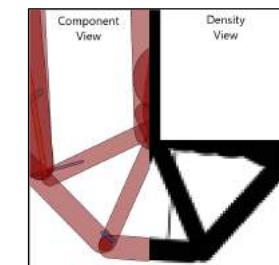
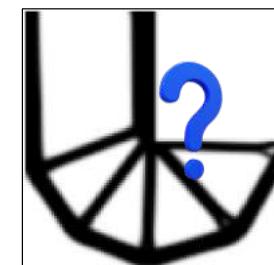
| Duration | Description | Agenda |
|----------|-------------|---------------------|
| 10' | MDO | Examples |
| 10' | Surrogate | SMT |
| 10' | Ecodesign | Lighter and Greener |
| 4' | Conclusions | And future works? |

Researcher view (Reproducible Research)

- <https://www.topopt.mek.dtu.dk>
- <https://www.top3d.app>



- <https://github.com/topggp/blog>
- Crystal clear and preliminary ALM
- <https://github.com/mid2SUPAERO/EMTO>
- Redesign for ALM
- <https://smt.readthedocs.io/en/latest/>
- Design Acceleration



on SMT

« Learning » an industrial (**&costly**) simulation code is interesting to easily exchange data only (without having access to the code in a collaborative project)



Given its focus on **derivatives**, SMT is synergistic with the OpenMDAO framework. **It can provide the derivatives that OpenMDAO requires from its components to compute the coupled derivatives of the multidisciplinary model.**

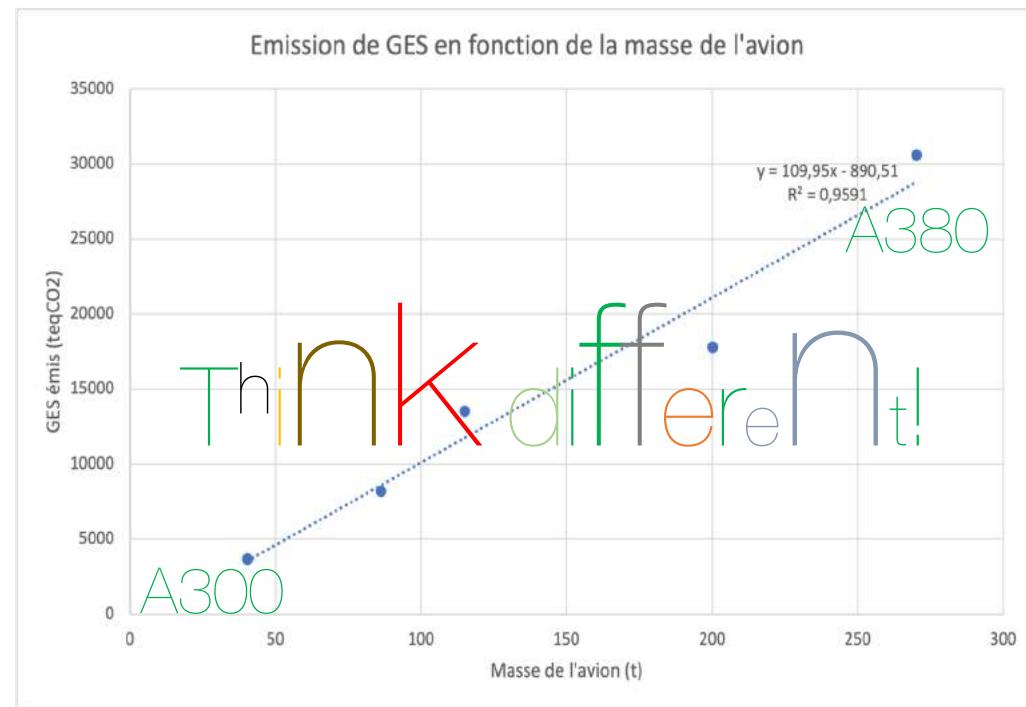


SMT is a natural framework for Bayesian Optimization (**DV<100 through KPLS**)

SMT core capabilities has been adapted for efficient **mixed variables / multifidelity / multiObjectives**

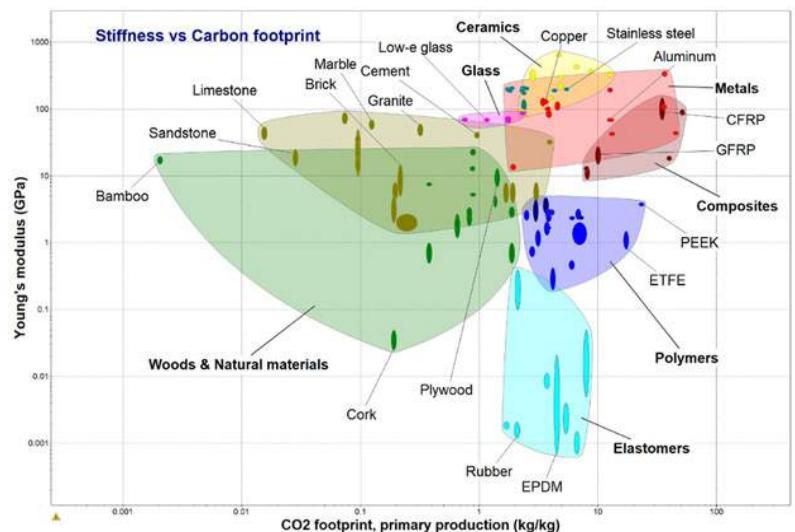
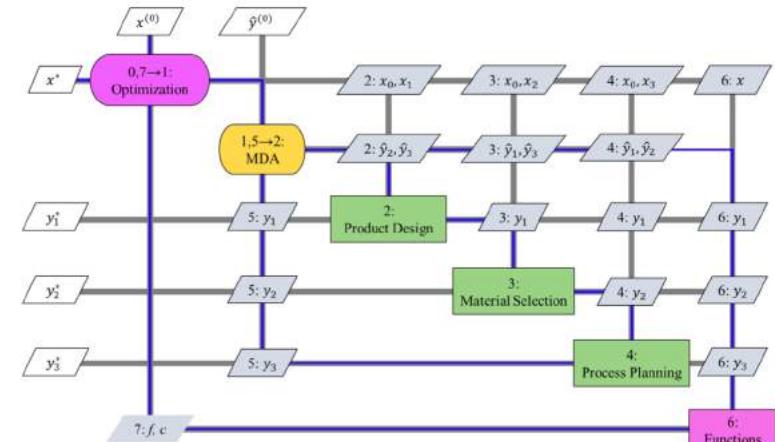
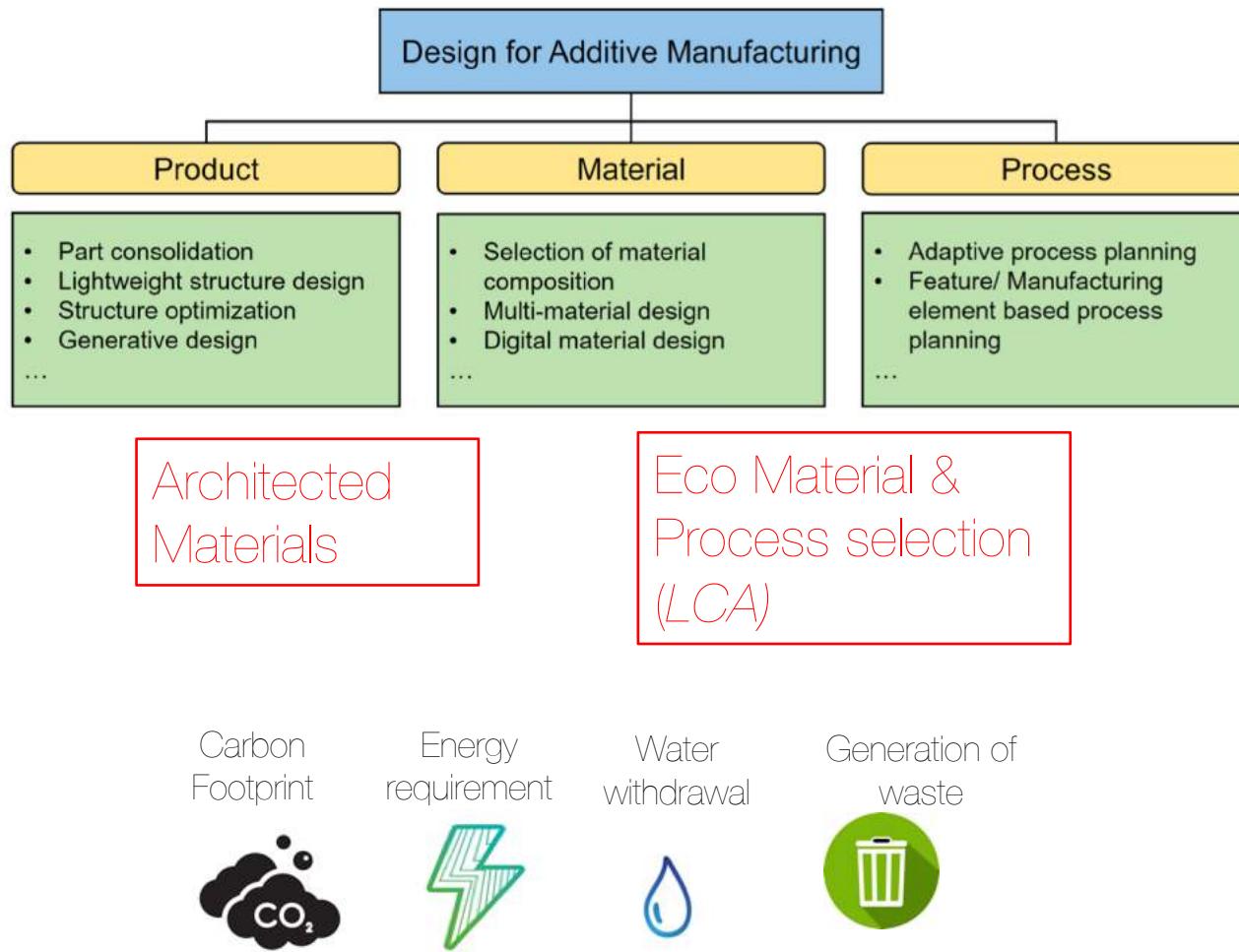
Rank1 on actual aircraft

At the first order
min {mass} is
proportional to
min {CO₂}



Stiffer, Lighter, Greener =
TOPOLOGY OPTIMIZATION + ARCHITECTED MATERIALS
+ DIGITAL FABRICATION + ECODESIGN

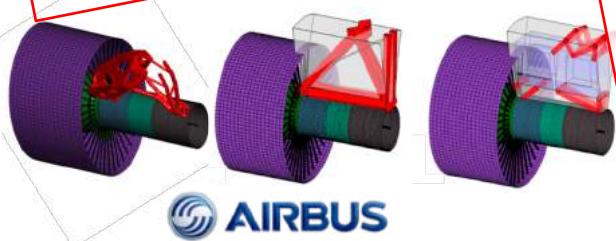
MDO approach for EcoDFAM



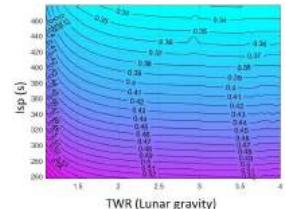
<https://ica.cnrs.fr/author/jmorlier/>



Structural Optimization &
Ecodesign



AIRBUS



#AI4E
Artificial Intelligence For
Engineers

<https://github.com/SMTorg/smt>

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THANK YOU
for Your
ATTENTION

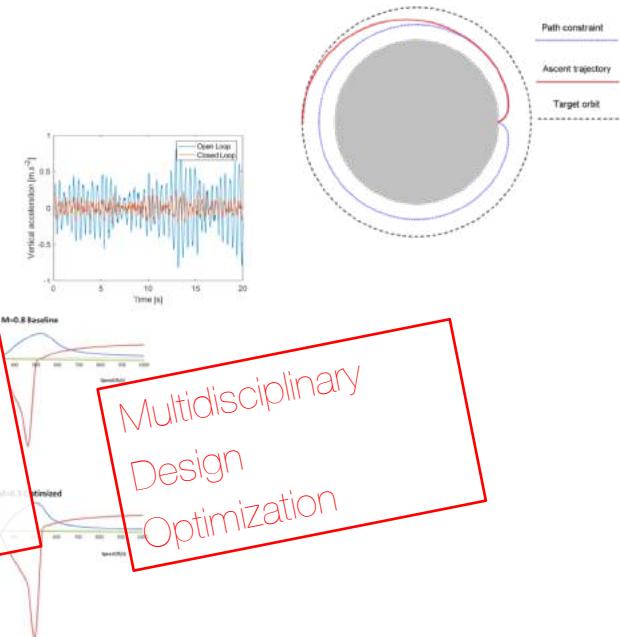


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ENGINEERING
UNIVERSITY OF MICHIGAN
NASA
ISAE SUPAERO
ONERA
THE FRANCHE AVIATION LAB

SMT: Surrogate Modeling Toolbox

The surrogate modeling toolbox (SMT) is an open-source Python package consisting of libraries of surrogate modeling methods (e.g., radial basis functions, kriging), sampling methods, and benchmarking problems. SMT is designed to make it easy for developers to implement new surrogate models in a well-tested and well-documented platform, and for users to have a library of surrogate modeling methods with which to use and compare methods.

The code is available open-source on [GitHub](#).

Cite us

To cite SMT: M. A. Bouhlel and J. T. Hwang and N. Bartoli and R. Lafage and J. Morlier and J. R. R. A. Martins.

A Python surrogate modeling framework with derivatives, *Advances in Engineering Software*, 2019.

```
@article{SMT2019,  
    Author = {Mohamed Amine Bouhlel and John T. Hwang and Nathalie Bartoli and Rémi Lafage},  
    Journal = {Advances in Engineering Software},  
    Title = {A Python surrogate modeling framework with derivatives},  
    pages = {102652},  
    year = {2019},  
    issn = {0965-9978},  
    doi = {https://doi.org/10.1016/j.advengsoft.2019.83.005},  
    Year = {2019}}
```

Focus on derivatives

SMT is meant to be a general library for surrogate modeling (also known as metamodeling, interpolation, and regression), but its distinguishing characteristic is its focus on derivatives, e.g., to be used for gradient-based optimization.