0

SYSTEM MODEL

02

ONLINE SIMULATION

03

FORMAL VERIFICATION

04

VISUALIZATION

05

Horizontal Handling Machine (HHM)



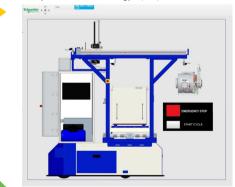
Execution Control Chart (ECC) START INT INT INTO OPEN OPEN STAT CNF CLOSE CMD CLOSE CMF OPEN CMD OPEN CNF CLOSED STAT OPEN

Function Blocks (FBs)



EVENT O INIT INITO O EVENT EVENT CART move BOOL O GOUP Pos O REAL BOOL O GOUP POS O REAL BOOL O GOUNT TIME O O TI-1 REAL O MAXP

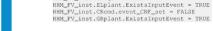
Composite Automation Type (CAT)



FB2SMV Conversion







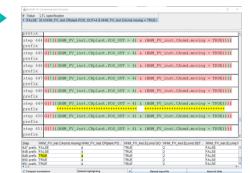
Visualization tool

Counterexample

HHM_FV_inst.ELplant.NDT = TRUE HHM_FV_inst.CRcmd.NA = 0 HHM_FV_inst.CRcmd.NI = 1 HHM_FV_inst.GRplant.NDT = TRUE

HHM FV inst.CRcmd CNF = TRUE

HHM_FV_inst.omega = FALSE



NuSMV verification

SPECIFICATION

DDOCESSING

DECLIET

Output trace

Output to file: spec1.txt
elapse: 18517.71 seconds, total: 18517.83 seconds
-- specification G !(HHM_FV_PART_1_2_3_inst.

ELplant.POS_OUT = 5) is true