

Commutative Algebra and Piecewise Polynomials

Michael DiPasquale

Marquette University
Colloquium

Piecewise Polynomials

Spline

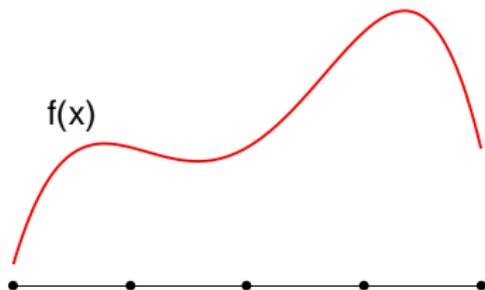
A piecewise polynomial function, continuously differentiable to some order.

Some Context: Splines in Calculus 1

Low degree splines are used in Calc 1 to approximate integrals.

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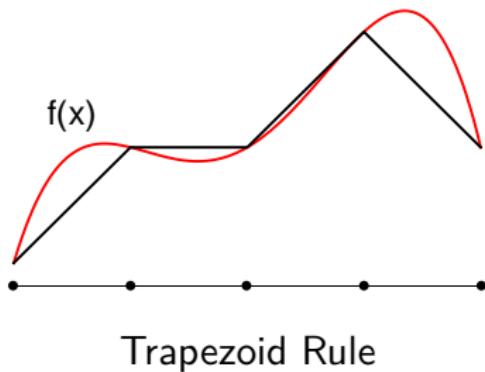
Low degree splines are used in Calc 1 to approximate integrals.



Graph of a function

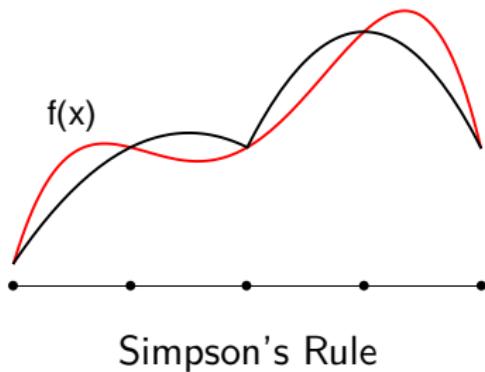
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Origin

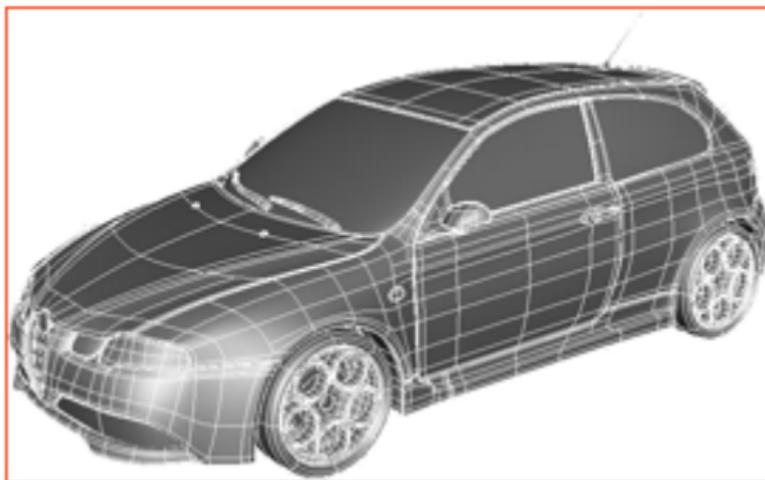
Term **spline** originated in shipbuilding - referred to flexible wooden strips anchored at several points.



Source: <http://technologycultureboats.blogspot.com/2014/12/gustave-caillebotte-and-curves.html>

Current applications

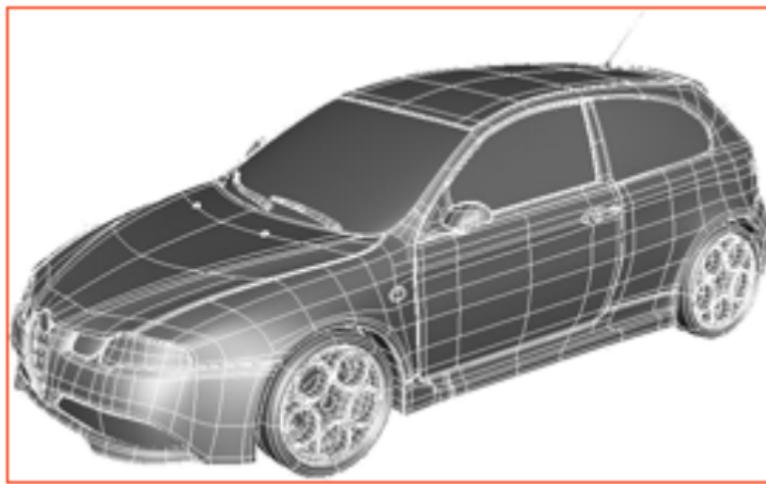
- ▶ Computer-Aided Geometric Design (CAGD): splines used to create models by interpolating datapoints.



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- ▶ Finite Element Method (FEM): best approximation to a solution of a partial differential equation (PDE) is obtained in a spline space
- ▶ FEM especially useful for PDEs in engineering and mathematical physics

Univariate splines

Most widely studied case: approximation of a function $f(x)$ over an interval $\Delta = [a, b] \subset \mathbb{R}$ by C^r piecewise polynomials.

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- ▶ Subdivide $\Delta = [a, b]$ into subintervals:
$$\Delta = [a_0, a_1] \cup [a_1, a_2] \cup \cdots \cup [a_{n-1}, a_n]$$
- ▶ Find a basis for the vector space $C_d^r(\Delta)$ of C^r piecewise polynomial functions on Δ with degree at most d (e.g. B-splines)
- ▶ Find best approximation to $f(x)$ in $C_d^r(\Delta)$

Example: two subintervals

$$\Delta = [a_0, a_1] \cup [a_1, a_2] \text{ (assume WLOG } a_1 = 0)$$

$$\begin{aligned} (f_1, f_2) \in C_d^r(\Delta) &\iff f_1^{(i)}(0) = f_2^{(i)}(0) \text{ for } 0 \leq i \leq r \\ &\iff x^{r+1}|(f_2 - f_1) \\ &\iff (f_2 - f_1) \in \langle x^{r+1} \rangle \end{aligned}$$

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Even more explicitly:

- ▶ $f_1(x) = b_0 + b_1x + \cdots + b_dx^d$
- ▶ $f_2(x) = c_0 + c_1x + \cdots + c_dx^d$
- ▶ $(f_1, f_2) \in C_d^r(\Delta) \iff b_0 = c_0, \dots, b_r = c_r.$

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- ▶ $(f_1, f_2) \in C_d^r(\Delta) \iff b_0 = c_0, \dots, b_r = c_r.$

$$\dim C_d^r(\Delta) = \begin{cases} d+1 & \text{if } d \leq r \\ (d+1) + (d-r) & \text{if } d > r \end{cases}$$

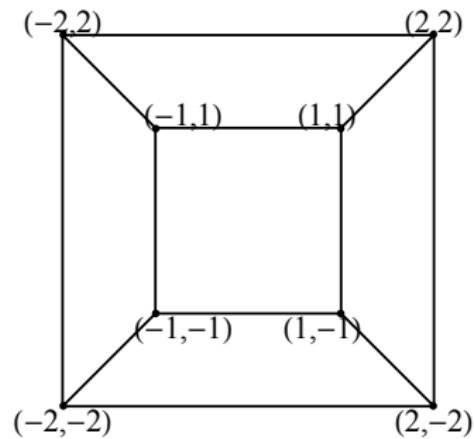
Note: $\dim C_d^r(\Delta)$ is polynomial in d for $d > r$.

Dimension two

Subdivision $I \subset \mathbb{R}^1 \rightarrow$ **polytopal complex** $\Delta \subset \mathbb{R}^2$

Dimension two

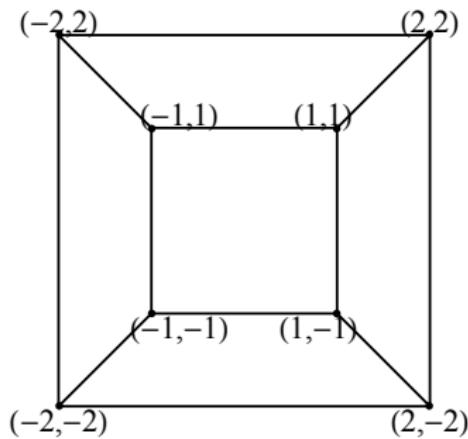
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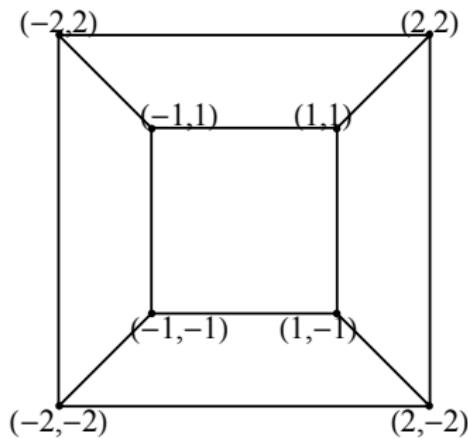


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- ▶ Δ : full dimensional convex polygons (polytopes) ‘glued’ together along faces to yield a domain Ω with no holes

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- ▶ Δ : full dimensional convex polygons (polytopes) ‘glued’ together along faces to yield a domain Ω with no holes
- ▶ $C^r(\Delta)$: piecewise polynomial functions on Δ which are continuously differentiable of order r (C^r splines)
- ▶ $C_d^r(\Delta)$: C^r splines of degree at most d

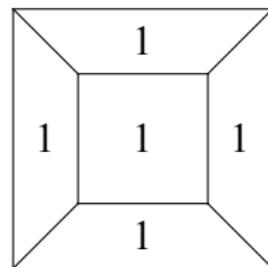
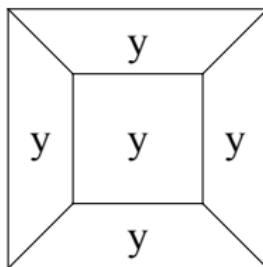
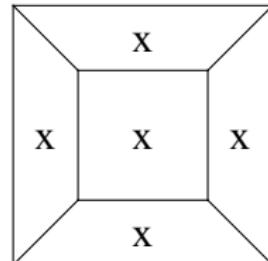
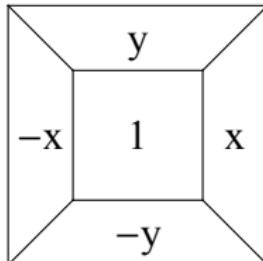
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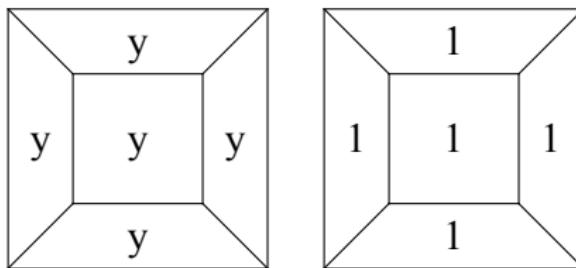
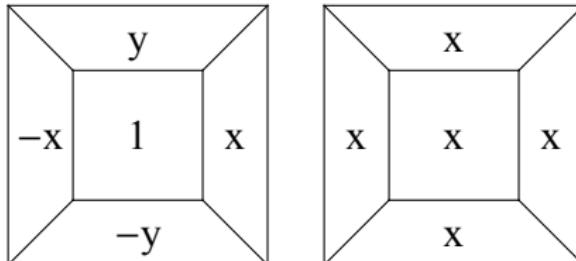


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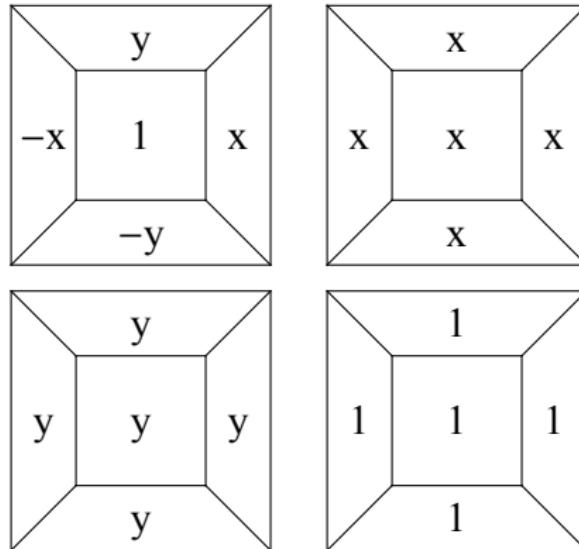


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Two central problems in approximation theory:

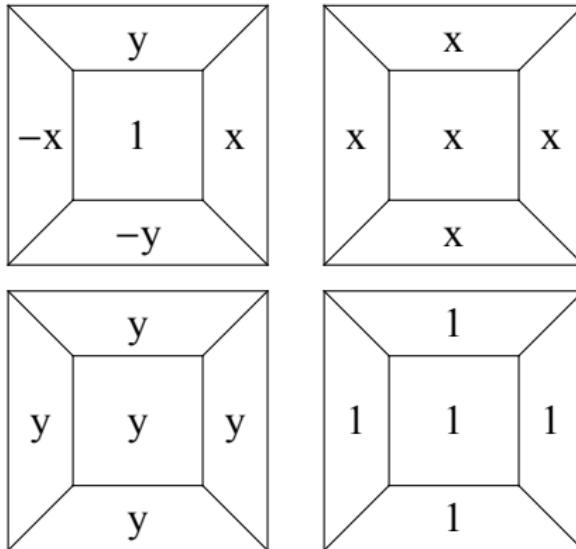
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Posed in 1973 by Strang for C^1 splines on triangulations

Translation to algebra

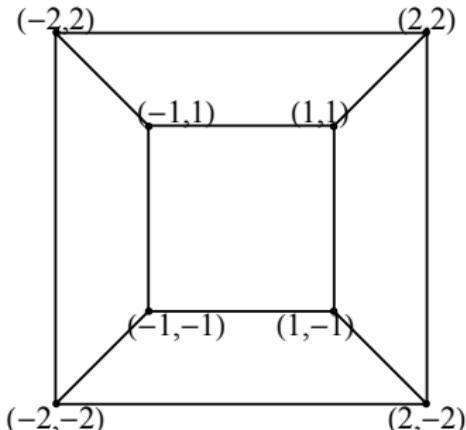
(Algebraic) Spline Criterion:

- ▶ If τ is an edge of Δ , $I_\tau =$ affine form vanishing on affine span of τ
- ▶ Collection $\{F_\sigma\}$ (one for each 2-dimensional polytope σ)
define $F \in C^r(\Delta) \iff$ for every pair of adjacent polytopes $\sigma_1, \sigma_2 \in \Delta_2$ with $\sigma_1 \cap \sigma_2 = \tau$, $I_\tau^{r+1} | (F_{\sigma_1} - F_{\sigma_2})$

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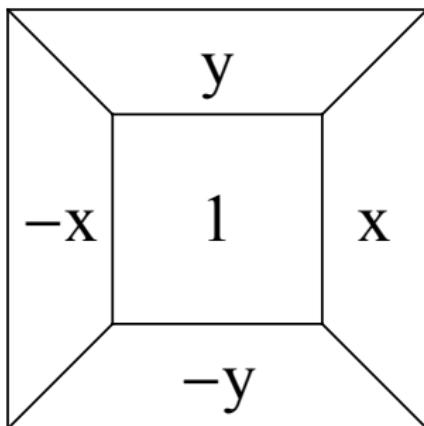


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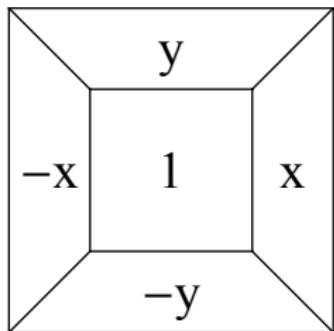
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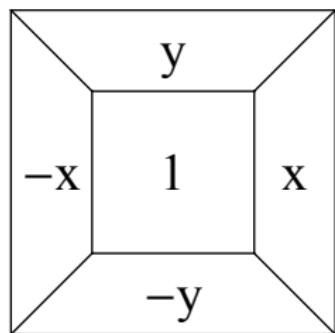
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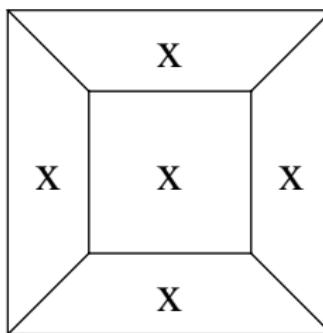
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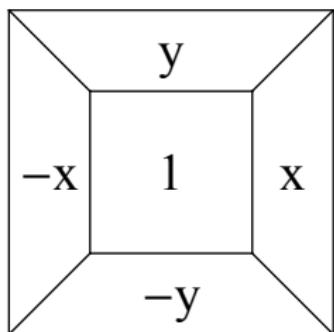
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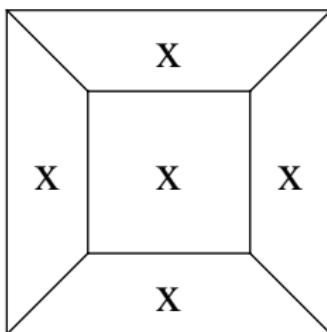
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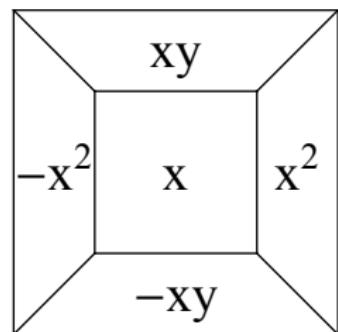
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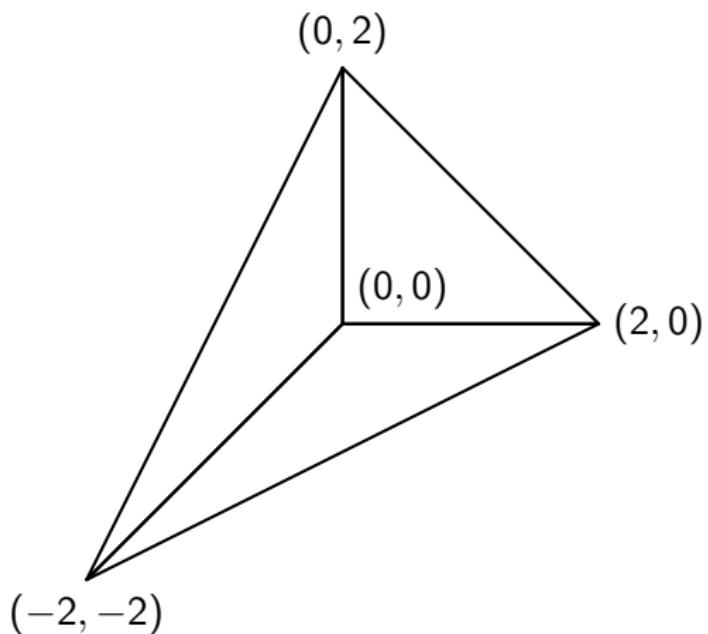


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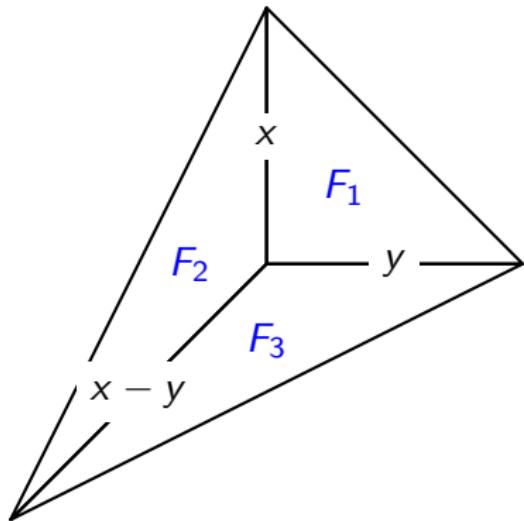


$$xF \in C_2^0(\mathcal{Q})$$

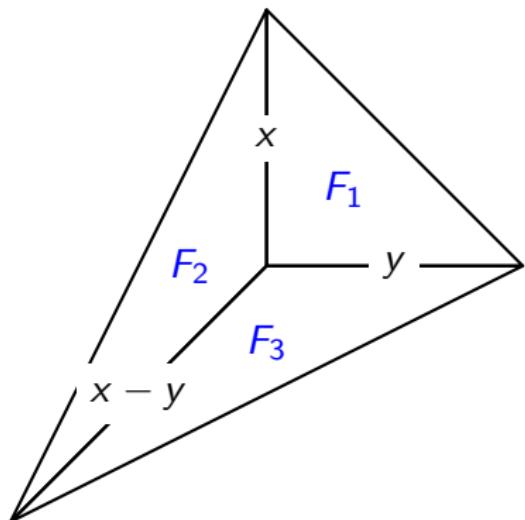
Example: continuous splines on a simplicial complex



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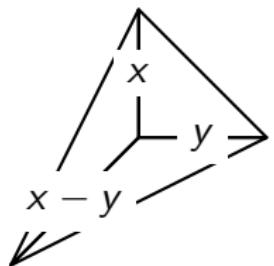


$$\begin{pmatrix} F_1 \\ F_2 \\ F_3 \end{pmatrix} \in C^0(\Delta) \iff \exists f_1, f_2, f_3$$

so that

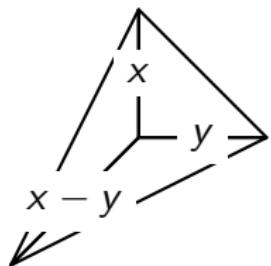
$$\begin{aligned} F_1 - F_2 &= f_1 x \\ F_2 - F_3 &= f_2(x - y) \\ F_3 - F_1 &= f_3 y \end{aligned}$$

Example, continued: freeness

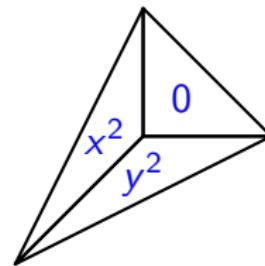
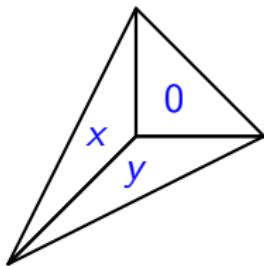
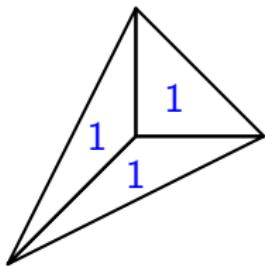


Three splines in $C^0(\Delta)$:

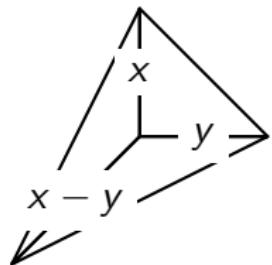
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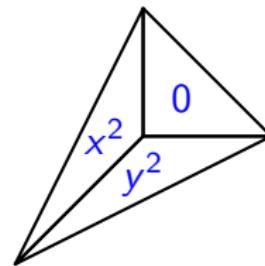
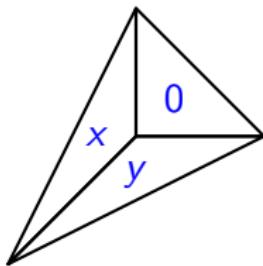
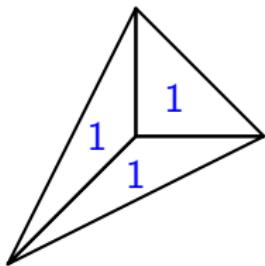
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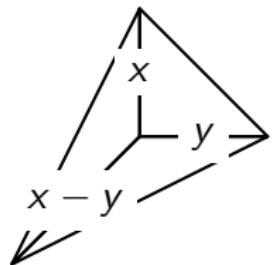


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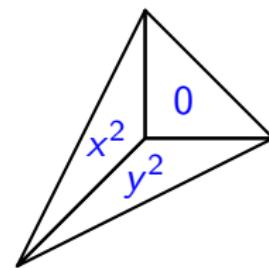
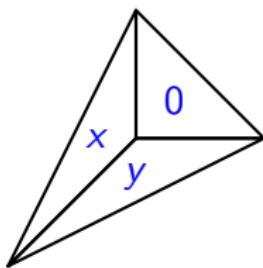
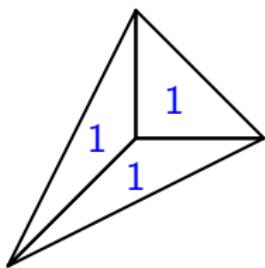


- ▶ In fact, every spline $F \in C^0(\Delta)$ can be written uniquely as a polynomial combination of these three splines.

Example, continued: freeness



Three splines in $C^0(\Delta)$:



- ▶ In fact, every spline $F \in C^0(\Delta)$ can be written uniquely as a polynomial combination of these three splines.
- ▶ We say $C^0(\Delta)$ is a **free** $\mathbb{R}[x, y]$ -module

Example, continued: dimension computation

$$C_d^0(\Delta) \cong \mathbb{R}[x, y]_{\leq d} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \oplus \mathbb{R}[x, y]_{\leq d-1} \begin{pmatrix} 0 \\ x \\ y \end{pmatrix} \oplus \mathbb{R}[x, y]_{\leq d-2} \begin{pmatrix} 0 \\ x^2 \\ y^2 \end{pmatrix}$$

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$$= \frac{3}{2}d^2 + \frac{3}{2}d + 1 \text{ for } d \geq 0$$

Hilbert series and polynomial

$\Delta \subset \mathbb{R}^2$. From commutative algebra

- ▶ $\dim C_d^r(\Delta)$ is called the **Hilbert function** of $C^r(\Delta)$
- ▶ Hilbert function is eventually a polynomial of degree 2 in d , called the **Hilbert polynomial** of $C^r(\Delta)$ and denoted $HP(C^r(\Delta), d)$

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$$HS(C^r(\Delta), t) = \sum_{d=0}^{\infty} \dim C_d^r(\Delta) t^d$$
; it has the form

$$HS(C^r(\Delta), t) = \frac{h(t)}{(1-t)^3}, \text{ where } h(t) \in \mathbb{Z}[t].$$

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Main questions:

- ▶ Determine $HS(C^r(\Delta), t)$. (too hard!)

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$\Delta \subset \mathbb{R}^2$. From commutative algebra

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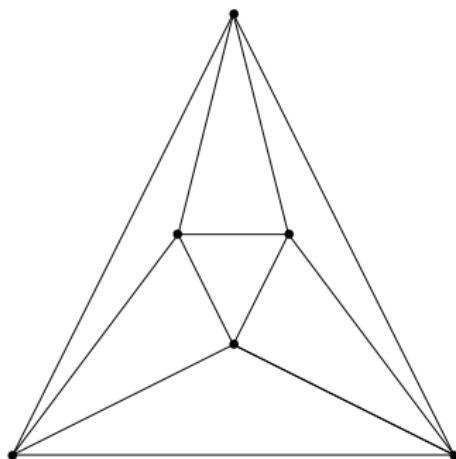
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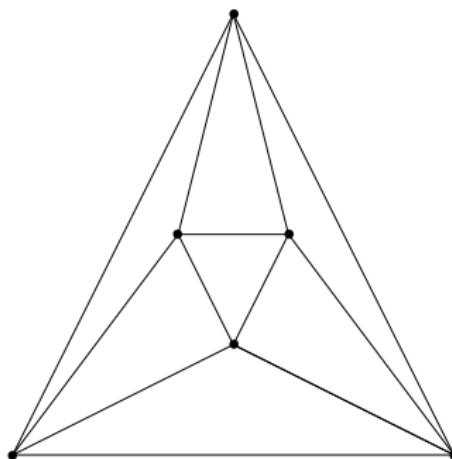
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Low Degree: Morgan-Scot triangulation

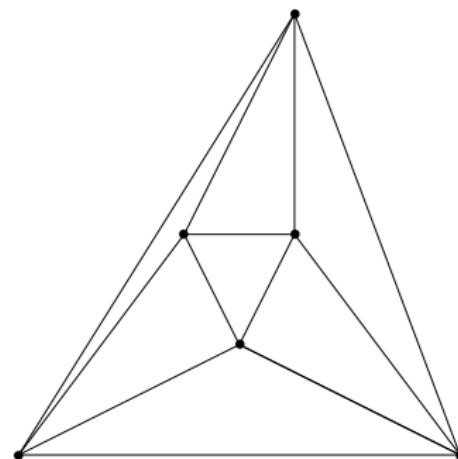


$$\dim C_2^1(\mathcal{T}) = 7$$

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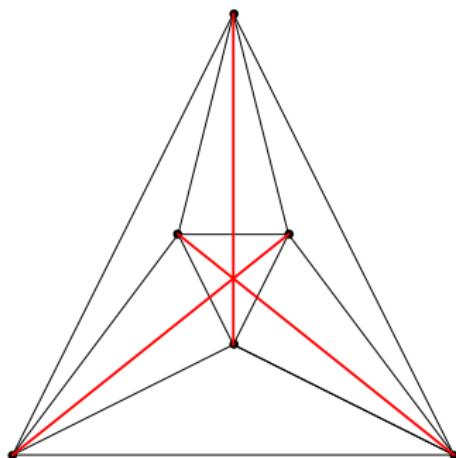


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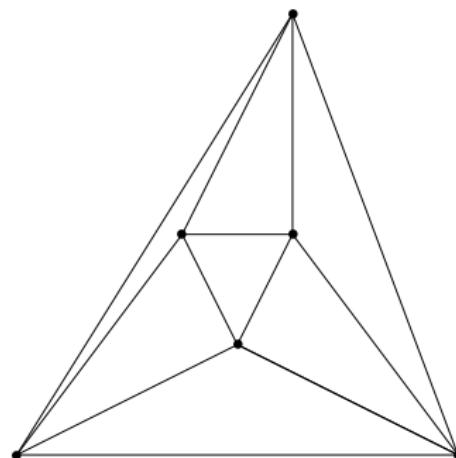


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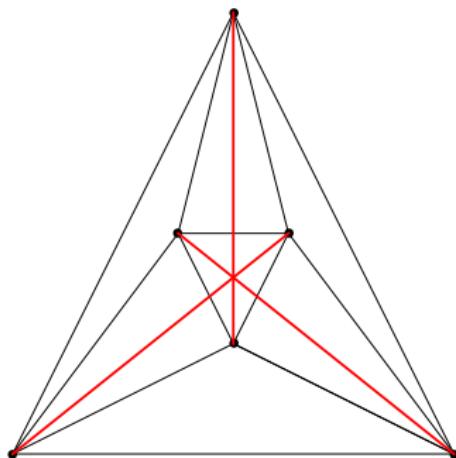


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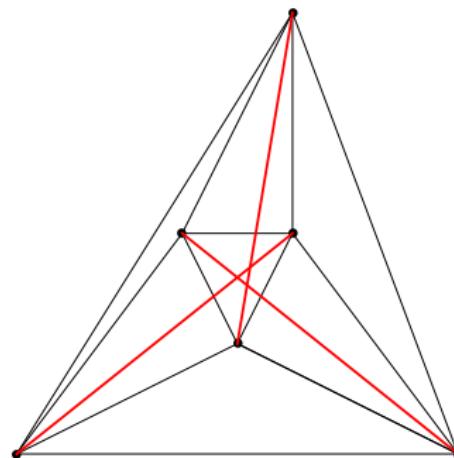


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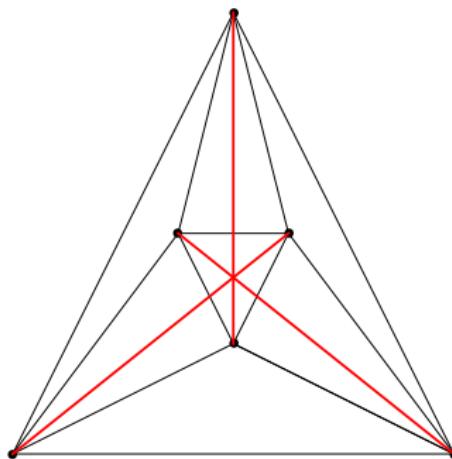


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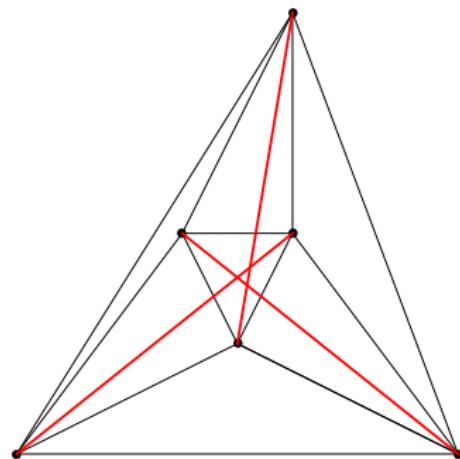


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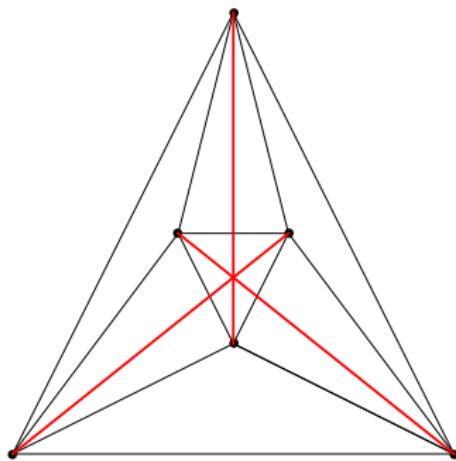
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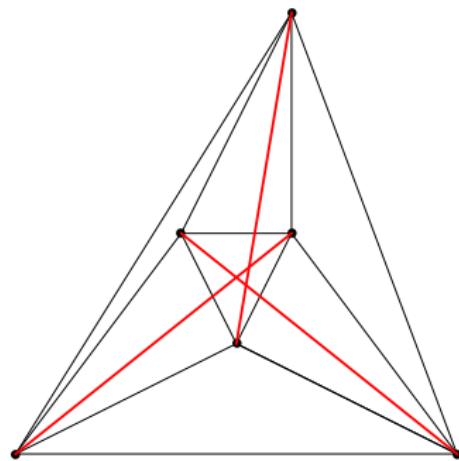
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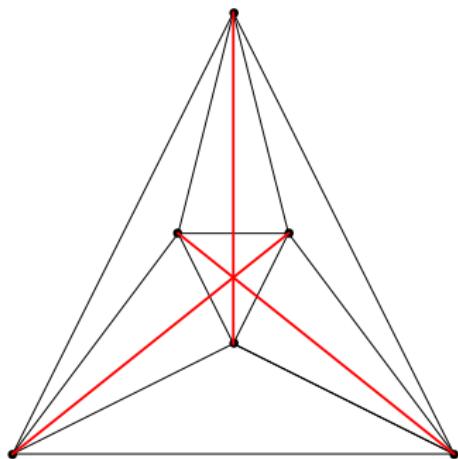
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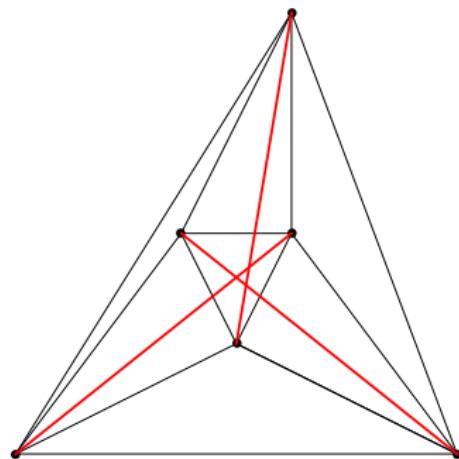
Conjecture (at least 30 years old)

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Only $\dim C_2^1(\Delta)$ can differ from expected dimension formula

Piecewise linear functions

If $\Delta \subset \mathbb{R}^2$ is a triangulation with v vertices, then $\dim C_1^0(\Delta) = v$.

Piecewise linear functions

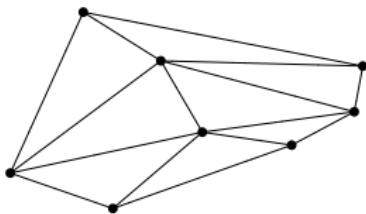
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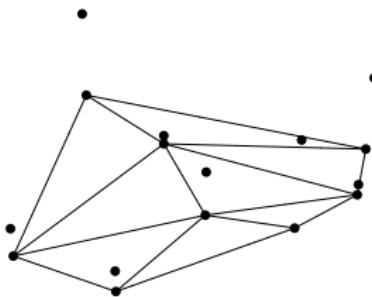
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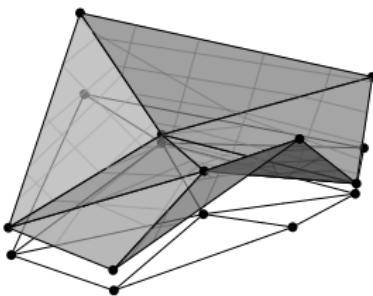
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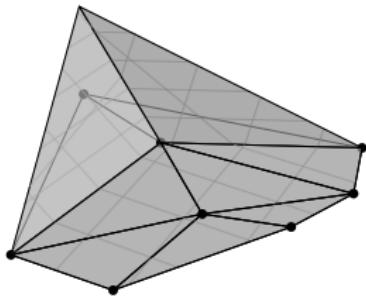


Tent functions

A basis for $C_1^0(\Delta)$ is given by Courant functions, which take a value of 1 at a chosen vertex and 0 at all other vertices.

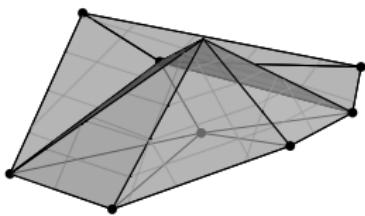
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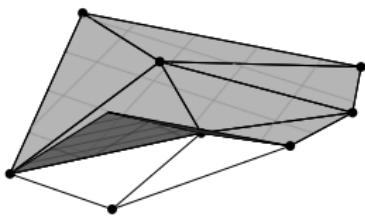
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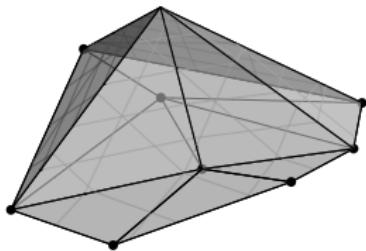
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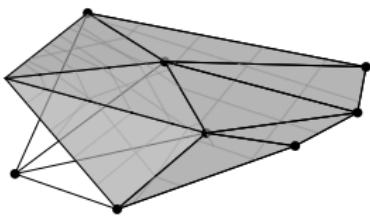
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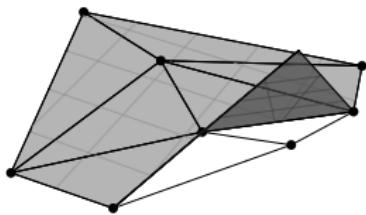
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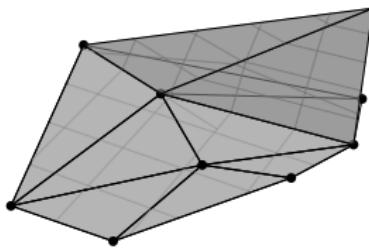
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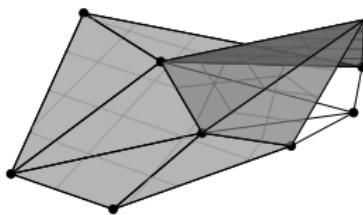
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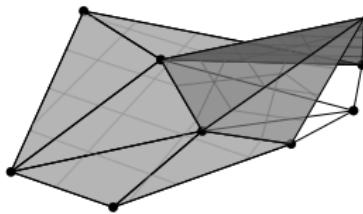
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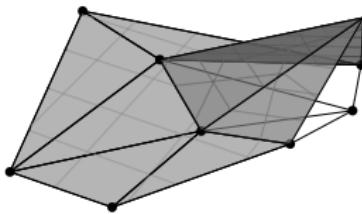
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- ▶ No dependence on geometry!

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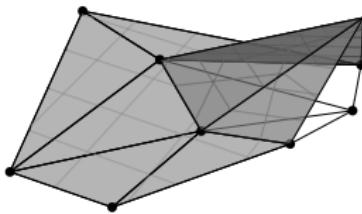
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- ▶ No dependence on geometry!
- ▶ [Billera '89]: If $\Delta \subset \mathbb{R}^2$ is a triangulation of a domain Ω without holes then
 - ▶ $C^0(\Delta)$ is a free module over $\mathbb{R}[x, y]$
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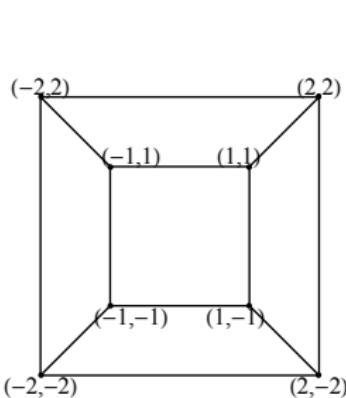
Generalizes to arbitrary dimensions.

PL functions depend on geometry

If $\Delta \subset \mathbb{R}^2$ is a polytopal complex, $\dim C_1^0(\Delta)$ depends on geometry of Δ .

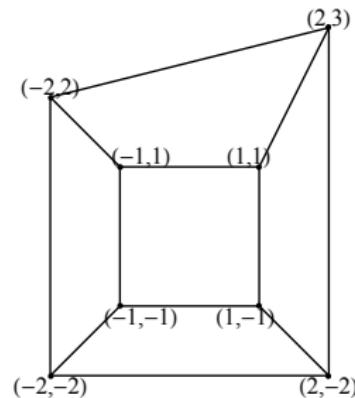
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Q_1

$$\dim C_1^0(Q_1) = 4$$

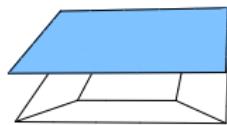


Q_2

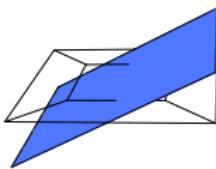
$$\dim C_1^0(Q_2) = 3$$

Trivial PL Functions

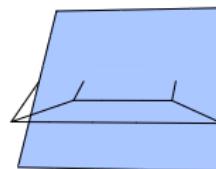
- ▶ A **trivial** PL function on $\Delta \subset \mathbb{R}^2$ has the same linear function on each face.
- ▶ $\dim(\text{trivial splines on } \Delta) = 3$ **always**, with basis $1, x, y$.



1



x



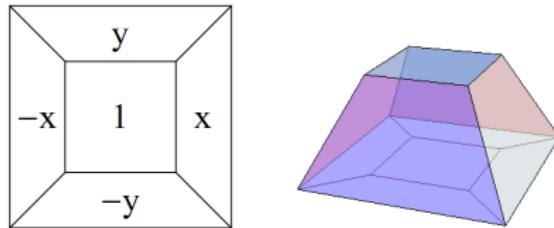
y

NonTrivial PL Functions

- ▶ **Nontrivial** PL function on has at least two different linear functions on different faces.

NonTrivial PL Functions

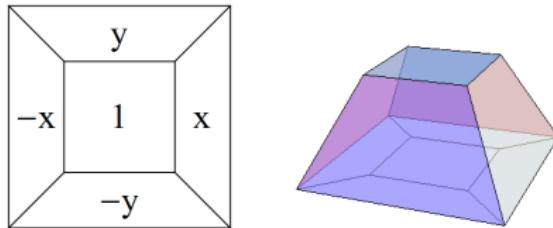
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When you move to Q_2 you lose this function!

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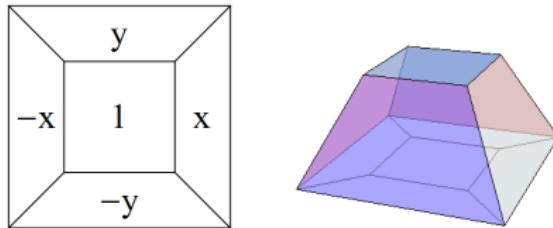


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- ▶ In general, computing $C_1^0(\Delta)$ entails determining when edges of Δ come from projecting a polyhedral surface
- ▶ Relates to *rigidity theory*, dates back to Maxwell in 1860s

Impact of PL functions on freeness

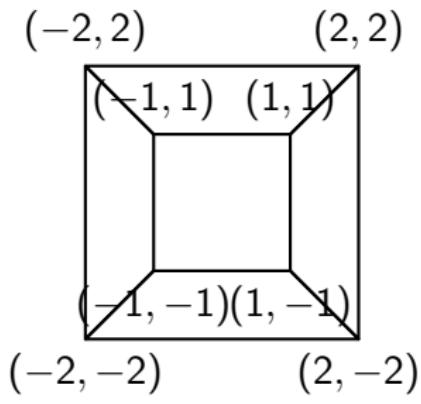
Nonfreeness for Polytopal Complexes [D. '12]

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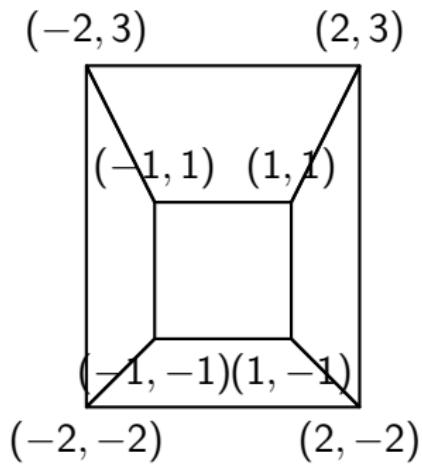


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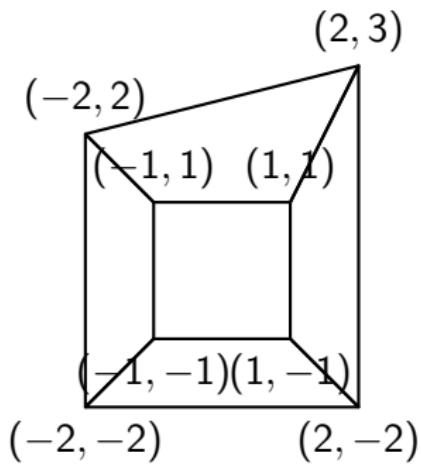


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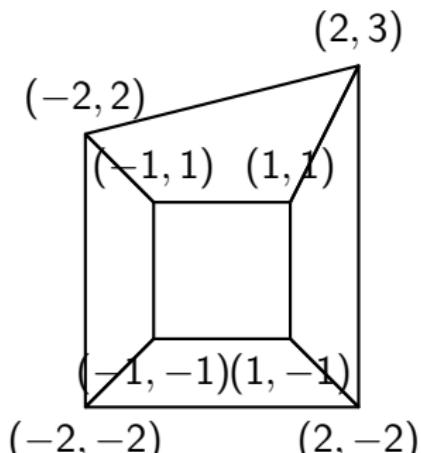


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$C^0(\Delta)$ is free

Persistence of 'extra' PL function determines freeness.

Planar simplicial splines of large degree

Planar simplicial dimension [Alfeld-Schumaker '90]

If $\Delta \subset \mathbb{R}^2$ is a simply connected triangulation and $d \geq 3r + 1$,

$$\dim C_d^r(\Delta) = f_2 \binom{d+2}{2} - f_1^0 \left(\binom{d+2}{2} - \binom{d-r+1}{2} \right) + \sigma,$$

- ▶ $f_i(f_i^0)$ is the number of i -faces (interior i -faces).
- ▶ σ = constant obtained as a sum of contributions from each interior vertex.

Planar non-simplicial splines of large degree

Planar non-simplicial dimension [McDonald-Schenck '09]

If $\Delta \subset \mathbb{R}^2$ is a simply connected polytopal complex and $d \gg 0$,

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- ▶ $f_i(f_i^0)$ is the number of i -faces (interior i -faces).
- ▶ σ = sum of constant contributions from interior vertices
- ▶ σ' = sum of constant contributions from ‘missing’ vertices

Agreement for non-simplicial splines

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Theorem: Using McDonald-Schenck Formula [D. '18]

$\Delta \subset \mathbb{R}^2$ a planar polytopal complex. Let F = maximum number of edges appearing in a polytope of Δ . Then

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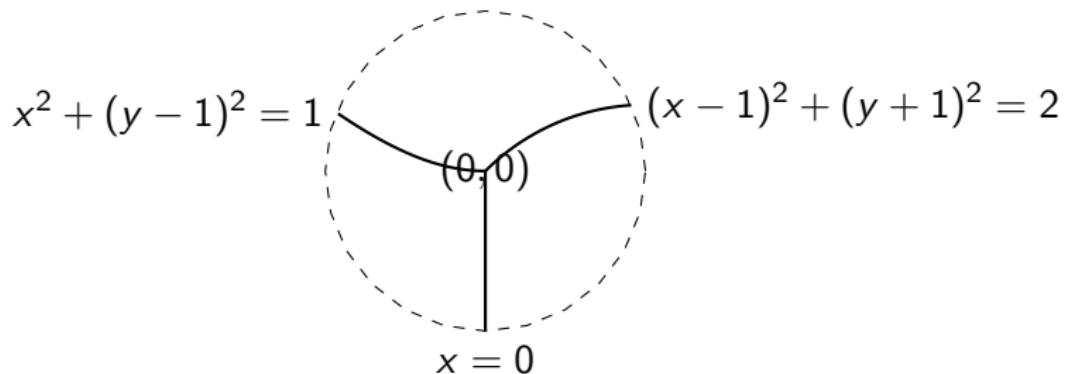
- ▶ Worst case examples indicate bound in theorem is off by a factor of about two (F is necessary!)
- ▶ Best known bounds in simplicial case are also off by a factor of 1.5
- ▶ Proof of theorem uses notion of regularity from algebraic geometry

Curved Partitions

More general problem: Compute $\dim C_d^r(\Delta)$ where Δ is a planar partition whose arcs consist of irreducible algebraic curves.

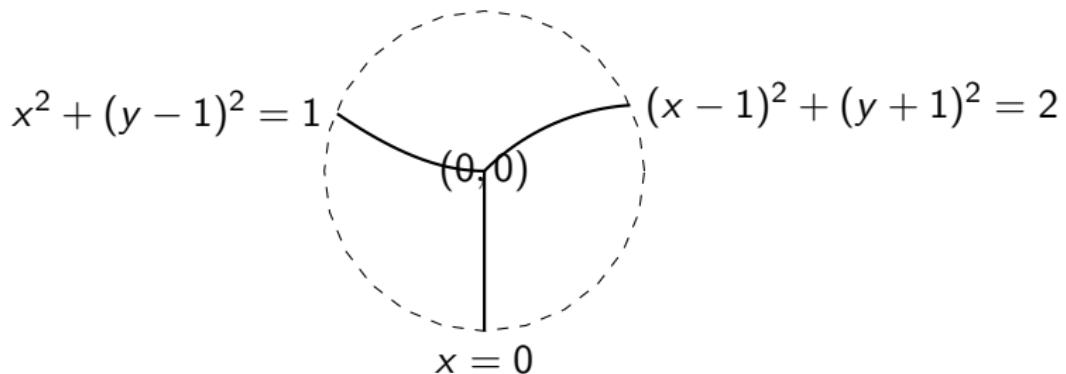
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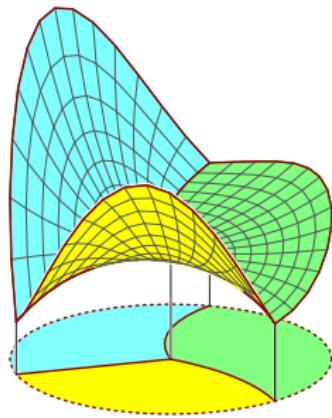
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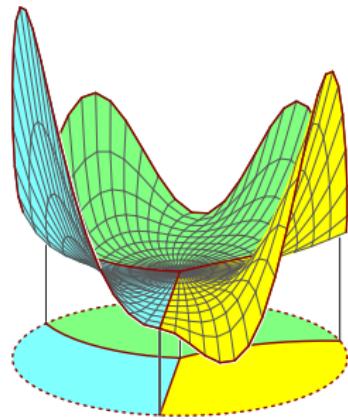
Call functions in $C^r(\Delta)$ *semi-algebraic splines* since they are defined over regions given by polynomial inequalities, or semi-algebraic sets.

Graphs of some semi-algebraic splines



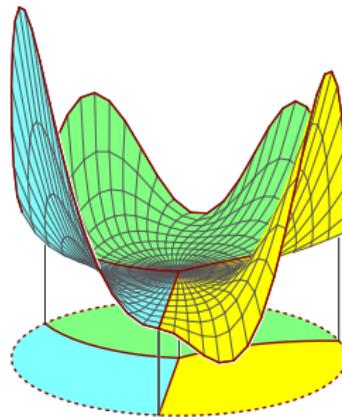
Graph of a spline in $C_3^0(\Delta)$

Graphs of some semi-algebraic splines



Graph of a spline in $C_6^1(\Delta)$

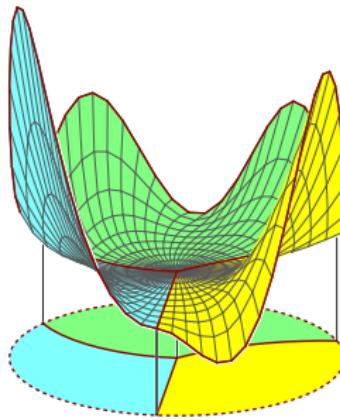
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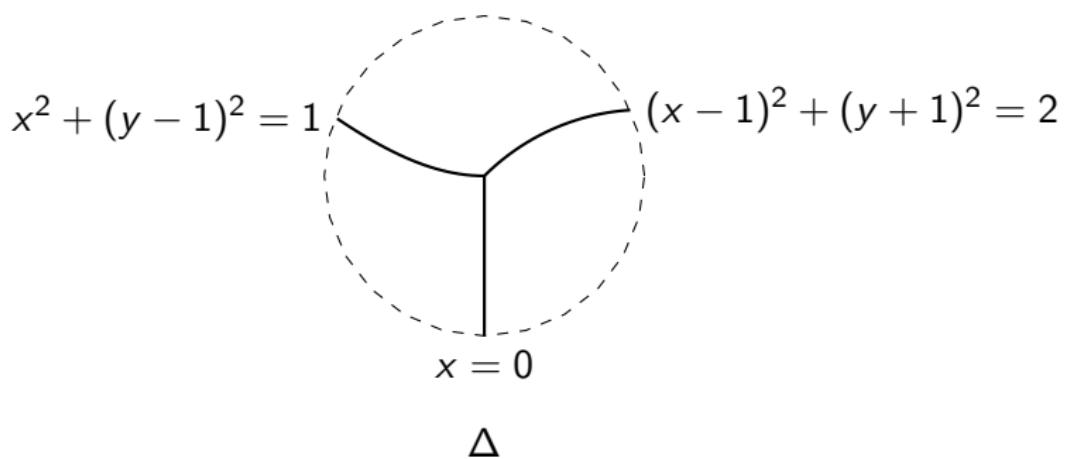
- ▶ First definitions in this context made in [Wang '75] - algebraic criterion for splines carries over verbatim
- ▶ Recent work suggests semi-algebraic splines may be increasingly useful in finite element method
[Davydov-Kostin-Saeed '16]

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- ▶ Focus on $\Delta \subset \mathbb{R}^2$ with single interior vertex at $(0, 0)$.
- ▶ Let Δ_L be the subdivision formed by replacing curves by tangent rays at origin

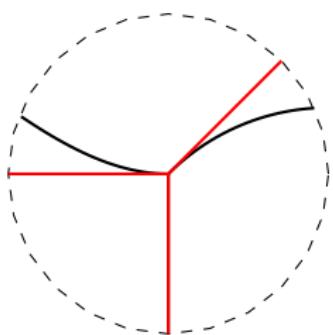
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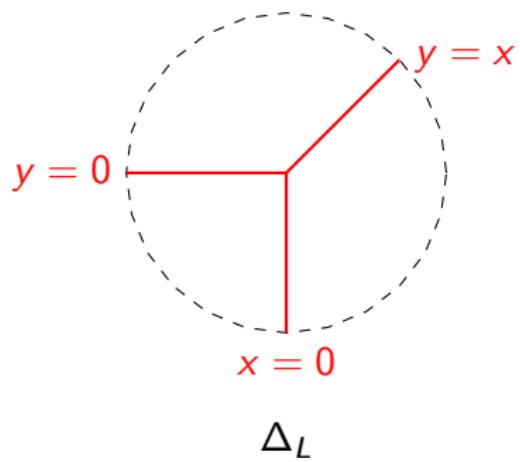
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Tangent rays

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Linearizing the local case

Theorem: Linearizing $\dim C_d^r(\Delta)$ [D.-Sottile-Sun '17]

Let Δ consist of n irreducible curves of degree d_1, \dots, d_n meeting at $(0, 0)$ with distinct tangents and no common zero in $\mathbb{P}^2(\mathbb{C})$ other than $(0, 0)$. Then, for $d \gg 0$,

$$\begin{aligned}\dim C_d^r(\Delta) &= \dim C_d^r(\Delta_L) \\ &\quad + \sum_{i=1}^n \left(\binom{d+2-d_i(r+1)}{2} - \binom{d-r-1}{2} \right)\end{aligned}$$

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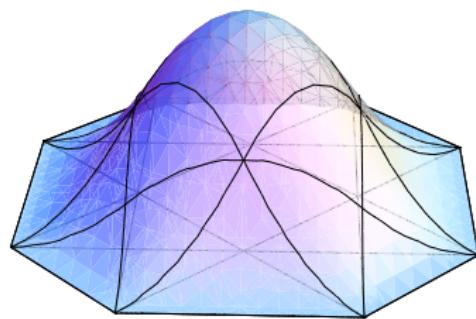
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- ▶ Bounds on d for when equality holds are also considered, using regularity

THANK YOU!



References I

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Open Questions

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- ▶ If $\Delta \subset \mathbb{R}^3$, $\dim C_d^r(\Delta)$ is not known for $d \gg 0$ except for $r = 1$, $d \geq 8$ on generic triangulations
[Alfeld-Schumaker-Whitely '93]. (connects to unsolved problems in algebraic geometry)

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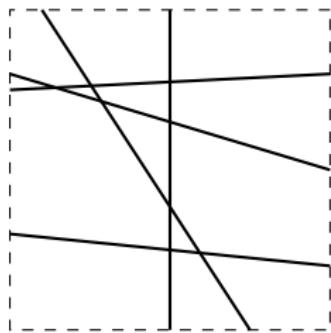
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- ▶ Compute $\dim C_d^r(\Delta)$ for semi-algebraic splines on more general planar partitions for $d \gg 0$

Cross-Cut Partitions

A partition of a domain D is called a *cross-cut partition* if the union of its two-cells are the complement of a line arrangement.

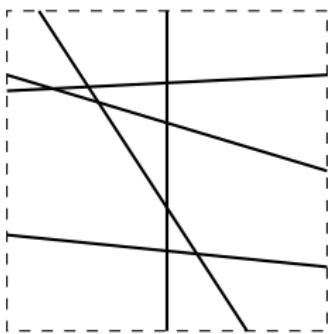
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- ▶ Basis for $C_d^r(\Delta)$ and $\dim C_d^r(\Delta)$ [Chui-Wang '83]
- ▶ $C^r(\Delta)$ is free for any r [Schenck '97]

Ziegler's Pair

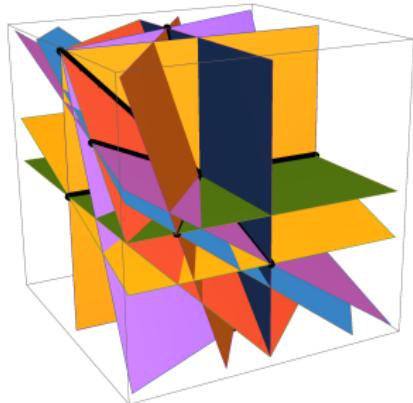
$\mathcal{A}_t = \text{union of planes defined by vanishing of the nine linear forms:}$

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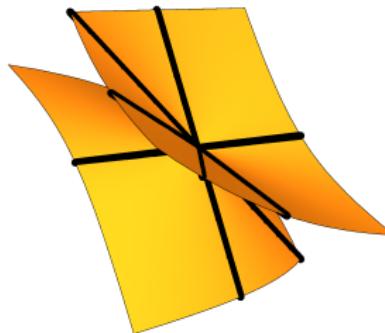
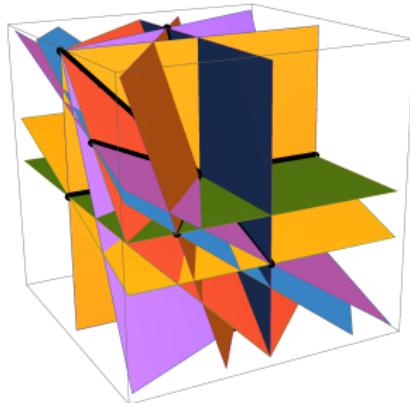


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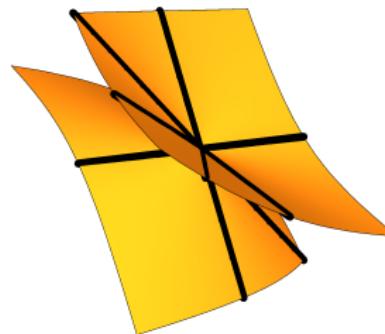
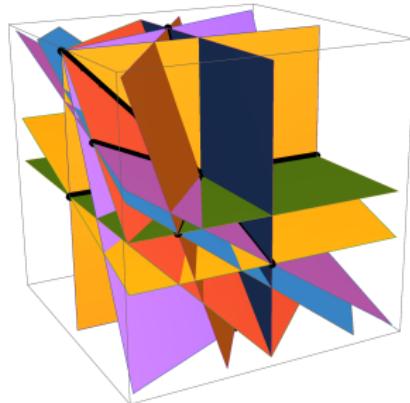


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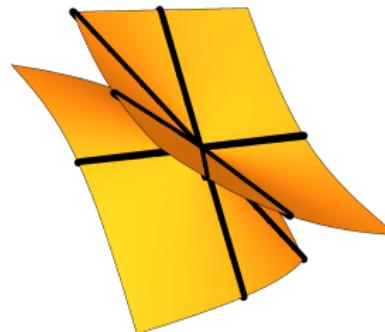
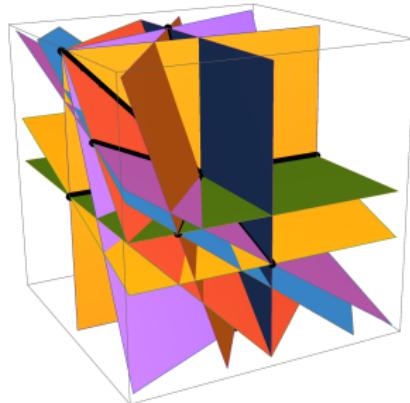
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- ▶ $C^0(\Delta_t)$ is free if and only if $t \neq 0$!