

Exercise:

Solving the Lippmann - Schwinger eqn

The R-matrix carries information about a particle scattered off the given potential V . For the s -wave scattering (angular momentum = 0) of a spin-0 particle, $R(q', q)$ is the R-matrix value for incoming momentum q and outgoing momentum q' .

B/c $R(q', q)$ is a two-variable function, it is called R "matrix". $R(q', q)$ satisfies the Lippmann-Schwinger equation, which can be derived from the Schrödinger equation (we don't need to know how)

$$R(q', q) = V(q', q) + \mathcal{P} \int_0^{\infty} dk \, k^2 \frac{M}{q^2 - k^2} V(q', k) R(k, q)$$

$V(q', q)$: potential V in momentum space

$$q', q, k \in [0, \infty)$$

M : mass of the particle (often can be taken as " q ")

$\mathcal{P} \int$ denotes principle-value integral, in order to define the integration near $k=q$.

$V(q', q)$ becomes exponentially small when q' or $q \rightarrow \infty$, so the integral can be assumed to converge even though the upper limit is ∞ .

Our goal is to solve for $R(q', q)$ for arbitrary q' and q , with $V(q', q)$ as the known input.

The key is to realize that ^① upon discretization,

$$q', q, k \rightarrow \{q'_i\} = \{q_i\} = \{k_i\}$$

$$0 < q_1 < q_2 < \dots < q_i < \dots < q_N < \infty$$

$\{q'_i\}$, $\{q_i\}$ and $\{k_i\}$ are the same set of positive real numbers

② discretization turns R and V into matrices

$$R(g', g) \rightarrow R_{ij} \quad 1 \leq i, j \leq N$$

$$V(g', g) \rightarrow V_{ij}$$

The integral equation becomes a matrix equation of the form,

$$R = V + V \otimes R$$

for a fixed j , the matrix equation can be thought of as a linear system of equations

$$R_{ij} = V_{ij} + \sum_{k=1}^N \underbrace{V_{ik}}_{\text{wavy line}} \underbrace{G(j, k)}_{\text{arrow}} R_{kj}$$

Diagram illustrating the matrix equation components:

- $\underline{R} = \begin{pmatrix} R_{1j} \\ R_{2j} \\ \vdots \\ R_{Nj} \end{pmatrix}$ (Vector of R_{ij} for fixed j)
- $\underline{B} = \begin{pmatrix} V_{1j} \\ V_{2j} \\ \vdots \\ V_{Nj} \end{pmatrix}$ (Vector of V_{ij} for fixed j)
- $\underline{A} = (a_{ik})$ (Matrix of $G(j, k)$ for fixed j)

$$\Rightarrow \underline{R} = \underline{B} + \underline{A} \cdot \underline{R}$$

And \underline{R} can be solved for by calling LAPACK routines.

★ More technical detail can be found in Machleidt Section 1.4.2, especially the following point.

$$\textcircled{P} \int_0^{\infty} dk \frac{k^2}{q^2 - k^2} f(k)$$

The integrand has a pole at $k = q$ ($q > 0$). "principle value"

$$\Rightarrow \int_0^{q-\varepsilon} dk \frac{k^2}{q^2 - k^2} f(k) + \int_{q+\varepsilon}^{\infty} dk \dots$$

It is important that the integrands in the neighborhood to the left and to the right of $k = q$ cancel each other out.

$$k = q - \varepsilon \quad (\varepsilon > 0)$$

$$\frac{k^2}{q^2 - k^2} f(k) \rightarrow \frac{q^2}{2q \cdot \varepsilon} f(q)$$

$$k = q + \varepsilon$$

$$\frac{k^2}{q^2 - k^2} f(k) \rightarrow \frac{q^2}{2q(-\varepsilon)} f(q)$$

How to ensure this cancellation numerically to a satisfactory precision? Read the beginning of Section 1.4.2