

EVAL-ADuCM350EBZ User Guide

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Evaluating the ADuCM350 16-Bit, Precision, Low Power Meter-on-a-Chip

FEATURES

ADuCM350 motherboard

Selection of daughter boards for analog front end and platform validation

3 power supply options: 2.5 V to 3.6 V from an external power supply, 5 V from interface/emulator board, or CR2032 battery connection

Interface options

UART and serial wire through 8-pin J-Link OB connector Trace capability

Power indicator/general-purpose LEDs

Reset, download, and external interrupt push-buttons

Supercapacitor and thermistor capability

USB connectivity

8-pin connector to the interface/emulator board

Access to ADuCM350 platform pins through Digital Header 1,

Digital Header2, and CapTouch header

32.768 kHz external crystal and 16 MHz external crystal

EVALUATION KIT CONTENTS

EVAL-ADuCM350EBZ board

USB-SWD/UART-EMUZ, also known as J-Link OB emulator
AFE daughter boards: ADuCM350 switch mux configuration
board, ADuCM350 4-wire bio Configuration 2 board
ADuCM350 breakout board

ADuCM350 GPIO test header board

USB cable

ADDITIONAL EQUIPMENT AND SOFTWARE NEEDED

Evaluation software for the ADuCM350 (download from the ADuCM350 design resources page)

Extra peripheral boards available for order: Ev-ADuCM350AUDZ, Ev-ADuCM350DISZ

See the ADuCM350 design resources page for more details

SYSTEM REQUIREMENTS

Minimum requirement to run examples and applications PC with USB 2.0 controller connection and 1 free COM port Windows XP SP3 or later, Windows Vista, or Windows 7 or later

ONLINE RESOURCES

Documents Needed

ADuCM350 data sheet

ADuCM350 hardware reference manual

AN-1262, AN-1263, AN-1271, AN-1281, AN-1286,

AN-1293, AN-1302 application notes

ADuCM350 software development kit quick start guide (UG-677)

Required Software

ADuCM350 software development kit (firmware/debug environment)

IAR Embedded Workbench for ARM (from Version 7.10+)

ADuCM350 evaluation kit software platform (GUI software)

Design and Integration Files

Schematics, layout files, bill of materials

TYPICAL SETUP

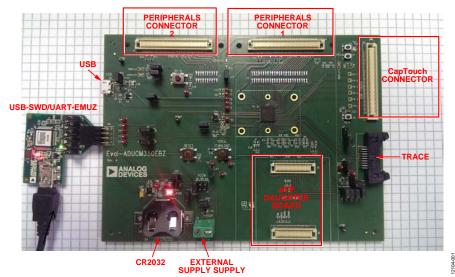


Figure 1. Typical Setup (USB-SWD/UART-EMUZ on Left and EVAL-ADuCM350EBZ on Right)

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REVISION HISTORY

5/14—Revision 0: Initial Version

GENERAL DESCRIPTION

The ADuCM350 is a 16 MHz ARM® Cortex-M3 processor with a high precision AFE specifically designed for high precision data acquisition.

The ADuCM350 has a 16-bit precision analog core with four dedicated voltage measurement channels and up to eight current measurement channels. It has an integrated complex impedance measurement system and uses an integrated parameterizable waveform generator to generate complex waveforms. It uses an excitation amplifier control loop to perform accurate potentiostat type measurements and has a highly configurable switch matrix that allows application specific amplifier configuration.

The device has a large array of peripherals, including USB, CapTouch*, display, audio, and an array of serial interfaces and GPIOs.

The ADuCM350 includes 384 kB of flash, 32 kB of SRAM, and 16 kB of flash configured as EEPROM.

The EVAL-ADuCM350EBZ kit provides scientists, system analyzers, and software developers a platform to migrate from sensor investigation and analysis to full ecosystem development. The evaluation kit consists of an ADuCM350 motherboard and a selection of analog front end and digital peripheral daughter boards.

The evaluation kit is designed specifically to work with the ADuCM350 software development kit (SDK) and the evaluation kit support package (EKSP)—both of which are available for download on the ADuCM350 design resources page.

The software development kit is designed to work with the IAR debugging environment only. The user guide for the ADuCM350 SDK is available on the SDK installer.

An example of where the kit is downloaded follows: C:\Analog Devices\ADuCM350BBCZ\Eval-ADUCM350EBZ\doc

The SDK quick start guide and the EKSP user guide are available in the **Support Documentation** zipped folder.

GETTING STARTED

SOFTWARE INSTALLATION PROCEDURES

For software installation procedures, refer to the following ADuCM350 software documentation for further details:

- For more information about the EKSP LabVIEW® GUI, refer to the EKSP user guide (ADuCM350_Evaluation_Kit_Software_Platform.pdf) within the Documentation folder of the software development kit.
- For more information about the SDK firmware/debug environment, refer to SDK user guide (ADuCM350BBCZ_ Software_Users_Guide.pdf) within the Documentation folder of the software development kit and to the ADuCM350 software development kit quick start guide, UG-677.

EVALUATION BOARD SETUP PROCEDURES

- 1. Plug the ADuCM350 switch mux configuration board into the ADuCM350 evaluation board, EVAL-ADuCM350EBZ.
- 2. Plug the USB-SWD/UART-EMUZ board into J14 on the ADuCM350 evaluation board, EVAL-ADuCM350EBZ.
- 3. Plug the USB cable into the USB-SWD/UART-EMUZ board. After the drivers are downloaded, you can begin communicating with the board.



Figure 2. EVAL-ADuCM350EBZ Setup

EVALUATION BOARD HARDWARE

POWER SUPPLIES

VCCM ANA

Table 1 describes the three options for supplying power to the VCCM_ANA pin.

Table 1. VCCM_ANA Supply Options

Link J10 Position		VCCM_ANA Supply	
A (Default Posi	tion)	Regulated 3.3 V from J3 wall socket supplied with board	
В		CR2032 battery connection, J19	
C		External supply	

VDD_IO

Table 2 describes the two options for supplying power to the VDD_IO pin.

Table 2. VDD_IO Supply Options

Link M5 Position	VDD_IO Supply
A (Default Position)	From VCCM_ANA
В	Regulated 3.3 V from J3 wall socket (supplied with board)

VLCDVDD

Table 3 describes the three options for supplying power to the VLCDVDD pin.

Table 3. VLCDVDD Supply Options

LK14 Position ¹	VLCDVDD Supply	
Inserted	Powered by VCCM	
Open	Not powered	

¹ The default position for LK14 is to be removed.

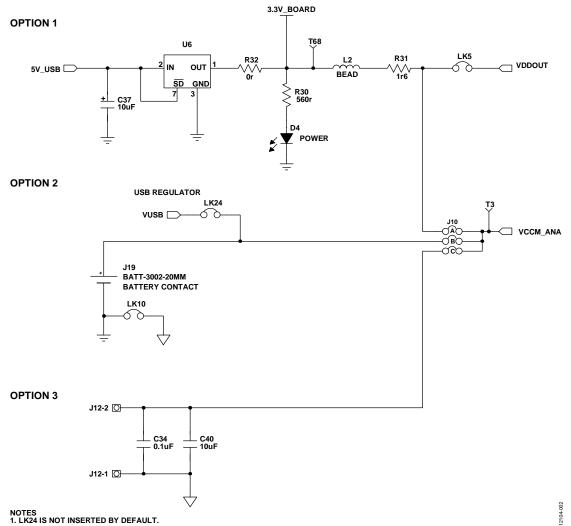


Figure 3. Power Supply Schematic for VCCM_ANA Pin Rev. 0 | Page 5 of 28

JUMPER SETTINGS

Table 4. Link Option Functions

Link Number	Default Position	Function	
LK1	Short	AN_A to AFE daughter board.	
LK2	Open	LED GPIO functionality of P2.1.	
LK3	Open	AN_B to AFE daughter board.	
LK4	Short	Connect the supercapacitor to the VBACK pin.	
LK6	Open	Thermistor voltage output measurement (AN_A).	
LK7	Open	VCCM_DIG to VCCM_ANA external connection (connected internally on chip).	
LK8	Short	LED GPIO functionality of P0.11.	
LK9	Open	AN_C to AFE daughter board.	
LK10	Short	AGND To DGND connector.	
LK11	Open	AN_D to AFE daughter board.	
LK12	Short	LED GPIO functionality of P4.2.	
LK13	Short	VBUS link.	
LK14	Open	Supply for VLCDVDD.	
LK24	Open	VUSB to VCCM_ANA connector. The battery must be removed when this link is inserted.	
M1	В	P0.6 selected for UART Tx.	
M2	В	P0.7 selected For UART Rx.	
M3	Open	AN_EXCITE used for thermistor operation.	
M5	A	VDD_IO connection. When this link is in Position A, the VDD_IO supply is from VCCM_ANA.	

EVALUATION BOARD CIRCUITRY

J-LINK OB EMULATOR

The J-Link OB emulator provides nonintrusive emulation via a serial wire and allows supply and UART communication with the ADuCM350 evaluation board (EVAL-ADuCM350EBZ). Figure 4 shows a top view of the emulator board. The J2 connector plugs into the ADuCM350 evaluation board (EVAL-ADuCM350EBZ). The J2 connector pinout is shown in Figure 5.

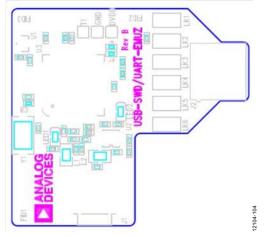


Figure 4. Emulator Top View

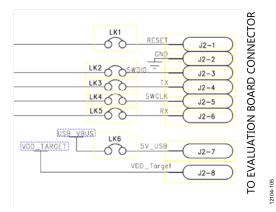


Figure 5. J2 Connector

For downloading and debugging, LK1, LK2, LK4, and LK6 must be inserted. LK3 and LK5 are required to communicate via UART. The required driver software for the J-Link OB can be downloaded from the Segger website. Ensure that you also install the virtual COM port drivers (see Figure 6).

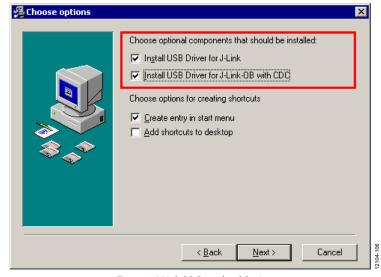


Figure 6. J-Link OB Download Options

DIGITAL HEADER PAD LOOKUP TABLE

Table 5. Pinout for Digital Header 1 Pad (J20) on EVAL-ADuCM350EBZ

Top Row (from Left to Right)		Bottom Row (from Left to Right)	
Pin No.	Internal Connection	Pin No.	Internal Connection
J20-2	P2.1	J20-1	P2.0
J20-4	P2.3	J20-3	P2.2
J20-6	P2.5	J20-5	P2.4
J20-8	P1.0	J20-7	P1.1
J20-10	P1.2	J20-9	P1.3
J20-12	P1.4	J20-11	P1.5
J20-14	P1.6	J20-13	P1.7
J20-16	P3.8	J20-15	P1.9
J20-18	P3.3	J20-17	P3.9
J20-20	P1.11	J20-19	P1.8
J20-22	P1.13	J20-21	P1.10
J20-24	P1.15	J20-23	P1.12
J20-26	P2.11	J20-25	P1.14
J20-28	P2.12	J20-27	P2.10
J20-30	P2.15	J20-29	P2.9
J20-32	P3.10	J20-31	P2.8
J20-34	P2.13	J20-33	P2.7
J20-36	P3.11	J20-35	P2.6
J20-38	P3.0	J20-37	P2.14
J20-40	P3.1	J20-39	P3.2
J20-42	P3.5	J20-41	P3.4
J20-44	P3.7	J20-43	P3.6
J20-46	N/A	J20-45	N/A
J20-48	N/A	J20-47	N/A
J20-50	N/A	J20-49	N/A

Table 6. Pinout for Digital Header 2 Pad (J5) on EVAL-ADuCM350EBZ

Top Row (from Left to Right)		Во	Bottom Row (from Left to Right)	
Pin No.	Internal Connection	Pin No.	Internal Connection	
J5-19	N/A	J5-20	N/A	
J5-17	N/A	J5-18	N/A	
J5-15	N/A	J5-16	N/A	
J5-13	N/A	J5-14	N/A	
J5-11	P0.14	J5-12	P0.15	
J5-9	P0.12	J5-10	P0.13	
J5-7	P1.0	J5-8	P0.11	
J5-5	P4.1	J5-6	P4.2	
J5-3	P3.14	J5-4	P4.0	
J5-1	P3.12	J5-2	P3.13	

ADUCM350 MOTHERBOARD SCHEMATICS

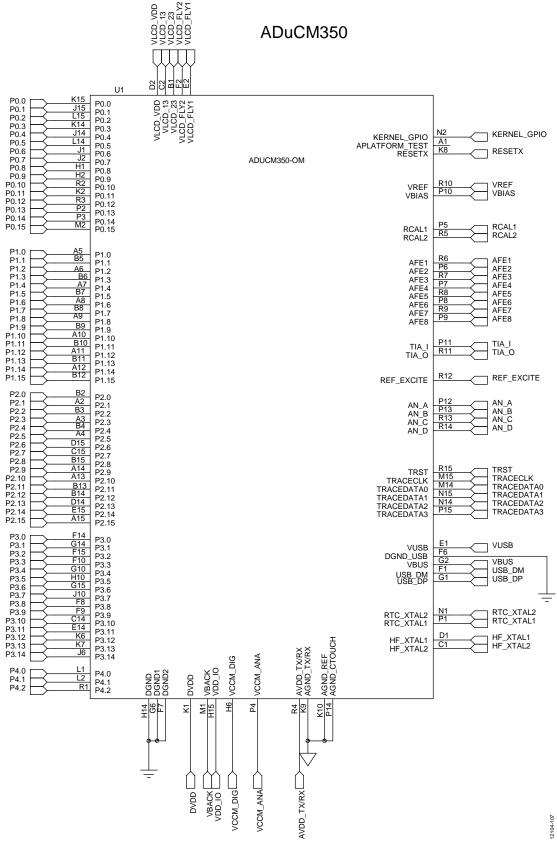
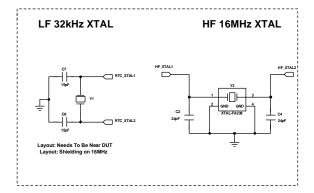
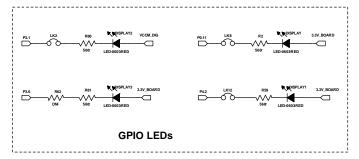
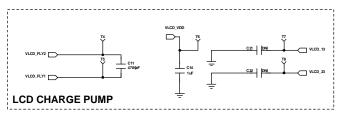


Figure 7. ADuCM350 Motherboard Schematic Device Drawing

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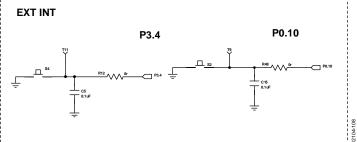


Figure 8. Digital Schematics 1

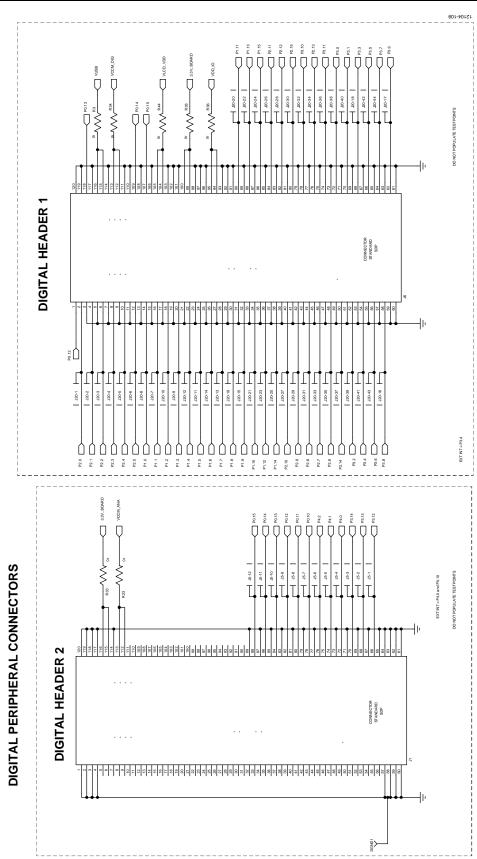


Figure 9. Digital Schematics 2

R

Ξ

N

TIA_0

R47

RCAL2

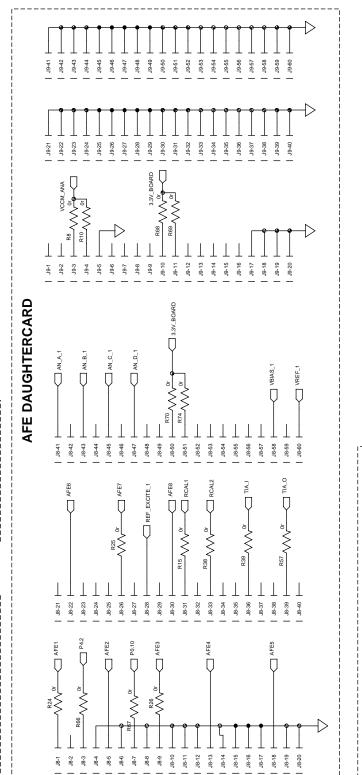
R5

LAyout: Needs To Be Near DUT

IV GAIN

RCAL

12104-110



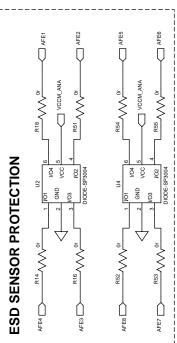
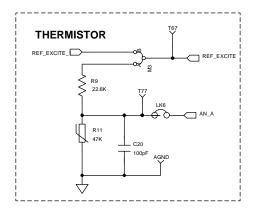
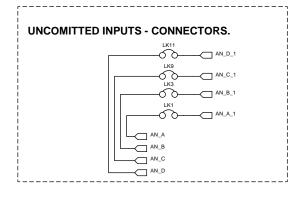
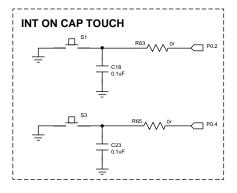


Figure 10. Analog Schematics 1







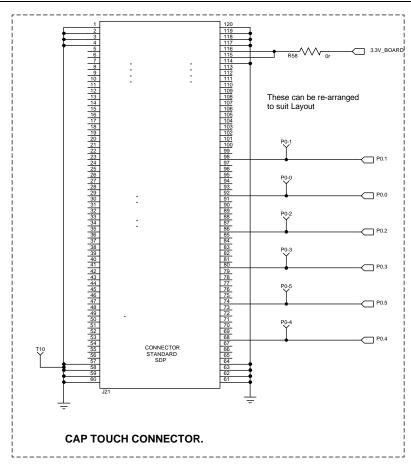


Figure 11. Analog Schematics 2

7

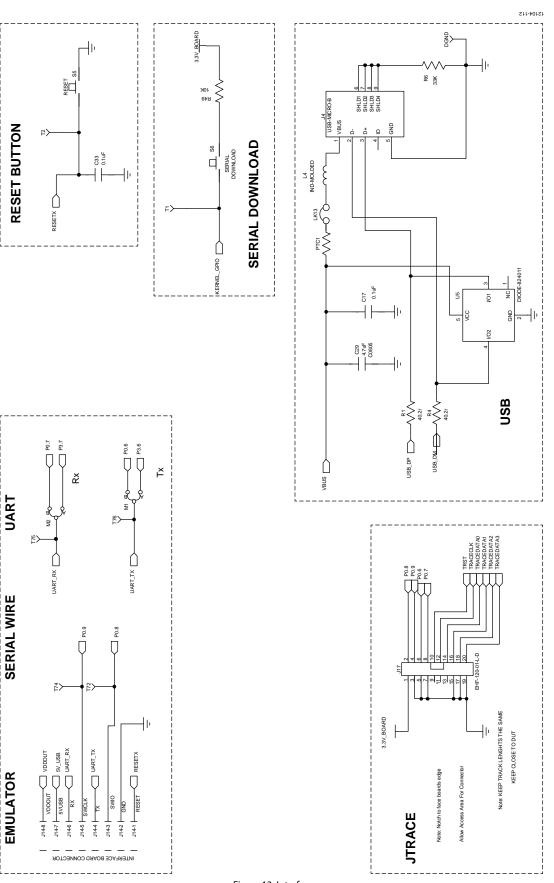


Figure 12. Interface
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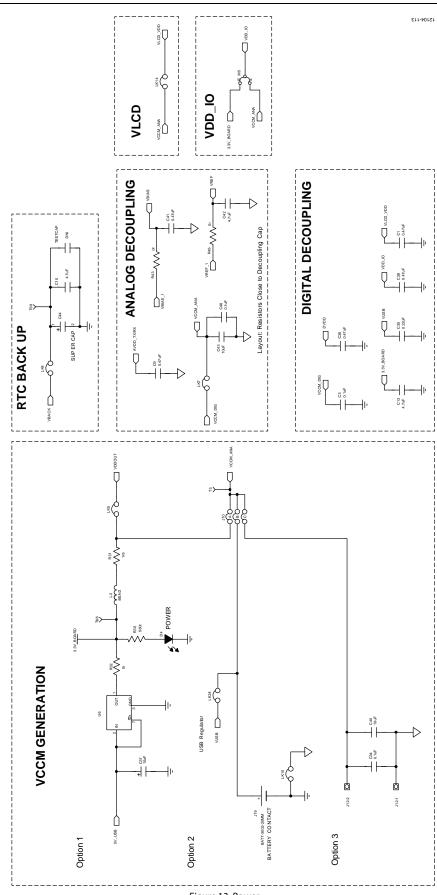


Figure 13. Power
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ADUCM350 DAUGHTER BOARD SCHEMATICS

ADUCM350 SWITCH MUX CONFIGURATION BOARD

MOTHERBOARD CONNECTOR—ALIGN J8 AND J9.

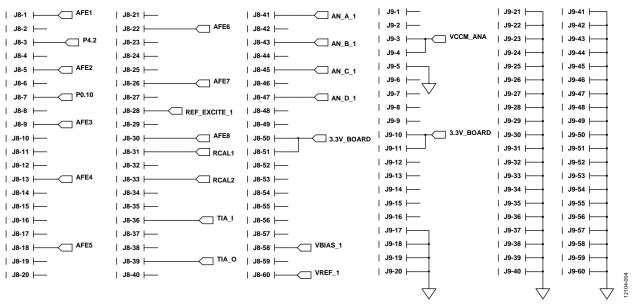


Figure 14. Switch Mux Configuration

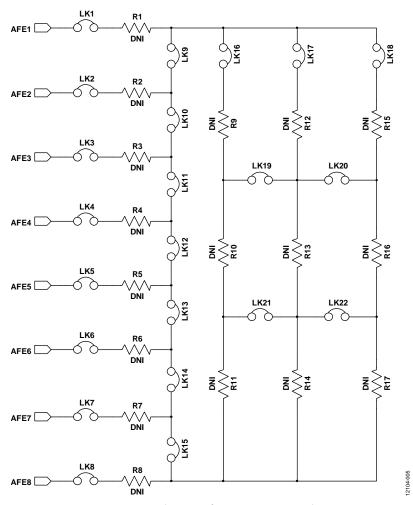


Figure 15. Switch Mux Configuration—Sensor Hookup

ADUCM350 4-WIRE BIO CONFIGURATION 2 BOARD

MOTHERBOARD CONNECTOR—ALIGN J8 AND J9.

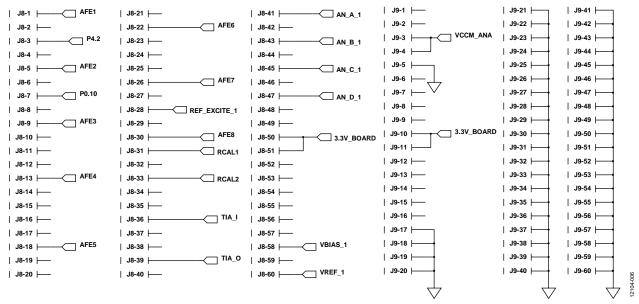


Figure 16. 4-Wire Bio Configuration Header Connections

4 WIRE BIO IMPEDANCE CONFIGURATION

UNCOMITTED CONFIGURATION

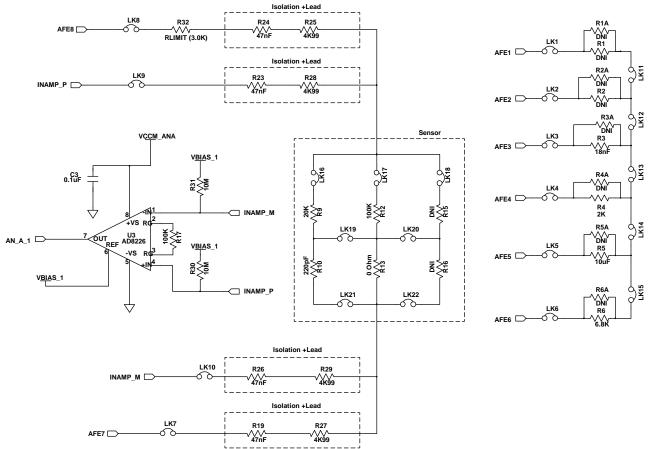


Figure 17. 4-Wire Bio Configuration Sensor Connections

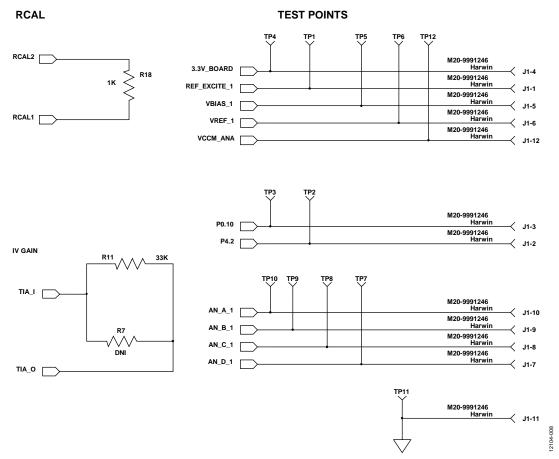


Figure 18. 4-Wire Bio Configuration Miscellaneous Connections

AUDIO DAUGHTER BOARD REFERENCE SCHEMATICS

The Figure 19 schematic is connected to Digital Header 2 (J1) on the EVAL-ADuCM350EBZ board.

BEEPER AND I2S AMPLIFIER

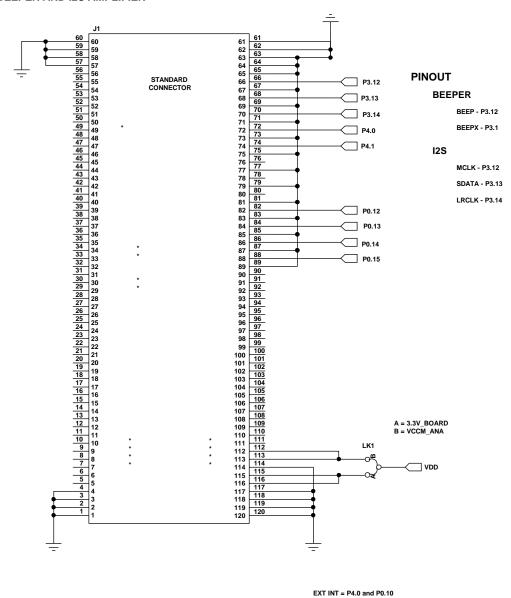


Figure 19. Audio Schematic

Figure 20 is a reference schematic both for the beeper/piezoelectric buzzer setup and for the I²S setup using the SSM2518.

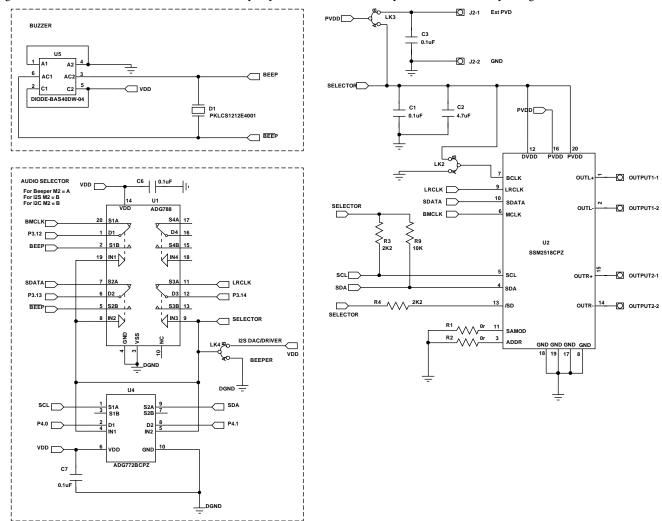


Figure 20. Audio Schematic

DISPLAY BOARD REFERENCE SCHEMATICS

The Figure 21 schematic is the connector to Digital Header 1 (J6) on the EVAL-ADuCM350EBZ board.

DISPLAY/PDI HEADER

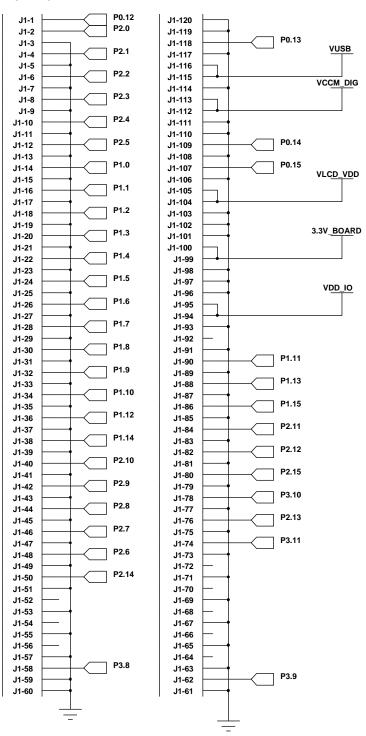


Figure 21. Display (LCD or TFT) Header Connector

TFT Display Reference Schematic

The schematic shown in Figure 22 is used to connect to an INT035TFT or INT035TFT-TS thin film transistor LCD module from Displaytech Ltd.

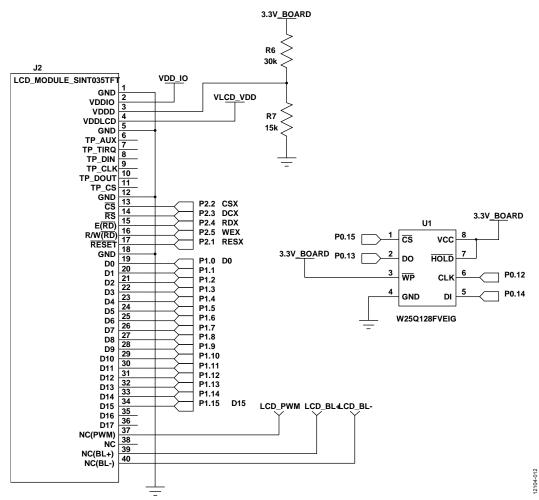


Figure 22. TFT Connector Displaytech Screen and External Flash Memory Schematic

LCD Segment Display Reference Schematic

The schematic shown in Figure 23 is used to connect to a VIM-828 LCD segment display from Varitronix.

CONNECTOR FOR VIM-828 - TO DISCUSS

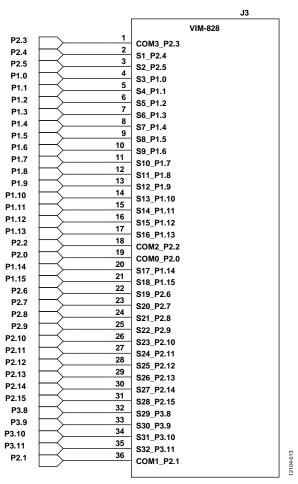


Figure 23. LCD Connector Schematic for VIM-828 LCD Segment Display

BREAKOUT BOARD PIN CONNECTIONS

If using the ADuCM350 breakout board, the connections shown in Figure 24 and Figure 25 are required.

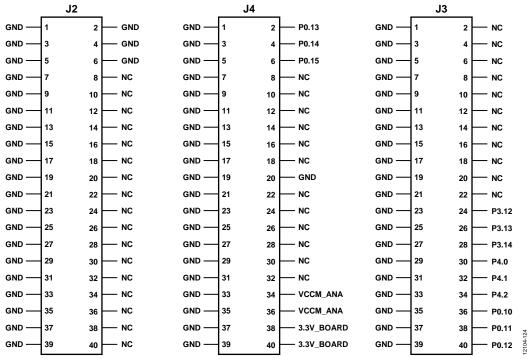


Figure 24. Breakout Board Connections for J1 on EVAL-ADuCM350EBZ with LK1 in Position B

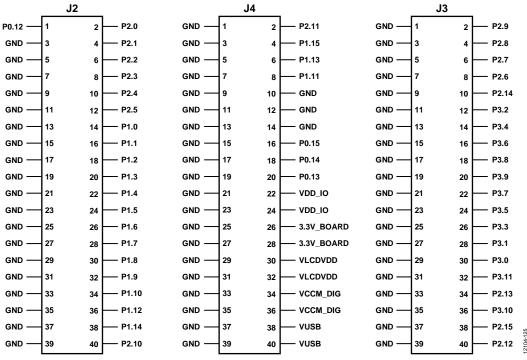


Figure 25. Breakout Board Connections for J1 on EVAL-ADuCM350EBZ with LK1 in Position A

GPIO TEST HEADER BOARD

The Figure 26 schematic is the connector to Digital Header 1 (J6) on the EVAL-ADuCM350EBZ board.

DIGITAL HEADER 1

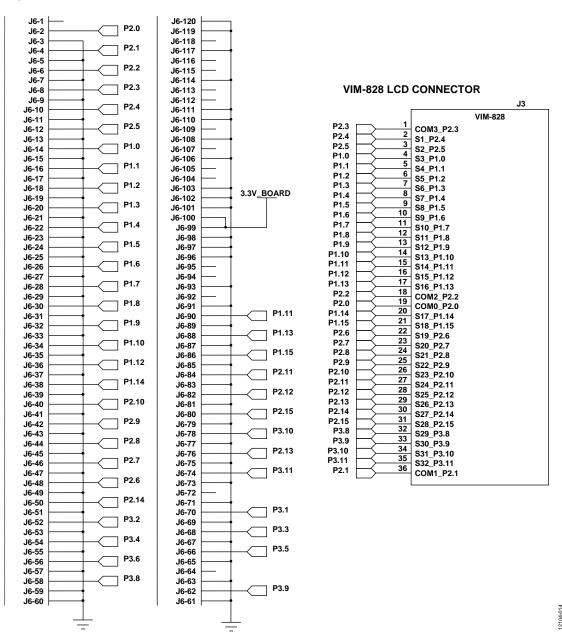


Figure 26. LCD Connector Schematic for VIM-828 LCD and Digital Header Schematic

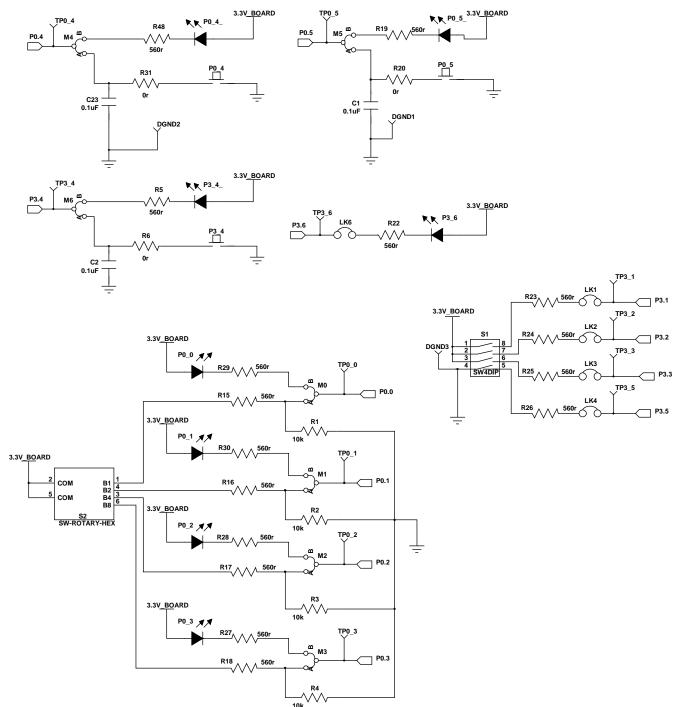


Figure 27. GPIO Evaluation Schematic

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NOTES



ESD Caution

ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

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