TE201416: SINYAL DAN SISTEM



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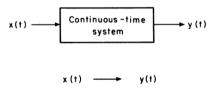
Bahan Kajian

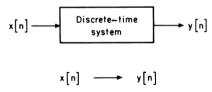


- 1. Definisi Sistem
- 2. Interkoneksi Antar Sistem
- 3. Karakteristik Sistem

Definisi Sistem



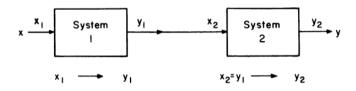


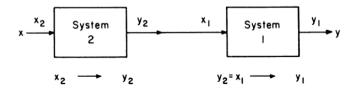


Interkoneksi Antar Sistem



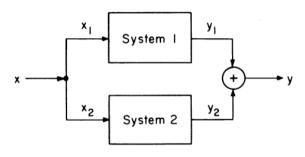
Cascade







parallel

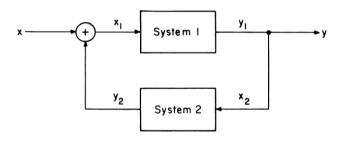


$$x_1 = x_2 = x$$
$$y = y_1 + y_2$$





feedback



$$y = y_1$$

Karakteristik Sistem



MEMORYLESS

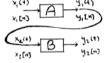
y(+) @t=t==+(+)@t=t,

y[n]@n=10 -x[n]@n=1.

Examples

 $\frac{1}{2}(y(t)) = \int_{0}^{t} x^{2}(t) dt$

I NYERTIBILITY



x2 = 4.

If 3 = Inverse of A



System A:

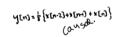
Karakteristik Sistem



Causality

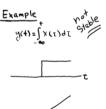
output at any time depends only on input prior or equal to that time or: system can't anticipate "future" inputs or: x, (4) - 4, (4) x2 (+) - 42 (+) TÇ: x, (+)= x2(+) t < +. Then: 4,(+) = 42(+) t + to Same for discrete Time

Example: ytrs=\frac{1}{3} \{x(n-0) + x(n-1) \times \{x(n-1) \times \{x(n-1)\}\} \ti



y[ri]

Stability >> For every bounded input the output is bounded



Stable?

Karakteristik Sistem



Time Invariance		Linearity
C-T;	Example	C.T & D.T
	(a) d)	*(+) -9,(+)
Then $\times (4-t_0) \longrightarrow 9(4-t_0)$	yce)=(sint)*ce)	xe(t) -> y2(t)
	x(t) - (sint)x(t)	Then:
D-T: x[n] - y[n] Then x[n-n ₀] - y[n-r ₀]	x(t-to) (Sint)x(t-to)	ax(4)+642(4)
x[n-no] - y[n-r.,]	+	Examples
Example Committee	yetton = sinct to excetta	y(+)= 5x(z)dz yes
Example y[n] = \(\sum_{k=-}^{n} \times \(\times \) \\ \text{Qccumulation} \\ \text{Qccumulation} \\ \text{Qccumulation} \\ \text{Qccumulation} \\ \text{Y[n]} = \(\sum_{k=-}^{n} \times \(\times \) \\ \text{Qccumulation} \\ \t	Time Invariant? No	y 603 = 2 x 603 +3 But
Time Invariant?		400 - x200 Not